

Sorting: Quicksort and Merge sort

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- enable processing of data in a defined order.



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Examples

The divide-and-conquer technique is the basis of efficient algorithms for many problems, such as sorting (e.g., quicksort, merge sort), multiplying large numbers (e.g., the Karatsuba algorithm), finding the closest pair of points, syntactic analysis (e.g., top-down parsers), and computing the discrete Fourier transform (FFT).

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- It was Developed by British computer scientist Tony Hoare in 1959 and published in 1961.
- It is an in-place sorting algorithm, requiring small additional amounts of memory to perform the sorting.
- When implemented well, it can be somewhat faster than merge sort and about two or three times faster than heapsort.



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- The sub-arrays are then sorted recursively.



Quicksort

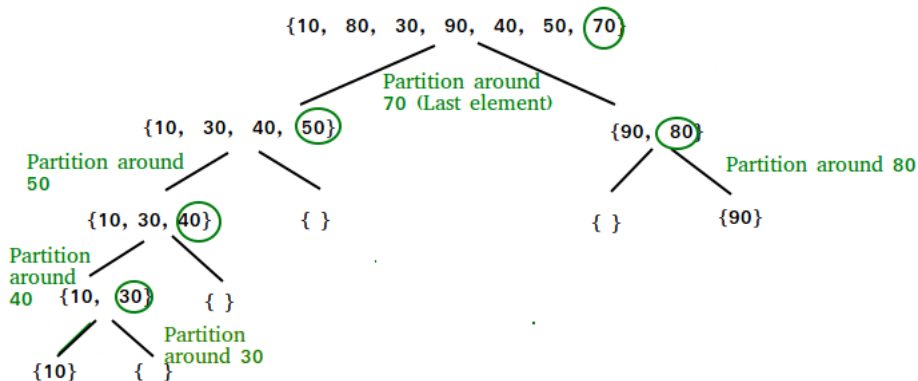


Figure: Quicksort Algorithm



Best-case Analysis

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Thus, each level of calls needs only $O(n)$ time all together (each call has some constant overhead, but since there are only $O(n)$ calls at each level, this is subsumed in the $O(n)$ factor). The result is that the algorithm uses only $O(n \log n)$ time.



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This means that the call tree is a linear chain of $n - 1$ nested calls. The i th call does $O(n - i)$ work to do the partition, and $\sum_{i=0}^{n-1} (n - i) = O(n^2)$, so in that case quicksort takes $O(n^2)$ time.



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Average-case Analysis

To sort an array of n distinct elements, quicksort takes $O(n \log n)$ time in expectation, averaged over all $n!$ permutations of n elements with equal probability.

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- A detailed description and analysis of bottom-up merge sort appeared in a report by Goldstine and von Neumann as early as 1948.



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- At last, the all sub arrays are merged to make it 'n' element size of the array.



Merge sort

39	27	43	3	9	82	10
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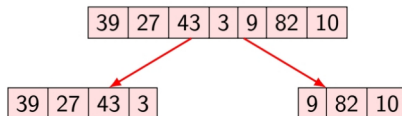


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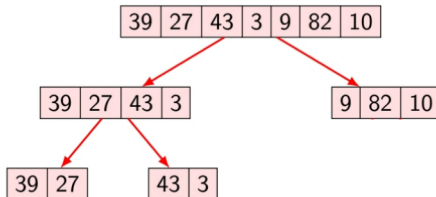


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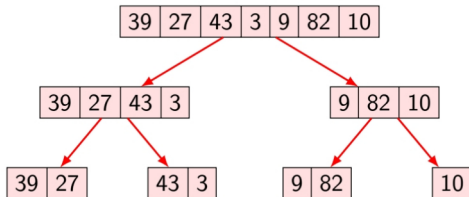


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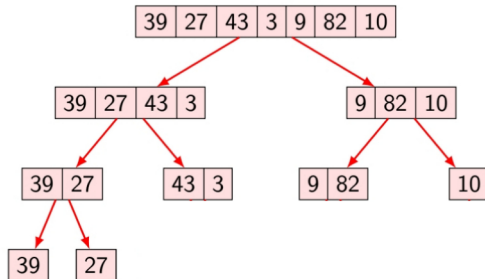


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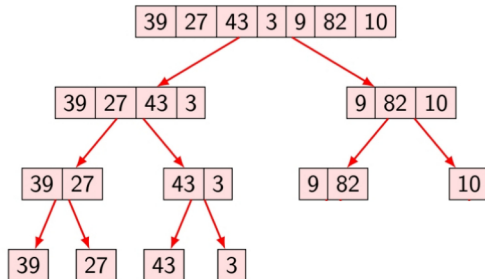


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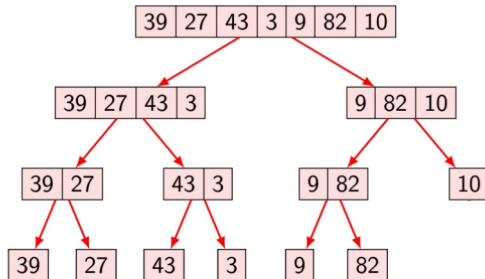


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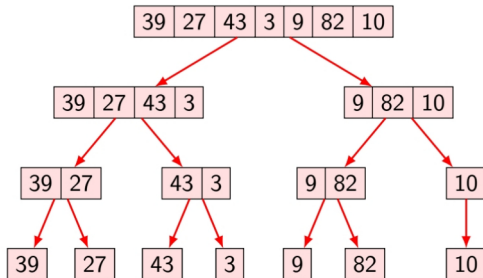


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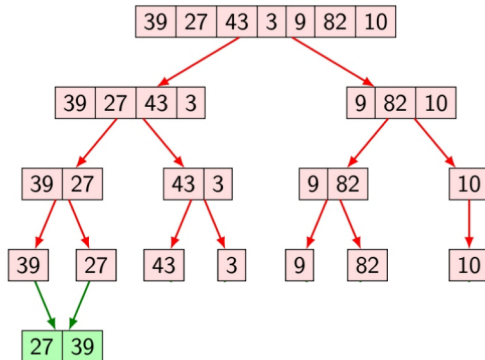


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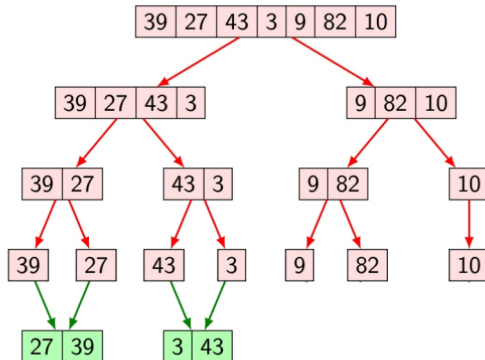


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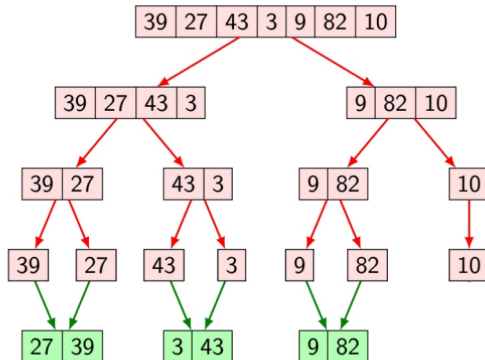


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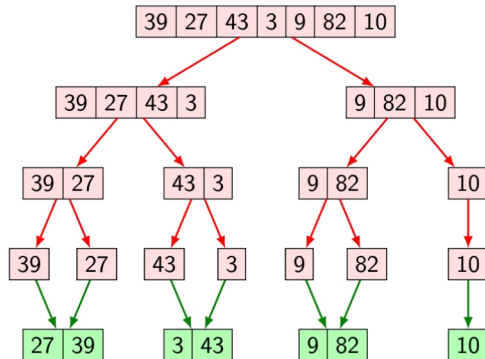


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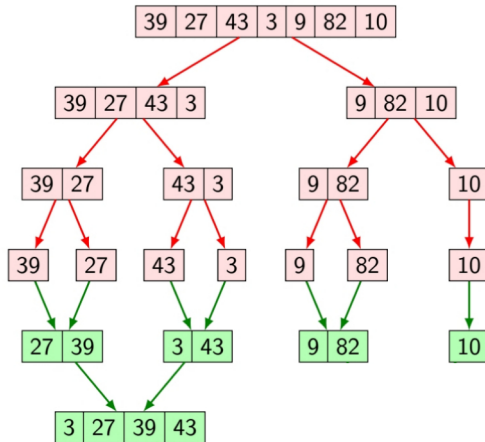


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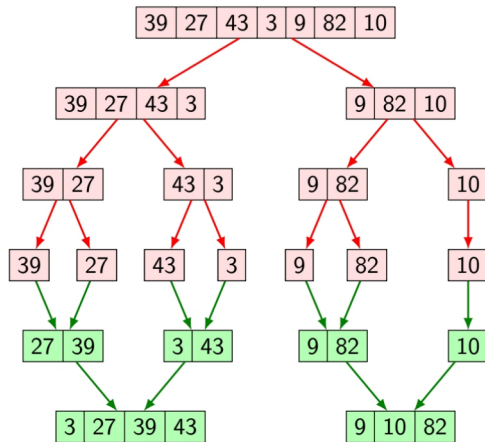


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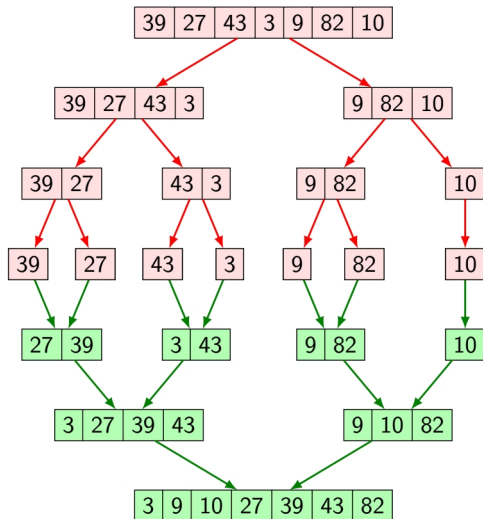


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Hence the total time for merge Sort function will become $n(\log n + 1)$, which gives us a time complexity of $O(n \log n)$.



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Basis for Comparison	Quicksort	Merge sort



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Partition of elements	An array can be divided into any ratio	An array will be divided into two sub arrays

