

Lab7 Let's play DDPM

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邱以中

1. Introduction

這次作業我們的目標是使用 conditional 的 diffusion model 來生成 iclevr dataset 的圖片，給定多個物體的描述(包括形狀、顏色)，生成對應描述的圖片。

2. Implementation details

- Describe how you implement your model, including your choice of DDPM, UNet architectures, noise schedule, and loss functions
 - (1) 這次作業我使用的 DDPM 是 pixel space 的
 - (2) 使用的 Unet 為 diffusers 套件中的 UNet2DModel具體架構如下

```
12 from diffusers import DDPMScheduler, UNet2DModel
```

```
self.model = UNet2DModel(  
    sample_size = 64,  
    in_channels = 3,  
    out_channels = 3,  
    layers_per_block = 2,  
    class_embed_type = None,  
    #num_class_embeds = 2325, #C (24, 3) + 1  
    block_out_channels = (128, 128, 256, 256, 512, 512),  
    down_block_types=(  
        "DownBlock2D", # a regular ResNet downsampling block  
        "DownBlock2D",  
        "DownBlock2D",  
        "DownBlock2D",  
        "AttnDownBlock2D", # a ResNet downsampling block with spatial self-attenti  
        "DownBlock2D",  
    ),  
    up_block_types=(  
        "UpBlock2D", # a regular ResNet upsampling block  
        "AttnUpBlock2D", # a ResNet upsampling block with spatial self-attenti  
        "UpBlock2D",  
        "UpBlock2D",  
        "UpBlock2D",  
        "UpBlock2D",  
    ),  
)  
'''embedding'''  
self.model.class_embedding = nn.Linear(24, class_emb_size)
```

因為輸入是一個 one hot encoding，所以我改寫了 UNet2DModel 的 class_embedding，將它改成一個 linear 的網路

(3) Noise schedule 則是使用 diffusers 套件中的 DDPMScheduler

Noise 步數設為 1000

```
12 from diffusers import DDPMScheduler, UNet2DModel

noise_scheduler = DDPMScheduler(num_train_timesteps=1000, beta_schedule='squaredcos_cap_v2')
```

(4) Loss function

loss function 則是使用 MSE loss

```
mse = nn.MSELoss()

loss = mse(noise, predicted_noise)
```

- Specify the hyperparameters (learning rate, epochs, etc.)
 - Batch size: 32
 - Lr: 0.0001
 - Epoch: 40

3. Results and discussion

- Show your results based on the testing data

- Test

```
(DL) icchiu@VLLab_24_146:~/NYCU_2023_ML/Lab7$ python ddpm.py --mode test
0%| 0/1 [
00:00<?, ?it/s]05:13:57 - INFO: Sampling 32 new images....
1000it [01:35, 10.49it/s][[C
100%| 1/1 [01:36<00
:00, 96.07s/it]
accuracy:0.8333333333333334
```



- New_test

```

~/NYCU_2023_ML/Lab7$ python ddpm.py --mode new_test
0%| 0/1 [00:00<?, ?it/s]
03:58:04 - INFO: Sampling 32 new images....
1000it [02:54, 5.73it/s]
100%| 1/1 [02:55<00:00, 175.28s/it]
accuracy:0.8095238095238095

```



- **Discuss the results of different model architectures.**

這次作業我一開始是選用一個比較小的 Unet 架構，架構圖如下，並嘗試使用不同加入 condition 的方法，但是結果都不太理想，最後發現可能是模型太小，無法很好的學習，最後加大 model 才讓效果提升，以下是我做的一些實驗。

```

self.model = UNet2DModel(
    sample_size=64,          # the target image resolution
    # in_channels=3 + num_classes, # direct
    # in_channels=3 + class_emb_size, # linear
    in_channels=3, # embedding
    out_channels=3,          # the number of output channels
    class_embed_type = None,
    layers_per_block=2,      # how many ResNet layers to use per UNet
    #small
    block_out_channels=(32, 64, 64),
    down_block_types=(
        "DownBlock2D",
        "AttnDownBlock2D",    # a ResNet downsampling block with spatial
        "AttnDownBlock2D",
    ),
    up_block_types=[
        "AttnUpBlock2D",
        "AttnUpBlock2D",      # a ResNet upsampling block with spatial
        "UpBlock2D",          # a regular ResNet upsampling block
    ],
)

```

	MSE Loss	Result
小 model + 將 condition 經過 linear layer concat 在 xt 上		
小 model + 將 condition 直接 concat 在 xt 上		
小 model + 改寫 UNet2DModel 的 class_embedding		
大 model + 改寫 UNet2DModel 的 class_embedding		

在上述表格中可以發現使用小 **model** 進行生成，都會導致 **loss** 的不穩定，以及背景會五顏六色，而使用較大的 **model** 就能很好的解決這些問題，因此最後使用較大的 **model** 來進行訓練以及生成。