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1. #include <iostream>
2. #include <locale>
3. #include <vector>
4. #include <string>
5. #include <iomanip>
6. using namespace std;
7.
8. //функция
9. double f(double x, double y)
10. {
11.     return (6 * pow(x, 2) + 4) * sin(y);
12. }
13.
14. //метод Эйлера
15. void euler(double x0, double y0, double h, double e)
16. {
17.     double x = x0, y = y0;
18.
19.     for (int i = 0; i < 11; i++)
20.     {
21.         cout << "\t" << y;
22.
23.         y = y + h * f(x, y);
24.
25.         x = x + h;
26.     }
27. }
28.
29. //модифицированный метод эйлера
30. void euler_modif(double x0, double y0, double h, double e)
31. {
32.     double x = x0, y = y0;
33.
34.     for (int i = 0; i < 11; i++)
35.     {
36.         cout << "\t" << y;
37.
38.         y = y + h * f(x + h / 2, y + h / 2 * f(x, y));
39.
40.         x = x + h;
41.     }
42. }
43.
44. //метод Рунге-Кутты
45. void runge_kutt(double x0, double y0, double h, double e)
46. {
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47.         vector<double> z(4);
48.
49.         double x = x0, y = y0;
50.         for (int i = 0; i < 11; i++)
51.         {
52.             //вычисляем коэффициенты
53.             z[0] = h * f(x, y);
54.             z[1] = h * f(x + h / 2, y + z[0] / 2);
55.             z[2] = h * f(x + h / 2, y + z[1] / 2);
56.             z[3] = h * f(x + h, y + z[2]);
57.
58.             cout << "\t" << y;
59.
60.             y = y + (z[0] + 2 * z[1] + 2 * z[2] + z[3]) / 6;
61.
62.             x = x + h;
63.         }
64.     }
65.
66.     //метод Адамса
67.     void adams(double x0, double y0, double h, double e)
68.     {
69.         vector<double> z(4), yk(4), xk(4);
70.
71.         double x = x0, y = y0;
72.         double t = 0;
73.
74.         yk[0] = y0;
75.         xk[0] = x0;
76.
77.         cout << setw(9) << y0;
78.
79.         for (int i = 1; i < 11; i++)
80.         {
81.             if (i < 4)
82.             {
83.                 z[0] = h * f(x, y);
84.                 z[1] = h * f(x + h / 2, y + z[0] / 2);
85.                 z[2] = h * f(x + h / 2, y + z[1] / 2);
86.                 z[3] = h * f(x + h, y + z[2]);
87.
88.                 y = y + (z[0] + 2 * z[1] + 2 * z[2] +
90.                 z[3]) / 6;
89.                 x = x + h;
91.                 yk[i] = y;
92.                 xk[i] = x;
93.             }
94.             else
95.             {

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96.             t = 55 * f(xk[3], yk[3]) - 59 *
f(xk[2], yk[2]) + 37 * f(xk[1], yk[1]) - 9 * f(xk[0], yk[0]);
97.             y = y + (h / 24) * t;
98.
99.             xk[0] = xk[0] + h;
100.            xk[1] = xk[1] + h;
101.            xk[2] = xk[2] + h;
102.            xk[3] = xk[3] + h;
103.
104.            yk[0] = yk[1];
105.            yk[1] = yk[2];
106.            yk[2] = yk[3];
107.            yk[3] = y;
108.        }
109.        cout << "\t" << y;
110.    }
111.    return;
112. }
113. int main()
114. {
115.     double x0 = 0, y0 = 1, h = 0.1, e = 0.001;
116.
117.     cout << "y' = (5 * x^2 + 4) * sin(y)" << endl;
118.
119.     cout << "Euler:" << endl;
120.     euler(x0, y0, h, e);
121.     cout << endl;
122.
123.     cout << "Euler mod:" << endl;
124.     euler_modif(x0, y0, h, e);
125.     cout << endl;
126.
127.     cout << "Runge-Kutt:" << endl;
128.     runge_kutt(x0, y0, h, e);
129.     cout << endl;
130.
131.     cout << "Adams:" << endl;
132.     adams(x0, y0, h, e);
133.     cout << endl;
134.
135.     return 0;
136. }

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Консоль отладки Microsoft Visual Studio

$y' = (5 * x^2 + 4) * \sin(y)$

Euler:

1	1.33659	1.7315	2.15004	2.52998	2.81478	2.99134	3.08355	3.12381	3.13775	3.14115
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Euler mod:

1	1.36941	1.78291	2.1825	2.51323	2.75524	2.91747	3.01879	3.07794	3.11021	3.12667
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Runge-Kutt:

1	1.36955	1.7806	2.17877	2.51268	2.76018	2.9265	3.02925	3.08767	3.11801	3.13228
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Adams:

1	1.36955	1.7806	2.17877	2.50034	2.75436	2.9199	3.0374	3.07877	3.14505	3.07752
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