Lab7 Let's play DDPM 311551040

邱以中

1. Introduction

這次作業我們的目標是使用 conditional 的 diffusion model 來生成 iclevr dataset 的圖片,給定多個物體的描述(包括形狀、顏色),生成對應描述的圖片。

2. Implementation details

- Describe how you implement your model, including your choice of DDPM,
 UNet architectures, noise schedule, and loss functions
 - (1) 這次作業我使用的 DDPM 是 pixel space 的
 - (2) 使用的 Unet 為 diffusers 套件中的 UNet2DModel 具體架構如下

12 from diffusers import DDPMScheduler, UNet2DModel

```
self.model = UNet2DModel(
   sample_size = 64,
   in_channels = 3,
   out channels = 3,
   layers_per_block = 2,
   class embed type = None,
   block_out_channels = (128, 128, 256, 256, 512, 512),
   down_block_types=(
    "DownBlock2D", # a regular ResNet downsampling block
    "DownBlock2D'
    "DownBlock2D",
    "DownBlock2D",
    "AttnDownBlock2D", # a ResNet downsampling block with spatial self-attenti
    "DownBlock2D",
   up_block_types=(
        "UpBlock2D", # a regular ResNet upsampling block
        "AttnUpBlock2D", # a ResNet upsampling block with spatial self-attenti
        "UpBlock2D",
        "UpBlock2D",
        "UpBlock2D"
        "UpBlock2D",
 'embedding'''
self.model.class_embedding = nn.Linear(24 ,class_emb_size)
```

因為輸入是一個 one hot encoding,所以我改寫了 UNet2DModel 的 class_embedding,將它改成一個 linear 的網路

(3) Noise schedule 則是使用 diffusers 套件中的 DDPMScheduler

12 from diffusers import DDPMScheduler, UNet2DModel

noise_scheduler = DDPMScheduler(num_train_timesteps=1000, beta_schedule='squaredcos_cap_v2')

(4) Loss function

loss function 則是使用 MSE loss

mse = nn.MSELoss()

loss = mse(noise, predicted_noise)

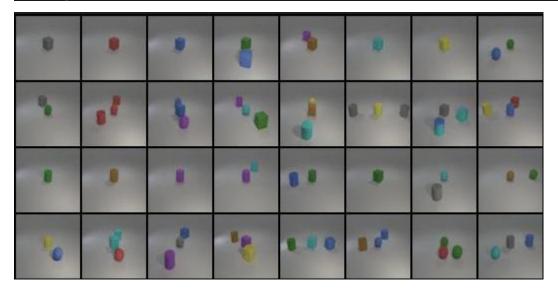
Specify the hyperparameters (learning rate, epochs, etc.)

- Batch size: 32

Lr: 0.0001Epoch: 40

3. Results and discussion

- Show your results based on the testing data
 - Test



New_test

```
0%| --mode new_test

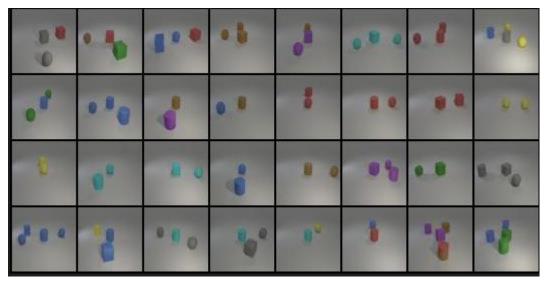
0%| | 0/1 [00:00<?, ?it/s]

03:58:04 - INFO: Sampling 32 new images....

1000it [02:54, 5.73it/s]

100%| | 1/1 [02:55<00:00, 175.28s/it]

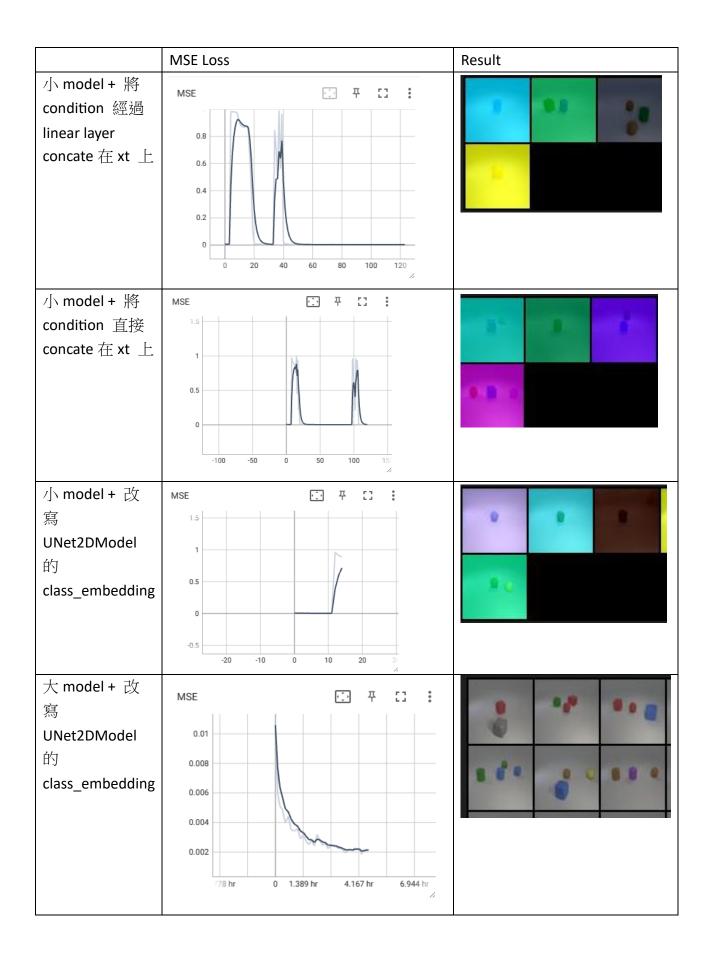
accuracy:0.8095238095238095
```



Discuss the results of different model architectures.

這次作業我一開始是選用一個比較小的 Unet 架構,架構圖如下,並嘗試使用不同加入 condition 的方法,但是結果都不太理想,最後發現可能是模型太小,無法很好的學習,最後加大 model 才讓效果提升,以下是我做的一些實驗。

```
self.model = UNet2DModel(
   sample_size=64,
                             # the target image resolution
   in_channels=3, # embedding
   out_channels=3,
   class_embed_type = None,
   layers_per_block=2,
   block_out_channels=(32, 64, 64),
   down block types=(
       "AttnDownBlock2D", # a ResNet downsampling block with spati
       "AttnDownBlock2D",
   up_block_types=(
       "AttnUpBlock2D",
       "AttnUpBlock2D",
                            # a ResNet upsampling block with spatial
        "UpBlock2D",
                            # a regular ResNet upsampling block
```



在上述表格中可以發現使用小 model 進行生成,都會導致 loss 的不穩定,以及 背景會五顏六色,而使用較大的 model 就能很好的解決這些問題,因此最後使 用較大的 model 來進行訓練以及生成。