Assignment:

Implement

- 1. Hill Climber Algorithm in the class HillClimberAgent,
- 2. Genetic Algorithm in the class GeneticAgent,
- 3. Monte Carlo Tree Search (MCTS) in the class MCTSAgent,

within the in pacmanAgents.py file, using scoreEvaluation & normalizedScoreEvaluation as a heuristic functions.

Notes:

- Python 2.7 is required to run the Framework.
- All your code must be inside the **pacmanAgents.py** file.
- Only submit **pacmanAgents.py** file. If you submit anything else you will fail the assignment.
- Only use the heuristic function in the **heuristics.py** file (do not implement your own heuristic).
- RandomAgent, GreedyAgent, and RandomSequenceAgent are implemented example agents.
- Hill Climber and Genetic Algorithm plans a sequence of actions to execute instead of building a tree. Check RandomSequenceAgent as an example of sequence planning.
- External libraries are not allowed (as you won't submit them)
- You will fail the assignment if you try to change any of the system params.
- You are only allowed to use these system functions (accessing/ changing any other functions or variables is considered cheating):
 - **state.getLegalPacmanActions():** return all the legal actions in this state

- state.getAllPossibleActions(): return all the possible actions (Directions.North, Directions.South, Directions.East, Directions.West)
- state.generatePacmanSuccessor(action): return the next state if pacman take a certain action (return a new copy, doesn't modify the current state)
- scoreEvaluation(state): evaluate the current state
- normalizedScoreEvaluation(rootState, currentState):
 evaluate the current state with respect to rootState then scale it down.
- state.isWin(): check if this state is win state
- state.isLose(): check if this state is lose state
- The forward model (generatePacmanSuccessor) is limited to a certain amount of calls, don't waste them. If you exceed the limit,
 None will be returned.
- For Hill Climber and Genetic Algorithm:
 - Use getAllPossibleActions to assign your action sequence.
 Don't worry applying illegal action. The forward model ignore illegal actions and apply Directions.STOP instead.
 - Make sure to check if you reach the terminal state while implementing your action sequence as the remaining actions can't be executed.
 - Always return the first action from the sequence with the highest scoreEvaluation.

For Hill Climber:

- Action Sequence are of length 5
- Each action in the sequence has 50% chance to be changed into random action.

For Genetic Algorithm:

- Each chromosome is an action sequence of length 5.

- Use a population of size 8.
- Where you have 70% to crossover followed by 10% mutation for each chromosome.
- For each individual you roll the die, 70% will do the crossover, then these two chromosomes have 10% chances to be mutated.
- Use rank selection to select chromosomes
 - Sort all chromosomes based on fitness.
 - Give each chromosome a rank (from 1 to length of chromosomes).
 - Select chromosomes proportionally to their rank

For MCTS:

- Exploitation should use normalizedScoreEvaluation function instead of scoreEvaluation to balance it with respect to the Exploration term.
- Use getLegalPacmanActions to build the tree.
- Use 1 as the constant between exploitation and exploration.
- Fix the number of rollouts to 5 as its hard to reach a terminal state in small amount of time.
- Don't save the state in the tree nodes as the game is stochastic. Always apply the actions from the root state. every time you go over the tree.
- Final Action Selection: return the action associated with the most visited node (Break ties randomly).
- You can't change name of the agent classes.
- For array sorting, you can use python internal sorting function.
 example: array.sort(key=lambda x: scoreEvaluation(x))

How to run:

- To play pacman: python pacman.py
- To run a certain agent using graphics use the following command: python pacman.py -p AgentName

Note: You are implementing a vanilla version of these Als, being slow or going back and forth might be part of the algorithm behavior in the amount of time given for each move