## 1 Problem

Compute the derivatives of the least squares loss  $L[\phi]$  with respect to  $\phi_0$  and  $\phi_1$  for the Gabor model equation 6.8.

## 2 Answer

$$f[x,\phi] = \sin(\phi_0 + 0.06 \cdot \phi_1 x) \cdot \exp\left(\frac{-(\phi_0 + 0.06 \cdot \phi_1 x)^2}{32.0}\right)$$
(1)

$$L[\phi] = \sum_{i=1}^{I} (f[x_i, \phi] - y_i)^2$$
(2)

$$\begin{split} \frac{\partial L[\phi]}{\partial \phi_0} &= \sum_{i=1}^{J} \frac{\partial L[\phi]}{\partial u_i} \cdot \frac{\partial u_i}{\partial \phi_0} \\ \text{Let us break it down} &\frac{\partial L[\phi]}{\partial u_i} &= 2 \cdot u_i = 2 \cdot \left( \sin(\phi_0 + 0.06 \cdot \phi_1 x) \cdot \exp\left( \frac{-(\phi_0 + 0.06 \cdot \phi_1 x_i)^2}{32.0} \right) - y_i \right) \\ &\frac{\partial u_i}{\partial \phi_0} &= \frac{\partial \sin(\phi_0 + 0.06 \cdot \phi_1 x) \cdot \exp\left( \frac{-(\phi_0 + 0.06 \cdot \phi_1 x_i)^2}{32.0} \right)}{\partial \phi_0} \\ \text{Let } p &= \sin(\phi_0 + 0.06 \cdot \phi_1 x_i) \\ \text{Let } q &= \exp\left( \frac{-(\phi_0 + 0.06 \cdot \phi_1 x_i)^2}{32.0} \right) \\ \text{So that } &\frac{\partial u_i}{\partial \phi_0} &= p \frac{\partial q}{\partial \phi_0} + q \frac{\partial p}{\partial \phi_0} \\ \text{Let } r &= \phi_0 + 0.06 \cdot \phi_1 x_i \\ \text{So that } &\frac{\partial q}{\partial \phi_0} &= \frac{\partial \sin(\phi_0)}{\partial r} \cdot \frac{\partial r}{\partial \phi_0} \\ \text{So that } &\frac{\partial q}{\partial \phi_0} &= \frac{\partial \cos(r)}{\partial r} \cdot \frac{\partial r}{\partial \phi_0} \\ \text{So that } &\frac{\partial q}{\partial \phi_0} &= \frac{\partial \cos(r)}{\partial r} \cdot \frac{\partial r}{\partial \phi_0} \\ \text{So that } &\frac{\partial q}{\partial \phi_0} &= \frac{\partial \cos(r)}{\partial r} \cdot \frac{\partial r}{\partial \phi_0} \\ \text{Let } t &= \phi_0 + 0.06 \cdot \phi_1 x_i \\ \text{So that } &\frac{\partial q}{\partial \phi_0} &= \frac{\partial \sin^2 t}{\partial r} \cdot \frac{\partial r}{\partial \phi_0} \\ \text{Let } t &= \phi_0 + 0.06 \cdot \phi_1 x_i \\ \text{So that } &\frac{\partial s}{\partial \phi_0} &= \frac{\partial \sin^2 t^2}{\partial r} \cdot \frac{\partial r}{\partial \phi_0} \\ \text{Substituting } &\frac{\partial q}{\partial \phi_0} &= \exp(s) \cdot \frac{\partial r}{\partial r} \cdot \frac{\partial r}{\partial r} \\ \text{Substituting } &\frac{\partial q}{\partial \phi_0} &= \exp(s) \cdot \frac{\partial r}{\partial r} \cdot \frac{\partial r}{\partial r} \\ \text{So that } &\frac{\partial r}{\partial \phi_0} &= \cos(\phi_0 + 0.06 \cdot \phi_1 x_i) \cdot (1) \\ \text{So that } &\frac{\partial r}{\partial \phi_0} &= \cos(\phi_0 + 0.06 \cdot \phi_1 x_i) \cdot \frac{\partial r}{\partial r} \\ \text{So that } &\frac{\partial r}{\partial \phi_0} &= \sin(\phi_0 + 0.06 \cdot \phi_1 x_i) \cdot \frac{\partial r}{\partial r} \cdot \exp\left(\frac{-(\phi_0 + 0.06 \cdot \phi_1 x_i)^2}{32.0}\right) \\ \text{So that } &\frac{\partial r}{\partial \phi_0} &= \sin(\phi_0 + 0.06 \cdot \phi_1 x_i) \cdot \frac{\partial r}{\partial r} \cdot \exp\left(\frac{-(\phi_0 + 0.06 \cdot \phi_1 x_i)^2}{32.0}\right) \\ \text{Finally } &\frac{\partial L[\phi]}{\partial \phi_0} &= \sum_{i=1}^{L} 2 \cdot \left(\sin(\phi_0 + 0.06 \cdot \phi_1 x) \cdot \exp\left(\frac{-(\phi_0 + 0.06 \cdot \phi_1 x_i)^2}{32.0}\right) - y_i\right) \\ &\cdot \left[\sin(\phi_0 + 0.06 \cdot \phi_1 x_i) \cdot -\frac{\phi_0 + 0.06 \cdot \phi_1 x_i}{16} \cdot \exp\left(\frac{-(\phi_0 + 0.06 \cdot \phi_1 x_i)^2}{32.0}\right) + \exp\left(\frac{-(\phi_0 + 0.06$$

Let  $u_i = f[x_i, \phi] - y_i$ 

Then  $L[\phi] = \sum_{i=1}^{I} (u_i)^2$