Examples of using vOptSpecific, vOptGeneric, and vOptTools

Xavier Gandibleux

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Abstract

This document provides examples of using vOptSpecific, vOptGeneric, and vOptTools.

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1 Examples with the bi-objective linear assignment problem

The bi-objective linear assignment problem (2LAP)

$$\begin{bmatrix} \min z^k &=& \sum_{i=1}^n \sum_{j=1}^n c_{ij}^k x_{ij} & k = 1, \dots, 2 \\ s/c & & \sum_{i=1}^n x_{ij} = 1 & j = 1, \dots, n \\ & & \sum_{j=1}^n x_{ij} = 1 & i = 1, \dots, n \\ & & x_{ij} = (0, 1) & i = 1, \dots, n \\ & & & j = 1, \dots, n \end{bmatrix}$$

A numerical instance of 2LAP

$$C^1 = \left(\begin{array}{rrr} 3 & 9 & 7 \\ 16 & 10 & 6 \\ 2 & 7 & 11 \end{array}\right)$$

$$C^2 = \left(\begin{array}{rrr} 16 & 15 & 6 \\ 5 & 7 & 13 \\ 1 & 2 & 13 \end{array}\right)$$

1.1 vOptSpecific and 2LAP: data are explicitely provided

The program

```
julia> z1
4-element Array{Int64,1}:
16
19
30
17
julia> z2
4-element Array{Int64,1}:
31
14
13
29
julia> S
4x3 Array{Int64,2}:
0 2 1
2 1 0
   2 0
2 0 1
```

1.2 vOptSpecific and 2LAP: data and solver are explicitely provided

The program

```
julia> z1
4-element Array{Int64,1}:
19
30
17
julia> z2
4-element Array{Int64,1}:
31
14
13
29
julia> S
4x3 Array{Int64,2}:
0 2 1
2 1 0
1 2 0
2 0 1
```

1.3 vOptSpecific and 2LAP: read data on a file according to the LAP format

The program

```
using vOptSpecific

m = load2LAP("2ap03.dat")

z1, z2, S = vSolve( m ) # solver by default: LAP_Przybylski2008()
```

Example of a datafile (2ap03.dat)

```
3
3 9 7
16 10 6
2 7 11
16 15 6
5 7 13
1 2 13
```

```
julia> z1
4-element Array{Int64,1}:
16
19
30
17
julia> z2
4-element Array{Int64,1}:
31
14
13
29
julia> S
4x3 Array{Int64,2}:
0 2 1
2 1 0
1 2 0
2 0 1
```

1.4 vOptGeneric and 2LAP (2IP): data are explicitly provided

The program

```
n = 3
    C1 = [397;
 3
          16 10 6 ;
2 7 11 ]
 7
    C2 = [ 16 15 6 ;
            5 7 13 ;
1 2 13 ]
 8
9
10
11
    using vOptGeneric
    using GLPK ; using GLPKMathProgInterface
12
13
   m = vModel( solver = GLPKSolverMIP() )
14
15
   @variable( m , x[1:n,1:n] , Bin )
    @addobjective( m , Min, sum( C1[i,j]*x[i,j] for i=1:n,j=1:n ) )
16
17
    @addobjective( m , Min, sum( C2[i,j]*x[i,j] for i=1:n,j=1:n ) )
18 @constraint( m , cols[i=1:n], sum(x[i,j] for j=1:n) == 1 )
19 @constraint( m , rows[j=1:n], sum(x[i,j] \text{ for } i=1:n) == 1)
20 solve( m , method = :epsilon , step = 0.5 )
```

```
julia> print_X_E(m)
(16.0, 31.0) : x[1,1]=1 x[2,3]=1 x[3,2]=1
(17.0, 29.0) : x[1,2]=1 x[2,3]=1 x[3,1]=1
(19.0, 14.0) : x[1,3]=1 x[2,2]=1 x[3,1]=1
(30.0, 13.0) : x[1,3]=1 x[2,1]=1 x[3,2]=1

julia> getY_N(m)
4-element Array{Tuple{Vararg{Float64,N}} where N,1}:
(16.0, 31.0)
(17.0, 29.0)
(19.0, 14.0)
(30.0, 13.0)
```

1.5 vOptGeneric and 2LAP (2LP): data are explicitly provided

The program

```
n = 3
    C1 = [397;
 3
           16 10 6 ;
2 7 11 ]
 7
    C2 = [ 16 15 6 ;
            5 7 13 ;
1 2 13 ]
 8
9
10
11
    using vOptGeneric
    using GLPK ; using GLPKMathProgInterface
12
13
   m = vModel( solver = GLPKSolverLP() )
14
15
    @variable( m , x[1:n,1:n] >= 0 )
    @addobjective( m , Min, sum( C1[i,j]*x[i,j] for i=1:n,j=1:n ) )
16
17
    @addobjective( m , Min, sum( C2[i,j]*x[i,j] for i=1:n,j=1:n ) )
18 @constraint( m , cols[i=1:n], sum(x[i,j] for j=1:n) == 1 )
19 @constraint( m , rows[j=1:n], sum(x[i,j] \text{ for } i=1:n) == 1)
20 solve( m , method = :epsilon , step = 0.5 )
```

```
julia> getY_N(m)
37-element Array{Tuple{Vararg{Float64,N}} where N,1}:
 (16.0, 31.0)
 (16.0882, 30.5)
 (16.1765, 30.0)
 (16.2647, 29.5)
 (16.3529, 29.0)
 (16.4412, 28.5)
 (16.5294, 28.0)
 (16.6176, 27.5)
 (16.7059, 27.0)
 (16.7941, 26.5)
 (18.4706, 17.0)
 (18.5588, 16.5)
 (18.6471, 16.0)
 (18.7353, 15.5)
 (18.8235, 15.0)
 (18.9118, 14.5)
 (19.0, 14.0)
 (24.5, 13.5)
 (30.0, 13.0)
```

1.6 vOptGeneric and 2LAP (2IP): write on a file according to the MOP format

The program

```
n = 3
    C1 = [397;
 3
           16 10 6;
2 7 11 ]
 7
    C2 = [ 16 15 6 ;
             5 7 13 ;
1 2 13 ]
 8
 9
10
11
    using vOptGeneric
    using GLPK ; using GLPKMathProgInterface
12
13
    m = vModel( solver = GLPKSolverMIP() )
14
15
    @variable( m , x[1:n,1:n] , Bin )
    @addobjective( m , Min, sum( C1[i,j]*x[i,j] for i=1:n,j=1:n ) )
16
    @addobjective( m , Min, sum( C2[i,j]*x[i,j] for i=1:n,j=1:n ) )
17
18 @constraint( m , cols[i=1:n], sum(x[i,j] \text{ for } j=1:n) == 1)
19 @constraint( m , rows[j=1:n], sum(x[i,j] for i=1:n) == 1 )
20 writeMOP( m , "2ap03.mop" )
```

Example of a datafile (2ap03.mop)

```
NAME
      vOptModel
OBJSENSE
MIN
ROWS
N OBJ1
N OBJ2
E CON1
E CON2
E CON3
E CON4
E CON5
E CON6
COLUMNS
                                    'INTORG'
   MARKER
             'MARKER'
   x_1_1 CON1 1
   x_1_1 CON4 1
   x_1_1 OBJ1 3
   x_1_1 OBJ2 16
   x_1_2 CON1 1
   x_1_2 CON5 1
   x_1_2 OBJ1 9
   x_1_2 OBJ2 15
   x_1_3 CON1 1
   x_1_3 CON6 1
   x_1_3 OBJ1 7
   x_1_3 OBJ2 6
```

```
x_2_1 CON2 1
   x_2_1 CON4 1
   x_2_1 OBJ1 16
   x_2_1 OBJ2 5
   x_2_2 CON2 1
   x_2_2 CON5 1
   x_2_2 OBJ1 10
   x_2_2 OBJ2 7
   x_2_3 CON2 1
   x_2_3 CON6 1
   x_2_3 OBJ1 6
   x_2_3 OBJ2 13
   x_3_1 CON3 1
   x_3_1 CON4 1
   x_3_1 OBJ1 2
   x_3_1 OBJ2 1
   x_3_2 CON3 1
   x_3_2 CON5 1
   x_3_2 OBJ1 7
   x_3_2 OBJ2 2
   x_3_3 CON3 1
   x_3_3 CON6 1
   x_3_3 OBJ1 11
   x_3_3 OBJ2 13
   MARKER 'MARKER'
                                    'INTEND'
RHS
   RHS
          CON1
   RHS
          CON2
                 1
   RHS
          CON3
   RHS
          CON4
                 1
   RHS
          CON5
                 1
   RHS
          CON6
                 1
BOUNDS
 UP BOUND x_1_1 1
 UP BOUND x_1_2 1
 UP BOUND x_1_3 1
 UP BOUND x_2_1 1
 UP BOUND x_2_2 1
 UP BOUND x_2_3 1
 UP BOUND x_3_1 1
 UP BOUND x_3_2 1
 UP BOUND x_3_3 1
ENDATA
```

1.7 vOptGeneric and 2LAP (2IP): read data on a file according to the MOP format

The program

```
using vOptGeneric
using GLPK; using GLPKMathProgInterface

m = parseMOP("2ap03.mop", solver=GLPKSolverMIP())
solve( m, method = :epsilon, step = 0.5)
```

Example of a datafile (2ap03.mop)

```
NAME
      v0ptModel
OBJSENSE
MIN
ROWS
N OBJ1
Ν
  OBJ2
E CON1
E CON2
E CON3
E CON4
E CON5
E CON6
COLUMNS
                                    'INTORG'
             'MARKER'
   MARKER
   x_1_1 CON1 1
   x_1_1 CON4
   x_1_1 0BJ1 3
   x_1_1 OBJ2 16
   x_1_2 CON1 1
   x_1_2
         CON5
   x_1_2 OBJ1 9
   x_1_2 OBJ2 15
   x_1_3 CON1
   x_1_3 CON6
   x_1_3 OBJ1 7
   x_1_3 OBJ2 6
   x_2_1 CON2
   x_2_1 CON4 1
   x_2_1 OBJ1 16
   x_2_1 OBJ2 5
   x_2_2 CON2
               1
   x_2_2 CON5 1
   x_2_2 OBJ1 10
   x_2_2 OBJ2 7
   x_2_3 CON2
               1
   x_2_3 CON6 1
   x_2_3 OBJ1 6
   x_2_3 OBJ2 13
   x_3_1 CON3
               1
```

```
x_3_1 CON4 1
   x_3_1 OBJ1 2
   x_3_1 OBJ2 1
    x_3_2 CON3
                1
   x_3_2 CON5 1
    x_3_2 OBJ1 7
    x_3_2 OBJ2 2
    x_3_3 CON3 1
    x_3_3 CON6 1
    x_3_3 OBJ1 11
    x_3_3 OBJ2 13
                                      'INTEND'
   MARKER
              'MARKER'
RHS
   RHS
          CON1
                  1
   RHS
          CON2
                  1
   RHS
          CON3
                  1
   RHS
          CON4
                  1
   RHS
          CON5
                  1
   RHS
          CON6
                  1
BOUNDS
 UP BOUND x_1_1 1
 UP BOUND x_1_2 1
 UP BOUND x_1_3 1
 UP BOUND x_2_1 1
 UP BOUND x_2_2 1
 UP BOUND x_2_3 1
 UP BOUND x_3_1 1
 UP BOUND x_3_2 1
 UP BOUND x_3_3 1
ENDATA
```

```
julia> print_X_E(m)
(16.0, 31.0) : x_1_1=1 x_2_3=1 x_3_2=1
(17.0, 29.0) : x_1_2=1 x_2_3=1 x_3_1=1
(19.0, 14.0) : x_1_3=1 x_2_2=1 x_3_1=1
(30.0, 13.0) : x_1_3=1 x_2_1=1 x_3_2=1

julia> getY_N(m)
4-element Array{Tuple{Float64,Float64},1}:
(16.0, 31.0)
(17.0, 29.0)
(19.0, 14.0)
(30.0, 13.0)
```

2 vOptTools

2.1 Script for plotting Y_N

The program

```
1
2  z1 = [ 16 ; 19 ; 30 ; 17 ]
3  z2 = [ 31 ; 14 ; 13 ; 29 ]
4
5  using PyPlot
6
7  title(L"$Y_N$")
8  xlabel(L"$z_1$")
9  ylabel(L"$z_2$")
10  axis([0, 40, 0, 40])
11
12  plot( z1, z2, color="green", linestyle="", marker="o", label="YN" )
```

