

## Problem 7.2

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### 1 Problem

Find the final derivatives for

$$f_0 = \beta_0 + \omega_0 \cdot x_i$$

$$h_1 = \sin[f_0]$$

$$f_1 = \beta_1 + \omega_1 \cdot h_1$$

$$h_2 = \exp[f_1]$$

$$f_2 = \beta_2 + \omega_2 \cdot h_2$$

$$h_3 = \cos[f_2]$$

$$f_3 = \beta_3 + \omega_3 \cdot h_3$$

$$l_i = (f_3 - y_i)^2$$

## 2 Answer

$$\begin{aligned}
\frac{\partial l_i}{\partial f_3} &= 2(f_3 - y_i) \\
\frac{\partial l_i}{\partial h_3} &= \frac{\partial l_i}{\partial f_3} \frac{\partial f_3}{\partial h_3} = 2(f_3 - y_i) \cdot \omega_3 \\
\frac{\partial l_i}{\partial f_2} &= \frac{\partial l_i}{\partial h_3} \frac{\partial h_3}{\partial f_2} = 2(f_3 - y_i) \cdot \omega_3 \cdot -\sin[f_2] = -2\omega_3(f_3 - y_i) \sin[f_2] \\
\frac{\partial l_i}{\partial h_2} &= \frac{\partial l_i}{\partial f_2} \frac{\partial f_2}{\partial h_2} = -2\omega_3(f_3 - y_i) \sin[f_2] \cdot \omega_2 = -2\omega_3\omega_2(f_3 - y_i) \sin[f_2] \\
\frac{\partial l_i}{\partial f_1} &= \frac{\partial l_i}{\partial h_2} \frac{\partial h_2}{\partial f_1} = -2\omega_3\omega_2(f_3 - y_i) \sin[f_2] \cdot \exp[f_1] \\
\frac{\partial l_i}{\partial h_1} &= \frac{\partial l_i}{\partial f_1} \frac{\partial f_1}{\partial h_1} = -2\omega_3\omega_2(f_3 - y_i) \sin[f_2] \cdot \exp[f_1] \cdot \omega_1 = -2\omega_3\omega_2\omega_1(f_3 - y_i) \sin[f_2] \cdot \exp[f_1] \\
\frac{\partial l_i}{\partial f_0} &= \frac{\partial l_i}{\partial h_1} \frac{\partial h_1}{\partial f_0} = -2\omega_3\omega_2\omega_1(f_3 - y_i) \sin[f_2] \cdot \exp[f_1] \cdot \cos[f_0] \\
\frac{\partial l_i}{\partial \beta_0} &= \frac{\partial l_i}{\partial f_0} \frac{\partial f_0}{\partial \beta_0} = -2\omega_3\omega_2\omega_1(f_3 - y_i) \sin[f_2] \cdot \exp[f_1] \cdot \cos[f_0] \\
\frac{\partial l_i}{\partial \omega_0} &= \frac{\partial l_i}{\partial f_0} \frac{\partial f_0}{\partial \omega_0} = -2\omega_3\omega_2\omega_1(f_3 - y_i) \sin[f_2] \cdot \exp[f_1] \cdot \cos[f_0] \cdot x_i
\end{aligned}$$

The final derivatives are just multiplying by 1 and  $h_k$  respectively from looking up the omega or beta from the formula definitions.

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dlldbeta3 = 2 * (f3 - y) * 1
dlldomega3 = 2 * (f3 - y) * h3
dlldbeta2 = dlldf2 * 1
dlldomega2 = dlldf2 * h2
dlldbeta1 = dlldf1 * 1
dlldomega1 = dlldf1 * h1
dlldbeta0 = dlldf0 * 1
dlldomega0 = dlldf0 * x

```