### Exercise sheet 9 - Introduction - Due date: June 29th

Submitted to:

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### Exercise 1 - Basics of NN (9 points)

From the MNIST database load the handwritten digits dataset.

1. Normalize your dataset before training your model. (1 point)

```
In [1]:
        import tensorflow as tf
        from tensorflow import keras
        import numpy as np
        mnist = tf.keras.datasets.mnist #28*28 image of handwritten of 0-9
In [5]:
        (x_train, y_train),(x_test,y_test) = mnist.load_data()
       x_train = tf.keras.utils.normalize(x_train, axis = 1)
In [ ]:
        x_test = tf.keras.utils.normalize(x_test,axis = 1)
        print("Training Data after normalizing is {}".format(x_train[0]))
        print("Testing Data after normalizing is {}".format(x_test[0]))
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```

1. Train a neural network once using Adam and once using AdaGrad optimizer. Hint: Set epochs = 20, neurons of hidden layer = 100, activation function = ReLU for reproducibility. (2 points)

```
0.9633
   Epoch 3/20
   0.9746
   Epoch 4/20
   0.9798
   Epoch 5/20
   0.9850
   Epoch 6/20
   0.9878
   Epoch 7/20
   0.9894
   Epoch 8/20
   0.9914
   Epoch 9/20
   0.9936
   Epoch 10/20
   0.9930
   Epoch 11/20
   0.9954
   Epoch 12/20
   0.9953
   Epoch 13/20
   0.9960
   Epoch 14/20
   0.9960
   Epoch 15/20
   0.9965
   Epoch 16/20
   0.9966
   Epoch 17/20
   Epoch 18/20
   0.9966
   Epoch 19/20
   0.9977
   Epoch 20/20
   0.9970
   model_grad = tf.keras.models.Sequential() # a basic feed-forward model
In [ ]:
   model_grad.add(tf.keras.layers.Flatten()) # takes our 28x28 and makes it 1x784
   model_grad.add(tf.keras.layers.Dense(100, activation=tf.nn.relu)) # a simple fully-
   model_grad.add(tf.keras.layers.Dense(100, activation=tf.nn.relu)) # a simple fully-
   model_grad.add(tf.keras.layers.Dense(10, activation=tf.nn.softmax)) # our output la
   model_grad.compile(optimizer='adagrad', # Good default optimizer to start with
         loss='sparse_categorical_crossentropy', # how will we calculate our "
         metrics=['accuracy']) # what to track
   adagrad=model_grad.fit(x_train, y_train, epochs=20) # train the model
```

```
Epoch 1/20
0.4672
Epoch 2/20
0.7869
Epoch 3/20
0.8376
Epoch 4/20
0.8589
Epoch 5/20
0.8721
Epoch 6/20
0.8798
Epoch 7/20
0.8855
Epoch 8/20
0.8898
Epoch 9/20
0.8938
Epoch 10/20
0.8968
Epoch 11/20
0.8993
Epoch 12/20
0.9015
Epoch 13/20
0.9037
Epoch 14/20
0.9050
Epoch 15/20
Epoch 16/20
0.9078
Epoch 17/20
Epoch 18/20
0.9104
Epoch 19/20
0.9116
Epoch 20/20
0.9129
```

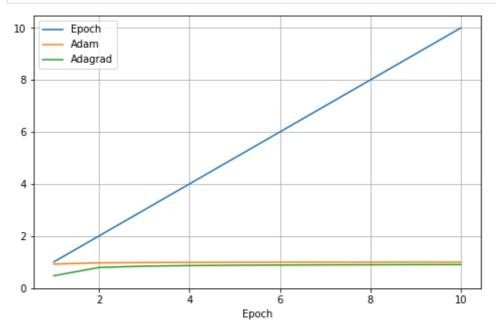
1. Plot the SparseCategoricalCrossentropy loss for both models. Plot the computed accuracy for both models. Which model performed better while training? (2 points)

```
In [ ]: # plot accuracy
import pandas as pd
import matplotlib.pyplot as plt
```

```
ep=np.arange(1,11,1)
ada=adam.history['accuracy']
adagrd=adagrad.history['accuracy']
list_of_tuples = list(zip(ep,ada,adagrd ))

df = pd.DataFrame(list_of_tuples, columns = ['Epoch','Adam','Adagrad'])
df.index = df['Epoch']
df.plot(figsize=(8, 5))
plt.grid(True)

plt.show()
```

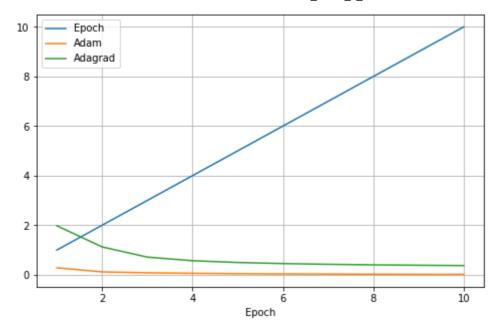


```
In []: # plot loss
    ep=np.arange(1,11,1)
    ada=adam.history['loss']
    adagrd=adagrad.history['loss']
    list_of_tuples = list(zip(ep,ada,adagrd ))

    df = pd.DataFrame(list_of_tuples, columns = ['Epoch','Adam','Adagrad'])

    df.index = df['Epoch']
    df.plot(figsize=(8, 5))
    plt.grid(True)

    plt.show()
```



1. Compute the model accuracy on the test set for both optimizers. Which model performed better? (1 point)

```
In [ ]:
       #adam
       val_loss, val_acc = model_adam.evaluate(x_test, y_test)
       print(val_loss) # model's loss (error)
       print(val_acc) # model's accuracy
       9748
       0.14294207096099854
       0.9747999906539917
       #adagrad
In [ ]:
       val_loss, val_acc = model_grad.evaluate(x_test, y_test)
       print(val_loss) # model's loss (error)
       print(val_acc) # model's accuracy
       313/313 [================== ] - 0s 1ms/step - loss: 0.2975 - accuracy: 0.
       9179
       0.29745998978614807
       0.917900025844574
```

- 1. Familiarize yourself with Layer Normalization and explain how it works. (1 point)
- layer normalization normalizes input across the features instead of normalizing input features across the batch dimension in batch normalization
- layer normalization is very effective at stabilizing the hidden state dynamics in recurrent networks. Empirically, we show that layer normalization can substantially reduce the training time compared with previously published techniques.
- Layer Normalization directly estimates the normalization statistics from the summed inputs to the neurons within a hidden layer so the normalization does not introduce any new dependencies between training cases

```
In [ ]:
```

1. Using the same dataset to train a neural network with Layer Normalization. Hint: Set epochs

- = 20, neurons of hidden layer = 100, activation function = ReLU for reproducibility.
- a. Compute the SparseCategoricalCrossentropy loss and model accuracy. (1 point)
- b. Evaluate the model performance using the test dataset. (1 point)

| In [ | ]  | : |  |
|------|----|---|--|
|      |    |   |  |
| In [ | ]: | : |  |

# Exercise 2 - Hyper Parameter Optimization (9 points)

1. What are the main challenges with hyper-parameter optimization for neural networks? (1 point)

#### Challenges with hyper-parameter optimization for neural networks:

- 1.) Overfitting is the issue in which our model performs extremely well during training and optimization, and very poorly out of sample
- 2.)It is recommended that you optimize all hyperparameters of your model, including architecture parameters and model parameters, at the same time.
- 3.) One of the drawbacks of grid search is that when it comes to dimensionality, it suffers when evaluating the number of hyperparameters grows exponentially. However, there is no guarantee that the search will produce the perfect solution, as it usually finds one by aliasing around the right set.

| In [ ]: |  |
|---------|--|
|---------|--|

1. Inform yourself about variants of Bayesian-HPO and explain them in detail (2 points)

The aim of Bayesian reasoning is to become "less wrong" with more data which these approaches do by continually updating the surrogate probability model after each evaluation of the objective function. The basic idea is: spend a little more time selecting the next hyperparameters in order to make fewer calls to the objective function.

Sequential model-based optimization (SMBO) methods (SMBO) are a formalization of Bayesian optimization. The sequential refers to running trials one after another, each time trying better hyperparameters by applying Bayesian reasoning and updating a probability model (surrogate).

There are five aspects of model-based hyperparameter optimization:

A domain of hyperparameters over which to search An objective function which takes in hyperparameters and outputs a score that we want to minimize (or maximize) The surrogate model of the objective function A criteria, called a selection function, for evaluating which hyperparameters to choose next from the surrogate model

A history consisting of (score, hyperparameter) pairs used by the algorithm to update the surrogate model

```
In [ ]:
```

1. Using the same MNIST dataset, optimize the activation function for the output layer and the number of dropout units in the NN model using the following methods. (6 points)

a. Grid search

```
from keras.layers import Dense, Dropout
 In [6]:
          from keras.wrappers.scikit learn import KerasClassifier
          from sklearn.model_selection import GridSearchCV
          from sklearn.model_selection import RandomizedSearchCV
          from skopt import BayesSearchCV
 In [7]:
          def build_model(activation,dropout_rate):
              model adam = tf.keras.models.Sequential()
              model adam.add(tf.keras.layers.Flatten())
              model_adam.add(tf.keras.layers.Dense(100, activation=activation))
              model_adam.add(tf.keras.layers.Dense(100, activation=activation))
              model_adam.add(tf.keras.layers.Dense(10, activation=activation))
              model_adam.add(tf.keras.layers.Dropout(dropout_rate))
              model_adam.compile(optimizer='adam',
                            loss='sparse categorical crossentropy',
                            metrics=['accuracy'])
              return model adam
          model = KerasClassifier(build_fn = build_model, verbose=0)
          parameters = {'dropout_rate' : [0.0, 0.1, 0.2, 0.3, 0.4, 0.5], 'activation' : ['relu'
          models = GridSearchCV(estimator = model, param_grid = parameters, n_jobs=1,scoring="
 In [8]:
          best_model = models.fit(x_train,y_train)
          print("Best parameters by GridSearchCV:", best_model.best_params_)
         /Users/rohitha/opt/anaconda3/lib/python3.8/site-packages/tensorflow/python/keras/eng
         ine/sequential.py:455: UserWarning: `model.predict_classes()` is deprecated and will
         be removed after 2021-01-01. Please use instead: * `np.argmax(model.predict(x), axis=
                 if your model does multi-class classification
                                                                 (e.g. if it uses a `softmax`
         last-layer activation).* `(model.predict(x) > 0.5).astype("int32")`, if your model
         does binary classification
                                      (e.g. if it uses a `sigmoid` last-layer activation).
           warnings.warn('`model.predict_classes()` is deprecated and
         Best parameters by GridSearchCV: {'activation': 'sigmoid', 'dropout_rate': 0.0}
         b. Random search
          random_search = RandomizedSearchCV(estimator=model, param_distributions=parameters,n
 In [9]:
          random search.fit(x train,y train)
          print("Best parameters by Random search:",random search.best params )
         Best parameters by Random search: {'dropout rate': 0.1, 'activation': 'sigmoid'}
         c. Bayesian Hyper-parameter optimization
In [10]:
         search = BayesSearchCV(estimator=model, search spaces=parameters, n jobs=-1)
          search.fit(x train,y train)
          print("Best parameters by Bayesian Hyper-parameter optimization:", search.best param
         /Users/rohitha/opt/anaconda3/lib/python3.8/site-packages/skopt/optimizer/optimizer.p
         y:449: UserWarning: The objective has been evaluated at this point before.
           warnings.warn("The objective has been evaluated "
         /Users/rohitha/opt/anaconda3/lib/python3.8/site-packages/skopt/optimizer/optimizer.p
         y:449: UserWarning: The objective has been evaluated at this point before.
           warnings.warn("The objective has been evaluated "
         /Users/rohitha/opt/anaconda3/lib/python3.8/site-packages/skopt/optimizer/optimizer.p
         y:449: UserWarning: The objective has been evaluated at this point before.
           warnings.warn("The objective has been evaluated "
```

```
/Users/rohitha/opt/anaconda3/lib/python3.8/site-packages/skopt/optimizer/optimizer.p
y:449: UserWarning: The objective has been evaluated at this point before.
  warnings.warn("The objective has been evaluated "
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y:449: UserWarning: The objective has been evaluated at this point before.
  warnings.warn("The objective has been evaluated "
```

```
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/Users/rohitha/opt/anaconda3/lib/python3.8/site-packages/skopt/optimizer/optimizer.p
y:449: UserWarning: The objective has been evaluated at this point before.
  warnings.warn("The objective has been evaluated "
Best parameters by Bayesian Hyper-parameter optimization: OrderedDict([('activatio
n', 'sigmoid'), ('dropout_rate', 0.0)])
```

#### In [ ]:

## Exercise 3 - Transfer Learning & CNNs (7 points)

- 1. Load the VGG16 pre-trained model using Keras Applications API. Use the model to classify the dog images in canines.zip after pre-processing each image by doing the following: (2 points)
- a. Load each image and set the size to 224 x 224 pixels
- b. Convert the image pixels to a numpy array and reshape it according to the model's input requirements
- c. Use the model to print out the predicted class and its probability for each image

```
In [17]: import numpy as np
    from keras.models import Model
    from keras.preprocessing import image
    from keras.applications.vgg16 import VGG16
    from keras.applications.vgg16 import preprocess_input
    from keras.applications.vgg16 import decode_predictions
    import tensorflow.keras as keras
    from tensorflow.keras.preprocessing.image import load_img, img_to_array, ImageDataGe
    import os
In [18]: model = VGG16()
    print(model.summary())
```

Model: "vgg16"

| Layer (type)  | Output Shape          | Param #      |  |  |  |  |
|---|-----------------------|--------------|--|--|--|--|
| <pre>input_1 (InputLayer)</pre>   | [(None, 224, 224, 3)] | .======<br>0 |  |  |  |  |
|   |                       |              |  |  |  |  |
| block1_conv1 (Conv2D)   | (None, 224, 224, 64)  | 1792         |  |  |  |  |
| block1_conv2 (Conv2D)   | (None, 224, 224, 64)  | 36928        |  |  |  |  |
| block1_pool (MaxPooling2D)  | (None, 112, 112, 64)  | 0            |  |  |  |  |
| block2_conv1 (Conv2D)   | (None, 112, 112, 128) | 73856        |  |  |  |  |
| block2_conv2 (Conv2D)   | (None, 112, 112, 128) | 147584       |  |  |  |  |
| block2_pool (MaxPooling2D)  | (None, 56, 56, 128)   | 0            |  |  |  |  |
| block3_conv1 (Conv2D)   | (None, 56, 56, 256)   | 295168       |  |  |  |  |
| block3_conv2 (Conv2D)   | (None, 56, 56, 256)   | 590080       |  |  |  |  |
| block3_conv3 (Conv2D)   | (None, 56, 56, 256)   | 590080       |  |  |  |  |
| block3_pool (MaxPooling2D)  | (None, 28, 28, 256)   | 0            |  |  |  |  |
| block4_conv1 (Conv2D)   | (None, 28, 28, 512)   | 1180160      |  |  |  |  |
| block4_conv2 (Conv2D)   | (None, 28, 28, 512)   | 2359808      |  |  |  |  |
| block4_conv3 (Conv2D)   | (None, 28, 28, 512)   | 2359808      |  |  |  |  |
| block4_pool (MaxPooling2D)  | (None, 14, 14, 512)   | 0            |  |  |  |  |
| block5_conv1 (Conv2D)   | (None, 14, 14, 512)   | 2359808      |  |  |  |  |
| block5_conv2 (Conv2D)   | (None, 14, 14, 512)   | 2359808      |  |  |  |  |
| block5_conv3 (Conv2D)   | (None, 14, 14, 512)   | 2359808      |  |  |  |  |
| block5_pool (MaxPooling2D)  | (None, 7, 7, 512)     | 0            |  |  |  |  |
| flatten (Flatten)   | (None, 25088)         | 0            |  |  |  |  |
| fc1 (Dense)   | (None, 4096)          | 102764544    |  |  |  |  |
| fc2 (Dense)   | (None, 4096)          | 16781312     |  |  |  |  |
| predictions (Dense)   | (None, 1000)          | 4097000      |  |  |  |  |
| Total params: 138,357,544 Trainable params: 138,357,544 Non-trainable params: 0 |                       |              |  |  |  |  |

None

```
#Top 1% of the probability of classes
In [19]:
```

```
for file in os.listdir("Canines"):
In [20]:
              print(file)
              img_path = 'Canines/'+file
              print(img_path)
              image = load_img(img_path, target_size=(224,224,3))
              image = img_to_array(image)
              image= image.reshape((1, image.shape[0], image.shape[1], image.shape[2]))
              image = preprocess_input(image)
              y_pred = model.predict(image)
              label = decode_predictions(y_pred, top=1)
```

```
print(label)
              print()
         dog5.jpg
         Canines/dog5.jpg
         [[('n02109047', 'Great_Dane', 0.45382115)]]
         dog4.jpg
         Canines/dog4.jpg
         [[('n02106166', 'Border_collie', 0.735858)]]
         dog6.jpg
         Canines/dog6.jpg
         [[('n02109047', 'Great_Dane', 0.9088881)]]
         dog7.jpg
         Canines/dog7.jpg
         [[('n02109961', 'Eskimo_dog', 0.49961603)]]
         dog3.jpg
         Canines/dog3.jpg
         [[('n02099601', 'golden_retriever', 0.78778)]]
         dog2.jpg
         Canines/dog2.jpg
         [[('n02113023', 'Pembroke', 0.7457447)]]
         dog1.jpg
         Canines/dog1.jpg
         [[('n02107142', 'Doberman', 0.93426067)]]
         dog8.jpg
         Canines/dog8.jpg
         [[('n02107142', 'Doberman', 0.35419115)]]
          #Top 2% of the probability of classes
In [21]:
          for file in os.listdir("Canines"):
In [22]:
              print(file)
              img_path = 'Canines/'+file
              print(img_path)
              image = load_img(img_path, target_size=(224,224,3))
              image = img_to_array(image)
              image= image.reshape((1, image.shape[0], image.shape[1], image.shape[2]))
              image = preprocess_input(image)
              y_pred = model.predict(image)
              label = decode_predictions(y_pred, top=2)
              print(label)
              print()
         dog5.jpg
         Canines/dog5.jpg
         [[('n02109047', 'Great Dane', 0.45382115), ('n02108422', 'bull mastiff', 0.4368719
         8)]]
         dog4.jpg
         Canines/dog4.jpg
         [[('n02106166', 'Border_collie', 0.735858), ('n02106030', 'collie', 0.23651241)]]
         dog6.jpg
         Canines/dog6.jpg
         [[('n02109047', 'Great_Dane', 0.9088881), ('n02087394', 'Rhodesian_ridgeback', 0.074
         75051)]]
         dog7.jpg
         Canines/dog7.jpg
         [[('n02109961', 'Eskimo_dog', 0.49961603), ('n02110185', 'Siberian_husky', 0.290228
```

```
9)]]
        dog3.jpg
        Canines/dog3.jpg
         [[('n02099601', 'golden_retriever', 0.78778), ('n02104029', 'kuvasz', 0.022645768)]]
        dog2.jpg
        Canines/dog2.jpg
         [[('n02113023', 'Pembroke', 0.7457447), ('n02113186', 'Cardigan', 0.2151999)]]
        dog1.jpg
        Canines/dog1.jpg
         [[('n02107142', 'Doberman', 0.93426067), ('n02087046', 'toy_terrier', 0.048935466)]]
        dog8.jpg
        Canines/dog8.jpg
         [[('n02107142', 'Doberman', 0.35419115), ('n02105412', 'kelpie', 0.19439045)]]
In [ ]:
          1. Downscale the given matrix by applying the following pooling operations: a. Max Pool (1
```

point) b. Average Pool (1 point)

```
import tensorflow as tf
In [23]:
          tf.keras.layers.MaxPooling2D(pool_size=(2, 2), strides=(1, 1), padding='valid')
          Matrix = tf.constant([[1., 4., 1., 5.],
                            [4., 9., 4., 8.],
                            [4., 5., 4., 3.],
                            [6., 5., 7., 4.]]
          Matrix = tf.reshape(Matrix, [1, 4, 4, 1])
          max_pool_2d = tf.keras.layers.MaxPooling2D(pool_size=(2, 2),
             strides=(1, 1), padding='valid')
          max_pool_2d(Matrix)
Out[23]: <tf.Tensor: shape=(1, 3, 3, 1), dtype=float32, numpy=
         array([[[[9.],
```

```
[9.],
[8.]],
[[9.],
[9.],
[8.]],
[[6.],
[7.],
[7.]]]], dtype=float32)>
```

```
In [24]:
          tf.keras.layers.AveragePooling2D(pool_size=(2, 2), strides=(1, 1), padding='valid')
          Matrix = tf.constant([[1., 4., 1., 5.],
                            [4., 9., 4., 8.],
                            [4., 5., 4., 3.],
                            [6., 5., 7., 4.]]
          Matrix = tf.reshape(Matrix, [1, 4, 4, 1])
          avg_pool_2d = tf.keras.layers.AveragePooling2D(pool_size=(2, 2),
             strides=(1, 1), padding='valid')
          avg pool 2d(Matrix)
```

```
Out[24]: <tf.Tensor: shape=(1, 3, 3, 1), dtype=float32, numpy=
         array([[[[4.5],
                  [4.5],
```

```
[4.5]],

[[5.5],
[4.75]],

[[5.],
[5.25],
[4.5]]]], dtype=float32)>

In []:
```

- 1. Load the CIFAR10 dataset using Keras datasets API and normalize the images' pixel values. Train a convolutional neural network to classify the dataset images with the following architecture: (3 points)
- a. Convolutional Base:
- i. An input convolution layer with 32 filters and a kernel size of (3,3).

Adjust your input shape to that of the CIFAR images' format

- ii. 2 convolution layers, each with 64 filters and a kernel size of (3,3)
- iii. 2 Max Pool layers, with a pool size of 2x2
- b. 2 dense layers, with 64 and 10 units respectively. Adjust the output of the convolutional base such that it satisfies the input requirements of the dense layers.
- c. Use the following parameters to train the network: i. Sparse categorical cross entropy as your loss function ii. Adam optimizer iii. 10 epochs iv. ReLU activation for your layers

Compile your model, then plot the accuracy across each epoch

```
import tensorflow as tf
In [ ]:
         from keras.models import Sequential
         from keras.layers import Dense, Conv2D, MaxPooling2D, Dropout, Flatten
         from keras.callbacks import Callback
         from keras.utils import np utils
         import numpy as np
         import matplotlib.pyplot as plt
         from keras import backend as K
         K.set_image_data_format('channels_last')
In [ ]:
         data = tf.keras.datasets.cifar10.load_data()
         (Xtrain, ytrain), (Xtest, ytest) = data
         Xtrain = Xtrain.astype('float32')
         Xtest = Xtest.astype('float32')
        #Normalize image pixels
In [ ]:
         mean = np.mean(Xtrain, axis = (0,1,2,3))
         std = np.std(Xtrain, axis = (0,1,2,3))
         Xtrain = (Xtrain - mean) / (std +1e-7)
         Xtest = (Xtest - mean) / (std +1e-7)
         n classes = 10
In [ ]:
         ytrain = np_utils.to_categorical(ytrain, n_classes)
```

```
ytest = np_utils.to_categorical(ytest, n_classes)
         input\_shape = (32, 32, 3)
In [ ]:
        def CNN():
             '''Function to create model with given layers for CNN training'''
             model = Sequential([
             Conv2D(32, (3,3,), padding = 'same', activation = 'relu', input_shape = input sh
             Conv2D(64, (3,3,), activation = 'relu'),
             Conv2D(64, (3,3,), activation = 'relu'),
             MaxPooling2D(pool size = (2,2)),
             MaxPooling2D(pool size = (2,2)),
             Flatten(),
             Dense(64, activation = 'relu'),
             Dense(10, activation = 'softmax')])
             return model
In [ ]:
         K.clear_session()
         model = CNN()
         model.compile(optimizer='adam', loss='categorical_crossentropy', metrics=['accuracy'
         model.summary()
        Model: "sequential"
        Layer (type)
                                    Output Shape
                                                              Param #
        conv2d (Conv2D)
                                     (None, 32, 32, 32)
                                                              896
        conv2d_1 (Conv2D)
                                     (None, 30, 30, 64)
                                                              18496
        conv2d_2 (Conv2D)
                                     (None, 28, 28, 64)
                                                              36928
        max_pooling2d (MaxPooling2D) (None, 14, 14, 64)
                                                              0
        max pooling2d 1 (MaxPooling2 (None, 7, 7, 64)
                                                              0
        flatten (Flatten)
                                     (None, 3136)
                                                              0
        dense (Dense)
                                     (None, 64)
                                                              200768
        dense 1 (Dense)
                                     (None, 10)
        -----
        Total params: 257,738
        Trainable params: 257,738
        Non-trainable params: 0
        from keras.callbacks import TensorBoard
In [ ]:
         tbCallBack = TensorBoard(log_dir='./log', histogram_freq=1, write_graph=True,
                                 write images=True)
         epochs = 10
         starttime = datetime.datetime.now()
         history = model.fit(Xtrain, ytrain, batch_size=32,
                           epochs=epochs, verbose=1,
                           validation data=(Xtest, ytest))
         endtime = datetime.datetime.now()
         print (endtime - starttime)
```

```
Epoch 1/10
     1563/1563 [===================== ] - 483s 309ms/step - loss: 0.3395 - accura
     cy: 0.8792 - val_loss: 1.0522 - val_accuracy: 0.7217
     Epoch 2/10
     cy: 0.8950 - val_loss: 1.2021 - val_accuracy: 0.7061
     Epoch 3/10
     cy: 0.9087 - val_loss: 1.3103 - val_accuracy: 0.7057
     Epoch 4/10
     1563/1563 [=============== ] - 441s 282ms/step - loss: 0.2317 - accura
     cy: 0.9165 - val_loss: 1.3325 - val_accuracy: 0.7088
     Epoch 5/10
     cy: 0.9215 - val loss: 1.4119 - val accuracy: 0.7057
     Epoch 6/10
     cy: 0.9294 - val loss: 1.4937 - val accuracy: 0.7059
     Epoch 7/10
     cy: 0.9342 - val_loss: 1.5788 - val_accuracy: 0.6950
     Epoch 8/10
     cy: 0.9378 - val_loss: 1.6260 - val_accuracy: 0.7047
     Epoch 9/10
     cy: 0.9441 - val_loss: 1.7186 - val_accuracy: 0.7062
     Epoch 10/10
     1563/1563 [==================== ] - 441s 282ms/step - loss: 0.1539 - accura
     cy: 0.9454 - val_loss: 1.8894 - val_accuracy: 0.6984
     1:14:20.835258
     plt.plot(history.history['accuracy'], 'black', linewidth = 3.0)
In [ ]:
     plt.plot(history.history['val_accuracy'], 'black', ls = '--', linewidth = 3.0)
```

