Math 400 Spring 2022 Final Project due: 5PM on Fri April 22

Project Directions

- Include a report on every group member's contribution.
- Submit the group's well commented code used for the project with instructions on how to compile and run.
- Make a 10 to 20 minute video presentation of your results.

The project consists of three problems. One from each section.

Section 1

Solve the nonlinear system using Newton's method with the given initial vector. Terminate the process when the maximum norm of the difference between successive iterates is less than 5×10^{-6} .

$$f(x,y,z) = x^{2} + y^{2} + z^{2} - 1 = 0$$
1. $g(x,y,z) = x^{2} + z^{2} - 0.25 = 0$
 $h(x,y,z) = x^{2} + y^{2} - 4z = 0$

$$f(x,y,z) = x^{2} + y^{2} + z^{2} - 10 = 0$$
2. $g(x,y,z) = x + 2y - 2 = 0$
 $h(x,y,z) = x + 3z - 9 = 0$

$$f(x,y,z) = x^{2} + 50x + y^{2} + z^{2} - 200 = 0$$
3. $g(x,y,z) = x^{2} + 50x + y^{2} + z^{2} - 200 = 0$
 $h(x,y,z) = -x^{2} - y^{2} + 40z + 75 = 0$

$$\mathbf{x}^{(0)} = \begin{bmatrix} 2 & 0 & 2 \end{bmatrix}^{T}.$$

Implement Gaussian elimination with partial pivoting to solve the linear system in each step. Use numerical differentiation to compute the Jacobian matrix at each step of the method.

Section 2

The problem in this section is the same for all groups.

Use both the Jacobi method and the Gauss-Seidel method to solve the indicated linear system of equations. Your code should efficiently use the "sparseness" of the coefficient matrix. Take $\mathbf{x}^{(0)} = \mathbf{0}$, and terminate the iteration when $||\mathbf{x}^{(k+1)} - \mathbf{x}^{(k)}||_{\infty}$ falls below 5×10^{-6} . Record the number of iterations required to achieve convergence.

Section 3

The problem in this section is the same for all groups.

Bicubic Interpolation

We want to interpolate a 2-dimensional function (surface), f(x, y) over the unit square with corners at (0,0), (1,0), (0,1) and (1,1). A bicubic interpolation of the surface is given by

$$p(x,y) = \sum_{i,j=0}^{3} a_{ij}x^{i}y^{j}$$

$$= a_{00} + a_{10}x + a_{20}x^{2} + a_{30}x^{3} + a_{01}y + a_{02}y^{2} + a_{03}y^{3} + a_{11}xy + a_{21}x^{2}y + a_{31}x^{3}y + a_{12}xy^{2} + a_{22}x^{2}y^{2} + a_{32}x^{3}y^{2} + a_{13}xy^{3} + a_{23}x^{2}y^{3} + a_{33}x^{3}y^{3}$$

An easy way to perform the summation above is to form the vectors $\alpha =$

$$\begin{vmatrix} a_{20} \\ a_{30} \\ a_{01} \\ a_{02} \\ a_{03} \\ a_{03} \\ a_{03} \\ a_{11} \\ a_{21} \\ a_{31} \\ a_{12} \\ a_{22} \\ a_{22} \\ a_{32} \\ a_{13} \\ a_{23} \\ a_{33} \end{vmatrix}, \mathbf{v} = \begin{vmatrix} x^2 \\ x^2 \\ x^2 \\ x^2 y \\ x^2 y \\ x^2 y^2 \\ x^2 y^2 \\ x^2 y^2 \\ x^2 y^3 \\ x^3 y^3 \\ x^3 y^3 \end{vmatrix}$$

then $p(x,y) = \alpha^T \mathbf{v}$.

We need 16 conditions to determine the 16 coefficients a_{ij} , $0 \le i, j \le 3$.

- (a) Enforce the conditions that at the corners f(x,y) = p(x,y), $f_x = p_x$, $f_y = p_y$, and $f_{xy} = p_{xy}$ and write down the resulting sixteen equations from these conditions.
- (b) Transform the equations in part (a) into a matrix-vector equation $B\alpha = \mathbf{f}$ where $B \in \mathbb{R}^{16 \times 16}$ is the coefficient matrix, $\alpha \in \mathbb{R}^{16}$ is the vector of coefficients a_{ij} and $\mathbf{f} \in \mathbb{R}^{16}$ is the right-hand side vector.
- (c) Write a function/subroutine whose input is any function f(x, y) and the output is the right-hand side vector \mathbf{f} computed by a finite difference scheme.
- (d) Perform an LU-factorization of matrix B from part (b).
- (e) Use part (c) and the LU-factorization in part (d) to solve for α for $f(x,y) = y^2 e^{-(x^2+y^2)}$.

 $\begin{bmatrix} f(0.5, 0.5) \\ f_x(0.5, 0.5) \\ f_y(0.5, 0.5) \\ f_{xy}(0.5, 0.5) \end{bmatrix}$ and find the 1, 2 and ∞ -norms of the Use the interpolation to estimate error in the interpolation.

(f) Use part (c) and the LU-factorization in part (d) to solve for α for $f(x,y) = x^2 \tanh(xy)$.

Use the interpolation to estimate $\begin{bmatrix} f(0.5,0.5) \\ f_x(0.5,0.5) \\ f_y(0.5,0.5) \\ f_{xy}(0.5,0.5) \end{bmatrix}$ and find the 1, 2 and ∞ -norms of the error in the interpolation

error in the interpolation.