/\* BLUETOOTH\*/

#include <SoftwareSerial.h> // create a simple communication setup between two serial interfaces.

SoftwareSerial mySerial(10, 11); // RX, TX // create the object for softwareserial

void setup() { //this methode runs once when Arduino ON or rst

// Open serial communications and wait for port to open:

Serial.begin(57600);

while (!Serial) {

; // wait for serial port to connect. Needed for native USB port only

}

Serial.println("Goodnight moon!");

// set the data rate for the SoftwareSerial port

mySerial.begin(4800);

mySerial.println("Hello, world?");

}

void loop() { // run over and over

if (mySerial.available()) {

Serial.write(mySerial.read()); //allows msg software to hardware

}

if (Serial.available()) {

mySerial.write(Serial.read()); // allows msg hardware to software

}

}