Virtual Reality

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Mixed Reality for Visualising the Structure of Organic Compounds using Microsoft HoloLens

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Abstract Education is the base for a thriving society and the transfer of knowledge has been a top priority since the very beginning. People are constantly looking for ways to make knowledge transfer more easy, quick and efficient. In this era of digital devices, Mixed Reality helps transform the way educational content is delivered, thus being effectively used to enhance student learning and engagement. The objective of this paper was to propose the design of a system that helps visualize the structure of various organic compounds. The proposed approach helped students better understand and compare different hydrocarbons and their respective structures. Transformations like Scale, Rotate and Translate provided a detailed aspect of each compound. An attempt has been made to overcome traditional 2D learning problems relating to perspective and cognition by using 3D models and adding various interactions in the Mixed Reality environment with the help of Vuforia markers and HoloLens, which together have a strong influence on developing meaningful learning. The use of interactive visualization through multi-dimensional graphics and simulation can provide an opportunity to present key learning content for students.

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1 Introduction

The value of traditional learning approaches in system modelling has been challenged with regards to students' understanding, learning performance and mastering of modelling techniques. The traditional way of visualizing certain concepts on a 2D screen may not be intuitive anymore, but we can always gain new depth of knowledge by visualizing them in a 3D environment. Organic chemistry is the study of structure, properties, composition of carbon-containing compounds (including hydrocarbons). It is an area that is perceived as difficult to understand, because it requires threedimensional thinking. Some of the problems faced by students while learning organic chemistry is the inability to see and manipulate three-dimensional structures on paper. Mostly these are problems that relate to cognition and the process of learning. Imparting knowledge with the help of pictures/videos or through traditional print textbook does not (present abstract concepts as tangible objects that can be manipulates) promote authentic engagement of students. Using a 3D approach improves spatial awareness and thinking in STEM subjects to a great extent. The Reality Virtuality Continuum was introduced by Paul Milgram[1]. It is a continuous scale ranging from completely real reality to completely virtual virtuality and encompasses all possible variations of real and virtual objects. Fig. 1 shows the continuum which to its extreme left has the Completely Real Environment - The physical space we live in, where real objects are overlaid on a real environment. Moving on, we have Augmented Reality - Virtual objects being



Fig. 1 Reality Virtuality Continuum

overlaid on a real environment. Next up is Augmented Virtuality - Real objects being overlaid on a virtual environment. Finally, we have the Completely Virtual Environment - Virtual objects are overlaid on a virtual environment. The area between the two extremes where the real and virtual environments are mixed is termed as Mixed Reality - Virtual objects being overlaid on a real environment in addition to direct interaction with these objects. The immersive technologies that are acquiring momentum are: Augmented Reality(AR), Virtual Reality(VR), Mixed Reality(MR).

Augmented Reality:

AR permits the user to perceive the real world, with virtual entities superimposed upon or composited with the real world [2]. Here, the virtual (computer-generated) objects appear to coexist in the same space as the real world [3]. AR systems track the position and orientation of the user's head so that the overlaid material can be aligned with the user's view of the world [4]. It generates stimuli at real time for the user's interaction that are superposed over the physical environment of the user [5]. An AR system includes a camera able to track the user movement for merging the virtual objects, and a visual display, like glasses through that the user can see the virtual objects overlaying to the physical world, adequate processing power for graphics and animation [6]. Augmented Reality, unlike Virtual Reality, does not seek to withdraw the user from the real environment; rather, it brings virtual elements that integrate into a physical space [2].

Virtual Reality:

In the case of VR, the real world is replaced by virtual objects and scenarios. It completely replaces what we have come to consider normal reality. Since a person is completely immersed in the virtual environment, he has no awareness about his/her surroundings. It produces an appearing of reality that allows the user to perceive a sensation of presence inside of it [5].

Mixed Reality:

MR is an amalgamation of physical objects and virtual objects/components that are overlaid onto the physical world. These virtual objects can be interacted with. Rather than being superimposed on top of normal real-

ity, as is done with augmented reality, MR experience blends the two realities together to create a new mixed reality. MR not only allows user's interaction with virtual environments even allows physical objects from the immediate environment of the user to be elements to interact with the virtual environment [5]. It is basically as continuum of the previously mentioned innovative technologies, provides a framework to position real and virtual worlds [7]. The benefit of our approach of implementing Mixed Reality in our project is that it promotes the potential to interact with the 3D structures and with the real world in the same context and time frame which comes handy when it comes to perform comparison between 3D hydrocarbon structures.

The motive of our application is to study the structure of Organic Compounds using Microsoft HoloLens. It is a Mixed Reality app that gives you the ability to visualize and interact with various hydrocarbons thereby charging over the current approach to education i.e., traditional teaching methods that are focused on providing facts, however having access to and consuming a lot of information that does not contribute to authentic learning. A lot of people have difficulties comprehending information. Using MR, students can be provided with easy demonstrations of crucial concepts through interactive experiences. Thus, through our application, we aim towards creating an interactive 3D environment that effectively simulates visualization of hydrocarbons along with a detailed description of each. The major difficulty in understanding the concepts of Organic Chemistry is that it has a requirement of stereoscopic visualization to get the understanding of compound structures [8]. Students find learning chemistry in real space exciting and with the 3D model being interactive, they can remember the structure vividly. Our application provides a student abundant space to perform comparisons between the chemical structures, which aids them to clear their chief doubts. Results from a few researches show improvements in student performance after using 3-dimensional learning methods. It is necessary that these methods are used frequently which in turn is beneficial to students for long term retention.

Following is the manner in which the remaining paper is organized: Section 2 includes the literature survey, Section 3 gives a detailed description of the adopted methodology for the proposed system, and Section 4 draws conclusion and future work.

2 Literature Review

The process of gaining knowledge through experience or feedback is termed as experiential learning; contrary

to lectures and classroom learning. During the process of learning, the learner is in touch with the realities of what is being studied. Kolb's Experiential Learning Theory (ELT) integrates a framework that aims at addressing 21st century issues of learning and education. Through ELT, the aim is to explain how experience is revolutionized into learning and reliable knowledge [9]. Technologies part of the Reality-Virtuality continuum provide a simulated environment which gives users an immersive experience, thereby enabling learning by being in touch with the concept's reality. Conrad Tucker, a professor, believes that replacing traditional learning methods with immersive experiences will enhance education. He observes that currently, there aren't many online courses related to STEM. These are some of the domains, especially Engineering, that always have the need of laboratories. While incomes are continuing to remain steady, the cost of education is soaring. Augmented, Virtual and Mixed Reality can be a helping hand in reversing the cost curve [10].

Supporting education with 3-D instructions is bringing a whole new dynamic to classrooms. A systematic review was conducted to test the efficacy of VR based teaching on students. The study analysed to see if advantages of the technology helped students in retaining information and favourable results were achieved, thus showing that the effects of VR learning provided better retention irrespective of when the assessment was carried out [11]. Such technologies provide the right set of circumstances that help in engaging students. Incorporating Virtual Reality into higher education curriculum impels students to learn and escalates their engagement. Students are able to immerse themselves into a virtual environment that delivers a whole new platform by providing them with the information they need and an interactive experience [12]. Virtual reality has allowed creation and simulation of numerous situations of information presentation (e.g., a virtual museum), object manipulation (e.g., a virtual anatomy laboratory) as well as problem solving, which permits its wide use in Education [13], [14], [15].

Students who possess spatial ability can surely delineate a spatial object even when the spatial entity isn't in front of them. With the help of spatial cognitive skills, a person learns to imagine, and inwardly represent real world objects from different perspectives [16]. Spatial potential consists of spatial visualization, spatial orientation and spatial relations [17]. Spatial visualization basically encompasses the mental representation of a spatial entity as well as performing manipulation over these spatial 3D objects. Spatial orientation refers to the capability of a person to be able to envision the pose and direction of an entity. It can be achieved by

performing transformations on the object. Spatial relations are the ability to form mental relationships between objects [18]. Through representation, a person's abstract mind can be known. Hence representation of abstract concepts is principal in the field of education. Spatial abilities are one of the cognitive factors that are relevant to the mastery of chemistry concepts because it includes various scenarios where a 3D mental model of a 2D depiction has to be assumed and possibly mentally rotating it, e.g. To know the bond angles [19]. High spatial ability students generally perform better in chemistry because they are able to mentally manipulate data belonging to spatial domain or represent complex information visually [19]. Students are expected to translate a chemical formula into its molecular structure(s), visualize the corresponding three-dimensional (3D) configurations, and compare these configurations. Therefore, being able to comprehend and mentally manipulate chemical representations is critical for students to understand the content and conduct advanced scientific research[19].

Creating fine 3D content for chemistry education has exhibited great improvement in grasping and visualising compound structures. A demonstration of the application of AR in classrooms and laboratories is done using a smartphone application and notecards. The instructor can create required AR content which can eventually be accessed by students upon downloading the application. Feedback given by the students included an ease in understanding the taught concept and an illusion that the user is walking through the setup process in the laboratory [20].

3 Methodology

3.1 Elements of the application

- Microsoft HoloLens

Microsoft HoloLens is a mixed reality (MR) device that permits the user to engage and interact with digital 3D content and collaborate with both real-world artefacts and virtual artefacts in the form of holographic-like images [21]. It is a head-mounted device comprising of multiple and diverse sensors, a computer, and a stereo pair of display panels. The built-in sensors include four cameras on the sides, a video camera at the front, a depth camera, and an inertial measurement unit (IMU). The computer includes a custom-built Holographic Processing Unit (HPU) with 2GB RAM designed for fast processing of holograms [22]. Important HoloLens features that have been put to use in the application:

- Gaze: It is the first mode of input and discloses and aids the user's intent and awareness [23].
- Gesture: These convert user intent or motive into some action. With gestures, users can interact and play around with holograms. It tracks the user's hand's position, acknowledges and responds to user input, and give feedback to the user established from hand state and position [23].
- Spatial mapping: The spatial mapping feature of HoloLens grants real-time display of the constructed 3D mesh on the stereo display panels of HoloLens creating a mixed reality visualisation of the map [22]. Microsoft researchers have previously developed Kinect Fusion [24] which is a simultaneous localisation and mapping (SLAM) algorithm for real-time 3D scene reconstruction and the same is being used here as well.



Fig. 2 Microsoft HoloLens

Fig 2. shows the Microsoft HoloLens 1st Gen

- Holograms: HoloLens lets you create holograms, which are 3D graphical models [22] made of light and sound that appear in the real space around you, just as if they were real entities. These holograms can be interacted with, with the help of gaze, gestures and voice commands, and these can also collaborate with real-world surfaces around you. With holograms, you can create digital bodies that are ingredients of real world. Fig. 3. shows a sample hologram.
- Unity engine: Unity3D is one of the most famous virtual reality and mixed reality tools that has windows mixed reality and HoloLens support, also a cross-platform game development software, and besides Mac OSX, Unity 3D can fully support WindowsXP/Vista/7, Unity3D supports three scripting languages: JavaScript, C#, and a dialect of Python called Boo[25]. It provides rich functionalities to create and deal with Holograms.

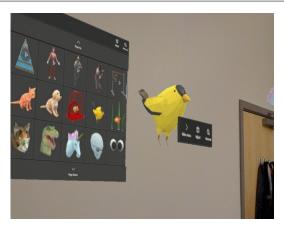


Fig. 3 Sample Hologram

- Vuforia: The Vuforia engine allows us to use Vuforia Image Targets to recognize an image and augment it with digital 3D content rendered on Microsoft HoloLens.
- Visual Studio: The final solution file (.sln) gets compiled here and the app is deployed on the HoloLens.
- Mixed Reality Toolkit: The Mixed Reality Toolkit (MRTK) is a cross-platform toolkit comprising of packages and resources used for building Mixed Reality applications. Important features:
 - Camera system
 The camera system enables the Microsoft Mixed
 Reality Toolkit to configure and optimize the application's camera for use in mixed reality applications.
 - Input system
 MRTK's Input System provides elements like
 interact-able object, cursor, focus and pointers
 which are crucial for input management.

3.2 Proposed System Architecture

The elementary organization of the system, embodying key elements, their relationships to each other and to the environment is covered here

Fig. 4 shows the system architecture which has 4 main units as follows : $\,$

- Visual Studio Unit The final solution file (.sln) gets compiled through and the app is deployed on the HoloLens.
- Vuforia Unit Its AR camera detects the image target, interacts with the Vuforia Engine which in turn reaches out to the Image Target Database to provide the corresponding 3D asset that needs to be superimposed.

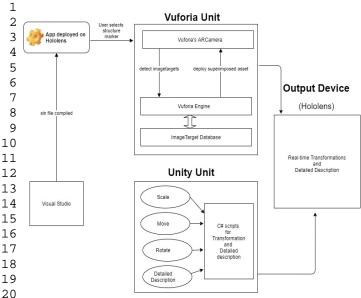


Fig. 4 System Architecture

- Unity Unit Maps hand gestures for transformations and enables the corresponding C# scripts.
- Device Unit Application is deployed and 3D structures are visualized.

Image Targets are images which will be identified by Vuforia's SDK and what sets apart these image targets from QR codes or data matrices is that they don't require special black and white regions or codes to be detected. These image targets are recognized based on features naturally present in the image. Once detected, Vuforia will track the image along the camera's field of view. A sample image target is shown in Fig. 5.



 ${\bf Fig.~5} \ \ {\bf Image~Target~Sample}$

Post detecting an image target, its corresponding 3D model needs to be superimposed on it. One such 3D model of the compound Methane is shown in Fig. 6.

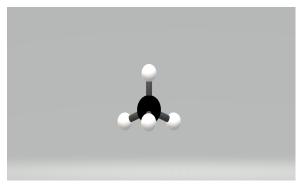


Fig. 6 Methane Model

The detailed process, as envisioned, right from defining the image target to associating a 3D model with it is depicted in Fig. 7.

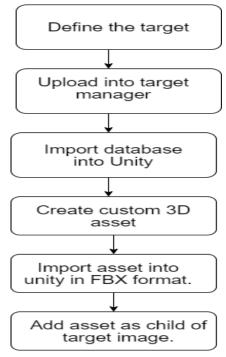


Fig. 7 Vuforia Image Target Process

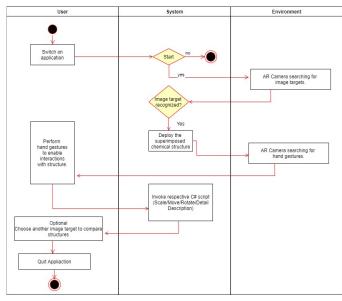
For image target recognition and rendering you need to define your image target on which you want to superimpose your 3D object. On the Vuforia developer console, we create a custom database into which we put our target image. Every image uploaded onto the target manager will have a star rating associated with it which denotes the number of features present in the uploaded image. Higher the star rating, more the features. This image now has to be brought into the unity environment. But firstly, to implement Vuforia in our project we have to specify the key in our project which

is available on the Vuforia developer console. In Vuforia settings, we then import our database which holds our target image. In the next step the appropriate 3D model needs to be created which will be superimposed on a particular image target.

This model can be created in any 3D model creation tool like Blender which then has to be imported into Unity in fbx format. Finally, the model will be added as a child (every scene in unity follows a hierarchy) of the image target.

3.3 Proposed Working of the application

Fig. 8. illustrates the basic working of our application



 ${\bf Fig.~8} \ \ {\bf Expected~Working}$

When the application has been deployed and started, the HoloLens' Mixed Reality camera (with Vuforia AR-Camera support) will start searching the physical space to detect any image targets. The user selects a structure marker, which when detected by the camera, its corresponding 3D model structure is rendered by the vuforia engine and deployed on the HoloLens, which is seen by the user. In order to perform transformations like rotate, scale and translate, hand gestures will be performed by the user which when recognised, the unity engine will enable required C# scripts and changes will be observed. The HoloLens and Unity Engine map these gestures and enable corresponding C# scripts.

Using unity editor the proposed model was validated

for a basic hydrocarbon - methane which resulted in the output shown in Fig. 9.



Fig. 9 Sample Output

The 3D model of methane is enclosed by a Bounding Box which has cubes and spheres on each of its sides. Using the cube and sphere, scale and rotate transformations can be applied on the model respectively.

4 Conclusion and Future Scope

In this project, we propose a Mixed Reality application to visualize the complex structures of molecular compounds in Organic Chemistry using image targets, effectively reducing the complexities to visualize chemical structures and properties in 3D space .Once the structure is visualized on the HoloLens the students can then play around with the structure thus increasing the learnability. Outcomes are expected to be an overall improvement in final skill level for all students. Considering the fact that mixed reality is a culmination of physical world and the virtual objects we don't have the restriction of a physical space/environment which can be used to our advantage. Students can rearrange multiple 3D structures to make comparisons which helps in better understanding of the compound family i.e. Alkane, Alkene, Alkyne, thus increasing the workload of our application.

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The SVJour3 document class users guide Version 3.2 – for Springer journals

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8 May 2007

Contents

1	Introduction 1.1 Overview	1 2 2
2	Initializing the class	2
3	The article header	4
	3.1 The title	4
	3.2 Authors	4
	3.3 Addresses	5
	3.4 Footnotes to the title block	5
	3.5 Changing the running heads	6
	3.6 Typesetting the header	6
4	Abstract, keywords, MSC, PACS, and CR codes	6
5	Theorem-like structures	
	5.1 Predefined environments	7
	5.2 Defining new structures	8
6	Additional commands	9

1 Introduction

This documentation describes the SVJOUR3 IATEX 2ε document class. It is not intended to be a general introduction to TeX or IATEX. For this we refer to [2] and [3].

SVJOUR3 was derived from the LATEX 2_{ε} article.cls, based on TeX version 3.141 and LATEX 2_{ε} . Hence text, formulas, figures and tables are typed using the standard LATEX 2_{ε} commands. The standard sectioning commands are also used.

The main differences to the standard article class are the presence of additional high-level structuring commands for the article header, new environments for theorem-like structures, and some other useful commands.

Please always give a \label where possible and use \ref for cross-referencing. Such cross-references will be converted to hyper-links in the electronic version. The \cite and \bibitem mechanism for bibliographic references is also obligatory.

1.1 Overview

The documentation consists of this document—which describes the whole class (i.e. the differences to the article.cls)—and a ready-to-use template to allow you to start writing immediately.

1.2 Using PostScript fonts

Springer journals produced in TEX are typeset using the PostScript¹ Times fonts for the main text. As the use of PostScript fonts results in different line and page breaks than when using Computer Modern (CM) fonts, we encourage you to use our document class together with the psnfss package mathptmx. This package makes all the necessary font replacements to show you the page makeup nearly as it will be printed. Ask your local TEXpert for details. PostScript previewing is possible on most systems. On some installations, however, onscreen previewing may be possible only with CM fonts.

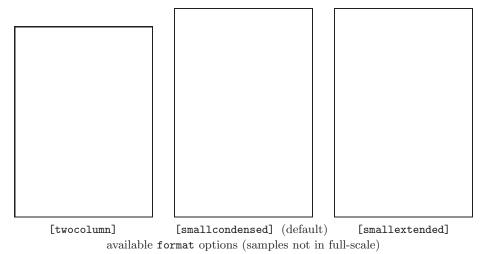
If, for technical reasons, you are not able to use the PS fonts, it is also possible to use our document class together with the ordinary Computer Modern fonts. Note, however, that in this case line and page breaks will change when we reT_{EX} your file with PS fonts, making it necessary for you to check them again carefully once you receive the proofs from the printer.

2 Initializing the class

To use the document class, enter

¹PostScript is a trademark of Adobe.

at the beginning of your article. The first option $[\langle format \rangle]$ is required and should be set according to the journal for which you are planning to submit a contribution. Three formats are available. The format is pre-set in the template, but choose the one that suits your specific journal if there is no journal-specific template available for your journal.



There is one general option $\lceil \langle glov3 \rangle \rceil$ that is auto-activated if no special option for the particular journal exists or is given. This option causes \LaTeX to read in the class option file svglov3.clo (part of the package). Do not try to use those options of the old SVJour classes version 1 and 2 as these are not suitable for SVJour3—you will get a class error, tops.

Other options, valid for every journal, are

draft to make overfull boxes visible,

final the opposite, and

referee required to produce a hardcopy for the referee with a special layout

(bigger interline spacing).

The next four additional options control the automatic numbering of figures, tables, equations, and theorem-like environments. The fifth option described below disables the "Springer" theorems (see also Sect. 5). The last option describes the natbib package.

numbook "numbering like the standard book class"—prefixes all the num-

bers mentioned above with the section number,

envcountsect the same for theorem like environments only,

environments, environments,

envcountreset resets the theorem counter(s) every new section,

nospthms use it only if you want to suppress all Springer theorem-like envi-

ronments (see Sect. 5) and use the theorem environments of original LaTeX package or other theorem packages instead. (Please

check this with your editor.)

natbib handles reference entries in the author-year system (with or with-

out BibTeX) by using the natbib package of Patrick W. Daly. It can be found at the *Comprehensive TeX Archive Network* (CTAN...tex-archive/macros/latex/contrib/supported/natbib/),

see [4, 5, 6].

If a journal contains articles in languages other than English the class provides two options "[deutsch]" and "[francais]" that automatically translate supplied texts or phrases given from LATeX.

There may be additional options for a specific journal—please refer to the extra documentation or to the template file.

As an example, we show how to begin a document for a two-column journal produced in draft mode:

\documentclass[twocolumn,draft]{svjour3}

3 The article header

In this section we describe the usage of the high-level structuring commands for the article header. Header in this context means everything that comes before the abstract.

3.1 The title

The commands for the title and subtitle of your article are

```
\title \{\langle your\ title \rangle\}
\subtitle \{\langle your\ subtitle \rangle\}
```

You can also dedicate your article to somebody by specifying

 $\del{dedication} \del{dedication}$

3.2 Authors

Information about the authors is provided with

```
\author \{\langle author\ name\ [\setminus and\ author\ name]\ \rangle\}
```

If there is more than one author, the names should be separated by \and. To make this clear, we provide an example:

\author{John B. Doe \and Sally Q. Public \and Joe A. Smith}

3.3 Addresses

Address information is marked with

```
\institute \{\langle address\ information\ | \ address\ information | \rangle\}
```

If there is more than one address, the entries are separated by \and.

As the address of the author appears as a footnote on the first page of your article, the author name is to be repeated in the address information with an **\at** depicting the affiliation. Addresses should be contained in one line, using commas to separate the parts of the address. In addition, you can use

$\ensuremath{\mbox{\mbox{$\sim$}}} \ensuremath{\mbox{\mbox{\sim}}} \ensuremath{\mbox{\sim}} \ensuremath{\m$

to provide an email address within \institute.

If there are authors appearing with different addresses the affiliations can be indicated with the same author listed "\at" (i.e. before) each particular address in the \institute{...} field—authors in such lists (read: at the same address) should again be separated by an \and.

To continue the example above, we could say

3.4 Footnotes to the title block

If footnotes to the title, subtitle, author's names or institute addresses are needed, please code them with

\thanks $\{\langle text \ of \ footnote \rangle\}$

immediately after the word in the corresponding field. Please note that these footnotes are not marked—they will appear above the address information at the bottom of the first page, enclosed in rules.

3.5 Changing the running heads

Normally the running heads—if present in the specific journal—are produced automatically by the \maketitle command using the contents of \title and \author. If the result is too long for the page header (running head) the class will produce an error message and you will be asked to supply a shorter version. This is done using the syntax

```
\begin{array}{l} \text{\tt titlerunning}\{\langle text \rangle\} \\ \text{\tt authorrunning}\{\langle first\ author\ \text{et\ al.} \rangle\} \end{array}
```

These commands must be entered before \maketitle.

3.6 Typesetting the header

Having entered the commands described in this section, please format the heading with the standard $\mbox{maketitle}$ command. If you leave it out, the work done so far will produce no text.

4 Abstract, keywords, MSC, PACS, and CR codes

The environment for the abstract is the same as in the standard article class. To insert keywords, a "Mathematics Subject Classification" (MSC), "Physics and Astronomy Classification Scheme" (PACS), or "ACM Computing Classification" (CR) codes you should use

```
\label{eq:local_codes} $$ \ \subclass{\MSC\ codes}$ \ \PACS{\PACS\ codes}$ \ \CRclass{\CR\ codes}$ $$
```

at the end—but still inside—of the abstract environment; the individual words or codes should be separated by \and.

Some journals published in other languages than English reapeat those elements in translation at the end of the header material before the actual article starts.

Please use the following environment for that and give the relevant codes (MSC, PACS, CR) only in the translated abstract (see also the particular template file)

```
\begin{translation}{english}
  \begin{abstract}
    ...
  \end{abstract}
  \end{translation}
```

5 Theorem-like structures

5.1 Predefined environments

In the SVJOUR3 document class the functions of the standard \newtheorem command have been enhanced to allow a more flexible font selection. All standard functions though remain intact (e.g. adding an optional argument specifying additional text after the environment counter). To typeset environments such as definitions, theorems, lemmas or examples, we have predefined the environments in the list below. Note that the font selection of environment heading vs. its body font is depicted in this list with

```
environment name = bold heading normal text body environment name = italic heading normal text body

Unnumbered environments will be produced by: claim and proof.

Numbered environments will be produced by: theorem, proposition, lemma, corollary, definition, exercise, problem, solution, remark, note, case, conjecture, example, property, and question.

The syntax is exactly the same as described in [3, Sect. 3.4.3]:
```

environment name = bold heading italic text body

```
\begin{\langle environment\rangle}[\langle name\rangle]\\ \dots\\ \\ \end{\langle environment\rangle}
```

where the optional name is often used for the common name of the theorem:

```
\begin{theorem}[Church, Rosser]
...
\end{theorem}
```

Sometimes the automatic braces around the optional argument are unwanted (e.g. when it consists only of a reference made with \cite). Then you can wrap the whole theorem-like structure in a theopargself environment. It suppresses the braces and gives you complete control over the optional argument, e.g.:

```
\begin{theopargself}
  \begin{theorem}[\cite{Church,Rosser}]
  ...
  \end{theorem}
\end{theopargself}
```

5.2 Defining new structures

For cases where you do not find an appropriate predefined theorem-like structure above, we provide two mechanisms to define your own environment. Use

to define an environment compliant with the selected class options (see Sect. 2) and designed as the predefined Springer theorem-like environments.

Continuative commands you can use here are

There is also a starred version, without optional arguments, which provides a theorem environment without numbers. Here *name* is the name of the environment, *label text* is the text to be typeset as heading, and the *label font* and *body font* are the font for the label text and the theorem body.

If you use the *numbered within* argument, the new structure will be numbered within the specified sectional unit—if you specify *numbered like*, it shares its numbering sequence with the referenced structure.

For instance, the predefined environments theorem and proof are defined as

```
\spnewtheorem{theorem}{Theorem}{\\it}{\\it}\\spnewtheorem*{proof}{Theorem}{\\it}{\\rm}
```

whereas one could define a theorem-like structure algorithm, numbered within the current section as

```
\spnewtheorem{algorithm}{Algorithm}[section]{\bf}{\rm}
```

It is also possible to skip all theorem features of the SVJOUR3 document class (see Sect. 2) and/or to use the *theorem* package shipped with \LaTeX 2 ε (see [1] for a complete description) or the *amsthm* package of $\mathcal{A}_{\mathcal{M}}$ SMTEX to define new theorem environments. But note that once you use them you should not change the predefined structures.

6 Additional commands

We provide some additional useful commands which you can use in your manuscript. The first is the *acknowledgements* environment

```
\begin{acknowledgements}
...
\end{acknowledgements}
```

which is usually used as the last paragraph of the last section.

The next is an enhancement of the standard \caption command used inside of figure environments to produce the legend. The added command

\sidecaption

can be used to produce a figure legend beside the figure. To activate this feature you have to enter it as the very first command inside the figure environment

```
\begin{figure}\sidecaption
\resizebox{0.3\hsize}{!}{\includegraphics*{figure.eps}}
\caption{A figure}
\end{figure}
```

If there is not enough room for the legend the normal **\caption** command will be used. Also note that this works only for captions that come *after* the included images.

We also have enhanced the *description* environment by an optional parameter, which lets you specify the largest item label to appear within the list. The syntax now is

```
\label{large-label} $$ \begin{description} [\langle large label \rangle] \\ \dots \\ \begin{description} \end{description} $$
```

The texts of all items are indented by the width of *largelabel* and the item labels are typeset flush left within this space. Note: The optional parameter will work only two levels deep.

The often missed command

\qed

yields the known \square symbol with appropriate spacing to close e.g. a proof, use the new declaration

\smartqed

to move the position of the predefined qed symbol to be flush right (in text mode). If you want to use this feature throughout your article the declaration

must be set in the preamble; otherwise it should be used individually in the relevant environment, i.e. proof. $\hfill\Box$

The last two commands working as markup in

mark vectors (e.g. S, or S) and tensors (e.g. S) respectively.

References

- 1. Mittelbach F., Goossens, M.: The L^ATEX Companion, 2nd edn. Addison-Wesley, Boston, Massachusetts (2004)
- 2. Knuth D.E.: The TEXbook (revised to cover TEX3). Addison-Wesley, Reading, Massachusetts (1991)
- 3. Lamport L.: LATEX: A Document Preparation System, 2nd edn. Addison-Wesley, Reading, Massachusetts (1994)
- 4. TEX Users Group (TUG), http://www.tug.org
- 5. Deutschsprachige Anwendervereinigung TEX e.V. (DANTE), Heidelberg, Germany, http://www.dante.de
- 6. UK TEX Users' Group (UK-TuG), http://uk.tug.org