

Single-Crossing Differences on Distributions*

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November 5, 2018

Abstract

We study when choices among lotteries are monotonic (with respect to some order) in an expected-utility agent's preference parameter or type. The requisite property turns out to be that the expected utility difference between any pair of lotteries is single-crossing in the agent's type. We characterize the set of utility functions that have this property; we identify the orders over lotteries that generate choice monotonicity for any such utility function. We discuss applications to cheap-talk games, costly signaling games, and collective choice problems. Our analysis provides some new results on monotone comparative statics and aggregating single-crossing functions.

Keywords: monotone comparative statics, choice under uncertainty, interval equilibria

*We thank Nageeb Ali, Federico Echenique, Mira Frick, Ben Golub, Ryota Iijima, Ian Jewitt, Alexey Kushnir, Shuo Liu, Daniele Pennesi, Jacopo Peregó, Lones Smith, Bruno Strulovici, and various audiences for helpful comments.

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1. Introduction

1.1. Overview

Motivation. Single-crossing properties and their resulting monotone comparative statics are at the heart of many economic models (Milgrom and Shannon, 1994). A limitation of the typical approach is that, either implicitly or explicitly, choices are restricted to deterministic outcomes when it is desirable to accommodate lotteries. For example:

1. In signaling models à la Spence (1973), workers with ability $\theta \in \mathbb{R}$ choose education $e \in \mathbb{R}$ to signal ability and garner a higher wage $w \in \mathbb{R}$. It is assumed—either directly or indirectly—that, in equilibrium, there is a deterministic mapping from education to wage. This assumption underlies the fundamental result that, in any equilibrium, workers with higher ability obtain more education if the workers’ utility function $v(w, e, \theta)$ satisfies the Milgrom and Shannon (1994) single-crossing property in wage-education pairs (w, e) and ability θ . More realistically, for any choice of education, workers face a lottery over wages due to aggregate and idiosyncratic uncertainty.
2. In voting models, a voter indexed by θ has preferences over outcomes a given by the utility function $v(a, \theta)$. A single-crossing property of $v(a, \theta)$ in a and θ guarantees a well-behaved majority preference (Gans and Smart, 1996) and the existence of a Condorcet winner. This result is central to various political competition models à la Downs (1957). But the presumption there is that voters or political candidates choose directly among final outcomes. More realistically, the relevant choice is only among some set of policies whose outcomes are uncertain at the time of voting.

In many applications it is not clear what *a priori* restrictions are reasonable on the set of lotteries facing the agent (e.g., various forms of stochastic dominance). For example, in the Spencian setting, higher education choices may well induce wage lotteries that have both higher mean and higher variance; or, in the voting context, the economic and political outcomes are multi-dimensional and so the set of lotteries is unlikely to comply with standard orders. Moreover, these lotteries may be the result of still further interactions—e.g., they may represent continuations in dynamic strategic problems—which would be intractable to structure without severe assumptions.

One is thus naturally led to seek the following property: an agent’s expected utility difference between *any* pair of lotteries over outcomes should be single crossing in the agent’s

type or preference parameter.¹ The purpose of this paper is to completely characterize the utility functions that have this property, which we term *single-crossing expectational differences*, or SCED. We also establish that SCED is not only sufficient but also necessary for certain monotone comparative statics: roughly, no matter the choice set, the set of types that choose any lottery is an interval. We demonstrate the use of these results in applications such as those mentioned earlier.

Summary. Let $v(a, \theta)$ be an agent's utility over outcomes $a \in A$ when her type is $\theta \in \Theta$. The set A is arbitrary while Θ is an arbitrary “doubly-directed” partially-ordered set. [Theorem 1](#) establishes that v has SCED if and only if

$$v(a, \theta) = g_1(a)f_1(\theta) + g_2(a)f_2(\theta) + c(\theta), \quad (1)$$

where f_1 and f_2 are single-crossing functions that satisfy a *ratio-ordering* property we introduce in [Subsection 2.1](#). Roughly speaking, ratio ordering requires that the relative importance placed on $g_1(a)$ versus $g_2(a)$ changes monotonically with type.² The idea is transparent when $\Theta \subset \mathbb{R}$ with a minimum $\underline{\theta}$ and a maximum $\bar{\theta}$. v having SCED is then equivalent to the existence of a (type-dependent) representation $\tilde{v}(a, \theta)$ that satisfies

$$\tilde{v}(a, \theta) = \lambda(\theta)\tilde{v}(a, \bar{\theta}) + (1 - \lambda(\theta))\tilde{v}(a, \underline{\theta}),$$

where $\lambda : \Theta \rightarrow [0, 1]$ is increasing ([Proposition 1](#)). In other words, SCED is equivalent to each type's preferences being representable by a utility function that is a convex combination of those of the extreme types, with higher types putting more weight on the highest type's utility.

SCED is satisfied by some canonical functional forms: in mechanism design and screening, $v((q, t), \theta) = \theta q - t$ (where $q \in \mathbb{R}$ is quantity, $t \in \mathbb{R}$ is a transfer, and $\theta \in \mathbb{R}$ is the agent's marginal rate of substitution); in optimal delegation without transfers, $v((q, t), \theta) = \theta q + g(q) - t$ (where $q \in \mathbb{R}$ is the allocation, $t \in \mathbb{R}_+$ is money burning, and $\theta \in \mathbb{R}$ is the agent's type; cf. [Amador and Bagwell \(2013\)](#)); in communication and voting, $v(a, \theta) = -(a - \theta)^2 = 2\theta a - a^2 - \theta^2$ (where $a \in \mathbb{R}$ is an outcome and $\theta \in \mathbb{R}$ is the agent's bliss point). On the other hand, our characterization also makes clear that SCED is quite restrictive. For example,

¹Throughout this paper, we restrict attention to preferences over lotteries that have an expected utility representation ([von Neumann and Morgenstern, 1944](#)). A real-valued function defined on a partially-ordered set is single crossing if its sign is monotonic.

²More generally, [Lemma 1](#) establishes that ratio ordering is necessary and sufficient for all linear combinations of two single-crossing functions to be single crossing.

within the class of power loss functions, only the quadratic loss function satisfies SCED (Corollary 1).

Theorem 3 establishes that SCED is necessary and sufficient for choices among lotteries to have a form of monotone comparative statics. We require choice monotonicity—for all subsets of lotteries the agent may be faced with—in the sense of the strong set order with respect to *some* order over lotteries. It suffices to highlight here that a failure of SCED is equivalent to the existence of three types, $\theta_1 < \theta_2 < \theta_3$, and two lotteries $P, Q \in \Delta A$ such that θ_2 prefers P to Q while θ_1 and θ_3 both prefer Q to P , with either the former’s or the latter two’s preference strict. Put differently, a failure of SCED is equivalent to the existence of a choice set in which some lottery is chosen by a “non-interval” set of types. Guaranteeing “interval choices” is an important desideratum in applications, as we illustrate in Section 3. Furthermore, the single-crossing differences required by SCED—without reference to an order—is also the key to guaranteeing that local incentive compatibility implies global incentive compatibility (Carroll, 2012, Proposition 4).³ For applications in which one seeks choice monotonicity with respect to a particular order, SCED can be combined with other assumptions on preferences; Claims 4 and 5 in Subsection 3.3 illustrate.

Section 4 discusses some additional general results: a strengthening of SCED to monotone expectational differences; and a relaxation of SCED to a subset of lotteries, motivated by the context of choice among signal structures (e.g., Kamenica and Gentzkow, 2011).

An intuition. A key step towards our main result is establishing that under SCED, every type’s utility function over actions is a linear combination of two (type-independent) functions: Equation 1. We can provide a succinct intuition. Suppose $\Theta \subset \mathbb{R}$ with a minimum $\underline{\theta}$ and a maximum $\bar{\theta}$. It suffices to show that there are three actions, a_1 , a_2 , and a_3 , such that any type θ ’s utility from any action a satisfies

$$v(a, \theta) = v(a_1, \theta)\lambda_1(a) + v(a_2, \theta)\lambda_2(a) + v(a_3, \theta)\lambda_3(a), \quad (2)$$

for some $\lambda(a) \equiv (\lambda_1(a), \lambda_2(a), \lambda_3(a))$ with $\sum_{i=1}^3 \lambda_i(a) = 1$. (Equation 1 follows by setting, for $i = 1, 2$, $f_i(\theta) = v(a_i, \theta) - v(a_3, \theta)$, $g_i(a) = \lambda_i(a)$, and $c(\theta) = v(a_3, \theta)$.) The desired $\lambda(a)$ is

³ More precisely, Carroll’s result implies that local incentive compatibility is sufficient for global incentive compatibility if there is strict single crossing differences as we define it (Definition 6).

the solution to

$$\begin{bmatrix} v(a, \underline{\theta}) \\ v(a, \bar{\theta}) \\ 1 \end{bmatrix} = \begin{bmatrix} v(a_1, \underline{\theta}) & v(a_2, \underline{\theta}) & v(a_3, \underline{\theta}) \\ v(a_1, \bar{\theta}) & v(a_2, \bar{\theta}) & v(a_3, \bar{\theta}) \\ 1 & 1 & 1 \end{bmatrix} \begin{bmatrix} \lambda_1(a) \\ \lambda_2(a) \\ \lambda_3(a) \end{bmatrix},$$

which exists at least when there are three actions for which the 3×3 matrix on the right-hand side is invertible. The interpretation of this matrix equation is that one can find two distinct lotteries over $\{a_1, a_2, a_3, a\}$ such that the lowest and highest types are both indifferent between them.⁴ It follows from SCED that all types must be indifferent between these two lotteries, which amounts to [Equation 2](#).

1.2. Related Literature

Our paper views an agent's choice as a lottery over outcomes. [Quah and Strulovici \(2012\)](#) (QS), on the other hand, consider an agent making choices with uncertainty about her preferences. Specifically, they consider an agent with utility $u(x, \theta, t)$, where $x \in \mathbb{R}$ is the choice variable, θ is the type, and t is an unobserved payoff parameter. They characterize when the agent's expected utility has the [Milgrom and Shannon \(1994\)](#) single-crossing property in (x, θ) for every distribution of t that is independent of x and θ .⁵ In a nutshell, their sufficient condition is *signed-ratio monotonicity* of certain pairs of functions of θ .

While QS's approach could, in principle, be applied for some problems we are interested in, it would be unwieldy. Consider an agent with utility function $v(a, \theta)$ choosing an action x that leads, perhaps through some strategic interaction, to an outcome function $a^*(x, t)$, where t is an independent random realization. Let $u(x, \theta, t) \equiv v(a^*(x, t), \theta)$. To ensure choice monotonicity, QS's approach would require checking that $u(x, \theta, t) - u(x', \theta, t)$ and $u(x, \theta, t') - u(x', \theta, t')$ have signed-ratio monotonicity for every $t, t', x > x'$, and candidate functions $a^*(\cdot)$. This is daunting, particularly when the set of $a^*(\cdot)$ is large and/or *a priori* difficult to characterize.

Our SCED approach instead views actions x and x' as each inducing arbitrary lotteries over outcomes a , and demands single-crossing differences directly on the lottery space. While this is conceptually more demanding—and leads to our stringent characterization—it provides a condition directly on $v(a, \theta)$ that can be easier to check; moreover, SCED is

⁴Take one lottery to be the uniform distribution $P = (1/4, 1/4, 1/4, 1/4)$ on $\{a_1, a_2, a_3, a\}$ and the other lottery to be $P + (1/M)(\lambda_1(a), \lambda_2(a), \lambda_3(a), -1)$, with any sufficiently large $M > 0$.

⁵[Athey \(2002\)](#) considers an agent with utility $\hat{u}(x, t)$ who receives a signal θ about the unobservable t . Athey asks when $\mathbb{E}_t[\hat{u}(x, t)|\theta]$ has the single-crossing property in (x, θ) . QS's approach is also sufficient for this problem because one can take $u(x, \theta, t) = \hat{u}(x, t) \Pr(t|\theta)$ so that $\mathbb{E}_t[\hat{u}(x, t)|\theta] \propto \int u(x, \theta, t) dt$.

in fact necessary when the set of $a^*(\cdot)$ functions is sufficiently rich, as in our cheap-talk application in [Subsection 3.1](#). We also note that sufficient conditions for any problem à la QS concerning $u(x, \theta, t)$ can be approached by defining $a \equiv (x, t)$, $v(a, t) \equiv u(x, \theta, t)$ and checking for SCED (or imposing assumptions guaranteeing it).⁶

When $\Theta \subseteq \mathbb{R}$, the utility specification $v(a, \theta) = \theta g_1(a) + g_2(a)$ has SCED; indeed, the expected utility difference between any two lotteries is monotonic in θ . The usefulness of this utility specification (or slight variants) to structure choices over arbitrary lotteries has been highlighted by [Duggan \(2014\)](#), [Celik \(2015\)](#), and [Kushnir and Liu \(2017\)](#). We provide in [Subsection 4.1](#) a detailed connection of our work with these authors'. Here we only note that, modulo some details, [Celik \(2015\)](#) defines the monotonicity property as “extended single-crossing” and mentions the utility specification, while [Kushnir and Liu \(2017\)](#) define the monotonicity property as “increasing differences over distributions” and provide a functional characterization. Both those papers’ substantive focus is on issues in mechanism design. [Duggan \(2014\)](#), on the other hand, uses the specification in the context of collective choice over lotteries; he observes that what is essential is single-crossing, and discusses why it might be difficult to go beyond positive affine transformations of the specification.

We recently became aware that in the operations research literature, there has been interest in functional forms for “multi-attribute utility functions”, i.e., when outcomes are multi-dimensional.⁷ For example, when there are two attributes, x and y , [Fishburn \(1977\)](#) suggested the form $u(x, y) = f_1(x)g_2(y) + f_2(x)g_2(y)$. [Abbas and Bell \(2011\)](#) discuss a “one-switch condition” that more or less amounts to requiring that, for any two lotteries over attribute x , the expected utility difference as a function of attribute y must be single crossing. They claim a characterization that is related to our [Theorem 1](#), within a more restrictive environment (e.g., the set of y is linearly ordered). They do not focus on the relationship between ratio ordering and the aggregation of single-crossing functions, a monotone comparative statics characterization of SCED, or economic applications.

Finally, there is a connection between our results and the famous theorem of [Harsanyi \(1955\)](#) concerning utilitarianism. Consider a set of three individuals, $\Theta = \{\underline{\theta}, S, \bar{\theta}\}$ endowed with the order $\underline{\theta} < S < \bar{\theta}$, and utility functions $v(a, \theta)$. Here, SCED is equivalent to S (which stands for society) satisfying a Pareto principle with respect to $\underline{\theta}$ ’s and $\bar{\theta}$ ’s preferences over lotteries (specifically, the conjunction of Weak Pareto and Pareto-weak preference, in the

⁶From a mathematical perspective, both QS’ and our results hinge on ensuring that aggregations (i.e., linear combinations) of single-crossing functions remain single crossing. The results differ because of differences in the domains of the functions and the set of aggregations considered. [Choi and Smith \(2016\)](#) observe that QS’ results can be related to those of [Karlin \(1968\)](#). We elaborate on these connections after [Lemma 1](#) in [Subsection 2.1](#).

⁷We are grateful to Daniele Pennesi for directing us to this literature after seeing our 2017 working paper.

terminology of De Meyer and Mongin (1995)). A version of Harsanyi’s theorem (De Meyer and Mongin, 1995, Proposition 2) implies that for some $\kappa \in \mathbb{R}_+$ and $\mu \in \mathbb{R}$, $\kappa v(\cdot, S) - \mu$ is a convex combination of $v(\cdot, \underline{\theta})$ and $v(\cdot, \bar{\theta})$; this result is also an implication of our Theorem 1, as seen from Proposition 1. More generally, the monotonicity identified in Proposition 1 owes to SCED’s inter-type restrictions, and there are cases—either because of the structure of Θ or the utility function $v(\cdot)$ —in which the ratio ordering of Theorem 1 cannot be simplified.⁸

2. Main Results

Let A be an arbitrary set and ΔA the set of probability distributions with finite support.⁹ Let (Θ, \leq) be a (partially) ordered set containing upper and lower bounds for its pairs.¹⁰ We often refer to elements of Θ as *types*. Let $v : A \times \Theta \rightarrow \mathbb{R}$ be a (type-dependent) utility function. Define the expected utility $V : \Delta A \times \Theta \rightarrow \mathbb{R}$ as

$$V(P, \theta) \equiv \int_A v(a, \theta) dP.$$

For any two probability distributions, also referred to as lotteries, $P \in \Delta A$ and $Q \in \Delta A$,

$$D_{P,Q}(\theta) \equiv V(P, \theta) - V(Q, \theta)$$

is the *expectational difference*.

2.1. Single-Crossing Expectational Differences

2.1.1. The Characterization

Our goal is to characterize when the expectational difference between arbitrary probability distributions is single crossing in the following sense.

⁸The latter issue has some connection with the question of signing the aggregation coefficients in Harsanyi’s theorem.

⁹We restrict attention to finite-support distributions throughout the paper for ease of exposition, as it guarantees that expected utility is well defined for all utility functions. We could alternatively restrict attention to bounded utility functions. More generally, our results apply so long as the requirement of SCED is restricted to those distributions for which expected utility is well defined for all types.

¹⁰A partial order—hereafter, also referred to as just an order—is a binary relation that is reflexive, anti-symmetric, and transitive (but not necessarily complete). An upper (resp., lower) bound of $\Theta_0 \subseteq \Theta$ is $\bar{\theta} \in \Theta$ (resp., $\underline{\theta} \in \Theta$) such that $\theta \leq \bar{\theta}$ (resp., $\underline{\theta} \leq \theta$) for all $\theta \in \Theta_0$. While none of our results require any assumptions on the cardinality of Θ , the results in Subsection 2.1 are trivial when $|\Theta| < 3$. Appendix H discusses how our results extend when (Θ, \leq) is only a pre-ordered set, i.e., when \leq does not satisfy anti-symmetry.

Definition 1. A function $f : \Theta \rightarrow \mathbb{R}$ is **single crossing** (resp., single crossing from below or from above) if $\text{sign}[f]$ is monotonic (resp., increasing or decreasing).¹¹

Definition 2. Given any set X , a function $f : X \times \Theta \rightarrow \mathbb{R}$ has **Single-Crossing Differences (SCD)** if $\forall x, x' \in X$, the difference $f(x, \theta) - f(x', \theta)$ is single crossing in θ .

Definition 3. The utility function $v : A \times \Theta \rightarrow \mathbb{R}$ has **Single-Crossing Expectational Differences (SCED)** if the expected utility function $V : \Delta A \times \Theta \rightarrow \mathbb{R}$ has SCD.

Our definition of SCD is related to but different from [Milgrom \(2004\)](#), who stipulates that $f : X \times \Theta \rightarrow \mathbb{R}$ has single-crossing differences given an order \succeq on X if for all $x' \succ x''$ (where \succ is the strict component of \succeq), $f(x', \theta) - f(x'', \theta)$ is single crossing from below. We use a different notion because, in applications that involve choice among lotteries, there is not always an obvious exogenous order. In [Subsection 2.3](#) we define an order on ΔA and justify our definition of SCD ([Theorem 3](#)).

Remark 1. If $A = \{a_1, a_2\}$, then for any two distributions $P, Q \in \Delta A$ with probability mass functions p and q , $D_{P,Q}(\theta) = (p(a_1) - q(a_1))(v(a_1, \theta) - v(a_2, \theta))$. It follows that v has SCED if and only if $v(a_1, \theta) - v(a_2, \theta)$ is single crossing, i.e., if and only if v has SCD. \square

However, the following example shows that when $|A| > 2$, SCED is not implied by SCD, or even supermodularity.

Example 1. Let $\Theta = [0, 2]$ and $A = \{a_0, a_1, a_2\}$ with $a_0 < a_1 < a_2$. Define $v : A \times \Theta \rightarrow \mathbb{R}$ by $v(a_0, \theta) = 0$, $v(a_1, \theta) = -(2 - \theta)^3 + 9$, and $v(a_2, \theta) = 12\theta + 4$. The function v not only has SCD, but it is strictly supermodular: for any $i > j$, $v(a_i, \theta) - v(a_j, \theta)$ is strictly increasing in θ . Consider the probability distributions $P, Q \in \Delta A$ with respective probability mass functions $p(a_1) = 1$ and $q(a_0) = q(a_2) = 1/2$. See [Figure 1](#), in which the red dot-dashed curve is $\int_A v(a, \theta) dQ$ while the others depict $v(a_i, \theta)$ for $i = \{0, 1, 2\}$. $D_{P,Q}(\theta)$ is not single crossing, and so v does not have SCED. \square

Our characterization of SCED ([Theorem 1](#)) uses the following definition.

Definition 4. Let $f_1, f_2 : \Theta \rightarrow \mathbb{R}$ each be single crossing.

1. f_1 **ratio dominates** f_2 if

$$(\forall \theta_l < \theta_h) \quad f_1(\theta_l)f_2(\theta_h) \leq f_1(\theta_h)f_2(\theta_l), \quad \text{and} \quad (3)$$

$$(\forall \theta_l < \theta_m < \theta_h) \quad f_1(\theta_l)f_2(\theta_h) = f_1(\theta_h)f_2(\theta_l) \iff \begin{cases} f_1(\theta_l)f_2(\theta_m) = f_1(\theta_m)f_2(\theta_l), \\ f_1(\theta_m)f_2(\theta_h) = f_1(\theta_h)f_2(\theta_m). \end{cases} \quad (4)$$

¹¹ For $x \in \mathbb{R}$, $\text{sign}[x] = 1$ if $x > 0$, $\text{sign}[x] = 0$ if $x = 0$, and $\text{sign}[x] = -1$ if $x < 0$. A function $h : \Theta \rightarrow \mathbb{R}$ is increasing (resp., decreasing) if $\theta' > \theta \implies h(\theta') \geq h(\theta)$ (resp., $h(\theta') \leq h(\theta)$).

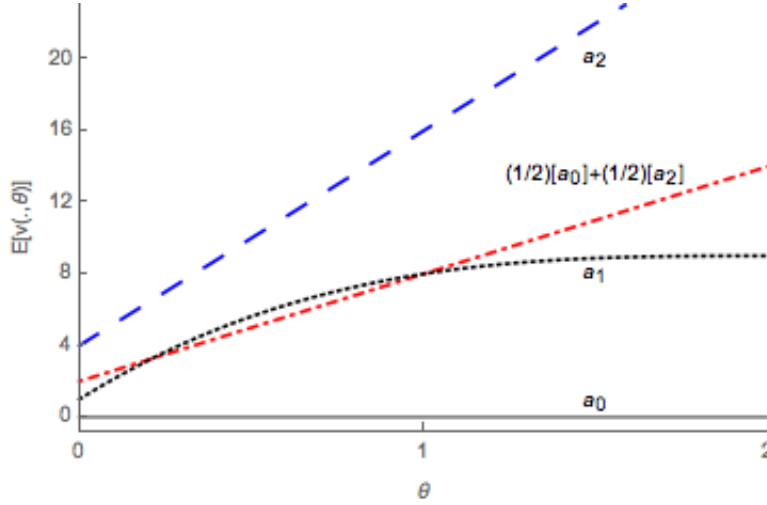


Figure 1: Single-crossing differences does not imply single-crossing expectational differences.

2. f_1 and f_2 are **ratio ordered** if either f_1 ratio dominates f_2 or f_2 ratio dominates f_1 .

Condition (3) contains the essential idea of ratio dominance; Condition (4) only rules out some special cases that we explain later.

Since ratio dominance involves weak inequalities, f_1 can ratio dominate f_2 and vice-versa even when $f_1 \neq f_2$: consider $f_1 = -f_2$. We use the terminology “ratio dominance” because when f_2 is a strictly positive function, (3) is the requirement that the ratio $f_1(\theta)/f_2(\theta)$ must be increasing in θ . Indeed, if both f_1 and f_2 are probability densities of random variables Y_1 and Y_2 , then (3) says that Y_1 stochastically dominates Y_2 in the sense of likelihood ratios.¹²

Condition (3) is a natural generalization of the increasing ratio property to functions that may change sign. To get a geometric intuition, suppose f_1 “strictly” ratio dominates f_2 in the sense that (3) holds with strict inequality. For any θ , let $f(\theta) \equiv (f_1(\theta), f_2(\theta))$. For every $\theta_l < \theta_h$, $f_1(\theta_l)f_2(\theta_h) - f_1(\theta_h)f_2(\theta_l) < 0$ implies that the vector $f(\theta_l)$ moves to $f(\theta_h)$ through a rescaling of magnitude and a clockwise—rather than counterclockwise—rotation (through-out our paper, a “rotation” must be no more than 180 degrees); see Figure 2.¹³

¹²From the viewpoint of information economics, think of θ as a signal of a state $s \in \{1, 2\}$, drawn from the density $f(\theta|s) \equiv f_s(\theta)$. Condition (3) is Milgrom’s (1981) monotone likelihood-ratio property for $f(\theta|s)$.

¹³To confirm this point, recall that from the definition of cross product,

$$\begin{aligned} (f_1(\theta_l), f_2(\theta_l), 0) \times (f_1(\theta_h), f_2(\theta_h), 0) &= \|f(\theta_l)\| \|f(\theta_h)\| \sin(r) e_3 \\ &= (f_1(\theta_l)f_2(\theta_h) - f_1(\theta_h)f_2(\theta_l)) e_3, \end{aligned}$$

where r is the counterclockwise angle from $f(\theta_l)$ to $f(\theta_h)$, $e_3 \equiv (0, 0, 1)$, \times is the cross product, and $\|\cdot\|$ is

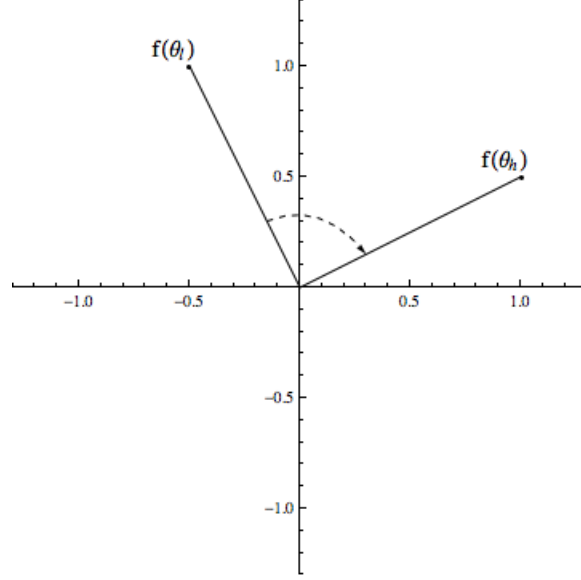


Figure 2: Geometric representation of Condition (3) for two points $\theta_l < \theta_h$.

Hence, f_1 and f_2 are ratio ordered only if $f(\theta)$ rotates *monotonically* as θ increases, either always clockwise or always counterclockwise.¹⁴ It follows that the set $\{f(\theta) : \theta \in \Theta\}$ must be contained in a closed half-space of \mathbb{R}^2 defined by a hyperplane that passes through the origin: otherwise, there will be two pairs of vectors such that an increase in θ corresponds to a clockwise rotation in one pair and a counterclockwise rotation in the other. When f_1 and f_2 are both strictly positive functions, monotonic rotation of $f(\theta)$ and ratio ordering are equivalent to monotonicity of the ratio $f_1(\theta)/f_2(\theta)$.

We impose Condition (4) to rule out cases in which, for some $\theta_l < \theta_m < \theta_h$, either (i) $f(\theta_l)$ and $f(\theta_h)$ are collinear in opposite directions while $f(\theta_m)$ is not, or (ii) $f(\theta_l)$ and $f(\theta_h)$ are non-zero vectors while $f(\theta_m)$ is not. See Figure 3, wherein panel (a) depicts case (i) and panel (b) depicts case (ii). Note that Condition (3) is satisfied in both panels.

Our main result is:

the Euclidean norm. If $\sin(r) < 0$ (resp., $\sin(r) > 0$), then $f(\theta_l)$ moves to $f(\theta_h)$ through a clockwise (resp., counterclockwise) rotation.

¹⁴The preceding discussion establishes this point under the presumption that Condition (3) holds strictly; however, because of the hypothesis in Definition 4 that f_1 and f_2 are single crossing and because of Condition (4), the conclusion holds without that presumption. Furthermore, it can be confirmed that a monotonic rotation of $f(\cdot)$ implies ratio ordering if there are no θ' and θ'' such that $f(\theta')$ and $f(\theta'')$ are collinear.

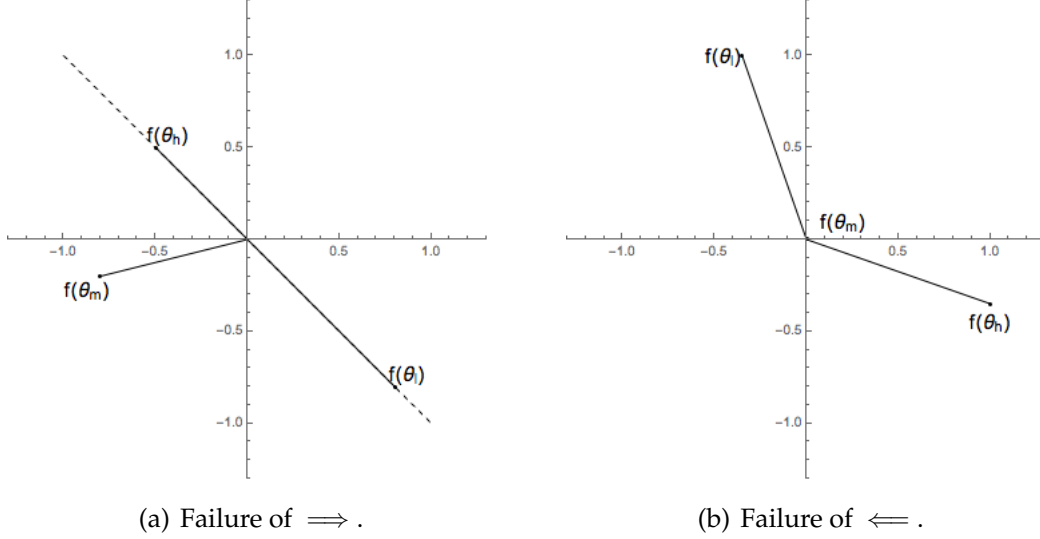


Figure 3: f_1 and f_2 are not ratio ordered because Condition (4) fails for $\theta_l < \theta_m < \theta_h$.

Theorem 1. *The function $v : A \times \Theta \rightarrow \mathbb{R}$ has SCED if and only if it takes the form*

$$v(a, \theta) = g_1(a)f_1(\theta) + g_2(a)f_2(\theta) + c(\theta), \quad (5)$$

with $f_1, f_2 : \Theta \rightarrow \mathbb{R}$ each single crossing and ratio ordered, $g_1, g_2 : A \rightarrow \mathbb{R}$, and $c : \Theta \rightarrow \mathbb{R}$.

A number of observations help interpret [Theorem 1](#). First, the Theorem says that for v to have SCED, it must be possible to write it in the form (5). Notice that given (5), for any $a_0, a \in A$, the function $v(a, \cdot) - v(a_0, \cdot)$ is a linear combination of $f_1(\cdot)$ and $f_2(\cdot)$. Therefore, to rule out the possibility of the form (5), it is sufficient to find $a_0, a_1, a_2, a_3 \in A$ and $\theta_l < \theta_m < \theta_h$ such that the 3×3 matrix $M \equiv [v(a_i, \theta_j) - v(a_0, \theta_j)]_{i \in \{1,2,3\}, j \in \{l,m,h\}}$ is invertible. This procedure is often useful to reject SCED, as illustrated by the next corollary, which identifies quadratic loss as the unique power loss function that satisfies SCED.

Corollary 1. *Let $A = \mathbb{R}$ and $\Theta \subseteq \mathbb{R}$ with $|\Theta| \geq 3$, with the interpretation that a is a decision or policy and θ parameterizes the agent's bliss point. A loss function of the form $v(a, \theta) = -|a - \theta|^z$ with $z > 0$ has SCED if and only if $z = 2$.*

Under quadratic loss, preferences over lotteries are summarized by the lotteries' first and second moments. The sufficiency of two statistics is a general property under SCED; given (5), the relevant statistics for any lottery $P \in \Delta A$ are $\int_A g_1(a)dP$ and $\int_A g_2(a)dP$.

The form (5) is not enough for SCED, however: the component f_1 and f_2 functions must be single crossing and ratio ordered. [Example 1](#) illustrates. Take $c(\theta) = 0$, $f_1(\theta) =$

$-(2 - \theta)^3 + 9$, $f_2(\theta) = 12\theta + 4$, and for each $i \in \{1, 2\}$, $g_i(a) = \mathbb{1}_{\{a=i\}}$, where $\mathbb{1}_{\{\cdot\}}$ is the indicator function. The [Example](#) then satisfies (5), with f_1 and f_2 each single crossing. But since f_1 and f_2 are both strictly positive while f_1/f_2 is not monotonic, they are not ratio ordered. Indeed, the requirement of ratio ordering underlies the following corollary.

Corollary 2. *Let $A \subseteq \mathbb{R}^2$ with $a \equiv (q, t)$ and $\Theta \subseteq \mathbb{R}$, with the interpretation that q is a quantity or allocation, t is money, and θ parameterizes the agent's marginal rate of substitution.*

1. *$v((q, t), \theta) = g(q)f(\theta) - t$ (as in mechanism design and screening), where g is not constant, has SCED if and only if f is monotonic.*
2. *$v((q, t), \theta) = q\theta + g(q) - t$ (as in delegation with money burning; cf. [Amador and Bagwell \(2013\)](#)) has SCED.*

An asymmetry between a and θ in the functional form (5) bears noting: the function $c : \Theta \rightarrow \mathbb{R}$ does not have a counterpart function $A \mapsto \mathbb{R}$. The reason is that whether the expectational difference between a pair of lotteries is single crossing or not could be altered by adding a function of a alone to the utility function $v(a, \theta)$. On the other hand, adding a function of θ alone to $v(a, \theta)$ has no effect on expectational differences. Indeed, SCED is an ordinal property of preferences over lotteries that is invariant to (type-dependent) positive affine transformations of $v(a, \theta)$: if $v(a, \theta)$ has SCED, then so does $b(\theta)v(a, \theta) + c(\theta)$ for any $b : \Theta \rightarrow \mathbb{R}_{++}$ and $c : \Theta \rightarrow \mathbb{R}$.

If $v(a, \theta)$ has the form (5) with strictly positive functions f_1 and f_2 , then up to a positive affine transformation (viz., subtracting $c(\theta)$ and dividing by $f_1(\theta) + f_2(\theta)$), any type's utility becomes a convex combination of two type-independent utility functions over actions, g_1 and g_2 . [Theorem 1](#)'s ratio ordering requirement then simply says that the relative weight on g_1 and g_2 changes monotonically with the agent's type. This idea underlies the following proposition.

Proposition 1. *If Θ has both a minimum and a maximum (i.e., $\exists \underline{\theta}, \bar{\theta} \in \Theta$ such that $(\forall \theta) \underline{\theta} \leq \theta \leq \bar{\theta}$), then $v : A \times \Theta \rightarrow \mathbb{R}$ has SCED if and only if v has a positive affine transformation \tilde{v} satisfying*

$$\tilde{v}(a, \theta) = \lambda(\theta)\tilde{v}(a, \bar{\theta}) + (1 - \lambda(\theta))\tilde{v}(a, \underline{\theta}), \quad (6)$$

with $\lambda : \Theta \rightarrow [0, 1]$ increasing.

The remainder of this subsection explains the logic behind [Theorem 1](#). As expected utility differences correspond to linear combinations of utilities, the central issue turns out to

be when arbitrary such aggregations are single crossing. [Lemma 1](#) below shows that ratio ordering is the characterizing property when aggregating two functions; [Proposition 2](#) then establishes that when aggregating more than two functions, no more than two can be linearly independent, which leads to the form (5).¹⁵

2.1.2. Aggregating Single-Crossing Functions

Lemma 1. *Let $f_1, f_2 : \Theta \rightarrow \mathbb{R}$. The linear combination $\alpha_1 f_1(\theta) + \alpha_2 f_2(\theta)$ is single crossing $\forall \alpha \in \mathbb{R}^2$ if and only if f_1 and f_2 are (i) each single crossing and (ii) ratio ordered.*

[Lemma 1](#) is related to [Quah and Strulovici \(2012, Proposition 1\)](#). They establish that for any two functions f_1 and f_2 that are each single crossing from below, $\alpha_1 f_1 + \alpha_2 f_2$ is single crossing from below for all $\alpha \in \mathbb{R}_+^2$ if and only if f_1 and f_2 satisfy a condition they call signed-ratio monotonicity. In general, ratio ordering is not comparable with signed-ratio monotonicity because we consider a different aggregation problem from Quah and Strulovici: (i) the input functions may be single crossing in either direction; (ii) the linear combinations involve coefficients of arbitrary sign; and (iii) the resulting combination can be single crossing in either direction. [Example 1](#) highlights the importance of point (ii): both $f_1(\theta) = -(2 - \theta)^3 + 9$ and $f_2(\theta) = 12\theta + 4$ are positive functions (hence, single crossing from below), and so all positive linear combinations are also positive functions, but $2f_1 - f_2$ is not single crossing because f_1 and f_2 are not ratio ordered. If the input functions in [Lemma 1](#) are restricted to be single crossing from below, then ratio ordering implies signed-ratio monotonicity.

[Lemma 1](#) implies a characterization of likelihood-ratio ordering for random variables with single-crossing densities, e.g., those with strictly positive densities. While this likelihood-ratio ordering characterization is not well-known among economists (to our knowledge), it is a special case of [Karlin's \(1968\)](#) results on the variation diminishing property of totally positive functions. More generally, however, we believe the full force of [Lemma 1](#) cannot be derived from the variation diminishing property. See [Appendix G](#) for further discussion of [Karlin \(1968\)](#) and [Quah and Strulovici \(2012\)](#).

Here is [Lemma 1](#)'s intuition. For sufficiency, consider any linear combination $\alpha_1 f_1 + \alpha_2 f_2$. Assume $\alpha \in \mathbb{R}^2 \setminus \{0\}$, as otherwise the linear combination is trivially single crossing. The vector α defines two open half spaces $\mathbb{R}_{\alpha,-}^2 \equiv \{x \in \mathbb{R}^2 : \alpha \cdot x < 0\}$ and $\mathbb{R}_{\alpha,+}^2 \equiv \{x \in \mathbb{R}^2 : \alpha \cdot x > 0\}$, where \cdot is the dot product; see [Figure 4\(a\)](#). As explained earlier, ratio ordering of f_1 and f_2 implies that the vector $f(\theta) \equiv (f_1(\theta), f_2(\theta))$ rotates monotonically as θ increases. If

¹⁵ Real-valued functions f_1, f_2, \dots, f_n are linearly independent if $(\forall \lambda \in \mathbb{R}^n \setminus \{0\}) \sum_{i=1}^n \lambda_i f_i$ is not a zero function, i.e., is not everywhere zero.

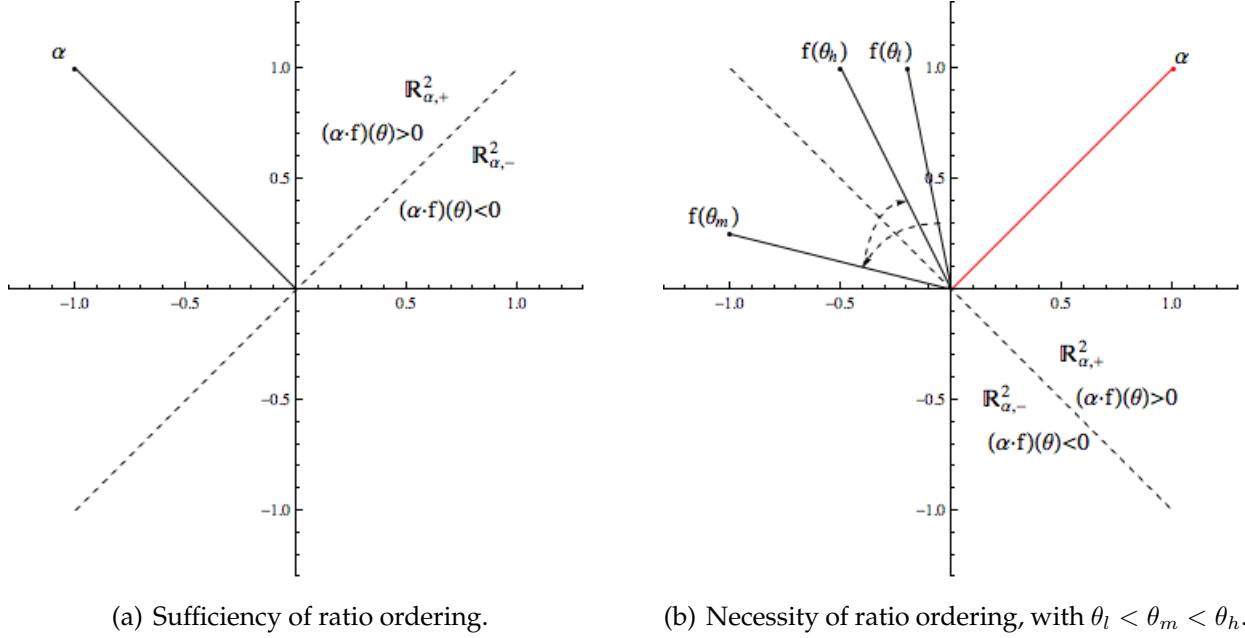


Figure 4: Ratio ordering and single crossing of all linear combinations.

the rotation is from $\mathbb{R}^2_{\alpha,-}$ to $\mathbb{R}^2_{\alpha,+}$ (resp., from $\mathbb{R}^2_{\alpha,+}$ to $\mathbb{R}^2_{\alpha,-}$), then $\alpha \cdot f \equiv \alpha_1 f_1 + \alpha_2 f_2$ is single crossing only from below (resp., only from above). If $\bigcup_{\theta \in \Theta} f(\theta) \subseteq \mathbb{R}^2_{\alpha,-}$ or $\bigcup_{\theta \in \Theta} f(\theta) \subseteq \mathbb{R}^2_{\alpha,+}$, then $\alpha \cdot f$ is single crossing both from below and above. Other cases are similar.

To see why Condition (3) of ratio ordering is necessary, suppose the vector $f(\theta)$ does not rotate monotonically. Figure 4(b) illustrates a case in which, for $\theta_l < \theta_m < \theta_h$, $f(\theta_l)$ rotates counterclockwise to $f(\theta_m)$, but $f(\theta_m)$ rotates clockwise to $f(\theta_h)$. As shown in the Figure, one can find $\alpha \in \mathbb{R}^2$ such that $f(\theta_m) \in \mathbb{R}^2_{\alpha,-}$ while both $f(\theta_l), f(\theta_h) \in \mathbb{R}^2_{\alpha,+}$, which implies that $\alpha \cdot f$ is not single crossing. The necessity of Condition (4) can be seen by returning to Figure 3. In panel (a), $(f_1 + f_2)(\theta_l) = (f_1 + f_2)(\theta_h) = 0$ while $(f_1 + f_2)(\theta_m) < 0$; in panel (b), $(f_1 + f_2)(\theta_l) > 0$ and $(f_1 + f_2)(\theta_h) > 0$ while $(f_1 + f_2)(\theta_m) = 0$.

Theorem 1 requires an extension of Lemma 1 to more than two functions. Consider any set X and $f : X \times \Theta \rightarrow \mathbb{R}$. We say that f is **linear combinations SC-preserving** if $\sum_{x \in X} f(x, \theta) \mu(x)$ is single-crossing in θ for every function $\mu : X \rightarrow \mathbb{R}$ with finite support.

Proposition 2. *Let $f : X \times \Theta \rightarrow \mathbb{R}$ for some set X . The function f is linear combinations SC-preserving if and only if there exist $x_1, x_2 \in X$ and $\lambda_1, \lambda_2 : X \rightarrow \mathbb{R}$ such that*

1. $f(x_1, \cdot) : \Theta \rightarrow \mathbb{R}$ and $f(x_2, \cdot) : \Theta \rightarrow \mathbb{R}$ are (i) each single crossing and (ii) ratio ordered, and
2. $(\forall x) f(x, \cdot) = \lambda_1(x) f(x_1, \cdot) + \lambda_2(x) f(x_2, \cdot)$.

[Proposition 2](#) says that a family of single-crossing functions $\{f(x, \cdot)\}_{x \in X}$ preserves single crossing of all finite linear combinations if and only if the family is “linearly generated” by two single-crossing functions that are ratio ordered. In particular, given any three single-crossing functions, f_1 , f_2 , and f_3 , all their linear combinations will be single crossing if and only if there is a linear dependence in the triple, say $\lambda_1 f_1 + \lambda_2 f_2 = f_3$ for some $\lambda \in \mathbb{R}^2$, and f_1 and f_2 are ratio ordered.

The sufficiency direction of [Proposition 2](#) follows from [Lemma 1](#), as does necessity of the “generating functions” being ratio ordered. The intuition for the necessity of linear dependence is as follows. Assume Θ is completely ordered. For any θ , let $f(\theta) \equiv (f_1(\theta), f_2(\theta), f_3(\theta))$. If $\{f_1, f_2, f_3\}$ is linearly independent, then there exist $\theta_l < \theta_m < \theta_h$ such that $\{f(\theta_l), f(\theta_m), f(\theta_h)\}$ spans \mathbb{R}^3 . Take any $\alpha \in \mathbb{R}^3 \setminus \{0\}$ that is orthogonal to the plane S_{θ_l, θ_h} that is spanned by $f(\theta_l)$ and $f(\theta_h)$, as illustrated in [Figure 5](#). The linear combination $\alpha \cdot f$ is not single crossing because $(\alpha \cdot f)(\theta_l) = (\alpha \cdot f)(\theta_h) = 0$ while $(\alpha \cdot f)(\theta_m) \neq 0$.

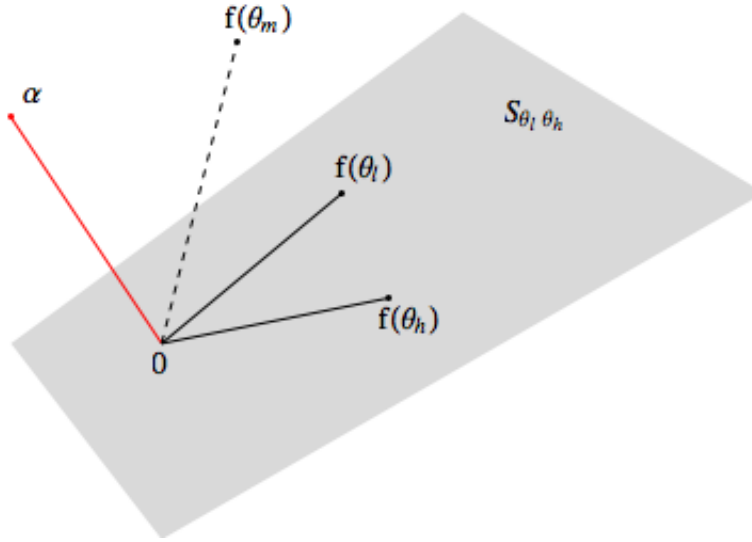


Figure 5: The necessity of linear dependence in [Proposition 2](#).

While the necessity portion of [Proposition 2](#) only asserts ratio ordering of the “generating functions”, [Lemma 1](#) implies that if $f : X \times \Theta \rightarrow \mathbb{R}$ is linear combinations SC-preserving, then for all $x, x' \in X$, the pair $f(x, \cdot) : \Theta \rightarrow \mathbb{R}$ and $f(x', \cdot) : \Theta \rightarrow \mathbb{R}$ must be ratio ordered.

2.1.3. Proof Sketch of [Theorem 1](#)

We can now sketch the argument for [Theorem 1](#). That its characterization is sufficient for SCED is straightforward from [Lemma 1](#). For necessity, suppose, as a simplification,

$A = \{a_0, \dots, a_n\}$ and $v : A \times \Theta \rightarrow \mathbb{R}$ is such that $(\forall \theta) v(a_0, \theta) = 0$.¹⁶ For any $(\lambda_0, \dots, \lambda_n)$, we build on the Hahn-Jordan decomposition of $(\lambda_1, \dots, \lambda_n)$ to write the linear combination $\sum_{i=0}^n \lambda_i v(a_i, \theta)$ as $M \sum_{i=0}^n (p(a_i) - q(a_i)) v(a_i, \theta)$, where p and q are probability mass functions on A , and M is a scalar.¹⁷ (Unless $\sum_{i=1}^n \lambda_i = 0$, we have $\sum_{i=1}^n p(a_i) \neq \sum_{i=1}^n q(a_i)$; the assumption that $v(a_0, \cdot) = 0$ permits us to assign all the “excess difference” to a_0 , as detailed in [fn. 17](#).) Since v has SCED, every such linear combination is single crossing, and so [Proposition 2](#) guarantees a' and a'' such that for all a , $v(a, \cdot) = g_1(a)v(a', \cdot) + g_2(a)v(a'', \cdot)$, with $v(a', \cdot)$ and $v(a'', \cdot)$ each single crossing and ratio ordered.

2.2. Strict Single-Crossing Expectational Differences

With an eye towards certain comparative statics, this subsection provides a “strict variant” of [Theorem 1](#). We now assume the existence of a strictly increasing real-valued function on (Θ, \leq) .¹⁸ This requirement is satisfied, for example, when Θ is finite, or $\Theta \subseteq \mathbb{R}^n$ is endowed with the usual order.

Definition 5. A function $f : \Theta \rightarrow \mathbb{R}$ is **strictly single crossing** (resp., strictly single crossing from below or from above) if it is single crossing (resp., from single crossing from below or from above) and there are no $\theta' < \theta''$ such that $f(\theta') = f(\theta'') = 0$.

Definition 6. Given any set X , a function $f : X \times \Theta \rightarrow \mathbb{R}$ has **Strict Single-Crossing Differences (SSCD)** if $\forall x, x' \in X$, the difference $f(x, \theta) - f(x', \theta)$ is either a zero function or strictly single crossing in θ . The utility function $v : A \times \Theta \rightarrow \mathbb{R}$ has **Strict Single-Crossing Expectational Differences (SSCED)** if the expected utility function $V : \Delta A \times \Theta \rightarrow \mathbb{R}$ has SSCD.

The zero-function possibility in the above definition cannot be avoided even if we restricted attention to distinct distributions P and Q ; for example, $D_{P,Q}$ is a zero function whenever P and Q have the same expectation and v is linear in a .

Definition 7. A function $f_1 : \Theta \rightarrow \mathbb{R}$ **strictly ratio dominates** $f_2 : \Theta \rightarrow \mathbb{R}$ if Condition (3) holds with strict inequality; f_1 and f_2 are **strictly ratio ordered** if either f_1 strictly ratio dominates f_2 or vice-versa.

¹⁶ The latter is a normalization, since $v(a, \theta)$ has SCED if and only if $\tilde{v}(a, \theta) \equiv v(a, \theta) - v(a_0, \theta)$ has SCED.

¹⁷ Let $L \equiv \sum_{i=1}^n \lambda_i$. For $i > 0$, set $p'(a_i) \equiv \max\{\lambda_i, 0\}$ and $q'(a_i) \equiv -\min\{\lambda_i, 0\}$. If $L \geq 0$, set $p'(a_0) = 0$ and $q'(a_0) \equiv L$; if $L < 0$, set $p'(a_0) \equiv -L$ and $q'(a_0) \equiv 0$. Let $M \equiv \sum_{i=0}^n p'(a_i) = \sum_{i=0}^n q'(a_i)$. Finally, for all $a \in A$, set $p(a) \equiv p'(a)/M$ and $q(a) \equiv q'(a)/M$.

¹⁸ That is, we assume $\exists h : \Theta \rightarrow \mathbb{R}$ such that $\underline{\theta} < \bar{\theta} \implies h(\underline{\theta}) < h(\bar{\theta})$. This requirement is related to utility representations for possibly incomplete preferences ([Ok, 2007](#), Chapter B.4.3). A sufficient condition is that Θ has a countable order dense subset, i.e., if there exists a countable set $\Theta_0 \subseteq \Theta$ such that $(\forall \underline{\theta}, \bar{\theta} \in \Theta \setminus \Theta_0) \quad \underline{\theta} < \bar{\theta} \implies \exists \theta_0 \in \Theta_0 \text{ s.t. } \underline{\theta} < \theta_0 < \bar{\theta}$ ([Jaffray, 1975](#), Corollary 1).

The definition of strict ratio dominance does not make reference to Condition (4) because that condition is vacuous when Condition (3) holds with strict inequality.

Theorem 2. *The function $v : A \times \Theta \rightarrow \mathbb{R}$ has SSCED if and only if it takes the form (5), with $f_1, f_2 : \Theta \rightarrow \mathbb{R}$ strictly ratio ordered, $g_1, g_2 : A \rightarrow \mathbb{R}$, and $c : \Theta \rightarrow \mathbb{R}$.*

2.3. Monotone Comparative Statics

There is a sense in which SCED is necessary and sufficient for monotone comparative statics, while SSCED guarantees that any selection of choices is monotonic. A precise statement requires monotonicity theorems (Theorem 3 and Proposition 3 below) related to, but distinct from, the influential Theorem 4 and Theorem 4' of Milgrom and Shannon (1994).

Choice Monotonicity. Throughout this subsection, we consider an ordered set of alternatives, (X, \succeq) , and, as earlier, an ordered set of types, (Θ, \leq) . We maintain the assumption that Θ contains upper and lower bounds for every pair of its elements. Neither \succeq nor \leq need be complete. We are interested in comparative statics for a function $f : X \times \Theta \rightarrow \mathbb{R}$. We assume the set X is **minimal** (with respect to f) in the sense that

$$(\forall x \neq x')(\exists \theta) f(x, \theta) \neq f(x', \theta).$$

For any $x, y \in X$, let $x \vee y$ and $x \wedge y$ denote the usual join and meet respectively.¹⁹ In general, neither need exist. Given any $Y, Z \subseteq X$, we say that Y dominates Z in the **strong set order**, denoted $Y \succeq_{SSO} Z$, if for every $y \in Y$ and $z \in Z$, (i) $y \vee z$ and $y \wedge z$ exist, and (ii) $y \vee z \in Y$ and $y \wedge z \in Z$.

Remark 2. The strong set order is neither reflexive nor transitive: for any $S \subseteq X$, it holds that $S \succeq_{SSO} \emptyset$ and $\emptyset \succeq_{SSO} S$, whereas $S \succeq_{SSO} S$ if and only if (S, \succeq) is a lattice (i.e., each pair of elements in S has a join and meet in S). However, the strong set order is transitive on non-empty subsets of (X, \succeq) . While this transitivity is well-known when (X, \succeq) is a lattice, it can be shown to be a general property.

Definition 8. $f : X \times \Theta \rightarrow \mathbb{R}$ has **Monotone Comparative Statics (MCS)** on (X, \succeq) if

$$(\forall S \subseteq X) \text{ and } (\forall \theta \leq \theta') : \arg \max_{s \in S} f(s, \theta') \succeq_{SSO} \arg \max_{s \in S} f(s, \theta).$$

¹⁹ $z \in X$ is the the join (or supremum) of $\{x, y\}$ if (i) $z \succeq x$ and $z \succeq y$, and (ii) if $w \succeq x$ and $w \succeq y$, then $w \succeq z$. The meet (or infimum) of $\{x, y\}$ is defined analogously.

Our definition of MCS is closely related to but not the same as [Milgrom and Shannon \(1994\)](#). We take (X, \succeq) to be any ordered set while they require a lattice. We focus only on monotonicity of choice in θ but require the monotonicity to hold for every subset $S \subseteq X$; [Milgrom and Shannon](#) require monotonicity of choice jointly in the pair (θ, S) , but this implicitly only requires choice monotonicity in θ to hold for every sub-lattice $S \subseteq X$.

Define binary relations \succ_{SCD} and \succeq_{SCD} on X as follows: $x \succ_{SCD} x'$ if $D_{x,x'}(\theta) \equiv f(x, \theta) - f(x', \theta)$ is single crossing *only* from below; $x \succeq_{SCD} x'$ if either $x \succ_{SCD} x'$ or $x = x'$. It is clear that \succeq_{SCD} is reflexive and anti-symmetric. If $f : X \times \Theta \rightarrow \mathbb{R}$ has SCD, then \succeq_{SCD} is also transitive.²⁰

Given two orders \succeq and \succeq' on X , the order \succeq' is a refinement of \succeq if

$$(\forall x, x' \in X) \quad x \succeq x' \implies x \succeq' x'.$$

Theorem 3. $f : X \times \Theta \rightarrow \mathbb{R}$ has monotone comparative statics on (X, \succeq) if and only if f has SCD and \succeq is a refinement of \succeq_{SCD} .

Our [definition of SCD](#) does not require an order on the set of alternatives, whereas MCS does. [Theorem 3](#) says that SCD is necessary and sufficient for there to exist an order that yields MCS. Moreover, the Theorem justifies viewing \succeq_{SCD} as the prominent order for MCS: MCS does not hold with any order that either coarsens \succeq_{SCD} or reverses a ranking by \succ_{SCD} . The argument for necessity in [Theorem 3](#) only makes use of binary choice sets. If SCD fails, then there is no order \succeq for which there is choice monotonicity for all binary choice sets. If SCD holds, then choice monotonicity on all binary choice sets requires \succeq to refine \succeq_{SCD} .

Regarding sufficiency, for each $S \subseteq X$, let $C(S) \equiv \bigcup_{\theta \in \Theta} \arg \max_{x \in S} f(x, \theta)$. Given that f has SCD and X is minimal, the set $C(S)$ is completely ordered by \succeq_{SCD} (as elaborated in the [proof of Theorem 3](#)). Since \succeq is a refinement of \succeq_{SCD} , \succeq coincides with \succeq_{SCD} on $C(S)$, and the strong set orders generated by \succeq and \succeq_{SCD} on the collection of all subsets of $C(S)$ also coincide. By definition of \succeq_{SCD} , f satisfies [Milgrom and Shannon's \(1994\)](#) single-crossing property in (x, θ) with respect to \succeq_{SCD} and \leq . It follows from [Milgrom and Shannon \(1994, Theorem 4\)](#) that $\forall \theta \leq \theta'$,

$$\arg \max_{s \in S} f(s, \theta') = \arg \max_{s \in C(S)} f(s, \theta') \succeq_{SSO} \arg \max_{s \in C(S)} f(s, \theta) = \arg \max_{s \in S} f(s, \theta).$$

²⁰ To confirm transitivity, take $x, y, z \in X$ such that $x \succeq_{SCD} y$ and $y \succeq_{SCD} z$. If $x = y$ or $y = z$, it is trivial that $x \succeq_{SCD} z$. If $x \neq y$ and $y \neq z$, then $x \succ_{SCD} y$ and $y \succ_{SCD} z$. Since f has SCD, $D_{x,z}$ is single crossing. As both $D_{x,y}$ and $D_{y,z}$ are single crossing only from below, $D_{x,z} = D_{x,y} + D_{y,z}$ is single crossing only from below. Thus, $x \succ_{SCD} z$.

A stronger notion of choice monotonicity is given by the next definition.

Definition 9. $f : X \times \Theta \rightarrow \mathbb{R}$ has **Monotone Selection (MS)** on (X, \succeq) if for any $S \subseteq X$, every selection $s^*(\theta)$ from $\arg \max_{s \in S} f(s, \theta)$ is increasing in θ .

Define binary relations \succ_{SSCD} and \succeq_{SSCD} on X as follows: $x \succ_{SSCD} x'$ if $D_{x,x'}$ is strictly single crossing only from below; $x \succeq_{SSCD} x'$ if either $x \succ_{SSCD} x'$ or $x = x'$. As before, if $f : X \times \Theta \rightarrow \mathbb{R}$ has SSCD, then \succeq_{SSCD} is an order.

Proposition 3. If $f : X \times \Theta \rightarrow \mathbb{R}$ has SSCD and \succeq is a refinement of \succeq_{SSCD} , then f has monotone selection on (X, \succeq) .

Remark 3. If $f : X \times \Theta \rightarrow \mathbb{R}$ has SCD (resp., SSCD), then a *complete* refinement \succeq of \succeq_{SCD} (resp., \succeq_{SSCD}) exists, and f has MCS (resp., MS) on (X, \succeq) . To construct one example of a completion of \succeq_{SCD} , define \succ_{dom} on X as follows: $x \succ_{dom} x'$ if $(\forall \theta) f(x, \theta) > f(x', \theta)$. Given that f has SCD, a pair $x, x' \in X$ is related by \succ_{dom} if and only if it is not related by \succeq_{SCD} . The relation $\succeq \equiv \succeq_{SCD} \cup \succ_{dom}$ is thus complete, reflexive, and anti-symmetric; it is not hard to check that \succeq is also transitive.

Choice Monotonicity over Lotteries. We apply [Theorem 3](#) and [Proposition 3](#) to our context of choice among lotteries. To get a minimal space of lotteries, we treat any pair $P, Q \in \Delta A$ that are utility-indistinguishable (i.e., $D_{P,Q}(\theta) = 0$ for all θ) as in an equivalence class. Let $\tilde{\Delta}A$ denote the resulting partition of ΔA . For readability, we abuse notation and treat elements of $\tilde{\Delta}A$ as lotteries rather than equivalence classes.

Let \succ_{SCED} and \succeq_{SCED} be the \succ_{SCD} and \succeq_{SCD} relations defined on $\tilde{\Delta}A$, with respect to the expected utility function V . That is, for $P, Q \in \tilde{\Delta}A$, $P \succ_{SCED} Q$ if $D_{P,Q}$ is single crossing only from below, and $P \succeq_{SCED} Q$ if $P \succ_{SCED} Q$ or $P = Q$. If v has SCED, then the expected utility function V has SCD and $(\tilde{\Delta}A, \succeq_{SCED})$ is an ordered set.

Corollary 3. V has monotone comparative statics on $(\tilde{\Delta}A, \succeq)$ if and only if v has SCED and \succeq is a refinement of \succeq_{SCED} . If v has SCED, then there is a complete order with respect to which V has monotone comparative statics.

Analogous to the discussion preceding [Corollary 3](#), we define \succ_{SSCED} and \succeq_{SSCED} as the \succ_{SSCD} and \succeq_{SSCD} relations defined on $\tilde{\Delta}A$, with respect to the expected utility function V . That is, for $P, Q \in \tilde{\Delta}A$, $P \succ_{SSCED} Q$ if $D_{P,Q}$ is strictly single crossing only from below, and $P \succeq_{SSCED} Q$ if $P \succ_{SSCED} Q$ or $P = Q$. If v has SSCED, then the expected utility function V has SSCD and $(\tilde{\Delta}A, \succeq_{SSCED})$ is an ordered set.

Corollary 4. *If v has SSCED and \succeq is a refinement of \succeq_{SSCED} , then V has monotone selection on $(\tilde{\Delta}A, \succeq)$. If v has SSCED, then there is a complete refinement of \succeq_{SSCED} with respect to which V has monotone selection.*

3. Applications

This section illustrates the usefulness of our results in three applications.

3.1. Cheap Talk with Uncertain Receiver Preferences

There are two players, a sender (S) and a receiver (R). The sender's type is $\theta \in \Theta$, where Θ is ordered by \leq . After learning his type, S chooses a payoff-irrelevant message $m \in M$, where $|M| > 1$. After observing m but not θ , R takes an action $a \in A$. The sender's von Neumann-Morgenstern utility function is $v(a, \theta)$; the receiver's is $u(a, \theta, \psi)$, where $\psi \in \Psi$ is a preference parameter that is unknown to S when choosing m , and known to R when choosing a . Note that ψ does not affect the sender's preferences. The variables θ and ψ are independently drawn from commonly-known probability distributions.

An example is $\Theta = [0, 1]$, $A = \mathbb{R}$, $\psi \in \Psi \subseteq \mathbb{R}^2$, $v(a, \theta) = -(a - \theta)^2$ and $u(a, \theta, \psi) = -(a - \psi_1 - \psi_2\theta)^2$. Here the variable ψ_1 captures the receiver's "type-independent bias" and ψ_2 captures the relative "sensitivity" to the sender's type. If ψ were commonly known and θ uniformly distributed, this would be the model of [Melumad and Shibano \(1991\)](#), which itself generalizes the canonical example from [Crawford and Sobel \(1982\)](#) that obtains when $\psi_1 \neq 0$ and $\psi_2 = 1$.

We focus on (weak Perfect Bayesian) equilibria in which S uses a pure strategy, $\mu : \Theta \rightarrow M$, and R plays a possibly-mixed strategy, $\alpha : M \times \Psi \rightarrow \Delta A$.²¹ Given any α , every message m induces some lottery over actions from the sender's viewpoint, $P_\alpha(m)$. An equilibrium (μ, α) is: (i) an *interval equilibrium* if every message is used by an interval of sender types, i.e., if $\theta_l < \theta_m < \theta_h$ and $\mu(\theta_l) = \mu(\theta_h)$, then $\mu(\theta_m) = \mu(\theta_l)$; and (ii) *sender minimal* if for all on-the-equilibrium-path $m \neq m'$, there is some θ such that $V(P_\alpha(m), \theta) \neq V(P_\alpha(m'), \theta)$. In other words, sender minimality rules out all sender types being indifferent between two distinct on-path messages.²²

Claim 1. *If v has the form stated in [Theorem 2](#), and hence has SSCED, then every sender-minimal equilibrium is an interval equilibrium.*

²¹ Our notion of equilibrium requires optimal play for every (not just almost every) type of sender. The restriction to pure strategies for the sender is for expositional simplicity.

²² In [Crawford and Sobel \(1982\)](#) and [Melumad and Shibano \(1991\)](#), all equilibria are outcome equivalent to sender-minimal equilibria. More generally, all equilibria are sender minimal when there is a complete order over messages under which higher messages are infinitesimally more costly for all sender types.

Proof. Assume v has SSCED and take a sender-minimal equilibrium (μ^*, α^*) . Suppose, to contradiction, there are $\theta_l < \theta_m < \theta_h$ such that $m' \equiv \mu^*(\theta_l) = \mu^*(\theta_h) \neq \mu^*(\theta_m) \equiv m''$. Let P' and P'' denote the equilibrium distributions of the receiver's actions induced by the messages m' and m'' respectively, from the viewpoint of the sender. Both P' and P'' are independent of θ because ψ and θ are independent. By [Theorem 2](#), $D_{P', P''}$ is either (i) a zero function, or (ii) strictly single crossing only from below, or (iii) strictly single crossing only from above. Case (i) contradicts sender minimality; case (ii) contradicts either m' being optimal for θ_l or m'' being optimal for θ_m ; case (iii) contradicts either m'' being optimal for θ_m or m' being optimal for θ_h . Q.E.D.

The result relates to [Seidmann \(1990\)](#), who first considered an extension of [Crawford and Sobel \(1982\)](#) to sender uncertainty about the receiver's preferences. His goal was to illustrate how such uncertainty could facilitate informative communication even when the sender always strictly prefers higher actions. Example 2 in [Seidmann \(1990\)](#) constructs a non-interval and sender-minimal equilibrium that is informative. [Claim 1](#) clarifies that the key is a failure of (S)SCED.

The strict single crossing property in standard cheap-talk models (e.g., [Crawford and Sobel \(1982\)](#) and [Melumad and Shibano \(1991\)](#)) not only yields interval equilibria, but it also implies that local incentive compatibility is sufficient for global incentive compatibility. This additional tractability also holds under SSCED. Let $\Theta = \mathbb{N}$ for convenience, and $P : \Theta \rightarrow \Delta A$ be a candidate equilibrium allocation (i.e., the distribution of receiver actions that each sender type induces in equilibrium). Under SSCED, it is sufficient for sender incentive compatibility that $(\forall i \in \mathbb{N}) V(P(\theta_i), \theta_i) \geq \max\{V(P(\theta_{i-1}), \theta_i), V(P(\theta_{i+1}), \theta_i)\}$.

Besides being sufficient, (S)SCED is also necessary to guarantee interval cheap-talk equilibria so long as the environment—specifically, the receiver utility function u and the distribution of his preference parameter ψ —is rich enough to generate appropriate pairs of lotteries. Say that v *strictly violates* SCED if there are $P, Q \in \Delta A$ and $\theta_l < \theta_m < \theta_h$ such that $\min\{D_{P,Q}(\theta_l), D_{P,Q}(\theta_h)\} > 0 > D_{P,Q}(\theta_m)$.

Claim 2. *Let $\Theta \subseteq \mathbb{R}$, $A = \mathbb{R}$, $\Psi \subseteq \mathbb{R}^2$, and $u(a, \theta, \psi) \equiv -(a - \psi_1 - \psi_2\theta)^2$. If v strictly violates SCED, then for some pair of distributions of θ and ψ there is a non-interval equilibrium in which each sender type plays its unique best response.*

Proof. Assume v strictly violates SCED and let P and Q be the distributions and $\theta_l < \theta_m <$

θ_h the types in that definition. Let $M \equiv \{m', m''\}$ and consider the sender's strategy

$$\mu(\theta) = \begin{cases} m' & \text{if } \theta \in \{\theta_l, \theta_h\} \\ m'' & \text{if } \theta = \theta_m. \end{cases}$$

Let F_θ be any distribution with support $\{\theta_l, \theta_m, \theta_h\}$ and $\theta' \equiv \mathbb{E}_{F_\theta}[\theta | \theta \in \{\theta_l, \theta_h\}] \neq \theta_m$. Then, the unique best response against μ for a receiver of type $\psi = (\psi_1, \psi_2)$ is

$$\alpha(m', \psi) = \psi_1 + \psi_2 \theta' \quad \text{and} \quad \alpha(m'', \psi) = \psi_1 + \psi_2 \theta_m.$$

It can be verified that there is a distribution F_ψ such that, from the sender's viewpoint, the message m' leads to the distribution P and the message m'' leads to the distribution Q , and so μ is the sender's unique best response.²³ Q.E.D.

The particular specification of u in [Claim 2](#) is not critical; what is important, as suggested earlier, is that there be enough flexibility to generate appropriate distributions of actions from the sender's viewpoint using best responses for the receiver. For example, the result would also hold—more straightforwardly, but less interestingly—if the receiver were totally indifferent over all actions for some preference realization. On the other hand, if $\psi \in \mathbb{R}$ and $u(a, \theta, \psi) \equiv -(a - \theta - \psi)^2$, then SCED is not necessary, because any pair of lotteries that the sender may face are ranked by first order stochastic dominance. Strict supermodularity of $v(a, \theta)$ then guarantees that all sender-minimal equilibria are interval equilibria; however, strict supermodularity does not imply SCED, as noted in [Example 1](#).

In our cheap-talk application it is uncertainty about the receiver's preferences that leads to the sender effectively choosing among lotteries over the receiver's action. Similar results could also be obtained when the receiver's preferences are known but communication is noisy, à la [Blume, Board, and Kawamura \(2007\)](#).

²³ Let x and y be random variables with distributions P and Q , respectively. Let F_ψ be the distribution of a random vector $\psi = (\psi_1, \psi_2)$ defined by

$$\begin{bmatrix} \psi_1 \\ \psi_2 \end{bmatrix} \equiv \begin{bmatrix} 1 & \theta' \\ 1 & \theta_m \end{bmatrix}^{-1} \begin{bmatrix} x \\ y \end{bmatrix}.$$

As $\psi \sim F_\psi$ (i.e., ψ has distribution F_ψ),

$$\begin{bmatrix} 1 & \theta' \\ 1 & \theta_m \end{bmatrix} \begin{bmatrix} \psi_1 \\ \psi_2 \end{bmatrix} = \begin{bmatrix} \psi_1 + \psi_2 \theta' \\ \psi_1 + \psi_2 \theta_m \end{bmatrix}$$

is stochastically equivalent to (x, y) . Thus, $\alpha(m', \psi) = \psi_1 + \psi_2 \theta' \sim P$ and $\alpha(m'', \psi) = \psi_1 + \psi_2 \theta_m \sim Q$.

3.2. Collective Choice

Collective choice over lotteries arises naturally in many contexts: elections entail uncertainty about what policies politicians will implement if elected; and a board of directors may view each candidate for CEO as a probability distribution over firm earnings. [Zeckhauser \(1969\)](#) first pointed out that pairwise-majority comparisons in these settings can be cyclical, even when comparisons over deterministic outcomes are not. Our results shed light on when such difficulties do not arise.

Consider a finite group of individuals indexed by $i \in \{1, 2, \dots, N\}$. The group must choose from a set of lotteries, $\mathcal{A} \subseteq \Delta A$, where A is the space of outcomes (political policies, earnings, etc.) with generic element a . Each individual i has von Neumann-Morgenstern utility function $v(a, \theta_i)$, where $\theta_i \in \Theta$ is a preference parameter or i 's type. We assume Θ is completely ordered; without further loss of generality, let $\Theta \subset \mathbb{R}$ and $\theta_1 \leq \dots \leq \theta_N$. The expected utility for an individual of type θ from lottery $P \in \mathcal{A}$ is $V(P, \theta) \equiv \int_A v(a, \theta) dP$.

Define the group's preference relation, \succeq_{maj} , over lotteries $P, Q \in \mathcal{A}$ by majority rule:

$$P \succeq_{maj} Q \text{ if } |\{i : V(P, \theta_i) \geq V(Q, \theta_i)\}| \geq N/2.$$

The relation \succeq_{maj} is said to be *quasi-transitive* if the corresponding strict relation is transitive. Quasi-transitivity of \succeq_{maj} is the key requirement for collective choice to be "rational": it ensures—given completeness, which \succeq_{maj} obviously satisfies—that a preference-maximizing choice (equivalently, a Condorcet Winner) exists for the group under standard conditions on the choice set, e.g., if \mathcal{A} is finite. We say there is a *unique median* if either (i) N is odd, in which case we define $M \equiv (N + 1)/2$ or (ii) N is even and $\theta_{N/2} = \theta_{N/2+1}$, in which case $M \equiv N/2$.

Claim 3. *If v has the form stated in [Theorem 1](#), and hence has SCED, then the group's preference relation is quasi-transitive. If v has the form stated in [Theorem 2](#) and hence has SSCED, and there is a unique median, then the group's preference relation is transitive and is represented by $V(\cdot, \theta_M)$.*

Proof. Suppose v has SCED. Define the minimal space $\tilde{\mathcal{A}}$ from \mathcal{A} by not distinguishing lotteries that give the same expected utility to all types. We work with $\tilde{\mathcal{A}}$ instead of \mathcal{A} in order to invoke a result from [Gans and Smart \(1996\)](#) that assumes a completely ordered set. [Corollary 3](#) implies there is a complete order \succeq on $\tilde{\mathcal{A}}$, which refines \succeq_{SCED} , such that

$$(\forall P \succ Q, \forall \theta' > \theta) V(P, \theta) \geq V(Q, \theta) \implies V(P, \theta') \geq V(Q, \theta'), \quad (7)$$

$$(\forall P \succ Q, \forall \theta' > \theta) V(P, \theta) > V(Q, \theta) \implies V(P, \theta') > V(Q, \theta'). \quad (8)$$

Conditions (7) and (8) imply that Gans and Smart's (1996) single-crossing condition is satisfied on $\tilde{\mathcal{A}}$; their Corollary 1 implies the group's preference relation is quasi-transitive on $\tilde{\mathcal{A}}$. Since \mathcal{A} differs from $\tilde{\mathcal{A}}$ only by distinguishing lotteries that all individuals are indifferent among, it follows that \succeq_{maj} is quasi-transitive on \mathcal{A} .

The claim's second statement follows similarly from Corollary 4 and Gans and Smart's (1996) Corollary 2. Q.E.D.

Claim 3 can be applied to a well-known problem in political economy (Shepsle, 1972). The policy space is a finite set $A \subset \mathbb{R}$ (for simplicity) and there are an odd N number of voters ordered by their ideal points in \mathbb{R} , $\theta_1 \leq \dots \leq \theta_N$ (i.e., for each voter i , $\{\theta_i\} = \arg \max_{a \in \mathbb{R}} v(a, \theta_i)$). Let $M \equiv (N + 1)/2$. There are two office-motivated candidates, L and R ; each $j \in \{L, R\}$ can commit to any lottery from some given set $\mathcal{A}_j \subseteq \Delta A$. A restricted set \mathcal{A}_j may capture various kinds of constraints; for example, Shepsle (1972) assumed the incumbent candidate could only choose degenerate lotteries. In our setting, what ensures the existence of an equilibrium, and which policy lotteries are offered in an equilibrium?²⁴

Claim 3 implies that if voters' utility functions v have SSCED, and if voter M is indifferent between her most-preferred lottery in \mathcal{A}_L and in \mathcal{A}_R (e.g., if $\mathcal{A}_L = \mathcal{A}_R$ and they are compact sets, or if both sets contain the degenerate lottery on θ_M , denoted δ_{θ_M} hereafter), then there is a unique equilibrium: each candidate offers the best lottery for voter M ; in particular, both candidates converge to δ_{θ_M} if that is feasible for both. A special case is when $v(a, \theta) = -(a - \theta)^2$ and $\delta_{\theta_M} \in \mathcal{A}_L \cap \mathcal{A}_R$. It bears emphasis, however, that there will be policy convergence at the median ideal point (so long as $\delta_{\theta_M} \in \mathcal{A}_L \cap \mathcal{A}_R$) given SSCED not because all voters need be globally "risk averse"; rather, it is because SSCED ensures the existence of a decisive voter whose most-preferred lottery is degenerate.²⁵

There is a sense in which (S)SCED is necessary to guarantee that each candidate j will offer the median ideal-point voter's most-preferred lottery from the feasible set \mathcal{A}_j . Suppose $v(a, \theta)$ strictly violates SCED, as defined in Subsection 3.1 before Claim 2. That is, there are $P, Q \in \Delta A$ and $\theta_l < \theta_m < \theta_h$ such that $\min\{D_{P,Q}(\theta_l), D_{P,Q}(\theta_h)\} > 0 > D_{P,Q}(\theta_m)$. Then, if the population of voters is just $\{l, m, h\}$ and $\mathcal{A}_L = \mathcal{A}_R = \{P, Q\}$, the unique equilibrium is for both candidates to offer lottery P , which is voter m 's less preferred lottery.

²⁴ More precisely: the two candidates simultaneously choose their lotteries, and each voter then votes for his preferred candidate (assuming, for concreteness, that a voter randomizes between the candidates with equal probability if indifferent). A candidate wins if he receives a majority of the votes. Candidates maximize the probability of winning. We seek a Nash equilibrium of the game between the two candidates.

²⁵ An example may be helpful. Let $A = [-1, 1]$, $\Theta = \{-1, 0, 1\}$, and $v(a, \theta) = a\theta + 1/(|a| + 1) + 1$. The corresponding functions $f_1(\theta) = \theta$ and $f_2(\theta) = 1$ are each strictly single crossing from below and strictly ratio ordered. For all θ , $v(\cdot, \theta) : A \rightarrow \mathbb{R}$ is maximized at $a = \theta$ but convex on some sub-interval of A .

3.3. Costly Signaling

Consider a version of [Spence's \(1973\)](#) signaling model. A worker is privately informed of his type θ that is drawn from some distribution with support $\Theta \subseteq \mathbb{R}$ and then chooses education $e \in \mathbb{R}_+$. There is a reduced-form market that observes e (but not θ) and allocates wage, or some other statistic of job characteristics, $w \in \mathbb{R}$ to the worker. The worker's von Neumann-Morgenstern payoff is given by $v(w, e, \theta)$. It is convenient to let $a \equiv (w, e)$, so that we can also write $v(a, \theta)$.

In the standard model, (i) w is an exogenously-given strictly increasing function of the market's expectation $\mathbb{E}[\theta|e]$, (ii) $v(w, e, \theta)$ is strictly increasing in w and strictly decreasing in e , and (iii) $v(w, e, \theta)$ has a strict single-crossing property in $((w, e), \theta)$.²⁶

Our results allow us to generalize some central conclusions about education signaling to settings in which there is uncertainty about what wage the worker will receive, even conditional on the market belief about his type. Such uncertainty is, of course, plausible for many reasons, e.g., economic fluctuations during the course of one's education. Accordingly, in our specification, we allow for $w \sim F_\mu$, i.e., w is drawn from an exogenously-given cumulative distribution F that depends on μ , the market belief about (i.e., probability distribution over) θ . Let $V(F, e, \theta) \equiv \int_w v(w, e, \theta) dF$ and $\mathcal{F} \equiv \{F_\mu\}_\mu$ be the family of feasible wage distributions. We assume that for any two beliefs μ and μ' , if μ (strictly) *support-dominates* μ' (i.e., $\inf \text{Supp}[\mu] \geq (>) \sup \text{Supp}[\mu']$), then $(\forall e, \theta) V(F_\mu, e, \theta) \geq (>) V(F_{\mu'}, e, \theta)$. This is a weak sense in which the worker wants to convince the market that his type is higher. We also assume that $v(w, e, \theta)$ is strictly decreasing in e .

A (weak Perfect Bayesian) equilibrium is described by a pair of functions $\sigma^*(\cdot)$ and $\mu^*(\cdot)$, where for each θ , $\sigma^*(\theta)$ is type θ 's probability distribution over education, and for each education level e , $\mu^*(e)$ is the market belief about the worker's type when that education is observed. For notational and technical simplicity, we will restrict attention to equilibria in which for all θ , $\sigma^*(\theta)$ has countable support. When the equilibrium is pure we write $e^*(\theta)$ instead of $\sigma^*(\theta)$. A pure-strategy equilibrium exists: all types pool on $e = 0$ and off-path beliefs are the same as the prior.

A fundamental conclusion of the standard model is that in any equilibrium higher types acquire more education. Our results deliver this conclusion in our specification; see [Liu and Pei \(2017\)](#) for related work. We say that a strategy σ is *increasing* if for all $\underline{\theta} < \bar{\theta}$, $\sigma(\bar{\theta})$ support-dominates $\sigma(\underline{\theta})$. In other words, a strategy is increasing if a higher type never acquires (with positive probability) strictly less education than a lower type.

²⁶ Given point (ii), point (iii) is implied by the Spence-Mirlees single crossing condition: v_w/v_e is increasing in θ , where a subscript on v denotes a partial derivative (assuming differentiability).

Claim 4. Assume $v(a, \theta) \equiv v(w, e, \theta)$ has the form stated in [Theorem 2](#), and hence has SSCED. If

$$F, G \in \mathcal{F}, \bar{e} \neq \underline{e} \implies (\exists \theta) V(F, \bar{e}, \theta) \neq V(G, \underline{e}, \theta), \quad (9)$$

then in any equilibrium $\sigma^*(\theta)$ is increasing.

The role of SSCED in the claim is to ensure that every equilibrium is monotonic (either increasing or decreasing). The fact that equilibria must then be increasing essentially stems from our assumptions that more education is more costly and higher beliefs are preferred. Condition (9) is a richness condition that plays an analogous role to the sender-minimality requirement in [Claim 1](#); given SSCED, it is automatically satisfied if the worker's utility is separable in wage and education.²⁷

Proof of Claim 4. Suppose, to contradiction, that $\sigma^*(\theta)$ is not increasing. Then there exist $\underline{\theta} < \bar{\theta}$ and $\underline{e} < \bar{e}$ such that $\min\{\sigma^*(\bar{e}|\underline{\theta}), \sigma^*(\underline{e}|\bar{\theta})\} > 0$. Let \underline{F} and \bar{F} be the wage distributions resulting from \underline{e} and \bar{e} respectively. By [Corollary 4](#), the minimal space of lotteries over wage and education pairs has a complete order, \succeq , with respect to which V has monotone selection. Condition (9) implies that some type is not indifferent between $(\underline{F}, \underline{e})$ and (\bar{F}, \bar{e}) , hence either $(\bar{F}, \bar{e}) \succ (\underline{F}, \underline{e})$ or $(\underline{F}, \underline{e}) \succ (\bar{F}, \bar{e})$. As $(\bar{F}, \bar{e}) \succ (\underline{F}, \underline{e})$ would contradict optimality of \bar{e} for $\underline{\theta}$ and \underline{e} for $\bar{\theta}$ (by monotone selection), it holds that $(\underline{F}, \underline{e}) \succ (\bar{F}, \bar{e})$.

Monotone selection now implies that $\sigma^*(\underline{e}|\theta) > 0 \implies (\forall \theta' > \theta) \sigma^*(\bar{e}|\theta') = 0$. Consequently, $\mu^*(\underline{e})$ support-dominates $\mu^*(\bar{e})$. Given the support-dominance, type $\underline{\theta}$ can profitably deviate from switching mass from \bar{e} to \underline{e} , because the reduction in education is strictly preferred and the change in market belief is weakly preferred, a contradiction. *Q.E.D.*

We can also study when there is a separating equilibrium. Let F_θ denote the wage distribution when the market puts probability one on θ .

Claim 5. Let $\Theta \equiv \{\theta_1, \theta_2, \dots\}$, either finite or infinite. If $v(a, \theta) \equiv v((w, e), \theta)$ has the form stated in [Theorem 1](#) and hence has SCED, and in addition:

1. $v(w, e, \theta)$ is continuous in e ,
2. $\lim_{e \rightarrow \infty} V(F_{\theta_n}, e, \theta_{n-1}) = -\infty$ for all $n > 1$, and

²⁷ Suppose v has SSCED and is separable in w and e , so that it has the form $v(w, e, \theta) = g_1(w)f_1(\theta) + g_2(e)f_2(\theta) + c(\theta)$. Fix any $F, G \in \mathcal{F}$ and $\bar{e} \neq \underline{e}$. We compute the expectational difference $V(F, \bar{e}, \theta) - V(G, \underline{e}, \theta) = [\int g_1(w)dF - \int g_1(w)dG] f_1(\theta) + [g_2(\bar{e}) - g_2(\underline{e})] f_2(\theta)$. The maintained assumption that v is strictly decreasing in e implies $g_2(\bar{e}) - g_2(\underline{e}) \neq 0$. As strict ratio ordering of f_1 and f_2 implies they are linearly independent, it follows that the expectational difference is non-zero for some θ .

3. for all $n > 1$ and $\bar{e} > \underline{e}$:

$$V(F_{\theta_n}, \bar{e}, \theta_{n-1}) = V(F_{\theta_{n-1}}, \underline{e}, \theta_{n-1}) \implies V(F_{\theta_n}, \bar{e}, \theta_n) \geq V(F_{\theta_{n-1}}, \underline{e}, \theta_n), \quad (10)$$

then there is a pure-strategy equilibrium in which $e^*(\theta)$ is strictly increasing.

The conditions in the result above are related to those in [Cho and Sobel \(1990\)](#). Part 2 of the Claim merely requires that no type θ_n ($n > 1$) would acquire arbitrarily high education to shift the market's belief from probability one on θ_{n-1} to probability one on θ_n . Despite a resemblance, Condition (10) is not by itself a single-crossing condition. Rather, loosely speaking, it ensures that the SCED order over wage distribution and education pairs goes in the “right direction”; the proof below clarifies.

Proof of Claim 5. Set $e_1 = 0$. For $n > 1$, inductively construct e_n as the solution to

$$V(F_{\theta_n}, e_n, \theta_{n-1}) = V(F_{\theta_{n-1}}, e_{n-1}, \theta_{n-1}). \quad (11)$$

Our assumptions ensure there is a unique solution and that $e_n > e_{n-1}$ for all $n > 1$.

We claim $(\forall n) e^*(\theta_n) = e_n$ can be supported as an equilibrium. To see this, first note that by [Corollary 3](#), the minimal space of wage distribution and education pairs has a complete order, \succeq , with respect to which V has monotone comparative statics. It follows that for $\forall n > 1$, (10) and (11) imply $(F_{\theta_n}, e_n) \succeq (F_{\theta_{n-1}}, e_{n-1})$. Hence, no type can profitably deviate to any on-path $e \in \{e_1, e_2, \dots\}$; off-path deviations can be deterred by simply setting off-path beliefs to put probability one on θ_1 . Q.E.D.

4. Extensions

4.1. Single Crossing vs. Monotonicity

We have characterized when $v : A \times \Theta \rightarrow \mathbb{R}$ has SCED. Viewing ΔA as a choice set and Θ as a parameter set, SCED is an *ordinal* property. Analogous to supermodularity on an ordered space, one might also be interested in a stronger *cardinal* property in our setting, which we call **Monotonic Expectational Differences (MED)**:

$$(\forall P, Q \in \Delta A) D_{P,Q}(\theta) \text{ is monotonic in } \theta.$$

To study which functions have MED, we begin with the following analog of [Lemma 1](#).

Lemma 2. Let $f_1, f_2 : \Theta \rightarrow \mathbb{R}$ be monotonic functions. The linear combination $\alpha_1 f_1(\theta) + \alpha_2 f_2(\theta)$ is monotonic $\forall \alpha \in \mathbb{R}^2$ if and only if either f_1 or f_2 is an affine transformation of the other, i.e., there exists $\lambda \in \mathbb{R}^2$ such that either $f_2 = \lambda_1 f_1 + \lambda_2$ or $f_1 = \lambda_1 f_2 + \lambda_2$.

We say that $f : X \times \Theta \rightarrow \mathbb{R}$ is **linear combinations monotonicity-preserving** if $\sum_{x \in X} f(x, \theta) \mu(x)$ is a monotonic function of θ for every function $\mu : X \rightarrow \mathbb{R}$ with finite support.

Proposition 4. Let $f : X \times \Theta \rightarrow \mathbb{R}$ for some set X . The function f is linear combinations monotonicity-preserving if and only if there exist $x' \in X$ and $\lambda_1, \lambda_2 : X \rightarrow \mathbb{R}$ such that (i) $f(x', \cdot)$ is monotonic, and (ii) $(\forall x) f(x, \cdot) = \lambda_1(x) f(x', \cdot) + \lambda_2(x)$.

Theorem 4. The function $v : A \times \Theta \rightarrow \mathbb{R}$ has MED if and only if it takes the form

$$v(a, \theta) = g_1(a) f_1(\theta) + g_2(a) + c(\theta), \quad (12)$$

where $f_1 : \Theta \rightarrow \mathbb{R}$ is monotonic, $g_1, g_2 : A \rightarrow \mathbb{R}$, and $c : \Theta \rightarrow \mathbb{R}$.

The proof of Theorem 4 uses Proposition 4, exhibiting a parallel with Proposition 2 and Theorem 1. However, there is a simple intuition for Theorem 4 based on the von Neumann-Morgenstern expected utility theorem. Suppose $\Theta = [\underline{\theta}, \bar{\theta}] \subset \mathbb{R}$ and $v_\theta(a, \theta)$, the partial derivative of v with respect to θ , exists and is continuous. Consider the following strengthening of MED: $(\forall P, Q \in \Delta A) D_{P,Q}(\theta)$ is either a zero function or strictly monotonic. Then, for any P and Q , $\text{sign} [\int_A v_\theta(a, \theta) dP - \int_A v_\theta(a, \theta) dQ]$ is independent of θ . In other words, for all θ , $v_\theta(\cdot, \theta)$ is a von Neumann-Morgenstern representation of the same preferences over lotteries. The conclusion of Theorem 4 follows from the expected utility theorem's implication that $(\forall \theta', \theta'') v_\theta(\cdot, \theta')$ must be a positive affine transformation of $v_\theta(\cdot, \theta'')$.²⁸ We are not aware of any related argument for Theorem 1's SCED characterization.

Comparing Theorem 1 and Theorem 4, we see that a function v with MED is a special case of a function v with SCED, in which the function f_2 in (5) is identically equal to one. Note that when this is the case, f_1 and f_2 being ratio ordered is equivalent to f_1 being monotonic. SCED is more general than MED; for example, given a function $v(a, \theta)$ of the form (12) with $f_1(\cdot) > 0$ and domain $\Theta \subseteq \mathbb{R}_{++}$, the function $\tilde{v}(a, \theta) \equiv \theta v(a, \theta)$ will satisfy SCED but generally violate MED. The generality translates into preferences: the set of preferences with SCED representations is larger than that with MED representations; see Example 2 in Appendix E. Proposition 7 in Appendix E characterizes exactly when preferences with an

²⁸ Pick any $\theta^* \in \Theta$. The expected utility theorem implies that for some $F_1 : \Theta \rightarrow \mathbb{R}_{++}$ and $C : \Theta \rightarrow \mathbb{R}$, $(\forall a, \theta) v_\theta(a, \theta) = v_\theta(a, \theta^*) F_1(\theta) + C(\theta)$. Equation 12 follows from integrating up θ at each a , as $v(a, \theta) = \int_{\underline{\theta}}^{\theta} v_\theta(a, t) dt + v(a, \underline{\theta})$.

SCED representation have an MED representation. It is when (a) there is a pair of types that do not share the same strict preference over every pair of lotteries, or (b) there is a pair of lotteries over which all types share the same strict preference (e.g., lotteries over money).

The MED characterization in [Theorem 4](#) has largely been obtained by [Kushnir and Liu \(2017\)](#). They restrict attention to $\Theta \subseteq \mathbb{R}$, $A \subset \mathbb{R}^k$, and functions v that have some smoothness. Modulo minor differences, [Kushnir and Liu](#) establish that for their environment, a strict version of MED (in fact the strengthening discussed in the paragraph after [Theorem 4](#)) is equivalent to the characterization in [Theorem 4](#) with f_1 strictly monotonic.²⁹ [Kushnir and Liu](#)'s focus is on the equivalence between Bayesian and dominant-strategy implementation. Their methodology requires certain functions to have MED rather than SCED, and they do not study the relationship between MED and SCED.

[Theorem 4](#) and the foregoing discussion support suggestions put forward by [Duggan \(2014\)](#). Although his setting is formulated a little differently and he does not obtain a necessary condition, [Duggan \(2014, Section 4\)](#) discusses the difficulties of finding preferences that are not representable in the form of [Theorem 4](#) and yet satisfy MED/SCED.

4.2. Information Design

In this subsection, we derive an extension of SCED when there is a restricted set of distributions over the set A .³⁰ The restriction we study is motivated by the recent literature on Bayesian persuasion ([Kamenica and Gentzkow, 2011](#)) or, more broadly, information design ([Bergemann and Morris, 2017](#)). Take A to be the set of beliefs about some random variable ω . When beliefs or posteriors about ω are generated by Bayesian updating, it is well known that every feasible distribution of posteriors has the same expectation: the prior distribution of ω . Hence, choices among experiments—distribution of posteriors—only involve those subsets of ΔA whose elements have the same expectation. Plainly, given any function $v(a, \theta)$ that satisfies SCED, the function $v(a, \theta) + f(a, \theta)$ with $f(\cdot, \theta)$ linear for each θ will satisfy a weaker form of SCED that only considers the aforementioned subsets of ΔA . We establish below in [Proposition 5](#) that this is essentially the only change to [Theorem 1](#). At the end of the subsection, we mention applications of the result.

Formally, let Ω be an arbitrary set. We refer to $\Delta\Omega$ as the set of beliefs or posteriors with finite support and $\Delta\Delta\Omega$ as the set of experiments with finite support. Let p denote a generic posterior and Q denote a generic experiment. We write δ_ω and δ_p for a degenerate belief on

²⁹ The statement in Proposition 3 of their paper is that f_1 is strictly increasing; monotonicity vs. increasing is immaterial, as the direction of monotonicity can be reversed by flipping the sign of the function g_1 .

³⁰ [Smith \(2011\)](#) provides sufficient conditions for a single-crossing property of the expectational difference between lotteries and their certainty equivalents.

ω and a degenerate experiment on p as usual. The *average* of an experiment $Q \in \Delta\Delta\Omega$ is the posterior $\bar{Q} \in \Delta\Omega$ defined by $\bar{Q} \equiv \int_{\Delta\Omega} p dQ$.

Let $v : \Delta\Omega \times \Theta \rightarrow \mathbb{R}$ denote a utility function, where for each θ , $v(\cdot, \theta)$ captures type θ 's preferences over posteriors in a reduced form. Note that $v(\cdot, \theta)$ is convex when induced by a single-person decision problem, while it can have arbitrary shape when induced by strategic settings such as those in [Kamenica and Gentzkow \(2011\)](#). Let $V : \Delta\Delta\Omega \times \Theta \rightarrow \mathbb{R}$ be the expected utility function corresponding to v .

Definition 10. The utility function $v : \Delta\Omega \times \Theta \rightarrow \mathbb{R}$ has **Single-Crossing Expectational Differences over Experiments** (SCED-X) if for every $Q, R \in \Delta\Delta\Omega$ with $\bar{Q} = \bar{R}$, the expected utility difference $D_{Q,R}(\theta) \equiv V(Q, \theta) - V(R, \theta)$ is single crossing in θ .

The above definition of SCED-X is simply the analog of SCED specialized to the current setting of experiments, with the twist that one only considers expected utility differences between experiments with the same average.

Proposition 5. *The function $v : \Delta\Omega \times \Theta \rightarrow \mathbb{R}$ has SCED-X if and only if*

$$v(p, \theta) = g_1(p)f_1(\theta) + g_2(p)f_2(\theta) + \sum_{\omega \in \Omega} v(\delta_\omega, \theta)p(\omega), \quad (13)$$

for some $f_1, f_2 : \Theta \rightarrow \mathbb{R}$ each single crossing and ratio ordered, and $g_1, g_2 : \Delta\Omega \rightarrow \mathbb{R}$.

[Proposition 5](#) parallels [Theorem 1](#). The $c(\theta)$ term from [Equation 5](#) is subsumed into the summation term in [Equation 13](#) because each p is a posterior. This summation term, being linear in the posterior, does not affect the expected utility difference between any two experiments with the same average. This means that if v has SCED-X, then insofar as comparisons between pairs of experiments with the same average go, there is a representation of preferences that has SCED. The heart of [Proposition 5](#), then, is in establishing that the restriction to comparing experiments with the same average introduces no further flexibility into the form of v .

As mentioned earlier, when there is a prior on Ω , say p^* , Bayesian updating restricts the agent's choice among experiments to (subsets of) those with average p^* . To capture this point, one would require the difference $D_{Q,R}(\theta)$ to be single crossing only when $\bar{Q} = \bar{R} = p^*$; call this requirement *SCED-X with prior p^** . It is clear that SCED-X implies SCED-X with any prior. If $\text{Supp}[p^*] = \Omega$, then the converse also holds: the characterization in [Proposition 5](#) is necessary for SCED-X with prior p^* . For an intuition, take any experiments Q and R with average $p \neq p^*$. Since p^* has full support, $p^* = \alpha p + (1 - \alpha)q$ for some $q \in \Delta\Omega$

and $\alpha \in (0, 1)$. The mixture experiments $Q^* = \alpha Q + (1 - \alpha)\delta_q$ and $R^* = \alpha R + (1 - \alpha)\delta_q$ have average p^* , and hence the difference $D_{Q,R}(\theta) = D_{Q^*,R^*}(\theta)/\alpha$ is single crossing.

The logic behind [Proposition 5](#) generalizes to other kinds of linear restrictions on pairs of distributions. Let $v : A \times \Theta \rightarrow \mathbb{R}$ and $h : A \rightarrow \mathbb{R}^k$. Consider the requirement that $D_{P,Q}(\theta)$ be single crossing for all pairs $P, Q \in \Delta A$ such that $\int_A h(a)dP = \int_A h(a)dQ$. (For instance, $A \subseteq \mathbb{R}$ and $h(a) = a^2$ impose the equality of second moments.) It can be shown that this requirement holds if and only if

$$v(a, \theta) = u(a, \theta) + h(a) \cdot \tilde{f}(\theta),$$

with u satisfying SCED, $\tilde{f} : \Theta \rightarrow \mathbb{R}^k$, and \cdot being the dot product. Moreover, this characterization also holds when the requirement is weakened to only consider pairs $P, Q \in \Delta A$ such that $\int_A h(a)dP = \int_A h(a)dQ = \varphi$, for any fixed $\varphi \in \mathbb{R}^k$ that is in the relative interior of the convex hull of $\bigcup_{a \in A} h(a)$. When $A = \Delta\Omega$ and $h(a) = a$ these requirements reduce to SCED-X and SCED-X with a fixed full-support prior, respectively.

To illustrate the use of [Proposition 5](#), consider [Kamenica and Gentzkow's \(2011\)](#) leading prosecutor-judge example. Let $\theta \in [0, 1]$ denote the judge's threshold belief for conviction (or more pertinently, the prosecutor's view about this threshold). The prosecutor's von Neumann-Morgenstern utility is $v(p, \theta) = \mathbb{1}_{\{p \geq \theta\}}$, where $p \in [0, 1]$ is the probability that the defendant is guilty. It is not hard to verify that this function cannot be written in the form [\(13\)](#), and hence does not have SCED-X.³¹ Using the arguments from [Subsection 2.3](#), monotone comparative statics fail with respect to any order over experiments. That is, there will be choice problems—the prosecutor must choose from some given subset of experiments—in which two types of the prosecutor, say θ_1 and θ_3 , will both optimally choose one experiment, while an intermediate type $\theta_2 \in (\theta_1, \theta_3)$ will choose a different experiment. The failure of SCED-X in this example is also at the core of [Silbert \(2018\)](#).

On the other hand, consider a different example in which $|\Omega| = 2$ (for simplicity, so we

³¹ Consider four posteriors p_1, p_2, p_3, p_4 and three types $\theta_1, \theta_2, \theta_3$. Analogous to the discussion in the paragraph after [Theorem 1](#), v cannot be written in the form [\(13\)](#) if there is an invertible 4×4 matrix M with elements $M_{i,j} \equiv \begin{cases} p_j & \text{if } i = 1 \\ v(p_j, \theta_{i-1}) - v(0, \theta_{i-1}) & \text{if } i \geq 2 \end{cases}$. In the current example, for any $0 < p_1 < \theta_1 < p_2 < \theta_2 < p_3 < \theta_3 < p_4$, this matrix is

$$\begin{bmatrix} p_1 & p_2 & p_3 & p_4 \\ 0 & 1 & 1 & 1 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & 1 \end{bmatrix},$$

which is invertible because it is upper triangular with a non-zero diagonal. We note that because of the simplicity of this example, it is also straightforward to directly find experiments such that the expected utility difference is not single-crossing in type.

can again view posteriors as $p \in [0, 1]$, $\Theta \subseteq \mathbb{R}$, and $v(p, \theta) = \theta g_1(p) + g_2(p) + f(\theta)p$, for some $g_1, g_2 : [0, 1] \rightarrow \mathbb{R}$ and $f : \Theta \rightarrow \mathbb{R}$. For instance, an agent chooses an experiment whose realization will be observed by two parties each of whom takes an action that depends on the posterior; the agent’s weighted utility from each party’s action is captured by each of the first two terms of v . The third, linear term captures the agent’s own action-independent preference over states (e.g., anticipatory utility over health or election outcomes). In general, this specification will not satisfy SCED but, by [Proposition 5](#), it does satisfy SCED-X. Monotone comparative statics implies that, no matter the feasible set of experiments, the set of agent types that choose any experiment will be an interval.

5. Conclusion

The main result of this paper is a full characterization of which von Neumann-Morgenstern utility functions of outcome and type satisfy single-crossing expectational differences (SCED): the difference in expected utility between every pair of probability distributions on outcomes is single crossing in type ([Theorem 1](#)). We have established that this property is necessary and sufficient for a form of monotone comparative statics when an agent chooses among distributions over outcomes ([Theorem 3](#)).

We close by suggesting directions for future research.

[Theorem 1](#)’s characterization leans on the requirement that the expectational difference must be single crossing for *all* pairs of distributions over outcomes. While a “sufficiently rich” set of pairs would suffice, as seen in our cheap-talk application ([Subsection 3.1](#)), there is a fundamental tradeoff. Requiring single crossing for only a subset of distributions would expand the set of utility functions satisfying the requirement—as seen in our extension to information design ([Subsection 4.2](#))—but applications must then have enough stochastic structure to validate the restriction on distributions. Another possibility would be to weaken or alter the expected utility hypothesis.

Our results have direct bearing on problems in which all types of an agent face the same choice set of distributions. Such situations arise naturally, as illustrated in [Section 3](#). But consider a variation of the cheap-talk application ([Subsection 3.1](#)) in which the sender’s type is correlated with the receiver’s type. Even though the receiver’s type does not affect the sender’s payoff, different sender types will generally have different beliefs about the distribution of the receiver’s action that any message induces in equilibrium. Effectively, different sender types will be choosing from different sets of distributions. An approach that synthesizes the current paper’s with that of, for example, [Athey’s \(2002\)](#) may be useful for such problems.

Appendices

Appendix A contains proofs for our core results on single crossing and SCED (Subsection 2.1); Appendix B proofs for strict single crossing and SSCED (Subsection 2.2); Appendix C for monotone comparative statics (Subsection 2.3); and Appendix D for MED (Subsection 4.1). Additional connections between SCED and MED are then provided in Appendix E. The proof of Proposition 5 on information design follows in Appendix F. We elaborate on some related literature in Appendix G. Finally, Appendix H explains how our results can be extended to settings in which the type set is equipped with a pre-order rather than an order (i.e., relaxing anti-symmetry).

A. Proofs for Single Crossing (Subsection 2.1)

A.1. Proof of Lemma 1

When $|\Theta| \leq 2$, the proof is trivial as all functions are single crossing and every pair of functions are ratio ordered. Hereafter, we assume $|\Theta| \geq 3$.

(\implies) It is clear that each function f_1 and f_2 is single crossing. We must show that f_1 and f_2 are ratio ordered.

To prove (3), we suppose towards contradiction that

$$\begin{aligned} (\exists \theta_l < \theta_h) \quad f_1(\theta_l)f_2(\theta_h) &< f_1(\theta_h)f_2(\theta_l), \text{ and} \\ (\exists \theta' < \theta'') \quad f_1(\theta')f_2(\theta'') &> f_1(\theta'')f_2(\theta'). \end{aligned} \tag{14}$$

Take any upper bound $\bar{\theta}$ of $\{\theta_l, \theta_h, \theta', \theta''\}$.

First, let $\alpha_l \equiv (f_2(\theta_l), -f_1(\theta_l))$. Then $(\alpha_l \cdot f)(\theta_l) = (f_2(\theta_l), -f_1(\theta_l)) \cdot (f_1(\theta_l), f_2(\theta_l)) = 0$, and $(\alpha_l \cdot f)(\theta_h) > 0$. Thus, $\alpha_l \cdot f$ is single crossing from below and $(\alpha_l \cdot f)(\bar{\theta}) > 0$.

Second, let $\alpha' \equiv (f_2(\theta'), -f_1(\theta'))$. Then $(\alpha' \cdot f)(\theta') = 0$ and $(\alpha' \cdot f)(\theta'') < 0$. Thus, $\alpha' \cdot f$ is single crossing from above and $(\alpha' \cdot f)(\bar{\theta}) < 0$.

Let $\bar{\alpha} = (f_2(\bar{\theta}), -f_1(\bar{\theta}))$. It follows that

$$\begin{aligned} (\bar{\alpha} \cdot f)(\theta_l) &= (f_2(\bar{\theta}), -f_1(\bar{\theta})) \cdot (f_1(\theta_l), f_2(\theta_l)) = -(\alpha_l \cdot f)(\bar{\theta}) < 0, \\ (\bar{\alpha} \cdot f)(\theta') &= -(\alpha' \cdot f)(\bar{\theta}) > 0, \text{ and} \\ (\bar{\alpha} \cdot f)(\bar{\theta}) &= 0. \end{aligned}$$

Therefore, $\bar{\alpha} \cdot f$ is not single crossing, a contradiction.

To prove (4), take any $\theta_l < \theta_m < \theta_h$.

First, we show that $f_1(\theta_l)f_2(\theta_h) = f_1(\theta_h)f_2(\theta_l)$ implies $f_1(\theta_m)f_2(\theta_h) = f_1(\theta_h)f_2(\theta_m)$ and $f_1(\theta_m)f_2(\theta_l) = f_1(\theta_l)f_2(\theta_m)$. Assume f_1 is not a zero function on $\{\theta_l, \theta_m, \theta_h\}$, as otherwise the proof is trivial. Since f_1 is single crossing, either $f_1(\theta_l) \neq 0$ or $f_1(\theta_h) \neq 0$. We consider the case of $f_1(\theta_h) \neq 0$ (and omit the proof for the other case, as it is analogous). Let $\alpha_h \equiv (f_2(\theta_h), -f_1(\theta_h))$. Since $\alpha_h \cdot f$ is single crossing and $(\alpha_h \cdot f)(\theta) = 0$ for $\theta = \theta_l, \theta_h$, it holds that $(\alpha_h \cdot f)(\theta_m) = f_2(\theta_h)f_1(\theta_m) - f_1(\theta_h)f_2(\theta_m) = 0$. It follows immediately that $f_1(\theta_m)f_2(\theta_h) = f_1(\theta_h)f_2(\theta_m)$. As $(f_1(\theta_m), f_2(\theta_m))$ and $(f_1(\theta_h), f_2(\theta_h))$ are linearly dependent and $(f_1(\theta_h), f_2(\theta_h))$ is a non-zero vector, there exists $\lambda \in \mathbb{R}$ such that $f_i(\theta_m) = \lambda f_i(\theta_h)$ for $i = 1, 2$. Thus,

$$f_1(\theta_l)f_2(\theta_m) = \lambda f_1(\theta_l)f_2(\theta_h) = \lambda f_2(\theta_l)f_1(\theta_h) = f_2(\theta_l)f_1(\theta_m).$$

Next, we show that if $f_1(\theta_l)f_2(\theta_m) = f_1(\theta_m)f_2(\theta_l)$ and $f_1(\theta_m)f_2(\theta_h) = f_1(\theta_h)f_2(\theta_m)$, then $f_1(\theta_l)f_2(\theta_h) = f_1(\theta_h)f_2(\theta_l)$. Let $\alpha \equiv (f_2(\theta_l) - f_2(\theta_h), -f_1(\theta_l) + f_1(\theta_h))$. It follows that

$$\begin{aligned} (\alpha \cdot f)(\theta_l) &= (f_2(\theta_l) - f_2(\theta_h))f_1(\theta_l) - (f_1(\theta_l) - f_1(\theta_h))f_2(\theta_l) = f_1(\theta_h)f_2(\theta_l) - f_1(\theta_l)f_2(\theta_h), \\ (\alpha \cdot f)(\theta_h) &= (f_2(\theta_l) - f_2(\theta_h))f_1(\theta_h) - (f_1(\theta_l) - f_1(\theta_h))f_2(\theta_h) = f_1(\theta_h)f_2(\theta_l) - f_1(\theta_l)f_2(\theta_h), \text{ and} \\ (\alpha \cdot f)(\theta_m) &= (f_2(\theta_l) - f_2(\theta_h))f_1(\theta_m) - (f_1(\theta_l) - f_1(\theta_h))f_2(\theta_m) = 0. \end{aligned}$$

As $\alpha \cdot f$ is single crossing, it follows that $(\alpha \cdot f)(\theta_l) = (\alpha \cdot f)(\theta_h) = 0$, as we wanted to show.

(\Leftarrow) Assume that f_1 and f_2 are each single crossing. We provide a proof for the case in which f_1 ratio dominates f_2 , and omit the other case's analogous proof. For any $\alpha \in \mathbb{R}^2$, we prove that $\alpha \cdot f$ is single crossing. We may assume that $\alpha \neq 0$, as the result is trivial otherwise.

Suppose, towards contradiction, that $\alpha \cdot f$ is not single crossing. We will use:

Claim 6. *There exist $\theta_l < \theta_m < \theta_h$ such that*

$$\text{sign}[(\alpha \cdot f)(\theta_l)] < \text{sign}[(\alpha \cdot f)(\theta_m)] \text{ and } \text{sign}[(\alpha \cdot f)(\theta_m)] > \text{sign}[(\alpha \cdot f)(\theta_h)], \quad \text{or} \quad (15)$$

$$\text{sign}[(\alpha \cdot f)(\theta_l)] > \text{sign}[(\alpha \cdot f)(\theta_m)] \text{ and } \text{sign}[(\alpha \cdot f)(\theta_m)] < \text{sign}[(\alpha \cdot f)(\theta_h)]. \quad (16)$$

Note that the claim is obvious when (Θ, \leq) is a completely ordered set.

Proof of Claim 6. Since $\alpha \cdot f$ is single crossing neither from below nor from above:

$$\begin{aligned} (\exists \theta_1 < \theta_2) \quad & \text{sign}[(\alpha \cdot f)(\theta_1)] < \text{sign}[(\alpha \cdot f)(\theta_2)], \text{ and} \\ (\exists \theta_3 < \theta_4) \quad & \text{sign}[(\alpha \cdot f)(\theta_3)] > \text{sign}[(\alpha \cdot f)(\theta_4)]. \end{aligned}$$

Let $\Theta_0 \equiv \{\theta_1, \theta_2, \theta_3, \theta_4\}$ and $\bar{\theta}$ and $\underline{\theta}$ be an upper and lower bound of Θ_0 . If $(\alpha \cdot f)(\underline{\theta}) = (\alpha \cdot f)(\bar{\theta}) = 0$, then $(\theta_l, \theta_m, \theta_h) = (\underline{\theta}, \theta_0, \bar{\theta})$ for some $\theta_0 \in \Theta_0$ with $(\alpha \cdot f)(\theta_0) \neq 0$ satisfies either (15) or (16). So assume $(\alpha \cdot f)(\bar{\theta}) \neq 0$, with a similar argument applying for $(\alpha \cdot f)(\underline{\theta}) \neq 0$. If $(\alpha \cdot f)(\bar{\theta}) < 0$, then $(\theta_l, \theta_m, \theta_h) = (\theta_1, \theta_2, \bar{\theta})$ satisfies (15). If $(\alpha \cdot f)(\bar{\theta}) > 0$, then $(\theta_l, \theta_m, \theta_h) = (\theta_3, \theta_4, \bar{\theta})$ satisfies (16). Q.E.D.

First, we consider the case in which $f(\theta) \equiv (f_1(\theta), f_2(\theta))$ for all $\theta \in \{\theta_l, \theta_m, \theta_h\}$ are non-zero vectors. Take any $\theta_1, \theta_2 \in \{\theta_l, \theta_m, \theta_h\}$ such that $\theta_1 < \theta_2$. As f_1 ratio dominates f_2 , by Condition (3), $f(\theta_1)$ moves to $f(\theta_2)$ in a clockwise rotation with an angle less than or equal to 180 degrees. Let r_{12} be the clockwise angle from $f(\theta_1)$ to $f(\theta_2)$. The vector $\alpha \neq 0$ defines a partition of \mathbb{R}^2 into $\mathbb{R}_{\alpha,+}^2 \equiv \{x \in \mathbb{R}^2 : \alpha \cdot x > 0\}$, $\mathbb{R}_{\alpha,0}^2 \equiv \{x \in \mathbb{R}^2 : \alpha \cdot x = 0\}$, and $\mathbb{R}_{\alpha,-}^2 \equiv \{x \in \mathbb{R}^2 : \alpha \cdot x < 0\}$. In both cases (15) and (16), both $f(\theta_l)$ and $f(\theta_h)$ are not in the same part of the partition that $f(\theta_m)$ belongs to. Thus, $r_{lm} > 0$ and $r_{mh} > 0$. On the other hand, both $f(\theta_l)$ and $f(\theta_h)$ are in the same closed half-space, either $\mathbb{R}_{\alpha,+}^2 \cup \mathbb{R}_{\alpha,0}^2$ or $\mathbb{R}_{\alpha,-}^2 \cup \mathbb{R}_{\alpha,0}^2$, and $f(\theta_m)$ is in the other closed half-space, either $\mathbb{R}_{\alpha,-}^2 \cup \mathbb{R}_{\alpha,0}^2$ or $\mathbb{R}_{\alpha,+}^2 \cup \mathbb{R}_{\alpha,0}^2$, respectively. Thus, $r_{lh} \geq 180$. Since Condition (3) implies $r_{lh} \leq 180$, it follows that $r_{lh} = 180$. Hence, $f(\theta_l)$ and $f(\theta_m)$ are linearly independent ($0 < r_{lm} < 180$), and similarly for $f(\theta_m)$ and $f(\theta_h)$. However, $f(\theta_l)$ and $f(\theta_h)$ are linearly dependent ($r_{lh} = 180$). This contradicts (4).

Second, suppose either $f(\theta_l) = 0$ or $f(\theta_h) = 0$. We provide the argument assuming $f(\theta_l) = 0$; it is analogous if $f(\theta_h) = 0$. Under either (15) or (16), $f(\theta_m) \neq 0$. By Condition (4), $f(\theta_m)$ and $f(\theta_h)$ are linearly dependent. In particular, because $f(\theta_m) \neq 0$, there exists a unique $\lambda \in \mathbb{R}$ such that $f(\theta_h) = \lambda f(\theta_m)$. Under either (15) or (16), $\lambda \leq 0$, which contradicts the hypothesis that f_1 and f_2 are single crossing.

Last, suppose $f(\theta_l) \neq 0$, $f(\theta_m) = 0$, and $f(\theta_h) \neq 0$. By Condition (4), $f(\theta_l)$ and $f(\theta_h)$ are linearly dependent. Hence, there exists a unique $\lambda \in \mathbb{R}$ such that $f(\theta_l) = \lambda f(\theta_h)$. Under either (15) or (16), $\lambda > 0$, which contradicts the hypothesis that f_1 and f_2 are single crossing.

A.2. Proof of Proposition 2

The result is trivial if $|X| = 1$ and it is equivalent to Lemma 1 if $|X| = 2$, so we may assume $|X| \geq 3$. The proof is also straightforward if all functions $f(x, \cdot) : \Theta \rightarrow \mathbb{R}$ are multiples of one function $f(x_1, \cdot)$, i.e., if there is x_1 such that $(\exists \lambda : X \rightarrow \mathbb{R})(\forall x)f(x, \cdot) =$

$\lambda(x)f(x_1, \cdot)$. Thus, we further assume there exist x', x'' such that $f(x', \cdot) : \Theta \rightarrow \mathbb{R}$ and $f(x'', \cdot) : \Theta \rightarrow \mathbb{R}$ are linearly independent.

(\Leftarrow) Assume $f(x_1, \cdot)$ and $f(x_2, \cdot)$ are (i) each single crossing and (ii) ratio ordered, and that there are functions $\lambda_1, \lambda_2 : X \rightarrow \mathbb{R}$ such that $(\forall x) f(x, \cdot) = \lambda_1(x)f(x_1, \cdot) + \lambda_2(x)f(x_2, \cdot)$. Then, for any function $\mu : X \rightarrow \mathbb{R}$ with finite support,

$$\int_X f(x, \theta) d\mu = \int_X \lambda_1(x)f(x_1, \theta) + \lambda_2(x)f(x_2, \theta) d\mu = \sum_{i=1,2} \left(\int_X \lambda_i(x) d\mu \right) f(x_i, \theta),$$

which is single crossing in θ by [Lemma 1](#).

(\Rightarrow) Take any $x_1, x_2 \in X$ such that $f_1(\cdot) \equiv f(x_1, \cdot)$ and $f_2(\cdot) \equiv f(x_2, \cdot)$ are linearly independent. Then, by [Lemma 1](#), f_1 and f_2 are each single crossing and ratio ordered, as their linear combinations are all single crossing.

For every θ', θ'' , let

$$M_{\theta', \theta''} \equiv \begin{bmatrix} f_1(\theta') & f_2(\theta') \\ f_1(\theta'') & f_2(\theta'') \end{bmatrix}.$$

We first prove the following claim:

Claim 7. *There exists $\theta_l < \theta_h$ such that $\text{rank}[M_{\theta_l, \theta_h}] = 2$.*

Proof of Claim 7. As f_1 and f_2 are linearly independent, there exists θ_0 such that $f_2(\theta_0) \neq 0$. Let $\lambda \equiv -\frac{f_1(\theta_0)}{f_2(\theta_0)}$. Then, for some θ_λ , $f_1(\theta_\lambda) + \lambda f_2(\theta_\lambda) \neq 0$ and $\text{rank}[M_{\theta_0, \theta_\lambda}] = 2$.

The proof is complete if $\theta_0 > \theta_\lambda$ or $\theta_0 < \theta_\lambda$. If not, take a lower and upper bound, $\underline{\theta}$ and $\bar{\theta}$, of $\{\theta_0, \theta_\lambda\}$. Then $\text{rank}[M_{\underline{\theta}, \bar{\theta}}] = 2$. For otherwise, there exists $\alpha \in \mathbb{R}^2 \setminus \{0\}$ such that $M_{\underline{\theta}, \bar{\theta}}\alpha = 0$. As θ_0 and θ_λ are between $\underline{\theta}$ and $\bar{\theta}$, and $\alpha_1 f_1 + \alpha_2 f_2$ is single crossing, we have $M_{\theta_0, \theta_\lambda}\alpha = 0$, which contradicts $\text{rank}[M_{\theta_0, \theta_\lambda}] = 2$. Q.E.D.

Now take any $x \in X$, the function $f_x(\cdot) \equiv f(x, \cdot)$, and θ_l, θ_h in [Claim 7](#). As $\text{rank}[M_{\theta_l, \theta_h}] = 2$, the system

$$\begin{bmatrix} f_x(\theta_l) \\ f_x(\theta_h) \end{bmatrix} = \begin{bmatrix} f_1(\theta_l) & f_2(\theta_l) \\ f_1(\theta_h) & f_2(\theta_h) \end{bmatrix} \begin{bmatrix} \lambda_1 \\ \lambda_2 \end{bmatrix} \quad (17)$$

has a unique solution $\lambda \in \mathbb{R}^2$. We will show that $f_x = \lambda_1 f_1 + \lambda_2 f_2$.

Suppose, towards contradiction, there exists θ_λ such that

$$f_x(\theta_\lambda) \neq \lambda_1 f_1(\theta_\lambda) + \lambda_2 f_2(\theta_\lambda). \quad (18)$$

Let $\underline{\theta}$ and $\bar{\theta}$ respectively be a lower and an upper bound of $\{\theta_l, \theta_h, \theta_\lambda\}$. If $\text{rank}[M_{\underline{\theta}, \bar{\theta}}] < 2$, there is $\lambda' \in \mathbb{R}^2 \setminus \{0\}$ such that $\lambda'_1 f_1(\theta) + \lambda'_2 f_2(\theta) = 0$ for $\theta = \underline{\theta}, \bar{\theta}$. As $\lambda'_1 f_1 + \lambda'_2 f_2$ is single crossing, we have $\lambda'_1 f_1(\theta) + \lambda'_2 f_2(\theta) = 0$ for $\theta = \theta_l, \theta_h$, which contradicts $\text{rank}[M_{\theta_l, \theta_h}] = 2$.³²

If, on the other hand, $\text{rank}[M_{\underline{\theta}, \bar{\theta}}] = 2$, the system

$$\begin{bmatrix} f_x(\underline{\theta}) \\ f_x(\bar{\theta}) \end{bmatrix} = \begin{bmatrix} f_1(\underline{\theta}) & f_2(\underline{\theta}) \\ f_1(\bar{\theta}) & f_2(\bar{\theta}) \end{bmatrix} \begin{bmatrix} \lambda'_1 \\ \lambda'_2 \end{bmatrix}$$

has a unique solution $\lambda' \in \mathbb{R}^2$. As $f_x - \lambda'_1 f_1 - \lambda'_2 f_2$ is single crossing,

$$f_x(\theta_l) = \lambda'_1 f_1(\theta_l) + \lambda'_2 f_2(\theta_l) \quad \text{and} \quad f_x(\theta_h) = \lambda'_1 f_1(\theta_h) + \lambda'_2 f_2(\theta_h), \quad \text{and} \quad (19)$$

$$f_x(\theta_\lambda) = \lambda'_1 f_1(\theta_\lambda) + \lambda'_2 f_2(\theta_\lambda). \quad (20)$$

(19) implies that λ' solves (17). As the unique solution to (17) was λ , it follows that $\lambda' = \lambda$. But then (18) and (20) are in contradiction. Therefore, there exist $\lambda_1, \lambda_2 : X \rightarrow \mathbb{R}$ such that

$$(\forall x, \theta) \quad f(x, \theta) = \lambda_1(x) f(x_1, \theta) + \lambda_2(x) f(x_2, \theta).$$

A.3. Proof of Theorem 1

(\Leftarrow) Suppose $v(a, \theta) = g_1(a) f_1(\theta) + g_2(a) f_2(\theta) + c(\theta)$, with $f_1, f_2 : \Theta \rightarrow \mathbb{R}$ each single crossing and ratio ordered. Then, for any $P, Q \in \Delta A$,

$$D_{P, Q}(\theta) = \left[\int_A g_1(a) dP - \int_A g_1(a) dQ \right] f_1(\theta) + \left[\int_A g_2(a) dP - \int_A g_2(a) dQ \right] f_2(\theta),$$

which is single crossing by Lemma 1.

(\Rightarrow) Assume, without loss of generality, that $|A| \geq 2$. Take any $a_0 \in A$, and define $A' \equiv A \setminus \{a_0\}$. Define $f : A \times \Theta \rightarrow \mathbb{R}$ as $f(a, \theta) \equiv v(a, \theta) - v(a_0, \theta)$. It is clear that $(\forall a \in A') f(a, \cdot)$ is single crossing: consider the expectational difference with probability distributions that put probability one on a and a_0 respectively.

We will show that, in some sense, every function $\mu' : A' \rightarrow \mathbb{R}$ can be represented as a multiple of the difference between two probability distributions $P, Q \in \Delta A$, and then apply Proposition 2.

³²The function $\lambda'_1 f_1 + \lambda'_2 f_2$ must be single crossing because we can consider $\mu : X \rightarrow \mathbb{R}$ such that $\mu(x_1) = \lambda'_1, \mu(x_2) = \lambda'_2$, and $\mu(x) = 0$ for any $x \neq x_1, x_2$. We use similar reasoning subsequently.

For any function $\mu' : A' \rightarrow \mathbb{R}$, we define a function $\mu : A \rightarrow \mathbb{R}$ as an extension of μ' :

$$\mu(a_0) \equiv - \sum_{a \in A'} \mu'(a), \text{ and } (\forall a \in A') \mu(a) \equiv \mu'(a).$$

In a sense, we let a_0 absorb the function values on A' . In particular, note that

$$\sum_{a \in A} \mu(a) = \mu(a_0) + \sum_{a \in A'} \mu(a) = 0.$$

We construct the Hahn-Jordan decomposition (μ_+, μ_-) of μ . That is, we define functions $\mu_+, \mu_- : A \rightarrow \mathbb{R}_+$ by $(\forall a \in A) \mu_+(a) \equiv \max\{\mu(a), 0\}$ and $\mu_-(a) \equiv -\min\{\mu(a), 0\}$. Then, μ_+ and μ_- are two positive functions with finite support such that $\mu = \mu_+ - \mu_-$. Let $M \equiv \sum_{a \in A} \mu_+(a) = \sum_{a \in A} \mu_-(a)$. If $M = 0$, pick an arbitrary $P \in \Delta A$ and let $Q = P$. If $M > 0$, define $P, Q \in \Delta A$ with probability mass functions p, q such that for any $a \in A$,

$$p(a) = \frac{\mu_+(a)}{M} \quad \text{and} \quad q(a) = \frac{\mu_-(a)}{M}.$$

Note that P and Q are probability distributions in ΔA : both are induced by positive real-valued functions μ_+ and μ_- with finite support, and $\sum_{a \in A} p(a) = \sum_{a \in A} q(a) = 1$.

It follows that

$$\begin{aligned} \int_{A'} f(a, \theta) d\mu' &= \int_A f(a, \theta) d\mu \quad (\text{because } f(a_0, \theta) = 0) \\ &= \int_A v(a, \theta) d\mu - v(a_0, \theta) \mu(A) \\ &= \int_A v(a, \theta) d\mu_+ - \int_A v(a, \theta) d\mu_- \quad (\text{as } \mu(A) = 0) \\ &= MD_{P,Q}(\theta). \end{aligned}$$

Thus, if v has SCED, then $f : A' \times \Theta \rightarrow \mathbb{R}$ is linear combinations SC-preserving. By [Proposition 2](#), there exist $a_1, a_2 \in A'$ and $\lambda_1, \lambda_2 : A' \rightarrow \mathbb{R}$ such that (i) $f(a_1, \theta)$ and $f(a_2, \theta)$ are each single crossing and ratio ordered, and (ii) $(\forall a \in A') f(a, \cdot) = \lambda_1(a)f(a_1, \cdot) + \lambda_2(a)f(a_2, \cdot)$. Hence, there exist functions $g_1, g_2 : A \rightarrow \mathbb{R}$ with $g_1(a_0) = g_2(a_0) = 0$ such that $(\forall a \in A) f(a, \cdot) = g_1(a)f(a_1, \cdot) + g_2(a)f(a_2, \cdot)$, or equivalently,

$$(\forall a, \theta) \quad v(a, \theta) = g_1(a)f(a_1, \theta) + g_2(a)f(a_2, \theta) + v(a_0, \theta).$$

A.4. Proof of Proposition 1

If $|\Theta| \leq 2$, then the proof is trivial, so assume $|\Theta| \geq 3$. The “if” direction of the result follows directly from Theorem 1: if v has a positive affine transformation \hat{v} of the form (6), then v , as a positive affine transformation of \hat{v} , has SCED.

For the “only if” direction, take any v that has SCED. Following the form given in Theorem 1, a positive affine transformation of v is

$$\hat{v}(a, \theta) = g_1(a)f_1(\theta) + g_2(a)f_2(\theta),$$

where $f_1, f_2 : \Theta \rightarrow \mathbb{R}$ are each single crossing and ratio ordered.

First, we consider the case in which $f(\underline{\theta})$ and $f(\bar{\theta})$ are linearly dependent. Assume, with a positive affine transformation of \hat{v} , that the length of the vector $f(\theta) \equiv (f_1(\theta), f_2(\theta))$ in \mathbb{R}^2 is either 0 or 1 for every θ . If $f(\underline{\theta}) = f(\bar{\theta}) = 0$, then because f_1 and f_2 are each single crossing, we have $(\forall \theta) f_1(\theta) = f_2(\theta) = 0$ and $(\forall a, \theta) \hat{v}(a, \theta) = 0$. We can easily now rewrite \hat{v} in the form (6), with $\lambda : \Theta \rightarrow [0, 1]$ increasing.

Suppose $f(\bar{\theta}) \neq 0$; we omit the analogous proof for the case of $f(\underline{\theta}) \neq 0$. By Condition (4) of ratio ordering, for every θ , the vector $f(\theta) \in \mathbb{R}^2$ is linearly dependent of $f(\bar{\theta})$. As $(\forall \theta) \|f(\theta)\| \in \{0, 1\}$, there exists $\lambda : \Theta \rightarrow \{-1, 0, 1\}$ such that $(\forall \theta) f(\theta) = \lambda(\theta)f(\bar{\theta})$. Note that λ is increasing because f_1 and f_2 are each single crossing. If either $\lambda(\underline{\theta}) = 0$ (and so $(\forall a) \hat{v}(a, \underline{\theta}) = 0$) or $\lambda(\underline{\theta}) = 1$ (and so $(\forall \theta) \lambda(\theta) = 1$), then

$$\hat{v}(a, \theta) = \lambda(\theta)\hat{v}(a, \bar{\theta}) + (1 - \lambda(\theta))\hat{v}(a, \underline{\theta}),$$

with the last term equal to zero. If, on the other hand, $\lambda(\underline{\theta}) = -1$, then

$$\begin{aligned} \hat{v}(a, \theta) &= \lambda(\theta)\hat{v}(a, \bar{\theta}) = \frac{\lambda(\theta) + 1}{2}\hat{v}(a, \bar{\theta}) + \frac{\lambda(\theta) - 1}{2}(-\hat{v}(a, \underline{\theta})) \\ &= \frac{\lambda(\theta) + 1}{2}\hat{v}(a, \bar{\theta}) + \left(1 - \frac{\lambda(\theta) + 1}{2}\right)\hat{v}(a, \underline{\theta}). \end{aligned}$$

Next, suppose that the vectors $f(\underline{\theta}), f(\bar{\theta}) \in \mathbb{R}^2$ are linearly independent, so the angle between the vectors is strictly less than 180 degrees. As f_1 and f_2 are ratio ordered, for each θ there exists $\alpha(\theta), \beta(\theta) \in \mathbb{R}_+$ such that

$$f(\theta) = \alpha(\theta)f(\bar{\theta}) + \beta(\theta)f(\underline{\theta}),$$

or equivalently,

$$\hat{v}(a, \theta) = \alpha(\theta)\hat{v}(a, \bar{\theta}) + \beta(\theta)\hat{v}(a, \underline{\theta}).$$

By Condition (4), $f(\theta) \neq 0$, which implies that $\alpha(\theta) + \beta(\theta) > 0$. A positive affine transformation of dividing $\hat{v}(\cdot, \theta)$ by $\alpha(\theta) + \beta(\theta)$ results in the form (6), where $\lambda(\theta) \equiv \frac{\alpha(\theta)}{\alpha(\theta) + \beta(\theta)} \in [0, 1]$.

To prove that the function λ is increasing, take θ_1, θ_2 such that $\underline{\theta} \leq \theta_1 \leq \theta_2 \leq \bar{\theta}$. To reduce notation below, let $\alpha_i \equiv \alpha(\theta_i)$ and $\beta_i \equiv \beta(\theta_i)$ for $i = 1, 2$. We must show that $\frac{\alpha_1}{\alpha_1 + \beta_1} \leq \frac{\alpha_2}{\alpha_2 + \beta_2}$, or equivalently that $\alpha_1\beta_2 \leq \alpha_2\beta_1$. Suppose f_1 ratio dominates f_2 ; the other case is analogous. Then $f_1(\theta_1)f_2(\theta_2) \leq f_1(\theta_2)f_2(\theta_1)$, and hence

$$(\alpha_1 f_1(\bar{\theta}) + \beta_1 f_1(\underline{\theta})) (\alpha_2 f_2(\bar{\theta}) + \beta_2 f_2(\underline{\theta})) \leq (\alpha_2 f_1(\bar{\theta}) + \beta_2 f_1(\underline{\theta})) (\alpha_1 f_2(\bar{\theta}) + \beta_1 f_2(\underline{\theta})),$$

or equivalently,

$$(\alpha_1\beta_2 - \alpha_2\beta_1) (f_1(\bar{\theta})f_2(\underline{\theta}) - f_1(\underline{\theta})f_2(\bar{\theta})) \leq 0.$$

Note that $f_1(\bar{\theta})f_2(\underline{\theta}) - f_1(\underline{\theta})f_2(\bar{\theta}) > 0$ because f_1 ratio dominates f_2 , and $f(\underline{\theta})$ and $f(\bar{\theta})$ are linearly independent. Hence, $\alpha_1\beta_2 \leq \alpha_2\beta_1$.

A.5. Proof of Corollary 1

It is clear from Theorem 1 that $v(a, \theta) = -|a - \theta|^2 = -a^2 + 2a\theta - \theta^2$ has SCED, as $f_1(\theta) = -1$ and $f_2(\theta) = 2\theta$ are each single crossing and ratio ordered, and we take $g_1(a) = a^2$, $g_2(a) = a$, and $c(\theta) = -\theta^2$.

For the converse, it is sufficient to prove the following claim.

Claim 8. *If there exist $g_1, g_2 : \mathbb{R} \rightarrow \mathbb{R}$ and $f_1, f_2, c : \Theta \rightarrow \mathbb{R}$ such that*

$$v(a, \theta) \equiv -|a - \theta|^z = g_1(a)f_1(\theta) + g_2(a)f_2(\theta) + c(\theta),$$

then $z = 2$.

Proof of Claim 8. Fix $a_0 \in \mathbb{R}$ and define $\tilde{v}(a, \theta) \equiv v(a, \theta) - v(a_0, \theta) = \tilde{g}_1(a)f_1(\theta) + \tilde{g}_2(a)f_2(\theta)$, where $\tilde{g}_1(a) \equiv g_1(a) - g_1(a_0)$ and $\tilde{g}_2 \equiv g_2(a) - g_2(a_0)$. Fix any $\theta_l < \theta_m < \theta_h$. There exists $(\lambda_l, \lambda_m, \lambda_h) \in \mathbb{R}^3 \setminus \{0\}$ such that

$$\begin{bmatrix} f_1(\theta_l) & f_1(\theta_m) & f_1(\theta_h) \\ f_2(\theta_l) & f_2(\theta_m) & f_2(\theta_h) \end{bmatrix} \begin{bmatrix} \lambda_l \\ \lambda_m \\ \lambda_h \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

Hence, for every $a \in \mathbb{R}$,

$$\begin{aligned} h(a) &\equiv \lambda_l \tilde{v}(a, \theta_l) + \lambda_m \tilde{v}(a, \theta_m) + \lambda_h \tilde{v}(a, \theta_h) \\ &= \begin{bmatrix} \tilde{g}_1(a) & \tilde{g}_2(a) \end{bmatrix} \begin{bmatrix} f_1(\theta_l) & f_1(\theta_m) & f_1(\theta_h) \\ f_2(\theta_l) & f_2(\theta_m) & f_2(\theta_h) \end{bmatrix} \begin{bmatrix} \lambda_l \\ \lambda_m \\ \lambda_h \end{bmatrix} = 0. \end{aligned}$$

We hereafter consider $\lambda_l \neq 0$ (and omit the proofs for the other two cases, $\lambda_m \neq 0$ and $\lambda_h \neq 0$, which are analogous). The previous equation implies that for any $a \in \mathbb{R}$,

$$\tilde{v}(a, \theta_l) = -\frac{\lambda_m}{\lambda_l} \tilde{v}(a, \theta_m) - \frac{\lambda_h}{\lambda_l} \tilde{v}(a, \theta_h). \quad (21)$$

At any $a < \theta$, $\tilde{v}(a, \theta) = -(\theta - a)^z - v(a_0, \theta)$ is differentiable in a , and hence (21) implies that the partial derivative $\tilde{v}_a(a, \theta_l)$ exists at $a = \theta_l$. Thus, the right partial derivative $\lim_{\varepsilon \downarrow 0} \frac{\tilde{v}(\theta_l + \varepsilon, \theta_l) - \tilde{v}(\theta_l, \theta_l)}{\varepsilon} = -\lim_{\varepsilon \downarrow 0} \varepsilon^{z-1}$ must equal the left partial derivative $\lim_{\varepsilon \downarrow 0} \frac{\tilde{v}(\theta_l - \varepsilon, \theta_l) - \tilde{v}(\theta_l, \theta_l)}{-\varepsilon} = \lim_{\varepsilon \downarrow 0} \varepsilon^{z-1}$, which implies $\lim_{\varepsilon \downarrow 0} \varepsilon^{z-1} = 0$, and thus $z > 1$.

Now suppose to contradiction that $z \neq 2$. At any $a > \theta_h$, (21) and $\tilde{v}(a, \theta) = -(a - \theta)^z - v(a_0, \theta)$ imply

$$-\lambda_l(a - \theta_l)^z = \lambda_m(a - \theta_m)^z + \lambda_h(a - \theta_h)^z + (\lambda_m + \lambda_h - \lambda_l)v(a_0, \theta),$$

and hence, differentiating with respect to a and simplifying using $z > 1$ and $z \neq 2$:

$$-\lambda_l(a - \theta_l)^{z-1} = \lambda_m(a - \theta_m)^{z-1} + \lambda_h(a - \theta_h)^{z-1}, \quad (22)$$

$$-\lambda_l(a - \theta_l)^{z-2} = \lambda_m(a - \theta_m)^{z-2} + \lambda_h(a - \theta_h)^{z-2}, \quad (23)$$

$$-\lambda_l(a - \theta_l)^{z-3} = \lambda_m(a - \theta_m)^{z-3} + \lambda_h(a - \theta_h)^{z-3}. \quad (24)$$

It follows that $\lambda_m \lambda_h \neq 0$: if, for example, $\lambda_m = 0$, then (22) implies $\lambda_h \neq 0$ (as $\lambda_l \neq 0$), and then (22) and (23) imply $a - \theta_l = a - \theta_h$ for all $a > \theta_h$, contradicting $\theta_l < \theta_h$. Since $((a - \theta_l)^{z-2})^2 = (a - \theta_l)^{z-1}(a - \theta_l)^{z-3}$, we manipulate the right-hand sides of (22)–(24) to obtain

$$2\lambda_m \lambda_h (a - \theta_m)^{z-2} (a - \theta_h)^{z-2} = \lambda_m \lambda_h \left((a - \theta_m)^{z-1} (a - \theta_h)^{z-3} + (a - \theta_m)^{z-3} (a - \theta_h)^{z-1} \right),$$

which simplifies, using $\lambda_m \lambda_h \neq 0$, to

$$2 = \frac{a - \theta_h}{a - \theta_m} + \frac{a - \theta_m}{a - \theta_h}.$$

Therefore, $a - \theta_h = a - \theta_m$ for all $a > \theta_h$, contradicting $\theta_m < \theta_h$.

Q.E.D.

A.6. Proof of Corollary 2

We only prove part (1) of the corollary, as it implies part (2).

If f is monotonic, its ratio dominates any positive constant function. It follows from Theorem 1 that $v((q, t), \theta)$ has SCED.

To prove the converse, suppose, towards contradiction, that f is not monotonic. Then there exist $\theta_l < \theta_m < \theta_h$ such that either $f(\theta_m) > \max\{f(\theta_l), f(\theta_h)\}$ or $f(\theta_m) < \min\{f(\theta_l), f(\theta_h)\}$. Let us assume the first of these two cases; the argument is analogous for the other case. Take any $z \in \mathbb{R}$ such that $f(\theta_m) > z > \max\{f(\theta_l), f(\theta_h)\}$, any $q_1, q_2 \in \mathbb{R}$ such that $g(q_1) - g(q_2) > 0$, and $t_1, t_2 \in \mathbb{R}$ such that $(g(q_1) - g(q_2))z - (t_1 - t_2) = 0$. The expectational difference between degenerate lotteries on $a_1 = (q_1, t_1)$ and $a_2 = (q_2, t_2)$,

$$D_{1,2}(\theta) \equiv v(a_1, \theta) - v(a_2, \theta) = (g(q_1) - g(q_2))f(\theta) - (t_1 - t_2)$$

is not single crossing as $D_{1,2}(\theta_m) > 0 > \max\{D_{1,2}(\theta_l), D_{1,2}(\theta_h)\}$.

B. Proofs for Strict Single Crossing (Subsection 2.2)

Similar to the proof of Theorem 1, our proof of Theorem 2 requires conditions ensuring that arbitrary linear combinations of functions are strictly single crossing. We state and discuss the analogs of Lemma 1 and Proposition 2 in Appendix B.1; their proofs are in Appendix B.2 and Appendix B.3 respectively. The proof of Theorem 2 then follows in Appendix B.4.

B.1. Aggregating Strictly Single-Crossing Functions

Lemma 3. *Let $f_1, f_2 : \Theta \rightarrow \mathbb{R}$. The linear combination $\alpha_1 f_1(\theta) + \alpha_2 f_2(\theta)$ is strictly single crossing $\forall \alpha \in \mathbb{R}^2 \setminus \{0\}$ if and only if f_1 and f_2 are strictly ratio ordered.*

Besides the change to strict single crossing and, correspondingly, strict ratio ordering, Lemma 3 has two other differences from Lemma 1. First, we rule out $(\alpha_1, \alpha_2) = 0$; this is unavoidable because a zero function is not strictly single crossing. Second, and more important, there is no explicit mention in Lemma 3 that f_1 and f_2 are each strictly single crossing. It turns out—as elaborated in the Lemma’s proof—that when two functions are strictly ratio ordered, each of them must be strictly single crossing.

To extend [Lemma 3](#) to more than two functions, we say that $f : X \times \Theta \rightarrow \mathbb{R}$ is **linear combinations SSC-preserving** if $\int_X f(x, \theta) d\mu$ is either a zero function or strictly single crossing in θ for every function $\mu : X \rightarrow \mathbb{R}$ with finite support. Parallel to [Proposition 2](#):

Proposition 6. *Let $f : X \times \Theta \rightarrow \mathbb{R}$ for some set X , and assume there exist $x_1, x_2 \in X$ such that $f(x_1, \cdot) : \Theta \rightarrow \mathbb{R}$ and $f(x_2, \cdot) : \Theta \rightarrow \mathbb{R}$ are linearly independent. The function f is linear combinations SSC-preserving if and only if there exist $\lambda_1, \lambda_2 : X \rightarrow \mathbb{R}$ such that*

1. $f(x_1, \cdot) : \Theta \rightarrow \mathbb{R}$ and $f(x_2, \cdot) : \Theta \rightarrow \mathbb{R}$ are strictly ratio ordered, and
2. $(\forall x) f(x, \cdot) = \lambda_1(x)f(x_1, \cdot) + \lambda_2(x)f(x_2, \cdot)$.

For the “if” direction of [Proposition 6](#), the existence of a pair of linearly independent functions need not be assumed, because strict ratio ordering implies linear independence. However, without that hypothesis, the “only if” direction would fail: given $X = \{x_1, x_2\}$, and $f(x_1, \cdot) = 2f(x_2, \cdot)$ with $f(x_1, \cdot)$ strictly single crossing, the function f is linear combinations SSC-preserving even though $f(x_1, \cdot)$ and $f(x_2, \cdot)$ are not strictly ratio ordered.

B.2. Proof of [Lemma 3](#)

When $|\Theta| \leq 2$.

If $|\Theta| = 1$, the proof is trivial as all functions are strictly single crossing and every pair of f_1, f_2 satisfy strict ratio ordering. So assume $|\Theta| = 2$ and denote $\Theta = \{\theta_l, \theta_h\}$; without loss, we may assume $\theta_h > \theta_l$ because of our maintained assumption that upper and lower bounds exist for all pairs.

(\implies) Either $(f_1(\theta_l), f_2(\theta_l)) \neq 0$ or $(f_1(\theta_h), f_2(\theta_h)) \neq 0$: otherwise, for every $\alpha \in \mathbb{R}^2 \setminus \{0\}$, $(\alpha \cdot f)(\theta_l) = (\alpha \cdot f)(\theta_h) = 0$, and hence $\alpha \cdot f$ is a zero function, which is not strictly single crossing. Assume $(f_1(\theta_l), f_2(\theta_l)) \neq 0$; the proof for the other case is analogous. Let $\alpha_l \equiv (f_2(\theta_l), -f_1(\theta_l))$ and consider $(\alpha_l \cdot f)(\theta) = f_2(\theta_l)f_1(\theta) - f_1(\theta_l)f_2(\theta)$. We have $(\alpha_l \cdot f)(\theta_l) = 0$ and, by strict single crossing of $\alpha_l \cdot f$, $(\alpha_l \cdot f)(\theta_h) \neq 0$. That is, $f_2(\theta_l)f_1(\theta_h) \neq f_1(\theta_l)f_2(\theta_h)$, which means that f_1 and f_2 are strictly ratio ordered.

(\impliedby) For any $\alpha \in \mathbb{R}^2 \setminus \{0\}$, $\alpha \cdot f$ is not strictly single crossing if and only if $(\alpha \cdot f)(\theta_l) = (\alpha \cdot f)(\theta_h) = 0$. This implies $\alpha_1 f_1(\theta_l) = -\alpha_2 f_2(\theta_l)$ and $\alpha_1 f_1(\theta_h) = -\alpha_2 f_2(\theta_h)$, and hence

$$\begin{aligned} \alpha_1 f_1(\theta_l) f_2(\theta_h) &= -\alpha_2 f_2(\theta_l) f_2(\theta_h) = \alpha_1 f_1(\theta_h) f_2(\theta_l) \quad \text{and} \\ \alpha_2 f_1(\theta_l) f_2(\theta_h) &= -\alpha_1 f_1(\theta_l) f_1(\theta_h) = \alpha_2 f_1(\theta_h) f_2(\theta_l). \end{aligned}$$

As $(\alpha_1, \alpha_2) \neq 0$, $f_1(\theta_l)f_2(\theta_h) = f_1(\theta_h)f_2(\theta_l)$, contradicting strict ratio ordering of f_1 and f_2 .

When $|\Theta| \geq 3$.

(\implies) Suppose, towards contradiction, that f_1 and f_2 are not strictly ratio ordered:

$$\begin{aligned} (\exists \theta_l < \theta_h) \quad f_1(\theta_l)f_2(\theta_h) &\leq f_1(\theta_h)f_2(\theta_l) \quad \text{and} \\ (\exists \theta' < \theta'') \quad f_1(\theta')f_2(\theta'') &\geq f_1(\theta'')f_2(\theta'). \end{aligned} \tag{25}$$

Take any upper bound $\bar{\theta}$ of $\{\theta_l, \theta_h, \theta', \theta''\}$. Letting $\alpha_l \equiv (f_2(\theta_l), -f_1(\theta_l))$, it holds that $\alpha_l \cdot f$ is strictly single crossing only from below, as $(\alpha_l \cdot f)(\theta_l) = (f_2(\theta_l), -f_1(\theta_l)) \cdot (f_1(\theta_l), f_2(\theta_l)) = 0$ and by (25), $(\alpha_l \cdot f)(\theta_h) \geq 0$. Hence $(\alpha_l \cdot f)(\bar{\theta}) \geq 0$. Analogously, letting $\alpha' \equiv (f_2(\theta'), -f_1(\theta'))$, we conclude that $(\alpha' \cdot f)(\bar{\theta}) \leq 0$. Now let $\bar{\alpha} \equiv (f_2(\bar{\theta}), -f_1(\bar{\theta}))$. It follows that

$$\begin{aligned} (\bar{\alpha} \cdot f)(\theta_l) &= (f_2(\bar{\theta}), -f_1(\bar{\theta})) \cdot (f_1(\theta_l), f_2(\theta_l)) = -(\alpha_l \cdot f)(\bar{\theta}) \leq 0, \\ (\bar{\alpha} \cdot f)(\theta') &= (f_2(\bar{\theta}), -f_1(\bar{\theta})) \cdot (f_1(\theta'), f_2(\theta')) = -(\alpha' \cdot f)(\bar{\theta}) \geq 0, \text{ and} \\ (\bar{\alpha} \cdot f)(\bar{\theta}) &= 0. \end{aligned}$$

Therefore, $\bar{\alpha} \cdot f$ is not strictly single crossing.

(\Leftarrow) We provide a proof for the case in which f_1 strictly ratio dominates f_2 , and omit the other case's analogous proof. For any $\alpha \in \mathbb{R}^2 \setminus \{0\}$, we prove that $\alpha \cdot f$ is single crossing. The argument is very similar to that used in proving [Lemma 1](#), but note that here we do not assume that f_1 and f_2 are each strictly single crossing.

As f_1 strictly ratio dominates f_2 ,

$$(\forall \theta_l < \theta_h) \quad f_1(\theta_l)f_2(\theta_h) < f_1(\theta_h)f_2(\theta_l). \tag{26}$$

Suppose, towards contradiction, that $\alpha \cdot f$ is not strictly single crossing.

Claim: There exist $\theta_l, \theta_m, \theta_h$ with $\theta_l < \theta_m < \theta_h$ such that

$$(\alpha \cdot f)(\theta_l) \leq 0, (\alpha \cdot f)(\theta_m) \geq 0, \text{ and } (\alpha \cdot f)(\theta_h) \leq 0, \quad \text{or} \tag{27}$$

$$(\alpha \cdot f)(\theta_l) \geq 0, (\alpha \cdot f)(\theta_m) \leq 0, \text{ and } (\alpha \cdot f)(\theta_h) \geq 0. \tag{28}$$

Proof of claim: Since $\alpha \cdot f$ is not strictly single crossing either from below or from above,

$$\begin{aligned} (\exists \theta_1 < \theta_2) \quad (\alpha \cdot f)(\theta_1) &\geq 0 \geq (\alpha \cdot f)(\theta_2), \text{ and} \\ (\exists \theta_3 < \theta_4) \quad (\alpha \cdot f)(\theta_3) &\leq 0 \leq (\alpha \cdot f)(\theta_4). \end{aligned}$$

Let $\Theta_0 \equiv \{\theta_1, \theta_2, \theta_3, \theta_4\}$ and let $\bar{\theta}$ and $\underline{\theta}$ be an upper and lower bound of Θ_0 , respectively. Either $(\alpha \cdot f)(\underline{\theta}) \neq 0$ or $(\alpha \cdot f)(\bar{\theta}) \neq 0$, as otherwise $f_1(\underline{\theta})f_2(\bar{\theta}) = f_2(\underline{\theta})f_1(\bar{\theta})$, contradicting (26). Suppose $(\alpha \cdot f)(\bar{\theta}) \neq 0$. If $(\alpha \cdot f)(\bar{\theta}) < 0$, then we choose $(\theta_l, \theta_m, \theta_h) = (\theta_3, \theta_4, \bar{\theta})$, which satisfies (27). If $(\alpha \cdot f)(\bar{\theta}) > 0$, then we choose $(\theta_l, \theta_m, \theta_h) = (\theta_1, \theta_2, \bar{\theta})$, which satisfies (28). A similar argument applies when $(\alpha \cdot f)(\underline{\theta}) \neq 0$. \parallel

Condition (26) implies that $f(\theta) \equiv (f_1(\theta), f_2(\theta)) \neq 0$ for all $\theta \in \{\theta_l, \theta_m, \theta_h\}$. Take any $\theta_1, \theta_2 \in \{\theta_l, \theta_m, \theta_h\}$ such that $\theta_1 < \theta_2$. By (26), $f(\theta_1)$ moves to $f(\theta_2)$ in a clockwise rotation with an angle $r_{12} \in (0, 180)$. Suppose (27) holds; the argument is analogous if (28) holds. It follows from $0 < r_{lh} < 180$, $(\alpha \cdot f)(\theta_l) \leq 0$, and $(\alpha \cdot f)(\theta_h) \leq 0$ that $\{f(\theta_l), f(\theta_h)\} \subseteq \mathbb{R}_{\alpha,-}^2 \cup \mathbb{R}_{\alpha,0}^2$ with $\{f(\theta_l), f(\theta_h)\} \not\subseteq \mathbb{R}_{\alpha,0}^2$.³³ This, together with $r_{lm} > 0$ and $r_{mh} > 0$, implies $f(\theta_m) \in \mathbb{R}_{\alpha,-}^2$, which contradicts (27).

B.3. Proof of Proposition 6

Appendix A.2 proved Proposition 2 assuming certain functions are linearly independent. Essentially the same proof can be used for Proposition 6, replacing statements involving “single crossing” with “either a zero function or strictly single crossing”.

B.4. Proof of Theorem 2

Most statements in the proof of Theorem 1 go through with strict single crossing when we replace “single crossing” with “either a zero function or strictly single crossing”. We need only to rewrite the proof of the “only if” part in the following two special cases:

1. $(\forall a', a'')(\forall \theta) v(a', \theta) = v(a'', \theta)$, or
2. $(\exists a', a'')$ such that (i) $v(a'', \theta) - v(a', \theta)$ is not a zero function of θ , and (ii) $(\forall a) v(a, \theta) - v(a', \theta)$ and $v(a'', \theta) - v(a', \theta)$ are linearly dependent functions of θ .

In the first case, we can write $v(a, \theta)$ in form of (5) where g_1, g_2 are zero functions, $c(\theta) \equiv v(a_0, \theta)$ for any a_0 , $(\forall \theta) f_1(\theta) = 1$, and $f_2(\theta)$ is any strictly decreasing function of θ . Then,

$$(\forall \theta_l < \theta_h) \quad f_1(\theta_l)f_2(\theta_h) = f_2(\theta_h) < f_2(\theta_l) = f_1(\theta_h)f_2(\theta_l).$$

In the second case, for every a , there exists $\lambda \in \mathbb{R}^2 \setminus \{0\}$ such that $\lambda_1 (v(a, \cdot) - v(a', \cdot)) + \lambda_2 (v(a'', \cdot) - v(a', \cdot))$ is a zero function. Note that $\lambda_1 \neq 0$, as otherwise $v(a'', \cdot) - v(a', \cdot)$

³³ Recall that $\mathbb{R}_{\alpha,+}^2 \equiv \{x \in \mathbb{R}^2 : \alpha \cdot x > 0\}$, $\mathbb{R}_{\alpha,0}^2 \equiv \{x \in \mathbb{R}^2 : \alpha \cdot x = 0\}$, and $\mathbb{R}_{\alpha,-}^2 \equiv \{x \in \mathbb{R}^2 : \alpha \cdot x < 0\}$.

would be a zero function. It follows that there exists $\lambda : A \rightarrow \mathbb{R}$ such that

$$(\forall a, \theta) \quad v(a, \theta) - v(a', \theta) = \lambda(a) (v(a'', \theta) - v(a', \theta)),$$

or equivalently,

$$(\forall a, \theta) \quad v(a, \theta) = \lambda(a) (v(a'', \theta) - v(a', \theta)) + v(a', \theta).$$

Note that $v(a'', \theta) - v(a', \theta)$ is a strictly single-crossing function of θ : consider the expectational difference with distributions that put probability one on a'' and a' respectively. If the difference is strictly single crossing from below, we can write $v(a, \theta)$ in the form of (5) where $g_1(a) = \lambda(a)$, $g_2(a) = 0$, $f_1(\theta) = v(a'', \theta) - v(a', \theta)$, and $c(\theta) = v(a', \theta)$. If the difference is strictly single crossing only from above, we let $g_1(a) = -\lambda(a)$ and $f_1(\theta) = v(a', \theta) - v(a'', \theta)$. Now take any strictly increasing function $h : \Theta \rightarrow \mathbb{R}$ and define

$$\hat{h}(\theta) \equiv \begin{cases} -e^{h(\theta)} & \text{if } f_1(\theta) \leq 0 \\ e^{-h(\theta)} & \text{otherwise} \end{cases} \quad \text{and} \quad f_2(\theta) \equiv \begin{cases} \hat{h}(\theta)f_1(\theta) & \text{if } f_1(\theta) \neq 0 \\ 1 & \text{otherwise.} \end{cases}$$

To verify that f_1 and f_2 are strictly ratio ordered, take any $\theta_l < \theta_h$. There are three possibilities to consider:

1. If $f_1(\theta_l)f_1(\theta_h) > 0$, then

$$f_1(\theta_l)f_2(\theta_h) = f_1(\theta_l)f_1(\theta_h)\hat{h}(\theta_h) < f_1(\theta_l)f_1(\theta_h)\hat{h}(\theta_l) = f_1(\theta_h)f_2(\theta_l),$$

as $\hat{h}(\theta)$ is strictly decreasing over $\{\theta \mid f_1(\theta) < 0\}$ and $\{\theta \mid f_1(\theta) > 0\}$.

2. If $f_1(\theta_l)f_1(\theta_h) < 0$, then as $f_1(\theta)$ is strictly single crossing from below, we have $f_1(\theta_l) < 0 < f_1(\theta_h)$. Hence,

$$f_1(\theta_l)f_2(\theta_h) = f_1(\theta_l)f_1(\theta_h)\hat{h}(\theta_h) < 0 < f_1(\theta_l)f_1(\theta_h)\hat{h}(\theta_l) = f_1(\theta_h)f_2(\theta_l).$$

3. If $f_1(\theta_l)f_1(\theta_h) = 0$, then because f_1 is strictly single crossing from below, we have either (i) $f_1(\theta_l) < 0 = f_1(\theta_h)$, which results in $f_1(\theta_l)f_2(\theta_h) = f_1(\theta_l) < 0 = f_1(\theta_h)f_2(\theta_l)$, or (ii) $f_1(\theta_l) = 0 < f_1(\theta_h)$, which results in $f_1(\theta_l)f_2(\theta_h) = 0 < f_1(\theta_h) = f_1(\theta_h)f_2(\theta_l)$.

C. Proofs for Monotone Comparative Statics (Subsection 2.3)

C.1. Proof of Theorem 3

(\implies) Suppose $f : X \times \Theta \rightarrow \mathbb{R}$ has MCS on X with some order \succeq . We first prove the following claim.

Claim 9. *For every $x, x' \in X$, if $\exists \theta_l < \theta_h$ such that $\text{sign}[D_{x,x'}(\theta_l)] < \text{sign}[D_{x,x'}(\theta_h)]$, then $x \succ x'$.*

Proof. Consider $S = \{x, x'\}$. Since $\text{sign}[D_{x,x'}(\theta_l)] \neq \text{sign}[D_{x,x'}(\theta_h)]$, we have

$$\arg \max_{s \in S} f(s, \theta_l) \neq \arg \max_{s \in S} f(s, \theta_h).$$

Thus, either (i) $x \in \arg \max_{s \in S} f(s, \theta_l)$ and $x' \in \arg \max_{s \in S} f(s, \theta_h)$, or (ii) $x' \in \arg \max_{s \in S} f(s, \theta_l)$ and $x \in \arg \max_{s \in S} f(s, \theta_h)$. Since f has MCS on (X, \succeq) , we have $\arg \max_{s \in S} f(s, \theta_h) \succeq_{SSO} \arg \max_{s \in S} f(s, \theta_l)$. Therefore, $x \wedge x' \in \arg \max_{s \in S} f(s, \theta_l)$ and $x \vee x' \in \arg \max_{s \in S} f(s, \theta_h)$, which implies that either $x \succeq x'$ or $x' \succeq x$. Since $x' \neq x$, we have either $x \succ x'$ or $x' \succ x$. If $x' \succ x$, then $x' = x \vee x' \in \arg \max_{s \in S} f(s, \theta_h)$, contradicting $\text{sign}[D_{x,x'}(\theta_l)] < \text{sign}[D_{x,x'}(\theta_h)]$. Thus, $x \succ x'$. Q.E.D.

To show that f has SCD on X , suppose not, per contra. Then there exist $x, x' \in X$ and $\theta_l < \theta_m < \theta_h$ such that either,³⁴

$$\text{sign}[D_{x,x'}(\theta_l)] < \text{sign}[D_{x,x'}(\theta_m)] \quad \text{and} \quad \text{sign}[D_{x,x'}(\theta_m)] > \text{sign}[D_{x,x'}(\theta_h)], \quad \text{or} \quad (29)$$

$$\text{sign}[D_{x,x'}(\theta_l)] > \text{sign}[D_{x,x'}(\theta_m)] \quad \text{and} \quad \text{sign}[D_{x,x'}(\theta_m)] < \text{sign}[D_{x,x'}(\theta_h)]. \quad (30)$$

Given either (29) or (30), Claim 9 implies $x \succ x'$ and $x' \succ x$, a contradiction.

To show that \succeq is a refinement of \succeq_{SCD} , it suffices to show that

$$(\forall x, x' \in X) \quad x \succ_{SCD} x' \implies x \succ x', \quad (31)$$

because both \succeq and \succeq_{SCD} are anti-symmetric. Take any $x, x' \in X$ such that $x \succ_{SCD} x'$. As $D_{x,x'}$ is single crossing only from below, $\exists \theta_l < \theta_h$ such that $\text{sign}[D_{x,x'}(\theta_l)] < \text{sign}[D_{x,x'}(\theta_h)]$. Claim 9 implies $x \succ x'$, which proves (31).

³⁴ The existence of such $\theta_l, \theta_m, \theta_h$ is immediate if (Θ, \leq) is a completely ordered set. More generally, the existence of $\theta_l, \theta_m, \theta_h$ follows from our maintained assumption that every pair in Θ has upper and lower bounds; see Appendix A.1.

(\Leftarrow) Suppose that $f : X \times \Theta \rightarrow \mathbb{R}$ has SCD, and \succeq is a refinement of \succeq_{SCD} . For any $S \subseteq X$, define $C(S) \equiv \bigcup_{\theta \in \Theta} \arg \max_{s \in S} f(s, \theta)$. It is clear that

$$(\forall \theta) \quad \arg \max_{s \in S} f(s, \theta) = \arg \max_{s \in C(S)} f(s, \theta).$$

We claim that $C(S)$ is completely ordered by \succeq_{SCD} . To see why, take any pair $x', x'' \in C(S)$ with $x' \neq x''$. As f has SCD, $D_{x', x''}$ is single crossing in θ . As X is minimal, $D_{x', x''}$ is not a zero function. Also, as $x', x'' \in C(S)$, $\text{sign}[D_{x', x''}]$ is not a constant function with value either 1 or -1. Thus, $D_{x', x''}$ is single crossing either only from below, or only from above. It follows that $x' \succ_{SCD} x''$ or $x'' \succ_{SCD} x'$.

Since \succeq is a refinement of \succeq_{SCD} , \succeq coincides with \succeq_{SCD} on $C(S)$, and the strong set orders generated by \succeq and \succeq_{SCD} on the collection of all subsets of $C(S)$ also coincide. By definition of \succeq_{SCD} , f satisfies [Milgrom and Shannon's](#) single-crossing property in (x, θ) with respect to \succeq_{SCD} and \leq .³⁵ It follows from [Milgrom and Shannon \(1994, Theorem 4\)](#) that $\forall \theta_l < \theta_h$,

$$\arg \max_{s \in S} f(s, \theta_h) = \arg \max_{s \in C(S)} f(s, \theta_h) \succeq_{SSO} \arg \max_{s \in C(S)} f(s, \theta_l) = \arg \max_{s \in S} f(s, \theta_l).³⁶$$

C.2. Proof of [Proposition 3](#)

The proof is similar to the [proof](#) of sufficiency for [Theorem 3](#) in [Appendix C.1](#).

For any $S \subseteq X$, define $C(S) \equiv \bigcup_{\theta \in \Theta} \arg \max_{s \in S} f(s, \theta)$. First, we claim that $C(S)$ is completely ordered by \succeq_{SSCD} . To see this, take any pair $x', x'' \in C(S)$ with $x' \neq x''$. As f has SSCD and X is minimal, $D_{x', x''}$ is strictly single crossing in θ . As $x', x'' \in C(S)$, $\text{sign}[D_{x', x''}]$ is not a constant function with value either 1 or -1. Thus, $D_{x', x''}$ is strictly single crossing either only from below or only from above. It follows that $x' \succ_{SSCD} x''$ or $x'' \succ_{SSCD} x'$. Next, since \succeq is a refinement of \succeq_{SSCD} , \succeq coincides with \succeq_{SSCD} on $C(S)$. By definition of \succeq_{SSCD} , f satisfies [Milgrom and Shannon's](#) strict single-crossing property in (x, θ) with

³⁵ Given (X, \succeq) that is completely ordered, (Θ, \leq) that is (partially) ordered, and $f : X \times \Theta \rightarrow \mathbb{R}$, [Milgrom and Shannon's](#) single-crossing property in (x, θ) is equivalent to

$$(\forall x' \succ x'')(\forall \theta_l < \theta_h) \quad f(x', \theta_l) \geq (>) f(x'', \theta_l) \implies f(x', \theta_h) \geq (>) f(x'', \theta_h).$$

³⁶ [Milgrom and Shannon \(1994, Theorem 4\)](#) identify their single-crossing property and quasi-supermodularity as jointly necessary and sufficient for their monotone comparative statics. (On a lattice (X, \succeq) , $h : X \rightarrow \mathbb{R}$ is quasisupermodular if $h(x) \geq (>) h(x \wedge x') \implies h(x \vee x') \geq (>) h(x')$.) When the choice set is completely ordered, the quasi-supermodularity holds trivially.

respect to \succeq_{SSCD} and \leq .³⁷ It follows from Milgrom and Shannon (1994, Theorem 4') that any selection $x^*(\theta)$ from $\arg \max_{s \in C(S)} f(s, \theta)$ ($= \arg \max_{s \in S} f(s, \theta)$) is increasing in θ .

D. Proofs for Monotonic Expectational Differences (Subsection 4.1)

D.1. Proof of Lemma 2

(\Leftarrow) Suppose there exist $\lambda \in \mathbb{R}^2$ such that $f_2 = \lambda_1 f_1 + \lambda_2$. Then, for any $\alpha \in \mathbb{R}^2$,

$$(\alpha \cdot f)(\theta) = \alpha_1 f_1(\theta) + \alpha_2 (\lambda_1 f_1(\theta) + \lambda_2) = (\alpha_1 + \alpha_2 \lambda_1) f_1(\theta) + \lambda_2,$$

which is monotonic.

(\Rightarrow) The proof is trivial if both f_1 and f_2 are constant functions. So we suppose that at least one function, say f_1 , is not constant:

$$(\exists \theta', \theta'') \quad f_1(\theta') \neq f_1(\theta''). \quad (32)$$

This implies that $\text{rank}[M_{\theta', \theta''}] = 2$, where

$$M_{\theta', \theta''} \equiv \begin{bmatrix} f_1(\theta') & 1 \\ f_1(\theta'') & 1 \end{bmatrix}.$$

Hence, the system

$$\begin{bmatrix} f_2(\theta') \\ f_2(\theta'') \end{bmatrix} = \begin{bmatrix} f_1(\theta') & 1 \\ f_1(\theta'') & 1 \end{bmatrix} \begin{bmatrix} \lambda_1 \\ \lambda_2 \end{bmatrix} \quad (33)$$

has a unique solution $\lambda^* \in \mathbb{R}^2$. We will show that $f_2 = \lambda_1^* f_1 + \lambda_2^*$.

Suppose, towards contradiction, there exists θ^* such that

$$f_2(\theta^*) \neq \lambda_1^* f_1(\theta^*) + \lambda_2^*. \quad (34)$$

Let $\underline{\theta}$ and $\bar{\theta}$ be a lower and upper bound of $\{\theta', \theta'', \theta^*\}$. If $\text{rank}[M_{\underline{\theta}, \bar{\theta}}] < 2$, then $f_1(\bar{\theta}) = f_1(\underline{\theta})$.

³⁷ Given (X, \succeq) that is completely ordered, (Θ, \leq) that is (partially) ordered, and $f : X \times \Theta \rightarrow \mathbb{R}$, Milgrom and Shannon's strict single-crossing property in (x, θ) is equivalent to

$$(\forall x' \succ x'')(\forall \theta_l < \theta_h) \quad f(x', \theta_l) \geq f(x'', \theta_l) \implies f(x', \theta_h) > f(x'', \theta_h).$$

As θ' and θ'' are in between $\underline{\theta}$ and $\bar{\theta}$ and f_1 is monotonic, we have $f_1(\theta') = f_1(\theta'')$, which contradicts (32). If, on the other hand, $\text{rank}[M_{\underline{\theta}, \bar{\theta}}] = 2$, then the system

$$\begin{bmatrix} f_2(\underline{\theta}) \\ f_2(\bar{\theta}) \end{bmatrix} = \begin{bmatrix} f_1(\underline{\theta}) & 1 \\ f_1(\bar{\theta}) & 1 \end{bmatrix} \begin{bmatrix} \lambda'_1 \\ \lambda'_2 \end{bmatrix}$$

has a unique solution $\lambda' \in \mathbb{R}^2$. As θ', θ'' , and θ^* are in between $\underline{\theta}$ and $\bar{\theta}$ and $f_2 - \lambda'_1 f_1$ is monotonic, we have

$$\begin{bmatrix} f_2(\theta') \\ f_2(\theta'') \end{bmatrix} = \begin{bmatrix} f_1(\theta') & 1 \\ f_1(\theta'') & 1 \end{bmatrix} \begin{bmatrix} \lambda'_1 \\ \lambda'_2 \end{bmatrix} \text{ and} \quad (35)$$

$$f_2(\theta^*) = \lambda'_1 f_1(\theta^*) + \lambda'_2. \quad (36)$$

Equation 35 implies that λ' solves (33). As the unique solution to (33) was λ^* , it follows that $\lambda' = \lambda^*$. But then (34) and (36) are in contradiction.

D.2. Proof of Proposition 4

(\Leftarrow) We omit the proof as it is similar to the proof of Proposition 2 in Appendix A.2.

(\Rightarrow) For the proof of necessity, if $(\forall x) f(x, \theta)$ is a constant function of θ , then we let $\lambda_1(x) = 0$ and $\lambda_2(x) = f(x, \theta)$. If there exists $x' \in X$ such that $f(x', \theta)$ is not a constant function of θ , then Lemma 2 implies $(\forall x, \theta) f(x, \theta) = \lambda_1(x)f(x', \theta) + \lambda_2(x)$, with $\lambda_1, \lambda_2 : X \rightarrow \mathbb{R}$.

D.3. Proof of Theorem 4

(\Leftarrow) We omit the proof as it is similar to the proof of Theorem 1 in Appendix A.3.

(\Rightarrow) The proof is trivial if $(\forall a, \theta) v(a, \theta) = 0$, so assume there exists a_0 such that $v(a_0, \cdot) : \Theta \rightarrow \mathbb{R}$ is not a zero function. Define $f : A \times \Theta \rightarrow \mathbb{R}$ by $f(a, \theta) \equiv v(a, \theta) - v(a_0, \theta)$. Note that $(\forall a) f(a, \theta)$ is a monotonic function of θ : consider the expectational difference with distributions that put probability one on a and a_0 respectively.

Let $A' \equiv A \setminus \{a_0\}$. As in the proof of Theorem 1 in Appendix A.3, for every real-valued function μ' over A' with finite support, there exist $P, Q \in \Delta A$ such that $\int_{A'} f(a, \theta) d\mu'$ is monotonic if and only if $D_{P, Q}$ is monotonic. By Proposition 4, there exist $a' \in A \setminus a_0$ and $\lambda_1, \lambda_2 : A \setminus \{a_0\} \rightarrow \mathbb{R}$ such that $(\forall a, \theta) f(a, \theta) = \lambda_1(a)f(a', \theta) + \lambda_2(a)$. Hence, there exist functions $g_1, g_2 : A \rightarrow \mathbb{R}$ with $g_1(a_0) = g_2(a_0) = 0$ such that $f(a, \theta) = g_1(a)f(a', \theta) + g_2(a)$, or equivalently, $v(a, \theta) = g_1(a)f(a', \theta) + g_2(a) + v(a_0, \theta)$.

E. Further Results Comparing MED and SCED

This appendix identifies when the preferences defined by a utility function with SCED also have a utility representation satisfying MED. [Appendix E.1](#) states and discusses the characterization result, [Proposition 7](#); the proof is provided in [Appendix E.2](#); and [Appendix E.3](#) applies the characterization.

E.1. SCED and MED Representations

Let $\succeq_\Theta \equiv \{\succeq_\theta : \theta \in \Theta\}$ be a family of type-dependent preferences (i.e., complete, reflexive, and transitive binary relations) over ΔA . We say that $v : A \times \Theta \rightarrow \mathbb{R}$ **represents** \succeq_Θ (in the expected utility form) if

$$(\forall \theta)(\forall P, Q \in \Delta A) \quad P \succeq_\theta Q \iff \int_A v(a, \theta) dP \geq \int_A v(a, \theta) dQ. \quad (37)$$

For any $v : A \times \Theta \rightarrow \mathbb{R}$ and \succeq_Θ defined by (37), a function $v' : A \times \Theta \rightarrow \mathbb{R}$ is a positive affine transformation of v if and only if v' represents \succeq_Θ .

Proposition 7. *Let $v : A \times \Theta \rightarrow \mathbb{R}$ have SCED:*

$$v(a, \theta) = g_1(a)f_1(\theta) + g_2(a)f_2(\theta) + c(\theta),$$

where $f_1, f_2 : \Theta \rightarrow \mathbb{R}$ are each single crossing and ratio ordered, $g_1, g_2 : A \rightarrow \mathbb{R}$, and $c : \Theta \rightarrow \mathbb{R}$. Let \succeq_Θ be the family of preferences over ΔA defined by (37). Then, \succeq_Θ can be represented by a function with MED if and only if (i) either g_1 is an affine transformation of g_2 or vice-versa, or (ii) f_1 and f_2 are linearly dependent, or (iii) there exists $\lambda \in \mathbb{R}^2 \setminus \{0\}$ such that $(\forall \theta) (\lambda \cdot f)(\theta) > 0$.

We can interpret [Proposition 7](#) as follows: given \succeq_Θ with an SCED representation, there is an MED representation if and only if either

- (a) there is a pair of types that do not share the same strict preference over any pair of lotteries (i.e., $(\exists \theta', \theta'') (\forall P, Q \in \Delta A) D_{P,Q}(\theta') D_{P,Q}(\theta'') \leq 0$), or
- (b) there is a pair of lotteries over which all types share the same strict preference (i.e., $(\exists P, Q \in \Delta A) (\forall \theta) D_{P,Q}(\theta) > 0$).

To see this interpretation, suppose Case (i) or (ii) holds in [Proposition 7](#). Then, there are functions \hat{g}_1, \hat{f}_1 , and \hat{c} such that $v(a, \theta) = \hat{g}_1(a)\hat{f}_1(\theta) + \hat{c}(\theta)$, with \hat{f}_1 single crossing. If \hat{g}_1 is constant or \hat{f}_1 is a zero function, every type is indifferent across all lotteries, and (a) holds.

Suppose \hat{g}_1 is not constant. If $\hat{f}_1 > 0$ (or < 0), then (b) holds.³⁸ If $\hat{f}_1(\theta)$ is single crossing only from below or only from above, then for some θ' and θ'' , $\hat{f}_1(\theta')\hat{f}_1(\theta'') \leq 0$; the pair θ' and θ'' does not share the same strict preference over any two lotteries, and so (a) holds. On the other hand, if [Proposition 7](#)'s Case (iii) applies and Case (i) does not, then (b) holds, because $(\exists P, Q \in \Delta A, M \in \mathbb{R}_{++}) (\forall \theta) MD_{P,Q}(\theta) = (\lambda \cdot f)(\theta) > 0$; see [\(38\)](#).³⁹

Here is some geometric intuition for the “if” direction of [Proposition 7](#). For Case (i) or (ii), $v(a, \theta) = \hat{g}_1(a)\hat{f}_1(\theta) + \hat{c}(\theta)$ with \hat{f}_1 single crossing, as already noted. We can rescale $\hat{f}_1(\theta)$ using a function $b : \Theta \rightarrow \mathbb{R}_{++}$ such that $b(\theta)\hat{f}_1(\theta)$ is monotonic. Thus, $v'(a, \theta) \equiv b(\theta)v(a, \theta)$ represents \succeq_Θ and has MED. For Case (iii), assume without loss of generality that $\|\lambda\| = 1$. Let $b(\theta) \equiv \frac{1}{(\lambda \cdot f)(\theta)}$. It follows that $(\forall \theta) (\lambda \cdot (bf))(\theta) = 1$, i.e., the function b adjusts the lengths of vectors $\{f(\theta) \in \mathbb{R}^2 : \theta \in \Theta\}$ while maintaining their directions, as illustrated in [Figure 6](#). The vector $(bf)(\theta)$ rotates monotonically as θ increases, while staying on the hyperplane $\{x \in \mathbb{R}^2 \mid \lambda \cdot x = 1\}$. Let $e_1 \equiv (1, 0)$ and $e_2 \equiv (0, 1)$. Suppose $\{e_1, \lambda\}$ is a basis for \mathbb{R}^2 (an analogous argument would hold if instead $\{e_2, \lambda\}$ were a basis). Then, for every θ , the vector $(bf)(\theta)$ is represented as $(b(\theta)\hat{f}_1(\theta), 1)$ with respect to the new basis. We define $\tilde{f}_1(\theta) \equiv b(\theta)\hat{f}_1(\theta)$ and

$$v'(a, \theta) \equiv b(\theta)v(a, \theta) = \tilde{g}_1(a)\tilde{f}_1(\theta) + \tilde{g}_2(a) + b(\theta)c(\theta),$$

with appropriately defined functions \tilde{g}_1 and \tilde{g}_2 . Since $(bf)(\theta)$ rotates monotonically, $\tilde{f}_1(\theta)$ is monotonic. It follows that v' has MED.

E.2. Proof of [Proposition 7](#)

(\Leftarrow) First we prove that if either (i) or (ii) holds, then we can write v as $v(a, \theta) = \hat{g}_1(a)\hat{f}_1(\theta) + \hat{c}(\theta)$, with \hat{f}_1 single crossing.

Suppose (i) holds; without loss, assume $(\exists d \in \mathbb{R}^2) (\forall a) g_2(a) = d_1g_1(a) + d_2$. Then, $\hat{g}_1(a) = g_1(a)$, $\hat{f}_1(\theta) = f_1(\theta) + d_1f_2(\theta)$, and $\hat{c}(\theta) = d_2f_2(\theta) + c(\theta)$. Next suppose (ii) holds; without loss, assume $(\exists d \in \mathbb{R}) (\forall \theta) f_2(\theta) = df_1(\theta)$. Then, $\hat{g}_1(a) = g_1(a) + dg_2(a)$, $\hat{f}_1(\theta) = f_1(\theta)$, and $\hat{c}(\theta) = c(\theta)$. In either case, \hat{f}_1 is a linear combination of f_1 and f_2 , so it is single crossing.

³⁸ Consider two degenerate lotteries over a' and a'' such that $\hat{g}_1(a') \neq \hat{g}_2(a'')$.

³⁹ Conversely, (a) implies either Case (i) or (ii) of [Proposition 7](#). If g_1 and g_2 are affinely independent (i.e., a violation of (i)), then $(\forall \lambda \in \mathbb{R}^2 \setminus \{0\}) (\exists P, Q \in \Delta A, M \in \mathbb{R}_{++}) (\forall \theta) (\lambda \cdot f)(\theta) = MD_{P,Q}(\theta)$; see [\(38\)](#). Then, (a) implies that for some θ', θ'' and for some $\beta \leq 0$, $f(\theta') = \beta f(\theta'')$, which, together with Condition [\(4\)](#) of ratio ordering, implies that f_1 and f_2 are linearly dependent. Moreover, (b) implies Case (iii) of the Proposition: letting $\lambda_i = \int_A g_i(a)d[P - Q]$ for $i = 1, 2$, it holds that $\lambda_1f_1(\theta) + \lambda_2f_2(\theta) = D_{P,Q}(\theta) > 0$ for all θ .

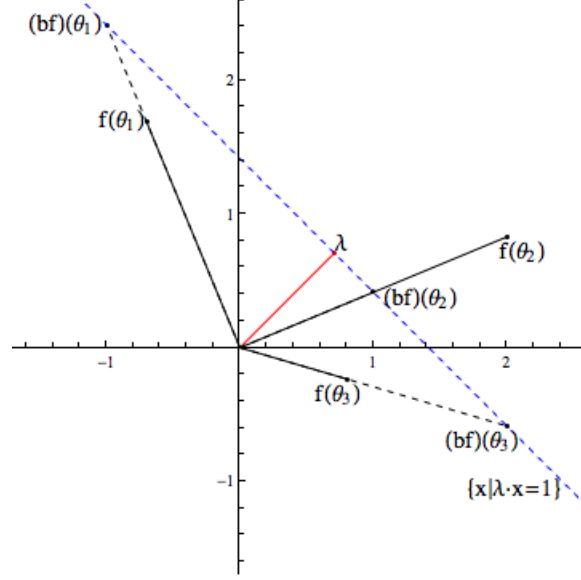


Figure 6: A geometric intuition for sufficiency of (iii) in Proposition 7.

Define

$$b(\theta) \equiv \begin{cases} \frac{1}{|\hat{f}_1(\theta)|} & \text{if } \hat{f}_1(\theta) \neq 0, \\ 1 & \text{otherwise.} \end{cases}$$

Since $(\forall \theta) b(\theta) > 0$, $v'(a, \theta) \equiv b(\theta)v(a, \theta) = \hat{g}_1(a)b(\theta)\hat{f}_1(\theta) + b(\theta)\hat{c}(\theta)$ is a positive affine transformation of v , and hence it also represents \succeq_Θ . As \hat{f}_1 is single crossing, $b(\theta)\hat{f}_1(\theta) = \text{sign}[\hat{f}_1(\theta)]$ is monotonic, and v' has MED.

Now suppose (iii) holds: $(\exists \lambda \in \mathbb{R}^2 \setminus \{0\}) (\forall \theta) (\lambda \cdot f)(\theta) > 0$. Define $b(\theta) \equiv \frac{1}{(\lambda \cdot f)(\theta)}$. Then $(\lambda \cdot (bf))(\theta) = 1$, so that either $(bf_1)(\theta)$ is an affine transformation of $(bf_2)(\theta)$, or vice-versa: $(\exists \gamma, \omega \in \mathbb{R})$ such that either $b(\theta)f_1(\theta) = \gamma b(\theta)f_2(\theta) + \omega$ or $b(\theta)f_2(\theta) = \gamma b(\theta)f_1(\theta) + \omega$.

We consider the case in which $b(\theta)f_2(\theta) = \gamma b(\theta)f_1(\theta) + \omega$ and omit the other case's analogous proof. If $\lambda_2 \geq (\leq) 0$, then as f_1 ratio dominates f_2 ,

$$\begin{aligned} (\forall \theta' < \theta'') \quad & f_1(\theta')f_2(\theta'') \leq f_1(\theta'')f_2(\theta') \\ \implies \quad & \lambda_1 f_1(\theta')f_1(\theta'') + \lambda_2 f_1(\theta')f_2(\theta'') \leq (\geq) \lambda_1 f_1(\theta')f_1(\theta'') + \lambda_2 f_1(\theta'')f_2(\theta') \\ \implies \quad & f_1(\theta')(\lambda \cdot f)(\theta'') \leq (\geq) f_1(\theta'')(\lambda \cdot f)(\theta') \\ \implies \quad & b(\theta')f_1(\theta') \leq (\geq) b(\theta'')f_1(\theta''). \end{aligned}$$

Thus, regardless of whether $\lambda_2 \geq 0$ or $\lambda_2 \leq 0$, $(bf_1)(\theta)$ is monotonic in θ . It follows that

$$\begin{aligned} v'(a, \theta) &\equiv b(\theta)v(a, \theta) = g_1(a)b(\theta)f_1(\theta) + g_2(a)b(\theta)f_2(\theta) + b(\theta)c(\theta) \\ &= g_1(a)b(\theta)f_1(\theta) + g_2(a)(\gamma b(\theta)f_1(\theta) + \omega) + b(\theta)c(\theta) \\ &= (g_1(a) + \gamma g_2(a))b(\theta)f_1(\theta) + \omega g_2(a) + b(\theta)c(\theta) \end{aligned}$$

has MED.

(\implies) We prove that if neither (i) or (ii) holds, then (iii) holds.

We first show that when (i) does not hold,

$$(\forall \lambda \in \mathbb{R}^2 \setminus \{0\}) (\exists P, Q \in \Delta A, M \in \mathbb{R}_{++}) (\forall \theta) \quad (\lambda \cdot f)(\theta) = MD_{P,Q}(\theta). \quad (38)$$

As (i) does not hold, the three functions g_1 , g_2 , and 1 (where 1 represents the constant function whose value is 1) are linearly independent. For otherwise, either g_1 and g_2 are linearly dependent, or $(\exists \alpha \in \mathbb{R}^2 \setminus \{0\}) (\forall a) \alpha_1 g_1(a) + \alpha_2 g_2(a) = 1$; in either case, either g_1 would be an affine transformation of g_2 or vice-versa.

By the aforementioned linear independence, there exist $a_0, a_1, a_2 \in A$ such that

$$\text{rank} \begin{bmatrix} g_1(a_0) & g_1(a_1) & g_1(a_2) \\ g_2(a_0) & g_2(a_1) & g_2(a_2) \\ 1 & 1 & 1 \end{bmatrix} = 3.$$

It follows that for any $\lambda \in \mathbb{R}^2 \setminus \{0\}$ there exists $(d_0, d_1, d_2) \in \mathbb{R}^3$ such that

$$\begin{bmatrix} g_1(a_0) & g_1(a_1) & g_1(a_2) \\ g_2(a_0) & g_2(a_1) & g_2(a_2) \\ 1 & 1 & 1 \end{bmatrix} \begin{bmatrix} d_0 \\ d_1 \\ d_2 \end{bmatrix} = \begin{bmatrix} \lambda_1 \\ \lambda_2 \\ 0 \end{bmatrix}.$$

Take a sufficiently large $M \in \mathbb{R}_{++}$ such that $|d_i| \leq M/3$ for $i = 0, 1, 2$, and define $P, Q \in \Delta A$ with probability mass functions p, q such that $p(a_i) = 1/3$ and $q(a_i) = 1/3 - d_i/M$ for $i = 0, 1, 2$. Then, both P and Q are probability distributions on $\{a_0, a_1, a_2\}$, and

$$\begin{aligned} (\lambda \cdot f)(\theta) &= (d_0 g_1(a_0) + d_1 g_1(a_1) + d_2 g_1(a_2)) f_1(\theta) + (d_0 g_2(a_0) + d_1 g_2(a_1) + d_2 g_2(a_2)) f_2(\theta) \\ &= \sum_{i \in \{0,1,2\}} d_i (g_1(a_i) f_1(\theta) + g_2(a_i) f_2(\theta)) \\ &= MD_{P,Q}(\theta). \end{aligned}$$

Suppose \succeq_Θ is represented by a function $v' : A \times \Theta \rightarrow \mathbb{R}$ with MED. As both v and v' represent \succeq_Θ in the expected utility form, v' is a positive affine transformation of v . It follows that there exist $b : \Theta \rightarrow \mathbb{R}_{++}$ and $d : \Theta \rightarrow \mathbb{R}$ such that

$$v'(a, \theta) = b(\theta)v(a, \theta) + d(\theta) = g_1(a)\hat{f}_1(\theta) + g_2(a)\hat{f}_2(\theta) + \hat{c}(\theta),$$

where $\hat{f}_1(\theta) = b(\theta)f_1(\theta)$, $\hat{f}_2(\theta) = b(\theta)f_2(\theta)$, and $\hat{c}(\theta) = b(\theta)c(\theta) + d(\theta)$.

Given (38), for any $\lambda \in \mathbb{R}^2 \setminus \{0\}$, there exist $P, Q \in \Delta A$ and $M \in \mathbb{R}_{++}$ such that

$$(\lambda \cdot \hat{f})(\theta) = b(\theta)(\lambda \cdot f)(\theta) = b(\theta)MD_{P,Q}(\theta) = M \int_A v'(a, \theta)d[P - Q],$$

which is monotonic.

We find $\lambda \in \mathbb{R}^2 \setminus \{0\}$ such that $(\forall \theta) (\lambda \cdot \hat{f})(\theta) = 1$. For any θ', θ'' , let

$$M_{\theta'\theta''} \equiv \begin{bmatrix} f_1(\theta') & f_1(\theta'') \\ f_2(\theta') & f_2(\theta'') \end{bmatrix} \quad \text{and} \quad \hat{M}_{\theta'\theta''} \equiv \begin{bmatrix} \hat{f}_1(\theta') & \hat{f}_1(\theta'') \\ \hat{f}_2(\theta') & \hat{f}_2(\theta'') \end{bmatrix}.$$

As f_1 and f_2 are linearly independent, there exist θ_1, θ_2 such that $\text{rank}[M_{\theta_1, \theta_2}] = 2$, which implies that $\text{rank}[\hat{M}_{\theta_1, \theta_2}] = 2$. Let $\lambda^* \in \mathbb{R}^2 \setminus \{0\}$ be the unique solution of $\hat{M}_{\theta_1, \theta_2}\lambda = (1, 1)$. Take any θ_0 , and let $\underline{\theta}$ and $\bar{\theta}$ be a lower and upper bound of $\{\theta_0, \theta_1, \theta_2\}$. It must be that $\text{rank}[\hat{M}_{\underline{\theta}, \bar{\theta}}] = 2$. If otherwise, there exists $\lambda \in \mathbb{R}^2 \setminus \{0\}$ such that $(\lambda \cdot \hat{f})(\underline{\theta}) = (\lambda \cdot \hat{f})(\bar{\theta}) = 0$. By (38), $\lambda \cdot \hat{f}$ is monotonic, so $(\lambda \cdot \hat{f})(\theta_1) = (\lambda \cdot \hat{f})(\theta_2) = 0$, which contradicts $\text{rank}[\hat{M}_{\theta_1, \theta_2}] = 2$. Let λ^{**} be the unique solution of $\hat{M}_{\underline{\theta}, \bar{\theta}}\lambda = (1, 1)$. By monotonicity of $\lambda^{**} \cdot \hat{f}$, $\hat{M}_{\theta_1, \theta_2}\lambda^{**} = (1, 1)$, which implies that $\lambda^{**} = \lambda^*$. It follows that $(\lambda^* \cdot \hat{f})(\theta_0) = 1$. As θ_0 is arbitrary, we have $(\forall \theta) (\lambda^* \cdot \hat{f})(\theta) = 1$.

Finally, $(\forall \theta) (\lambda^* \cdot f)(\theta) = \frac{(\lambda^* \cdot \hat{f})(\theta)}{b(\theta)} > 0$.

E.3. An Example of SCED-but-not-MED Preferences

We can use Proposition 7 to provide an example of type-dependent preferences representable by an SCED function that are not representable by any MED function.

Example 2. Let $\Theta \equiv (-1, 1] \subset \mathbb{R}$ and $A \equiv \{a_0, a', a''\}$. Consider $v(a, \theta) = g_1(a)f_1(\theta) + g_2(a)f_2(\theta)$, with

1. $g_1(a_0) = g_2(a_0) = 0$, $g_1(a') = g_2(a') = 1$, $g_1(a'') = 2$, $g_2(a'') = 3$, and
2. $f_1(\theta) = \theta$, $f_2(\theta) = 1 - \theta^2$.

Observe that f_1 ratio dominates f_2 : if $\theta' < \theta''$, then $\theta'\theta'' < 1$, and hence $f_1(\theta')f_2(\theta'') < f_1(\theta'')f_2(\theta')$. It follows that v has SCED.

We claim the family of type-dependent preferences \succeq_Θ represented by v is not representable by any MED function. It is easy to verify that neither g_1 is an affine transformation of g_2 nor vice-versa, and that f_1 and f_2 are linearly independent. By [Proposition 7](#), it suffices to show that $\nexists \lambda \in \mathbb{R}^2$ such that $(\forall \theta) (\lambda \cdot f)(\theta) > 0$. Take any $\lambda \in \mathbb{R}^2 \setminus \{0\}$. If $\lambda_1 = 0$, then $(\lambda \cdot f)(1) = 0$. If, on the other hand, $\lambda_1 \neq 0$, then $\text{sign}[(\lambda \cdot f)(1)] = \text{sign}[\lambda_1]$ and $\lim_{\theta \rightarrow -1} \text{sign}[(\lambda \cdot f)(\theta)] = -\text{sign}[\lambda_1]$, and so $(\exists \theta)(\lambda \cdot f)(\theta) < 0$. \square

F. Proof for Information Design ([Subsection 4.2](#))

This appendix proves [Proposition 5](#).

(\Leftarrow) For any $Q \in \Delta\Delta\Omega$,

$$V(Q, \theta) = \left(\int_{\Delta\Omega} g_1(p) dQ \right) f_1(\theta) + \left(\int_{\Delta\Omega} g_2(p) dQ \right) f_2(\theta) + \int_{\Delta\Omega} \left(\sum_{\omega \in \Omega} v(\delta_\omega, \theta) p(\omega) \right) dQ.$$

The last term on the right-hand side is equal to

$$\sum_{\omega \in \Omega} v(\delta_\omega, \theta) \left(\int_{\Delta\Omega} p(\omega) dQ \right) = \sum_{\omega \in \Omega} v(\delta_\omega, \theta) \bar{Q}(\omega).$$

Thus, for any $Q, R \in \Delta\Delta\Omega$ with $\bar{Q} = \bar{R}$,

$$D_{Q,R}(\theta) = \left(\int_{\Delta\Omega} g_1(p) dQ - \int_{\Delta\Omega} g_1(p) dR \right) f_1(\theta) + \left(\int_{\Delta\Omega} g_2(p) dQ - \int_{\Delta\Omega} g_2(p) dR \right) f_2(\theta),$$

which is single crossing in θ by [Lemma 1](#).

(\Rightarrow) For each posterior $p \in \Delta\Omega$, consider two experiments: $\delta_p \in \Delta\Delta\Omega$ yields p with certainty, and $Q_p \in \Delta\Delta\Omega$ yields each degenerate posterior $\delta_\omega \in \Delta\Omega$ with probability $p(\omega)$. For every θ ,

$$V(\delta_p, \theta) = v(p, \theta) \quad \text{and} \quad V(Q_p, \theta) = \sum_{\omega \in \Omega} v(\delta_\omega, \theta) p(\omega).$$

The average of both experiments is the posterior p : $(\forall \omega) \bar{\delta}_p(\omega) = \bar{Q}_p(\omega) = p(\omega)$. Thus,

$$f(p, \theta) \equiv V(\delta_p, \theta) - V(Q_p, \theta) = v(p, \theta) - \sum_{\omega \in \Omega} v(\delta_\omega, \theta) p(\omega)$$

is single crossing in θ .

The remaining part of the proof is similar to the proof of [Proposition 2](#) in [Appendix A.2](#). If there exists $p_1 \in \Delta\Omega$ such that

$$(\exists \lambda : \Delta\Omega \rightarrow \mathbb{R})(\forall p, \theta) \quad f(p, \theta) = \lambda(p)f(p_1, \theta),$$

then v is in the form of [\(13\)](#) with $f_1(\theta) = f(p_1, \theta)$, $f_2(\theta) = 0$, $g_1(p) = \lambda(p)$, and $g_2(p) = 0$. Otherwise, there exist p_1 and p_2 such that $f(p_1, \cdot), f(p_2, \cdot) : \Theta \rightarrow \mathbb{R}$ are linearly independent. The following claim, together with [Lemma 1](#), then implies that $f(p_1, \cdot)$ and $f(p_2, \cdot)$ are ratio ordered.

Claim 10. *For all $\alpha \in \mathbb{R}^2$, the linear combination $\alpha_1 f(p_1, \theta) + \alpha_2 f(p_2, \theta)$ is single crossing in θ .*

Proof. Assume that $\alpha \in \mathbb{R}^2 \setminus \{0\}$; otherwise the linear combination is a zero function, which is clearly single crossing. Moreover, without loss assume that $\alpha_1 > 0$. (If $\alpha_1 < 0$, multiply the linear combination by -1 , while if $\alpha_1 = 0$, swap indices $i = 1, 2$; neither modification affects whether the linear combination is single crossing or not.)

If $\alpha_2 \geq 0$, let $M \equiv \alpha_1 + \alpha_2$ and define $R_1, R_2 \in \Delta\Delta\Omega$ by

$$R_1 \equiv \frac{\alpha_1}{M}\delta_{p_1} + \frac{\alpha_2}{M}\delta_{p_2}, \quad \text{and} \quad R_2 \equiv \frac{\alpha_1}{M}Q_{p_1} + \frac{\alpha_2}{M}Q_{p_2}.$$

Note that $\bar{R}_1 = \bar{R}_2 = \frac{\alpha_1}{M}p_1 + \frac{\alpha_2}{M}p_2$. Thus,

$$\begin{aligned} \alpha_1 f(p_1, \theta) + \alpha_2 f(p_2, \theta) &= \alpha_1 (V(\delta_{p_1}, \theta) - V(Q_{p_1}, \theta)) + \alpha_2 (V(\delta_{p_2}, \theta) - V(Q_{p_2}, \theta)) \\ &= M (V(R_1, \theta) - V(R_2, \theta)) \end{aligned}$$

is single crossing in θ .

If, on the other hand, $\alpha_2 < 0$, let $M \equiv \alpha_1 - \alpha_2$ and define $R_1, R_2 \in \Delta\Delta\Omega$ by

$$R_1 \equiv \frac{\alpha_1}{M}\delta_{p_1} - \frac{\alpha_2}{M}Q_{p_2}, \quad \text{and} \quad R_2 \equiv \frac{\alpha_1}{M}Q_{p_1} - \frac{\alpha_2}{M}\delta_{p_2}.$$

As before, $\bar{R}_1 = \bar{R}_2$, and

$$\alpha_1 f(p_1, \theta) + \alpha_2 f(p_2, \theta) = M (V(R_1, \theta) - V(R_2, \theta))$$

is single crossing in θ .

Q.E.D.

We can now follow the proof of [Proposition 2](#) in [Appendix A.2](#) and show that there exist

$\lambda_1, \lambda_2 : \Delta\Omega \rightarrow \mathbb{R}$ such that $(\forall p) f(p, \cdot) = \lambda_1(p)f(p_1, \cdot) + \lambda_2(p)f(p_2, \cdot)$. By definition of $f(p, \theta)$, the function v satisfies (13).

G. Relationship to Signed-Ratio Monotonicity and the Variation Diminishing Property

G.1. Signed-Ratio Monotonicity

Quah and Strulovici (2012) establish that for any two functions $f_1 : \Theta \rightarrow \mathbb{R}$ and $f_2 : \Theta \rightarrow \mathbb{R}$ that are each single crossing from below, $\alpha_1 f_1 + \alpha_2 f_2$ is single crossing from below for all $\alpha \in \mathbb{R}_+^2$ if and only if f_1 and f_2 satisfy **signed-ratio monotonicity**: for all $i, j \in \{1, 2\}$,

$$(\forall \theta_l < \theta_h) \quad f_j(\theta_l) < 0 < f_i(\theta_l) \implies f_i(\theta_h)f_j(\theta_l) \leq f_i(\theta_l)f_j(\theta_h). \quad (39)$$

Given our discussion in Subsection 2.1.1 of a graphical interpretation of ratio ordering, one can see that Condition (39) implies that the vector $f(\theta) \equiv (f_1(\theta), f_2(\theta))$ rotates clockwise as θ increases within the upper-left quadrant (i.e., when $f_1(\cdot) < 0 < f_2(\cdot)$), while it rotates counterclockwise within the lower-right quadrant (i.e., when $f_1(\cdot) > 0 > f_2(\cdot)$); there are no restrictions in the other two quadrants.⁴⁰ The dashed curve with arrowheads in Figure 7 provides a depiction. Note that if f_1 and f_2 are both single crossing from below (or both from above), then there cannot exist $\theta_l < \theta_h$ such that one of $f(\theta_l)$ and $f(\theta_h)$ is in the upper-left quadrant and the other in the lower-right quadrant. It follows that if f_1 and f_2 are both single crossing from below, then ratio ordering implies signed-ratio monotonicity; more generally, however, the implication is not valid.

Figure 7 also illustrates Quah and Strulovici's (2012) result, analogous to Figure 4 for Lemma 1. Any linear combination $\alpha \in \mathbb{R}_+^2 \setminus \{0\}$ defines two open half spaces, $\mathbb{R}_{\alpha,-}^2 \equiv \{x \in \mathbb{R}^2 : \alpha \cdot x < 0\}$ and $\mathbb{R}_{\alpha,+}^2 \equiv \{x \in \mathbb{R}^2 : \alpha \cdot x > 0\}$, as indicated in Figure 7. If the vector $f(\theta)$ rotates monotonically as θ increases from $\mathbb{R}_{\alpha,-}^2$ to $\mathbb{R}_{\alpha,+}^2$, or either half space contains the vector $f(\theta)$ for all θ , then $\alpha \cdot f \equiv \alpha_1 f_1 + \alpha_2 f_2$ is single crossing from below. Conversely, if $f(\theta)$ does not rotate monotonically in the upper-left or lower-right quadrant, then there exists $\alpha \in \mathbb{R}_+^2 \setminus \{0\}$ such that $\alpha \cdot f$ is not single crossing from below.

G.2. Variation Diminishing Property

Karlin (1968) assumes a completely ordered domain, so consider a completely ordered Θ , with $|\Theta| \geq 3$ to avoid trivialities. Let $K(i, \theta) \equiv K_i(\theta)$ for $i = 1, 2$ and some functions

⁴⁰ To be precise: by “quadrant” we mean the interiors, i.e., excluding the axes.

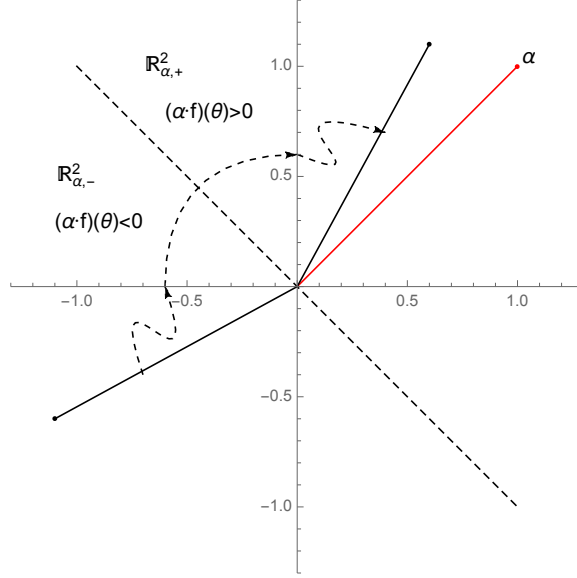


Figure 7: Signed-ratio monotonicity and single crossing of a convex combination.

$K_i : \Theta \rightarrow \mathbb{R}$. The function K is said to be totally positive of order two, abbreviated TP_2 , if K_1 and K_2 are both non-negative functions and $(\forall \theta_l < \theta_h) K_1(\theta_l)K_2(\theta_h) \leq K_1(\theta_h)K_2(\theta_l)$. The variation diminishing property of [Karlin \(1968, Theorem 3.1 in Chapter 5\)](#) implies that if—and, more or less, only if— K is TP_2 , then any linear combination of K_1 and K_2 is single crossing. There are, however, single-crossing functions f_1 and f_2 that are ratio ordered such that there is no TP_2 function K with

$$\{\alpha_1 f_1 + \alpha_2 f_2 : \alpha \in \mathbb{R}^2\} = \{\alpha_1 K_1 + \alpha_2 K_2 : \alpha \in \mathbb{R}^2\}. \quad (40)$$

When f_1 and f_2 are each single crossing, ratio ordered, and linearly independent, a TP_2 function K satisfying (40) exists if and only if the set $\{f(\theta) : \theta \in \Theta\}$ lies in an open half space of \mathbb{R}^2 defined by a hyperplane that passes through the origin. (A proof is available from the authors on request.) Ratio ordering does imply that the set lies in a half space, as noted earlier, but the half space need not be open.

H. Relaxing Anti-Symmetry

This appendix shows how anti-symmetry of \leq over Θ can be dropped by appropriately generalizing the definition of single crossing. This extension is useful, for example, because rankings over Θ based on norms (say, when $\Theta \subseteq \mathbb{R}^n$) generally violate anti-symmetry.

Assume (Θ, \leq) is a preordered set, i.e., \leq is a binary relation that is reflexive and transi-

tive, but not necessarily anti-symmetric. We write $\theta' \cong \theta''$ when $\theta' \geq \theta''$ and $\theta' \leq \theta''$.

Definition 11. When (Θ, \leq) is a preordered set, a function $f : \Theta \rightarrow \mathbb{R}$ is **single crossing** (resp., single crossing from below or from above) if $\text{sign}[f]$ is monotonic (resp., increasing or decreasing) and

$$(\forall \theta' \cong \theta'') \quad \text{sign}[f(\theta')] = \text{sign}[f(\theta'')]. \quad (41)$$

Definition 11 reduces to **Definition 1** when (Θ, \leq) is a partially-ordered set, because in that case $\theta' \cong \theta'' \iff \theta' = \theta''$.

Lemma 4. Let (Θ, \leq) be a preordered set and $f_1, f_2 : \Theta \rightarrow \mathbb{R}$. The linear combination $\alpha_1 f_1(\theta) + \alpha_2 f_2(\theta)$ is single crossing $\forall \alpha \in \mathbb{R}^2$ if and only if f_1 and f_2 are (i) each single crossing and (ii) ratio ordered.

The rest of our main results (**Proposition 2**, **Theorem 1**, and **Theorem 3**) and their proofs remain the same.

The proof of **Lemma 4** consists of establishing **Claim 11** and **Claim 12** below.

Claim 11. For any $\alpha \in \mathbb{R}^2$,

$$\begin{aligned} & \text{either } (\forall \theta' < \theta'') \quad \text{sign}[(\alpha \cdot f)(\theta')] \leq \text{sign}[(\alpha \cdot f)(\theta'')], \\ & \text{or } (\forall \theta' < \theta'') \quad \text{sign}[(\alpha \cdot f)(\theta')] \geq \text{sign}[(\alpha \cdot f)(\theta'')] \end{aligned}$$

if and only if (i) $\text{sign}[f_1]$ and $\text{sign}[f_2]$ are monotonic, and (ii) for either $i = 1$ and $j = 2$, or vice-versa,

$$\begin{aligned} & (\forall \theta_l < \theta_h) \quad f_i(\theta_l) f_j(\theta_h) \leq f_i(\theta_h) f_j(\theta_l) \quad \text{and} \\ & (\forall \theta_l < \theta_m < \theta_h) \quad f_i(\theta_l) f_j(\theta_h) = f_i(\theta_h) f_j(\theta_l) \iff \begin{cases} f_i(\theta_l) f_j(\theta_m) = f_i(\theta_m) f_j(\theta_l), \\ f_i(\theta_m) f_j(\theta_h) = f_i(\theta_h) f_j(\theta_m). \end{cases} \end{aligned}$$

Proof. The proof is the same as the proof of **Lemma 1**, as that proof does not use anti-symmetry of \leq over Θ . Q.E.D.

Claim 12. For any $\alpha \in \mathbb{R}^2$,

$$(\forall \theta' \cong \theta'') \quad \text{sign}[(\alpha \cdot f)(\theta')] = \text{sign}[(\alpha \cdot f)(\theta'')] \quad (42)$$

if and only if (i) f_1 and f_2 each satisfy (41), and (ii) $(\forall \theta' \cong \theta'') \quad f_1(\theta') f_2(\theta'') = f_1(\theta'') f_2(\theta')$.

Proof. (\implies) Part (i) holds trivially: consider $\alpha = (1, 0)$ or $\alpha = (0, 1)$. For Part (ii), suppose, towards contradiction, that $(\exists \theta' \cong \theta'') \quad f_1(\theta') f_2(\theta'') \neq f_1(\theta'') f_2(\theta')$. Then, $\alpha' \equiv (-f_2(\theta'), f_1(\theta')) \neq 0$. It follows that $(\alpha' \cdot f)(\theta') = 0 \neq (\alpha' \cdot f)(\theta'')$, contradicting (42).

(\Leftarrow) Take any $\alpha \in \mathbb{R}^2$ and $\theta' \cong \theta''$. If $f_1(\theta')f_2(\theta'') = f_1(\theta'')f_2(\theta') \neq 0$, then all four function values are non-zero. Thus,

$$\begin{aligned} \text{sign}[(\alpha \cdot f)(\theta')] &= \text{sign} \left[\frac{f_1(\theta'')}{f_1(\theta')} (\alpha_1 f_1(\theta') + \alpha_2 f_2(\theta'')) \right] \quad (\text{because } \text{sign}[f_1(\theta')] = \text{sign}[f_1(\theta'')] \neq 0) \\ &= \text{sign} [\alpha_1 f_1(\theta'') + \alpha_2 f_2(\theta'')] \quad (\text{using } f_2(\theta'') = f_2(\theta')f_1(\theta'')/f_1(\theta')) \\ &= \text{sign}[(\alpha \cdot f)(\theta'')]. \end{aligned}$$

If, on the other hand, $f_1(\theta')f_2(\theta'') = f_1(\theta'')f_2(\theta') = 0$, then at least one function value, say $f_1(\theta')$, equals zero. It follows from (41) that $f_1(\theta') = f_1(\theta'') = 0$. Thus,

$$\text{sign}[(\alpha \cdot f)(\theta')] = \text{sign}[\alpha_2 f_2(\theta')] = \text{sign}[\alpha_2 f_2(\theta'')] = \text{sign}[(\alpha \cdot f)(\theta'')]. \quad Q.E.D.$$

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