

Falah Sheikh

+1-587-969-6241 | falah.h.sheikh@gmail.com | [LinkedIn/falah-sheikh](https://www.linkedin.com/in/falah-sheikh) | [GitHub/falahsheikh](https://github.com/falahsheikh)

Education

University of Calgary

Bachelor of Science in Computer Science

Calgary, AB, Canada

Expected Sept. 2026

Relevant Coursework: Data Structures & Algorithms, Computer Architecture, Operating Systems, Database Management Systems

Skills

Languages: Python, R, Java, C, C++, SQL, ARM Assembly, LaTeX

Developer Tools: Git, GitHub, IntelliJ IDEA, VS Code, PyCharm, Eclipse, Emacs

Experience

Machine Learning Researcher

University of Calgary

Calgary, AB, Canada

Jan. 2025 – Present

- Developing an efficient and interpretable AI model for early diagnosis

Machine Learning Researcher

University of Calgary

Calgary, AB, Canada

May 2024 – Jan. 2025

- Trained a CNN model for lunar phase classification, achieving **82.74% accuracy** on over 20,000 astronomical images and **98% prediction accuracy** on test cases
- Engineered end-to-end data pipeline using Python, Selenium, and NASA's API to create a first-of-its-kind dataset spanning 13 years of lunar imagery
- Optimized model architecture through transfer learning with ResNet18 and strategic data augmentation, **improving accuracy from 78% to 82%** while reducing false positives

Software Team Engineer

TechStart UCalgary

Calgary, AB, Canada

Oct. 2022 – Apr. 2023

- Designed and implemented a reinforcement learning pipeline for the Kinova Gen3 robotic arm, achieving a **90% success rate** in object manipulation tasks, demonstrating the efficacy of policy learning in real-world robotic applications
- Developed and optimized object recognition and distance estimation algorithms using Python and OpenCV, enhancing robotic perception for precise manipulation and autonomous operation
- Engineered a custom OpenAI Gym environment to simulate and evaluate robotic arm performance, enabling rapid prototyping and reducing reliance on physical hardware for reinforcement learning experiments
- Developed a custom OpenAI Gym environment to simulate and test robotic arm operations, accelerating prototyping by reducing dependency on physical hardware
- Successfully transferred a learned policy from simulation to the physical Kinova Gen3 arm within **2.5 days**, achieving real-world pick-and-place operations through integrated reinforcement learning and computer vision

Publications

Automated Lunar Age Detection Using Convolutional Neural Networks: A Photographic Approach to Determining the Day of the Synodic Month | 2025 | Co-author | Under review

- Developed a CNN-based approach using ResNet18 to determine the moon's age in a synodic month from lunar images, contrasting with traditional mathematical methods

Explainable light-weight AI for early Alzheimer's detection using MRI scans | 2025 | First-author | Ongoing research

- Designing a Lightweight AI model for early Alzheimer's detection from MRI scans, focusing on efficiency and clinical applicability

Adaptive Energy-Aware Round Robin Scheduling: A Dynamic Time Quantum Approach Integrating Battery Levels and Process Burst Characteristics | 2025 | First-author | Ongoing research

- Proposing an energy-efficient Round Robin scheduling approach that dynamically adjusts time quantum based on battery levels and process burst characteristics