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# **SVR API ASSIGNMENT**

SVR acknowledges the presence of non-linearity in the data and provides a proficient prediction model. It uses the same principle as SVM, but for regression problems. best fit line is the hyperplane that has a maximum number of points.

We Have to decide a decision boundary at 'x' distance from the original hyperplane such that data points closest to the hyperplane or the support vectors are within that boundary line. Hence, we are going to take only those points that are within the decision boundary and have the least error rate or are within the Margin of Tolerance.

## API:

Epsilon-Support Vector Regression.

The free parameters in the model are C and epsilon.

The implementation is based on libsvm. The fit time complexity is more than quadratic with the number of samples which makes it hard to scale to datasets with more than a couple of 10000 samples. For large datasets consider using LinearSVR or SGDRegressor instead, possibly after a Nystroem transformer.

#### CODE:

class sklearn.svm.SVR(\*, kernel='rbf', degree=3, gamma='scale', coef0=0.0, tol=0.001, C=1.0, epsilon=0.1, shrinking=True, cache size=200, verbose=False, max iter=-1)

#### PARAMETERS:

kernel: {'linear', 'poly', 'rbf', 'sigmoid', 'precomputed'}, default='rbf'

Specifies the kernel type to be used in the algorithm. It must be one of 'linear', 'poly', 'rbf', 'sigmoid', 'precomputed' or a callable. If none is given, 'rbf' will be used.

degree: int, default=3

Degree of the polynomial kernel function ('poly'). Ignored by all other kernels.

gamma: {'scale', 'auto'} or float, default='scale'

Kernel coefficient for 'rbf', 'poly' and 'sigmoid'. If gamma='scale' (default) is passed then it uses 1 / (n\_features \* X.var()) as value of gamma and if 'auto', uses 1 / n\_features.

coef0: float, default=0.0

Independent term in kernel function. It is only significant in 'poly' and 'sigmoid'.

#### tol: float, default=1e-3

Tolerance for stopping criterion.

#### C: float, default=1.0

Regularization parameter. The strength of the regularization is inversely proportional to C.

# epsilon: float, default=0.1

Epsilon in the epsilon-SVR model. It specifies the epsilon-tube within which no penalty is associated in the training loss function with points predicted within a distance epsilon from the actual value.

#### shrinking: bool, default=True

Whether to use the shrinking heuristic.

# cache\_size: float, default=200

Specify the size of the kernel cache (in MB).

## verbose: bool, default=False

Enable verbose output.

#### max iter: int, default=-1

Hard limit on iterations within solver, or -1 for no limit.

# **ATTRIBUTES:**

# class\_weight\_: ndarray of shape (n\_classes,)

Multipliers of parameter C for each class. Computed based on the class weight parameter.

# coef\_: ndarray of shape (1, n\_features)

Weights assigned to the features (coefficients in the primal problem). This is only available in the case of a linear kernel.

## dual\_coef\_: ndarray of shape (1, n\_SV)

Coefficients of the support vector in the decision function.

# fit\_status\_: int

0 if correctly fitted, 1 otherwise (will raise warning)

#### intercept\_: ndarray of shape (1,)

Constants in decision function.

n\_support\_: ndarray of shape (n\_classes,), dtype=int32

Number of support vectors for each class.

shape\_fit\_: tuple of int of shape (n\_dimensions\_of\_X,)

Array dimensions of training vector X.

support\_: ndarray of shape (n\_SV,)

Indices of support vectors.

support\_vectors\_: ndarray of shape (n\_SV, n\_features)

Support vectors.