Question 1. [10 MARKS]

Part (a) [1 mark]

For a convex optimization problem which of the following will never converge:

- i. batch gradient descent
- ii. mini-batch gradient descent
- iii. stochastic gradient descent
- iv. only (ii) and (iii) will not converge
- v. none of the above

Part (b) [1 mark]

What is the computational complexity of sorting a list of n numbers?

- i. O(n)
- ii. O(nlogn)
- iii. $O(n^2)$
- iv. $O(n^2 \log n)$
- v. none of the above

Part (c) [1 mark]

What is the computational complexity of the following sample code?

$$a = n$$
while $a > 1$:
 $a=a*0.9$

- i. O(n)
- ii. O(sqrt(n))
- iii. O(logn)
- iv. O(nlogn)
- v. none of the above

Part (**d**) [1 mark]

L2 regularization should be applied on which of the following:

- i. learning rate
- ii. bias
- iii. weights
- iv. both (ii) and (iii)
- v. none of the above

Part (e) [1 mark]

Which of the following is true about optimizers?

- i. We can speed up training by applying a different learning rates on each weight.
- ii. Reducing the batch size will always speed up training time.
- iii. You wouldn't use SGD to train a linear regression model.
- iv. You can only find the global minimum when the problem is convex.
- v. none of the above

Part (**f**) [1 mark]

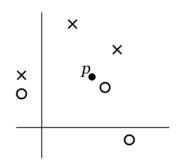
We would like to use 1-Nearest Neighbour to classify point *p* using the data to the right. What is our prediction if we use cosine similarity distance? Euclidean distance?

i. Cosine distance: O, Euclidean distance: O

ii. Cosine distance: X, Euclidean distance: O

iii. Cosine distance: O, Euclidean distance: X

iv. Cosine distance: X, Euclidean distance: X



Part (**g**) [1 mark]

Which of the following about a high variance model (in the context of bias-variance tradeoff) is true, compared to a high bias model?

- i. A high variance model is more prone to underfitting.
- ii. A high variance model requires more training data to train.
- iii. A high variance model will have a higher training accuracy.
- iv. A high variance model should be trained with a smaller batch size.
- v. Both (ii) and (iii) are true.

Part (**h**) [1 mark]

For which of the following problems would you choose a machine learning technique?

- i. Determining where a piece of Python code prints out the value "Hello, world".
- ii. Determining whether a photograph is in black and white or in colour.
- iii. Determining whether a photograph is of a young person or an old person.
- iv. All of the above.
- v. Only (ii) and (iii).

Part (i) [1 mark]

Which of the following will most likely produce a more noisy training curve?

- i. Decreasing the batch size.
- ii. Decreasing the learning rate.
- iii. Decreasing the size of the training set.
- iv. Increasing the size of the training set.
- v. Increasing the number of parameters of the neural network.

Part (**j**) [1 mark]

Which of the following helps prevent overfitting?

- i. Increasing the number of layers in a neural network.
- ii. Training for more epochs.
- iii. Using a larger batch size.
- iv. Using a larger training set.
- v. Both (iii) and (iv).

Question 2. [10 MARKS]

Circle either "True" or "False" for each of the below statements.

a	True	False	Data augmentation techniques can be applied to both the training and test data to limit overfitting.
b.	True	False	Gradient descent cannot get stuck in a local minimum when training a logistic regression model.
c.	True	False	PCA can be applied on a correlation matrix
d.	True	False	It is not necessary to have a target variable for applying dimensionality reduction algorithms.
e.	True	False	In general, a mixture of gaussian model will perform better if you restrict the covariance matrix to be diagonal.
f.	True	False	L2 regularization works better when the data is standardized.
g.	True	False	You cannot use ROC to measure the performance on a multiclass classification problem.
h.	True	False	You can use squared-error loss to solve classification problems.
i.	True	False	Importance sampling allows us to sample from a known distribution when using the true distribution is intractable.
j	True	False	Hyperparameters are tuned and updated during backpropagation.

Question 3. [8 MARKS]

Provided below is sample code for k-means clustering. You may assume all the necessary libraries are includes and that there are no syntax errors.

```
def kmeans(x, k, n_iter):
    ind = np.random.randint(0, len(x)-1, k)
    centroids = x[ind, :]
    distances = compute distances(x, centroids)
    labels = np.array([np.argmin(i) for i in distances])
    for in range(n iter):
        centroids = []
        for ind in range(k):
            cent = x[points==ind].mean(axis=0)
            centroids.append(cent)
        centroids = np.vstack(centroids)
        distances = compute_distances(x, centroids)
        labels = np.array([np.argmin(i) for i in distances])
    return (labels, centroids)
def compute distances(x, centroids):
```

Part (a) [2 mark]

Fill in the compute_distances function to obtain the Euclidean distance between all points and k clusters.

Part (b) [4 mark]

What would you add and/or change in the kmeans function to ensure that we converge to the global minimum? Provide your answer(s) in/next to the code above. Assume k is fixed.

Part (c) [2 mark]

As the dimensionality of the input data increases what happens to the Euclidean distance measurements?

Question 4. [8 MARKS]

Consider a dataset of physiological measurements of elite athletes.

	Meaning of variables
X1	Skinfold thickness
X2	Grip strength
Х3	Maximal vertical jump capacity
X4	Maximal lactate steady state (endurance)
X5	Maximum oxygen uptake (aerobic fitness)
Х6	Mean corpuscalar hemoglobin count (resistance to and recovery from fatigue)

	Meaning of variables
X7	Anaerobic power
X8	Maximum heart rate
Х9	Muscle mass
X10	Muscle fatigue onset time
X11	Pulmonary ventilation rate

A principal component analysis was performed yielding the following results.

Eigenvalues = $[7.49 \ 3.23 \ 1.84 \ 0.26 \ 0.20 \ 0.13 \ 0.08 \ 0.05 \ 0.04 \ 0.02 \ 0.01]^T$

The first five eigenvectors are:

	0.075	-0.034	-0.130	0.241	0.019
	0.010	-0.109	0.007	-0.122	-0.008
	-0.147	-0.102	-0.164	0.345	0.027
	0.397	-0.032	-0.033	-0.109	-0.006
Figure ve et eus -	0.833	-0.165	-0.113	-0.220	-0.011
Eigenvectors =	-0.232	-0.891	-0.285	-0.193	-0.032
	0.004	-0.003	0.040	0.029	0.004
	0.034	-0.166	0.208	-0.026	0.008
	-0.234	0.109	0.311	-0.783	-0.066
	-0.108	0.341	-0.849	-0.294	-0.062
	0.016	-0.001	0.038	0.095	-0.995
	-				

Part (a) [2 marks]

If we would like to capture 90% of the variance, what would you recommend as the dimensionality? Justify your answer.

Part (b)	[2 marks]	
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Given a sample $x = [0.1 -0.3 \ 0.4 -0.1 \ 0.2 \ 0.6 -0.2 \ 0.5 -0.1 \ 0.9 \ -0.1]^T$ what would be its new coordinates using the top two principal components?

Part (c) [2 marks]

How would you go about determining a name or label for the principal components? Try to assign a semantic label for the first two principal components.

Part (d) [2 marks]

Can SVD and PCA produce the same projection result? If yes, under what condition are they the same?

Question 5. [7 MARKS]

Answer the following questions given that V is of \mathbb{R}^2 and we have two sets of bases, $U = \{[a \ b]^T, [c \ d]^T\}$, $W = \{[e \ f]^T, [g \ h]^T\}$ that span V. We are also provided sample points $v_1 = [1 \ 1]^T$ and $v_2 = [2 \ 1]^T$ and their coordinates in U and W, $[v_1]_W = [7 \ 1]^T$, $[v_2]_W = [13 \ 3]^T$, $[v_1]_U = [-1 \ 25]^T$ and $[v_2]_U = [-6 \ 22]^T$.

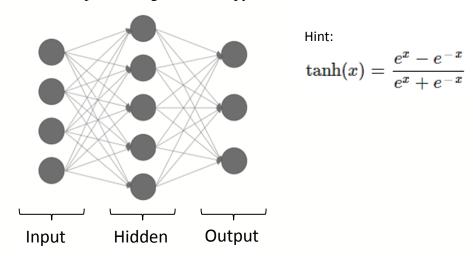
Part (a) [5 marks]

Compute the transformation matrix $A_{U\to W}$.

Part (b) [2 marks] If $[v_3]_W = \begin{bmatrix} 1 & -4 \end{bmatrix}^T$, calculate $[v_3]_U$.

Question 6. [9 MARKS]

The following question pertains to a 2-layer artificial neural network used for multiclass classification. The network uses a tanh activation on the hidden layer and softmax activation on the output layer. The error is computed using cross-entropy loss.



Part (a) [2 mark]

Write out the equations to perform the forward pass for the proposed neural network using vectorized notation.

Part (**b**) [2 mark]

Can this network learn nonlinearly separable decision boundaries? If yes, which part(s) of the architecture are necessary for nonlinear modelling?

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Part (c) [5 mark]

Determine the gradients with respect to the weights using vectorized notation. For this calculation you can ignore the bias terms.

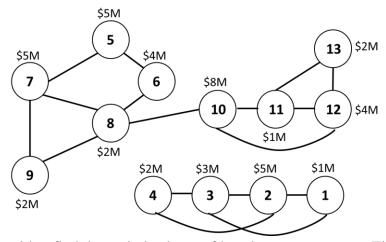
Question 7. [4 MARKS]

Show that minimizing the cross-entropy loss is equivalent to maximizing the log-likelihood of the training data under the assumption that data can be modeled by the provided distribution, where y ϵ {0, 1}:

$$P(y|x,\theta) = \hat{y}(x)^y \big(1 - \hat{y}(x)\big)^{(1-y)}$$

Question 8. [4 MARKS]

The following diagram represents a system of buildings that are interconnected on the university campus. Your goal is to select the optimal locations (1-13) to construct a Tim Hortons so that students can obtain a beverage and/or snack without having to traverse more than one connection. For example, a Tim Hortons at location 1 can be accessed by students in buildings 1, 2 and 3.



Using a greedy algorithm find the optimized sets of locations to construct a Tim Hortons. The cost to construct the Tim Horton's is specified for each of the proposed locations. Show all your work.