

# **Minimum Spanning Tree**

#### What is a Spanning Tree?

Given an undirected and connected graph G=(V,E), a spanning tree of the graph G is a tree that spans G (that is, it includes every vertex of G) and is a subgraph of G (every edge in the tree belongs to G)

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#### **Minimum Spanning Tree**

#### What is a Minimum Spanning Tree?

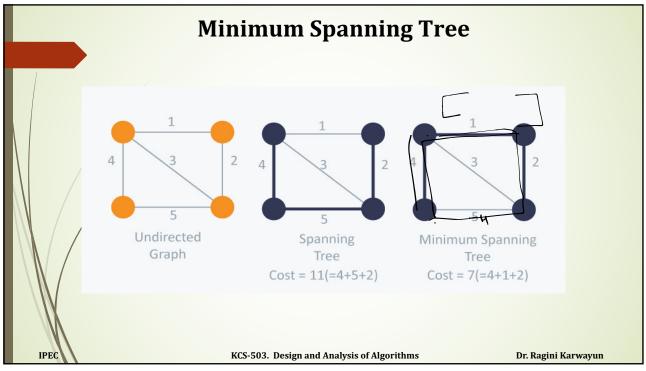
woight are unique

- The cost of the spanning tree is the sum of the weights of all the edges in the tree. There can be many spanning trees. Minimum spanning tree is the spanning tree where the cost is minimum among all the spanning trees. There also can be many minimum spanning trees.
- Minimum spanning tree has direct application in the design of networks. It is used in algorithms approximating the travelling salesman problem, multi-terminal minimum cut problem and minimum-cost weighted perfect matching.

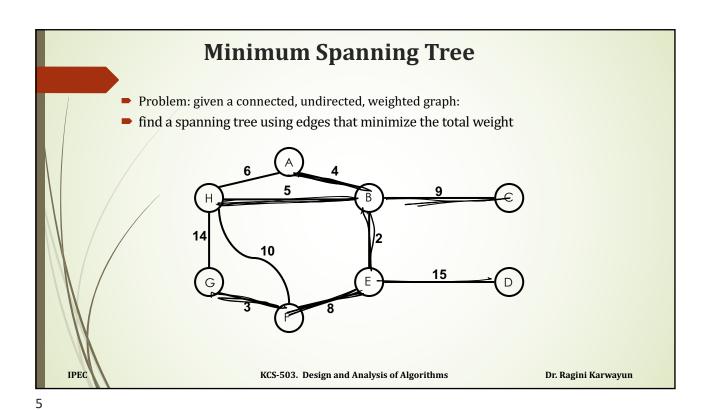
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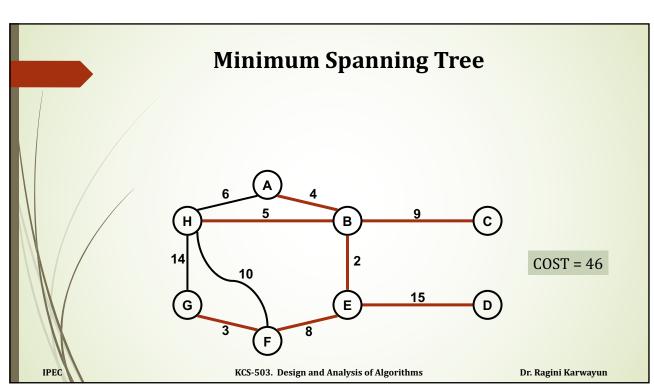
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#### **Minimum Spanning Tree**

- A spanning tree whose weight is minimum over all spanning trees is called minimum spanning tree.
- Greedy approach is followed to achieve MST.
- Problem: Connect a set of nodes by a network of minimal total length
- Some applications:
  - Communication networks
  - Circuit design
  - ► Layout of highway systems
- The resulting connection graph is connected, undirected, and acyclic, i.e., a *free tree* (sometimes called simply a *tree*).

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#### **Formal Definition of MST**

- Given a connected, undirected, graph G = (V, E), a spanning tree is an acyclic subset of edges  $T \subseteq E$  that connects all the vertices together.
- Assuming G is weighted, we define the cost of a spanning tree T to be the sum of edge weights in the spanning tree

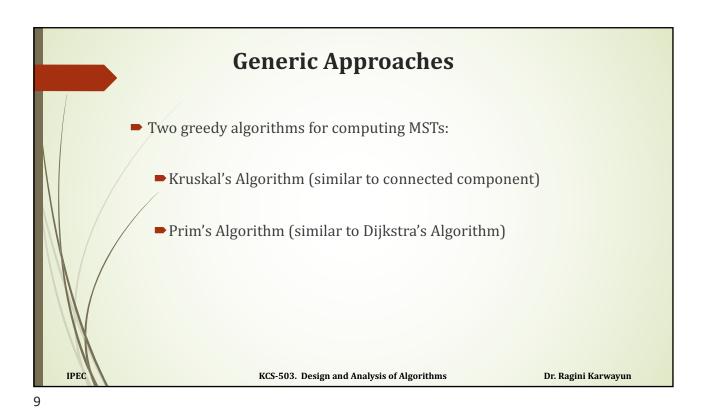
$$w(T) = \sum_{(u,v) \in T} w(u,v)$$

A minimum spanning tree (MST) is a spanning tree of minimum weight.

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Facts about (Free) Trees

• A tree with *n* vertices has exactly *n*-1 edges

(|E| = |V| - 1)

• There exists a unique path between any two vertices of a tree

• Adding any edge to a tree creates a unique cycle; breaking any edge on this cycle restores a tree

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#### **Intuition Behind Greedy MST**

- We maintain in a subset of edges A, which will initially be empty, and we will add edges one at a time, until equals the MST.
- ▶ We say that a subset  $A \subseteq E$  is *viable* if A is a subset of edges in some MST.
- ▶ We say that an edge  $(u,v) \in E$ -A is safe if  $A \cup \{(u,v)\}$  is viable.
- Basically, the choice (u,v) is a safe choice to add so that A can still be extended to form an MST.
- Note that if A is viable it cannot contain a cycle.
- A generic greedy algorithm operates by repeatedly adding any *safe edge* to the current spanning tree.

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## Generic-MST (G, w)

- 1.  $A \leftarrow \emptyset$  // A trivially satisfies invariant
  - // lines 2-4 maintain the invariant
- 2. while A does not form a spanning tree
- 3. find an edge (u,v) that is safe for A
- 4.  $A \leftarrow A \cup \{(u,v)\}$
- 5. return A // A is now a MST

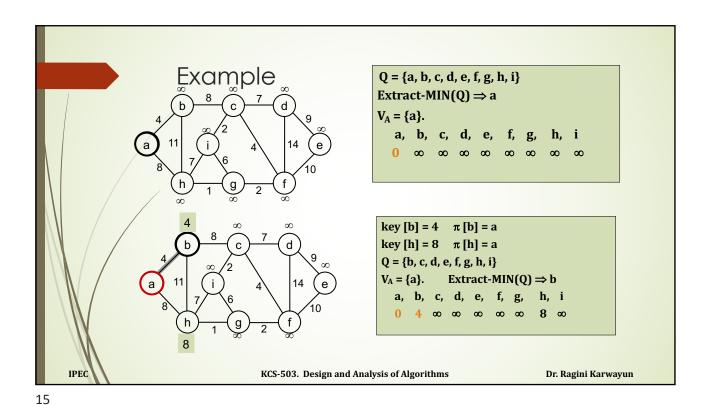
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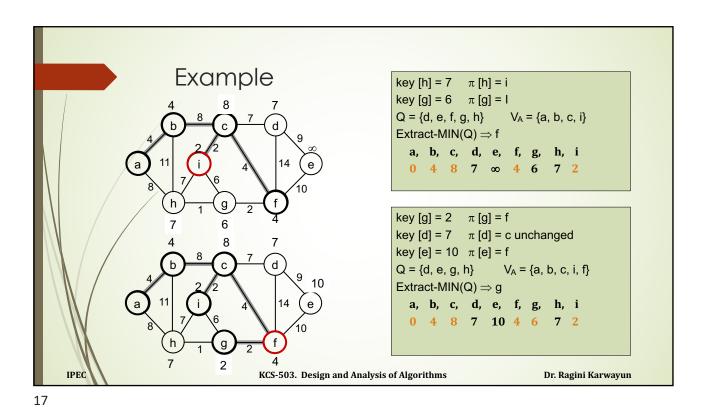
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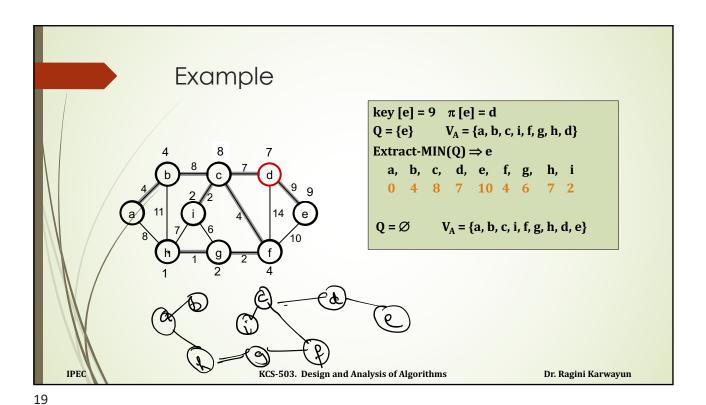
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MST-Prim(G, w, r)
1. Q \leftarrow V[G]
2. for each vertex u \in Q
                                  // initialization: O(V) time
        do key[u] \leftarrow \infty
        \pi[u] \leftarrow \text{NIL}
4. key[r] \leftarrow 0
                        // start at the root
5. \pi[r] \leftarrow \text{NIL} // set parent of r to be NIL
6. while Q \neq \emptyset
                              // until all vertices in MST
           u \leftarrow \text{Extract-Min}(Q) // vertex with lightest edge
8.
          for each v \in adj[u]
                 if v \in Q and w(u,v) < key[v]
9.
                     \pi[v] \leftarrow u
10.
                         key[v] \leftarrow w(u,v) // new lighter edge out of v
11.
                         decrease_{Key}(Q, v, key[v])
12.
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PRIM(V, E, w, r)  $Q \leftarrow \emptyset$ for each  $u \in V$ 3. do key[u]  $\leftarrow \infty$  $\pi[u] \leftarrow NIL$ 4. 5. INSERT(Q, u) DECREASE-KEY(Q, r, 0) 6. 7. while  $Q \neq \emptyset$  $Q = \{a, b, c, d, e, f, g, h, i\}$  $V_{\Delta} = \emptyset$ . do  $u \leftarrow EXTRACT-MIN(Q)$ . c, d, h, 9. for each  $v \in Adj[u]$  $\infty$   $\infty$   $\infty$ 10. do if  $v \in Q$  and w(u, v) < key[v]then  $\pi[v] \leftarrow u$ 11. DECREASE-KEY(Q, a, 0) 12. DECREASE-KEY(Q, v, w(u, v)) IPEC KCS-503. Design and Analysis of Algorithms Dr. Ragini Karwayun 14



key [c] =  $8 \pi [c] = b$ **Example** key [h] =  $8 \pi$  [h] = a - unchanged  $Q = \{c, d, e, f, g, h, i\}$   $V_A = \{a, b\}$  $Extract-MIN(Q) \Rightarrow c$ a, b, c, d, e, f, g, h, i 0 4 8 ∞ ∞ ∞ ∞ 8 ∞ key [d] =  $7 \pi [d] = c$ key[f] = 4 $\pi[f] = c$ key [i] =  $2 \pi [i] = c$  $Q = \{d, e, f, g, h, i\}$   $V_A = \{a, b, c\}$  $Extract-MIN(Q) \Rightarrow i$ a, b, c, d, e, f, g, **0 4 8 7** ∞ **4** ∞ KCS-503. Design and Analysis of Algorithms **IPEC** Dr. Ragini Karwayun





PRIM(V, E, w, r) 1.  $Q \leftarrow \emptyset$ Total time: O(VlgV + ElgV) = O(ElgV) 2. for each  $\mathbf{u} \in V$ 3. do key[u] ← ∞ O(V) if Q is implemented as a min-heap  $\pi[u] \leftarrow \text{NIL}$ 4. INSERT(Q, u) DECREASE-KEY(Q, r, 0) ▶  $\text{key}[r] \leftarrow 0$ while Q ≠ Ø ← Executed V times Min-heap operations: O(VlgV) do  $u \leftarrow EXTRACT-MIN(Q) \leftarrow Takes O(lqV)$ 8.  $\text{for each } v \in Adj[u] \qquad \longleftarrow \quad \text{Executed O(E) times}$ 9. do if  $v \in Q$  and w(u, v) < key[v] Constant O(ElqV) 10. Takes O(lgV) then  $\pi[v] \leftarrow u$ 11. 12. DECREASE-KEY(Q, v, w(u, v)) KCS-503. Design and Analysis of Algorithms Dr. Ragini Karwayun

### Performance of PRIM's Algorithm

Total time: O(VlgV + ElgV) = O(ElgV)

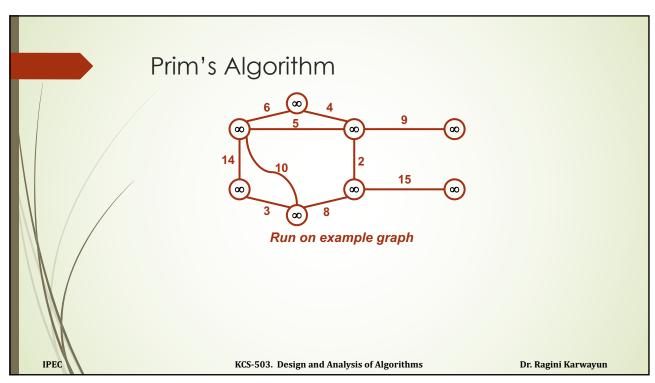
- Time Complexity of the above program is O(V^2), if the input graph is represented using adjacency list,
- The time complexity of Prim's algorithm can be reduced to O(E log V) with the help of binary heap.
- The time complexity of Prim's algorithm can be reduced to O(E + log V) with the help of Fibonacci Heap

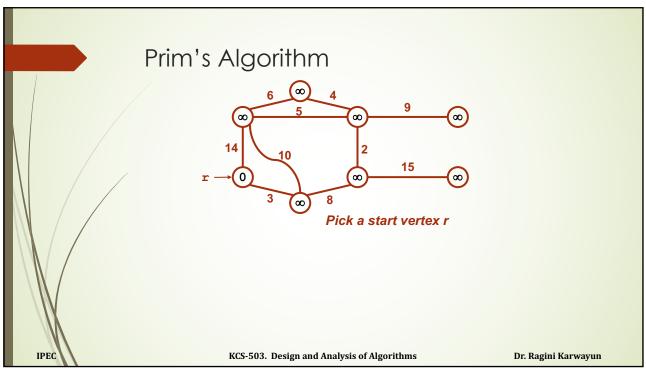
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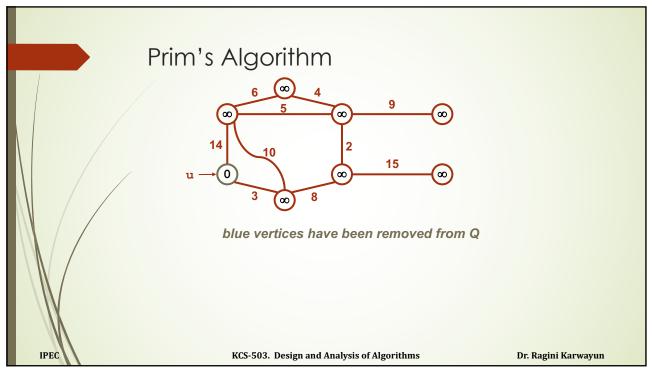
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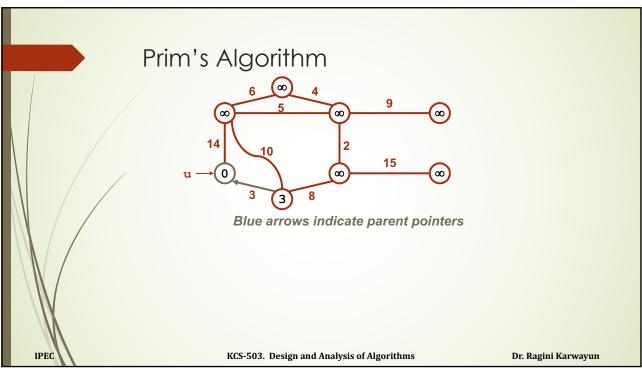
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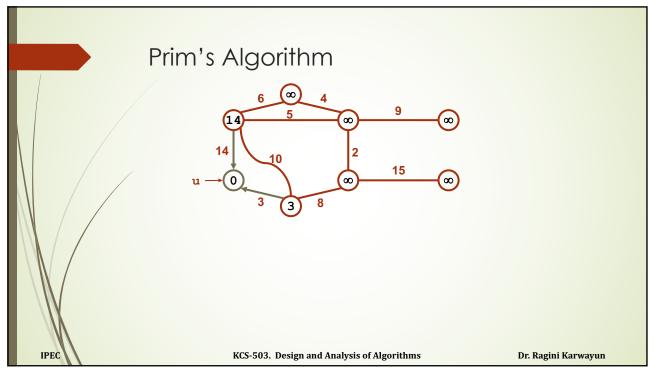
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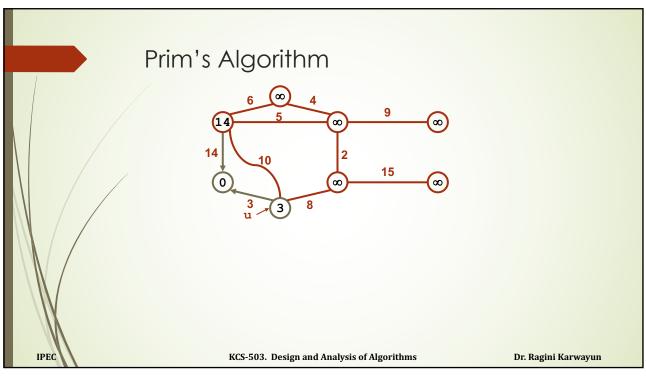


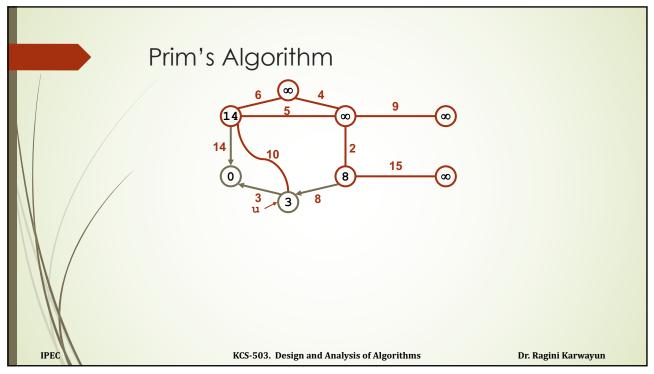


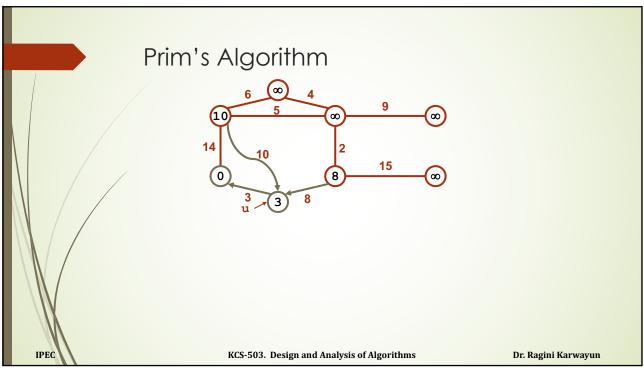


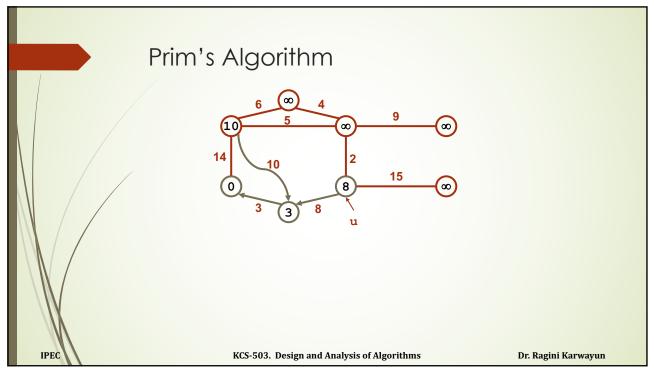


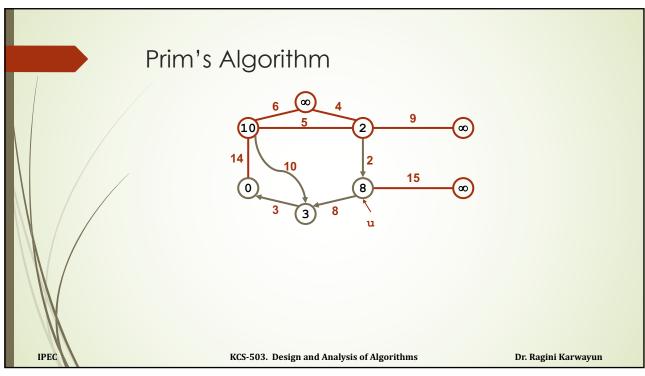


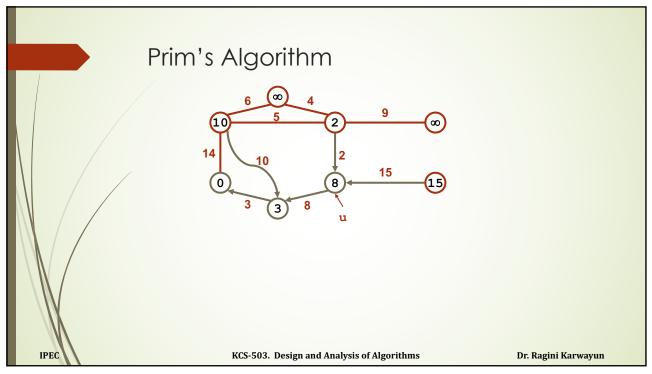


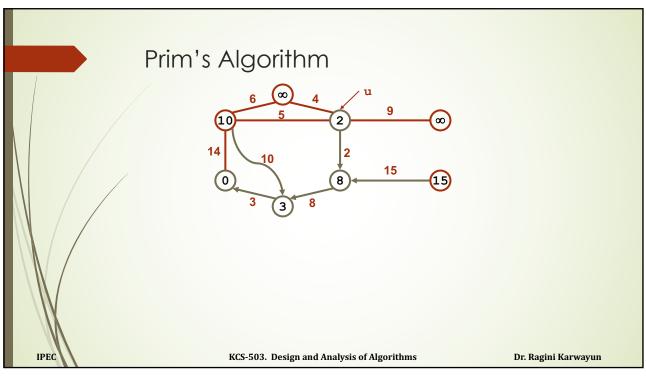


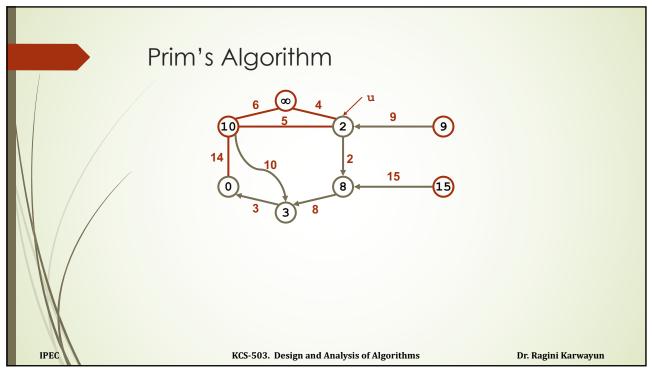


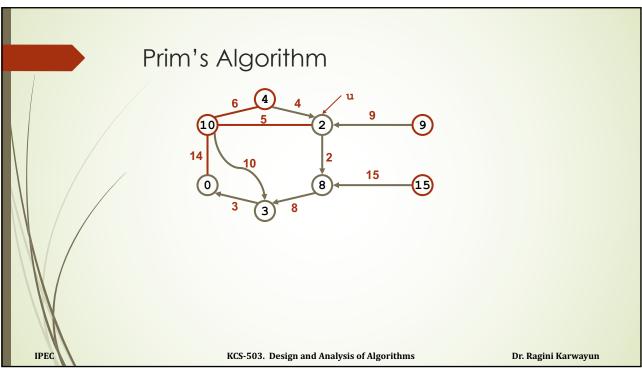


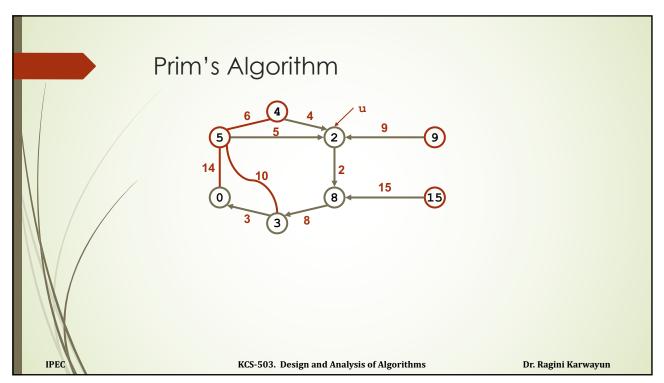


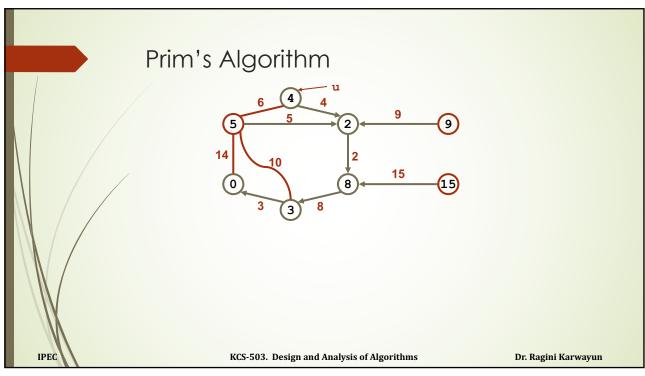


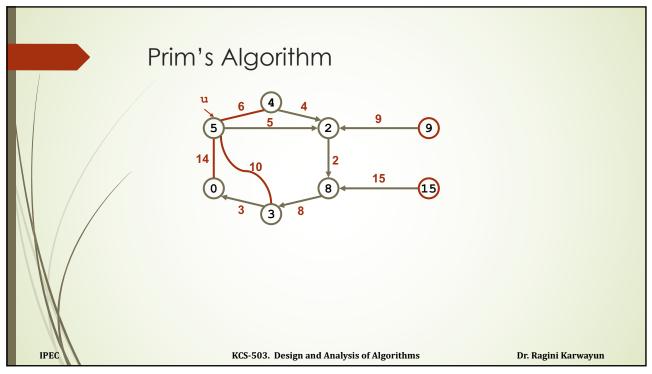


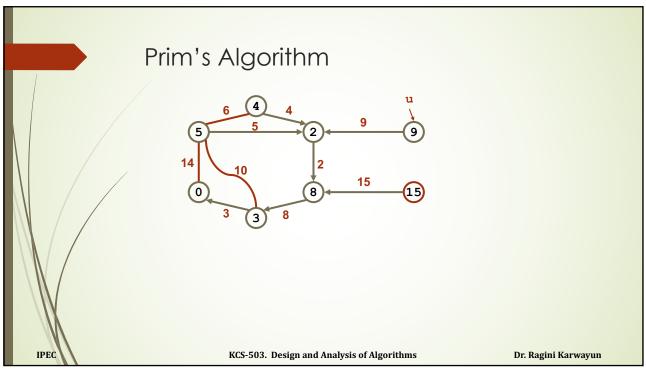


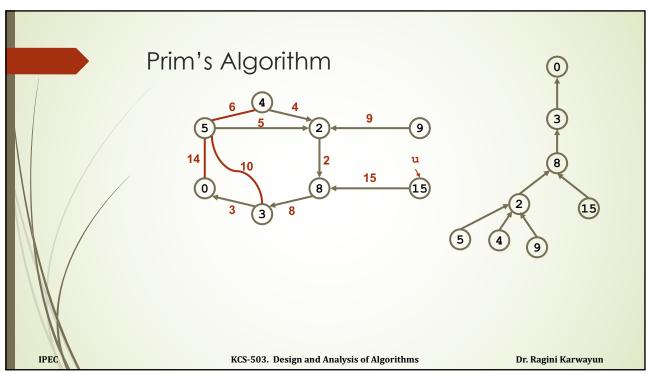












### **Basics of Kruskal's Algorithm**

- Attempts to add edges to A in increasing order of weight (lightest edge first)
  - If the next edge does not induce a cycle among the current set of edges, then it is added to *A*.
  - If it does, then this edge is passed over, and we consider the next edge in order.
  - As this algorithm runs, the edges of *A* will induce a forest on the vertices and the trees of this forest are merged together until we have a single tree containing all vertices.

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# MST-Kruskal(G, w)

```
1. A \leftarrow \emptyset
                                                 // initially A is empty
2. for each vertex v \in V[G]
                                                 // line 2-3 takes O(V) time
      do Make-Set(v)
                                                 // create set for each vertex
4. sort the edges of E by nondecreasing weight w
5. for each edge (u,v) \in E, in order by nondecreasing weight
      do if Find-Set(u) \neq Find-Set(v)
                                                 // u & v on different trees
            then A \leftarrow A \cup \{(u,v)\}
                 Union(u,v)
9. return A
                                                 Total running time is O(E \lg E).
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