# A Data-Driven Approach for Inferring Student Proficiency from Game Activity Logs

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### **ABSTRACT**

Traditional assessments are important in education because they allow collecting evidence about student progress. Unfortunately, they can be very tedious to their stakeholders. In contrast, invisible assessment unobtrusively gathers performance data from students' daily activities to make inference about student relevant competency. We present a novel data analysis pipeline, Student Profficiency Inferrer from Game data (SPRING), that allows modeling game playing behavior in educational games. Unlike prior work, SPRING is a fully data-driven method that does not require costly domain knowledge engineering. We validate our method using data collected from students playing 11 educational mini-games. Our results suggest that SPRING is accurate to predict Math assessments ( $R^2 = 0.55$ , Spearman  $\rho = 0.82$ ).

# **ACM Classification Keywords**

K.3.1 Computer Uses in Education.

# **Author Keywords**

Educational Games, Student Modeling, Stealth Assessment

# INTRODUCTION

Educational assessments are important because they collect evidence about about whether the teaching goals are being met. Unfortunately, the process of administering assessments is usually disconnected to the learning environment, and it is often disruptive to the classroom. In many developed countries, students now find themselves spending increasing amounts of time preparing and taking tests instead of learning [7]. For example, a survey of the current state of testing in America revealed that students are taking an average of 113 standardized tests between pre-K and highschool [8]. For these reasons, it is not surprising that the recent political climate and the general population have been weighing in on the question of whether students are being tested too much [8].

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According to Evidence Centered Design (ECD) [13], the goal of assessment is to characterize the strength of evidence regarding claims one wants to make about individuals or groups. Therefore, the assessment process involves identifying, organizing, or creating activities for students so we may observe that evidence. An interesting alternative to traditional (summative) assessment is invisible (often called stealth) assessment [15], where the evidence is gathered from leaners unobtrusively from the digital interactions of their ongoing activities. This data is used to understand claims regarding what students know and what they can do [16]. Stealth assessment is also intended to reduce or eliminate test anxiety, while not sacrificing validity and reliability [14].

A promising opportunity for invisible assessment is using log data collected from educational games. Unfortunately, engineering a system that parses logs is costly and time-consuming. For example, prior work [15, 16] has relied extensively on subject matter expertise to define a student model in form of a Bayesian Network to build both the competency model, and to extract features of the performance data.

Our motivation is that invisible assessment from game data may become more accurate and cheaper to implement if the domain knowledge engineering could be automated by a data-driven process. Game data is often logged with what we call a *slot and filler* structure. In Table 1, we show a simplified example of a real educational game log that uses slot and filler structure. The slots are discrete sets of events that are initiated by the leaner. Each slot may accept zero to multiple fillers. Each filler represents a value of a property of the slot event. For example, a "move" event that represents that the learner moved an object in the screen may have an *x* and *y* fillers, to represent the target position in two-dimensional space. Generic machine learning algorithms input *feature vectors* or *sequences* and not slot and filler structures.

Id	User Id	<b>Event Name</b>	<b>Event Data</b>
1	ABC	Game Start	{}
2	ABC	Move Object	{endPosX:363,endPosY:82}
3	ABC	Move Object	{endPosX:361,endPosY:54}
4	ABC	Open Toolbox	{}
4	ABC	Activate Tool	{tool:gluumi}
5	ABC	Use Gluumi	{sizeGluedTo:8,sizeNew:9}
•••			

Table 1. An example fragment of a log from an educational game.

Unfortunately, conventional machine learning algorithms cannot input slot and filler data, as they work in structures called feature vectors or sequences. Prior work [4] provides a review of the difference between feature vectors and sequences. A feature vector representation requires mapping an observation onto a fixed number of features. It is not trivial to map sequences of student actions that can be of arbitrary length into a feature vector that needs to be of a predetermined lenth. Traditional feature vector classifiers, like logistic regression or decision trees, that are used in off-the-shelf data mining packages, such as Weka [5], cannot use slot and filler data. In contrast, machine learning algorithm that allow sequential representations, like Hidden Markov Models (HMM), require a parametric model with the same number of dimensions for every observation, which does not occur in slot and filler structures.

In this paper, we propose Student PRofficiency INferrer from Game data (SPRING), a novel data analysis pipeline that models game playing behavior. SPRING allows modeling raw data in slot and filler structure. We demonstrate our approach on real student game playing data. Our experiments suggest that SPRING can be used to predict student proficiency without costly domain expertise.

# **SPRING FRAMEWORK**

In this section, we describe the discretization, sequence modeling and regression steps of SPRING

### Discretization

In order to gather the evidence for learning from student trajectories? of interactions with the game, we needed to create features that are homogenous? and can be used in an interpretable model. Each student trajectory consists of a sequence of discrete actions accompanied by some details that are usually continuous variables. Our main challenge in this phase was to transform the movements into a set of observable values that are usefull as evidence for learning. In order to make sure that the model is generalizable across multiple game levels, we first used DBSCAN

clustering algorithm [2] on the x and y coordinates of the movements to extract the crucial regions within the game interface. DBSCAN was a good candidate because it can find arbitrarily shaped clusters and does not require one to specify the number of clusters in the data a-priori. It is also robust to outliers which in our case can be interpreted as noisy movements that are not representative of learning competency. After clustering, we transformed each movement into its cluster number and considered outliers as a separate cluster. Figure 1 shows the clusters detected for one of the game levels.

We replace each (slot, filler) tuple with its corresponding clusterID. Procedure 1 shows the steps.

## **Sequence Modeling**

In the modeling phase, we hypothesized that high- and lowperforming students have similar usage patterns that are representative of their sequential decision-making process. Our



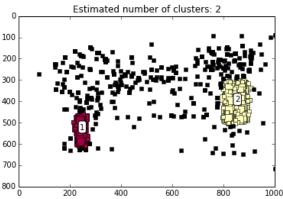


Figure 1. The clusters detected for game level 2, None Shall Pass!, using DBSCAN method. We transform each movement action into corresponding cluster number during the discretization step.

```
Procedure 1 The Discretization Step of SPRING
                                                                           procedure DISCRETIZE(S)
                                                                               A = empty dictionary of slots and possible fillers
                                                                               for each sequence s in S do
                                                                                   for each action a in s do
                                                                                       if a.filler \neq \emptyset then
Say that in our implementation we used DBSCan, but the algorithm allows any cluster algorithm allows any cluster algorithm allows any cluster algorithm.
                                                                                   end for
                                                                               end for
                                                                               for each slot and fillers tuple in A do
                                                                                   clustersIDs = DBSCAN(a.fillers)
                                                                                   C[a.slot] = K-NN classifier on fillers and clusterIDs
                                                                               end for
                                                                               D = [][] -2D array of multinomial observations
                                                                               for each sequence s in S do
                                                                                   P[i] = s.post-test
                                                                                   for each action a in s do
                                                                                       D[i,j] = C[a.slot].predict(filler)
                                                                                   end for
                                                                               end for
                                                                               return D
```

end procedure

model should be able to successfully capture this difference across different game levels and use it to predict post-test scores. Hidden Markov Models are good candidate for the task of unsupervised analysis of sequential data. Given the sequence of student actions, we aim to infer meaningful sequence of (latent) states, which describe the process that generated the actions, along with statistical patterns that can describe and distinguish those states. Since a large portion of student interactions are based on the logic of the game, we had no idea about the number of states and what they mean. As a result, we used the Hierarchical Diriclet Process HMM (HDP-HMM) [3], which is allows state spaces of unknown size to be learned from data. HDP-HMM defines a hierarchical Dirichlet process prior on transition matrices over countably infinite state spaces and is able to make a principled choice of how many states it needs based on the complexity of its training data. For details on training methods please refer to [3].

We used the output of the discretization step as sequence of multinomial observations and trained two HDP-HMMs, one for high-performing and the other for low-performing students using the student trajectories in our development set. After that, we calculated the likelihood of student trajectories in the heldout set using each of the HMMs and used the likelihood difference as a feature in a regression model for predicting the post-test scores.

# Regression

In this phase, created regreswe linear 5-fold model using cross-validation sion So spring requires 5fold cross validation for it to work?; -) I think this gives vious the particular and th on the data in our development set. We tried different regularization methods (lasso and ridge regression) to find the optimum parameters and tested it on the heldout set in order to evaluate our model. What are the features? Write equation

# **EMPIRICAL EVALUATION**

# **Game Environment**

Alice in AreaLand is an educational game developed for research purposes. It focuses on teaching and assessing geometric measurement, specifically the understanding of area, among 6th grade students. The game targets three main stages in the development of area: 1) area unit iteration, 2) use of unit squares to measure area, and 3) use of composites to measure area. The current version has 11 game levels. A simple student scenario involves covering a 2D area with smaller unit squares placed end-to-end in non-overlapping fashion, combining the single squares into rows or columns, and then determining the number of rows or columns needed. Figure 2 shows a screenshot of one game level.

Throughout the game, Alice is accompanied by Flat Cat – an assistant character who provides feedback and scaffolding to the player in the beginning of each game level and upon request when students push a hint button (represented by two magnifiers at the bottom center of Figure 2). Earlier game levels are designed for students to learn about area unit iteration and usually require them to cover a number of predefined areas with unit squares (not necessarily in a non-overlapping

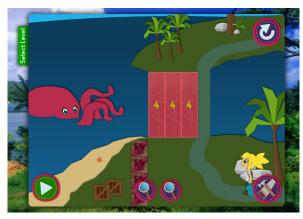


Figure 2. A screenshot of hint provided in game level 11, You Kraken Me Up!, in Alice in AreaLand. Students should combine four squares into a column and create three copies of the column to cover the designated area and prevent the octopus from attacking Alice while she crosses the bridge.

fashion). By advancing through game levels, students are presented with three tools: Gluumi for combining unit squares by gluing them together; Multy, for making copies of different objects; and Esploda for breaking compound shapes into single units. There is no limit for completing a game level regarding time or number of actions students may execute. The students press the Go Alice button (bottom left corner of Figure 2) if they deem their performance to be satisfactory for Alice to proceed. Based on the covered area and the arrangement of the and stay in the same level.

## **Dataset**

Our dataset consists of time-stamped interactions of 129 students in 11 game levels. For 77 students, we also have post-test scores from a paper-based exam with 20 questions in the 3 skills of geometric measurement. In total, there are 88,458 events recorded in the dataset from 1,510 game sessions, meaning that student tried some of the game levels for multiple times. Based on the ECD framework, beginning levels only involve area unit iteration skill and the other skills and related features are gradually added to the later game levels. Figure 3 shows the frequency of different events in each game level. As depicted in Figure 3, the student interactions with the system in all game levels is dominated by movements.

We only used the trajectories of the students who participated in the post-test. In the case of multiple attempts in a game level, we only considered the trajectory from the first attempt. Figure 4 shows the boxplot of sequence length in each game level.

# **Experimental Setup**

First we divide students into two groups, one (%80) for training and development purposes and the other (%20) for test and verification. In the synthesis phase, we transform log data of different nature (eg. movements, use of the tools, requests for hints) in each game level to observable values that can be used as evidence for learning. In the modeling phase, we use the

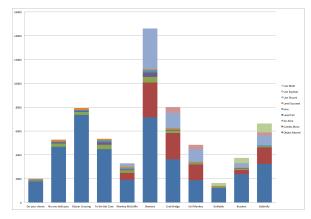


Figure 3. Frequency of Events in Each Game Level

observations to train two Hidden Markov Model (HMM)s that capture the sequence of actions for high- and low-performing students. In the aggregation phase, we uses the likelihood of students' sequence of action in order to build a regression model that is predictive of the post-test results. Finally, we test the regression model on the held-out set (%20) and report the results.

### Results

In order to evaluate our regression model we decided to compare its performance agains two baselines: 1) A regression model that uses success and failure of students in each game level as feature Write equation and 2) A regression model that uses the sequence lengths in each game level Write equation. Our model was able to significantly outperform both baselines regarding to mean absolute error and root mean squared error. Moreover, the  $R^2$  correlation and Spearman  $\rho$  of our predicted values with the true values was much higher than both baselines. Table 2 shows the results.

Show residual plot Show confidence intervals

# **RELATION TO PRIOR WORK**

In order to deal with such highly unstructured data, researchers often use carefully designed network structures (such as

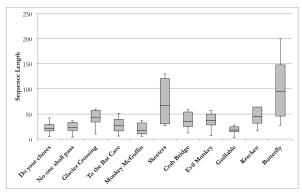


Figure 4. Boxplot of Sequence Length in Each Game Level

Predictive Features	$R^2$	ρ	MAE	RMSE
Sequence Length (Normal)	0.06	0.79	3.24	4.15
Success / Failure	0.01	0.63	3.22	4.14
SPRING	0.55	0.82	2.84	3.35

Table 2. The results of predicting post-test scores using three different feature sets

Bayesian Networks [1, 15]) or game-specific heuristics and benchmarks generated by experts playing the game [12, 17]. However, this approach is extremely labor intensive and might fail to capture meaningful patterns in student exploratory habits within the game. Given these limitations, data-driven analysis of student interactions provides a powerful alternative that facilitates the discussions around what does and does not work in a particular educational game.

The potential of computer games for educational purposes has been of interest since nearly the beginning of videogames. Unlike video games, which focus on creating an entertaining experience for the user, educational games require principles and strategies that engage students while maximizing their learning gain. Therefore, data-driven analysis of student behavior is crucial to better understand the learning process and improve the tools in the future.

There have been numerous attempts among the educational research community to develop analytic methods and build predictive models based on the data from educational games. *Newton's Playground* is an ECD based educational game with 74 problems that designed to teach qualitative physics to students in eighth- and ninth-grade. Students have to guide a green ball to a red ball by creating simple machines. Everything obeys the basic rules of physics relating to gravity and Newtons three laws of motion. Shute et al. [15] studied the effect of ECD design on student learning and found that students who played the game in a 4 hour session, showed significant improved in their qualitative, conceptual physics understanding.

Rumble Blocks is another educational game designed to teach basic concepts of structural stability and balance to children in grades K-3 (ages 5-8 years old). Harpstead et al. [6], studied the alignment of game to its target learning goals by examining whether student solutions follows the targeted principals. They employ clustering techniques on the individual solutions created by actual students and use principle-relevant metric (PRM) to measure how closely the representative solution embodies a specific targeted principle. The results demonstrated a misalignment between the feedback provided to students and the targeted knowledge.

Battleship Numberline is another educational game for understanding fraction using number line estimation. Students attempt to explode target ships and submarines by estimating numbers on a number line. Lomas et al. [11] performed a large-scale online experiment in order to study the effect of challenge on player motivation and learning. They presented different configurations of the game for different groups of students and used a combination of time spent and challenges

attempted as a measure of engagement and the average success rate of each design configuration as a measure of challenge. The results showed a linear correlation between challenge (difficulty) and engagement, meaning the easier the game, the longer students played.

Refraction is another educational game for learning about fractions by splitting laser beams into fractional amounts to target spaceships by avoiding asteroids. Liu et al. [10], created an ensemble algorithm that combines elements of Markov models, player heuristic search, and collaborative filtering techniques with state-space clustering in order to predict player movements on last game-level based on the history of movements in previous game levels. Lee et al. [9] extended the former framework by building state-action graph and using feature selection techniques to reduce the number of features for each state. To ensure extensibility, they also tested the framework on another game *DragonBox* and reported improvement over a Markov predictor.

### CONCLUSION

Limitation, we don't compare to Valerie Schultz

Limitation, we don't control for game ability like Valrerie does

Limitation, we only used data from Alice in wonderland

Method is accuaate

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