#### Sustainable Energy Transformation Technologies, SH2706

Lecture No 6

Title:

Work extraction constraints: entropy and exergy

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#### **Outline**

- Introduction
- Balance equations using lumped parameter approach
  - control mass formulation
  - control volume formulation
- Entropy analysis
- Exergy analysis

#### Introduction

- Thermal analyses of energy transformation systems involve solution of conservation (balance) equations
- Primarily, conservation of mass, momentum and energy is considered
- Often these equations are referred to as transport equations
- The thermal analyses allow to determine the distributions of temperature, pressure and flows in the system

#### Types of Transport Equations

Integral

Lumped parameter

Distributed parameter

Differential

Lagrangian equations

Eulerian equations

#### Integral Approach

 The integral approach is suitable for an analysis of the behaviour of a specific mass or region of a system as a whole

It can be divided as:

System of three connected volumes

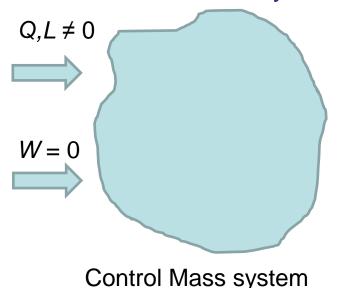
- lumped parameter integral approach, when the medium is present in several sections (volumes), and within each section the spatial distributions of variables and material properties are ignored
- distributed parameter integral approach, in which the spatial distributions of variables and material properties are taken into account

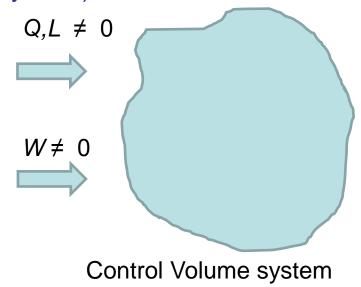
#### Differential Approach

- The differential approach is a distributed parameter approach where the balance equations are formulated for each point and not for the entire system
- It can be divided into two categories:
  - Lagrangian approach, when the coordinates move at the local medium velocity
  - Eulerian approach, when the coordinates are moving at any velocity, and in particular, they can be stationary in space at a particular position
- Further in this lecture we discuss lumped parameter approach only

# Control Mass and Control Volume

- Lumped parameter approach can be applied in two types of systems:
  - control mass system (or closed system)
  - control volume system (or open system)





#### Control Mass Formulation (1)

- Control mass (CM) system is defined as such a system that no mass crosses its boundary
- A boundary which is not crossed by mass is called a material boundary and the corresponding volume: a material volume
- Mass conservation for such system is just stating that the mass (m) in the system (material) volume  $(V_m)$  is constant

$$\frac{Dm}{Dt} = 0$$

• Here D/Dt is the material (or substantial) derivative  $\frac{D}{Dt} = \frac{\partial}{\partial t} + \mathbf{v} \cdot \nabla$ 

#### Control Mass Formulation (2)

 The rate of momentum creation of the CM system is equal to the net external force (Newton's second law)

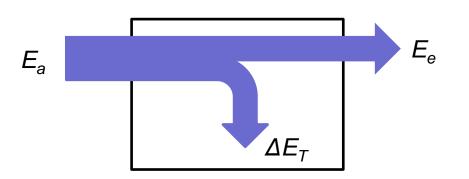
$$\frac{D(m\mathbf{v})}{Dt} = \frac{D\mathbf{p}}{Dt} = \sum_{k} \mathbf{F}_{k}$$

Here p = mv is the system momentum and F<sub>k</sub> is the k-th external force acting on the system

#### Control Mass Formulation (3)

 The energy conservation (first law) states that the rate of change of the stored energy in CM is equal to the difference between the rate of energy addition (as heat or work) to CM and the rate of energy extraction from

CM



Since no substance passes through the boundary, energy transfer can take place only through heat (Q) and work (L):

$$\Delta E_T = Q - L$$

By convention, heat added to a system and work extracted from a system are considered positive

 $E_a$  – energy added;  $E_e$  – energy extracted;  $\Delta E_T$  – system total energy change;

#### Control Mass Formulation (4)

• The total energy of the system can be defined as a sum of the internal energy  $(E_l)$ , kinetic energy  $(E_K)$  and potential energy  $(E_P)$ :

$$E_T = E_I + E_K + E_P$$

- The kinetic and the potential energies are related to the macroscopic effects of the system as a whole
- The internal energy is entirely resulting from microscopic effects:
  - oscillatory, translational and rotational kinetic energy of atoms and molecules; potential energy in the field of attraction forces between molecules; chemical energy related to a possibility of reconstruction of molecules; nuclear energy

#### Control Mass Formulation (5)

• The total work can be partitioned into a shaft work  $L_{shaft}$  (positive in a turbine and negative in a pump), work transmitted through a control boundary by normal  $(L_{normal})$  and tangential  $(L_{shear})$  forces:

$$L = L_{shaft} + L_{normal} + L_{shear}$$

Thus the energy equation for a control mass system is

$$\Delta E_{T} = Q - L_{shaft} - L_{normal} - L_{shear}$$

#### Control Mass Formulation (6)

 Typically energy transformation systems operate continuously, and the energy conservation equation can be expressed in the time rate:

$$\frac{dE_T}{dt} = \frac{\delta Q}{dt} - \frac{\delta L_{shaft}}{dt} - \frac{\delta L_{normal}}{dt} - \frac{\delta L_{shear}}{dt}$$

• Using notation  $q = \delta Q/dt$  (thermal power) and  $N = \delta L/dt$  (mechanical power), we have

$$\frac{dE_T}{dt} = q - N_{shaft} - N_{normal} - N_{shear}$$

#### Control Mass Formulation (7)

• Frequently the energy equation is expressed in terms of the specific total energy, that is the total energy per unit mass,  $e_T = E_T/m$ , where  $e_T = e_I + e_K + e_P$ :

$$\frac{dE_T}{dt} = \frac{d}{dt} \left[ m \left( e_I + e_K + e_P \right) \right] = q - N_{shaft} - N_{normal} - N_{shear}$$

• we should note that  $e_l$  is the specific internal energy,  $e_K = U^2/2$  – is the specific kinetic energy and  $e_P = gh$  – is the specific potential energy

#### Control Mass Formulation (8)

- The entropy inequality (the second law) states that the net change of the entropy of CM interacting with its surroundings and the entropy change of the surroundings of CM should be equal to or greater than zero
- Since no mass is crossing CM boundary, the entropy exchanges with the surroundings are associated with heat interactions
- The entropy inequality is then

$$\frac{DS}{Dt} = \left(\frac{dS}{dt}\right)_{CM} \ge \frac{\left(\delta Q/dt\right)_{CM}}{T_S}$$

 $T_S$  – temperature at the location where  $\delta Q$  is supplied

#### Control Mass Formulation (9)

• For irreversible (real-life) processes the inequality holds, since additional entropy is generated in CM due to irreversibility. Then we have:

$$\left(\frac{dS}{dt}\right)_{CM} = \dot{S}_{gen} + \frac{\left(\delta Q/dt\right)_{CM}}{T_{S}}$$

• here  $\dot{S}_{\it gen}$  is the rate of entropy generation due to irreversibility

#### Control Mass Formulation (10)

 An immediate consequence of the entropy balance equation is that for a reversible adiabatic process the entropy of the control mass system is unchanged

$$\left(\frac{dS}{dt}\right)_{CM} = \dot{S}_{gen} + \frac{\left(\frac{\partial Q}{\partial t}\right)_{CM}}{T_{S}} = 0$$

Such process is also termed as an isentropic process

#### Control Volume Formulation (1)

- Control volume (CV) system is defined as such a system that both mass and heat can cross its boundary
- Mass conservation for such system is stating that the net mass flow rate into the system volume ( $V_{CV}$ ) equals the rate of change of the mass in the volume

$$\frac{Dm}{Dt} = \left(\frac{dm}{dt}\right)_{CV} - \sum_{i} W_{i} = 0 \qquad \text{or} \qquad \left(\frac{dm}{dt}\right)_{CV} = \sum_{i} W_{i}$$

- Here  $W_i$  is a mass flow rate through port i and  $(dm/dt)_{CV}$  is the rate of mass change in the control volume
- Note that W>0 for mass flow into the volume

#### Control Volume Formulation (2)

 The rate of momentum creation of the system is equal to the net external force and the net influx of momentum to the system (Newton's second law)

$$\left[\frac{d\left(m\mathbf{v}\right)}{dt}\right]_{CV} = \sum_{i} W_{i}\mathbf{v}_{i} + \sum_{i} \mathbf{F}_{k}$$
momentum rate-of-change

net influx of momentum

net external force

#### Control Volume Formulation (3)

- The energy conservation (first law) applied to a control volume states that the rate of change of the stored energy in CV is equal to the net rate of energy influx to CV and any sources or sinks within the volume
- Let us assume that substance with mass dm and the total specific energy  $e_T = e_I + e_K + e_P$  enters the control volume, in which the prevailing pressure is p
- Since mass dm has a volume d $V = dm/\rho$  ( $\rho$  density) this process requires additional work to be performed against the system pressure equal to  $\delta L_m = -pdV = -pdm/\rho$

#### Control Volume Formulation (4)

Thus the total energy change of the system is

$$\frac{dE_T}{dt} = e_T W - \left(-pW/\rho\right) = \left(e_T + p/\rho\right)W = W\left(e_I + p/\rho + e_K + e_P\right)$$

• since the specific enthalpy is  $i = e_i + p/\rho$  we can write

$$\frac{dE_T}{dt} = W\left(i + e_K + e_P\right)$$

and the energy conservation equation becomes

$$\frac{dE_{\scriptscriptstyle T}}{dt} = q - N_{\scriptscriptstyle shaft} - N_{\scriptscriptstyle normal} - N_{\scriptscriptstyle shear} + \sum_{j \in in} \left(i + e_{\scriptscriptstyle P} + e_{\scriptscriptstyle K}\right)_j W_j - \sum_{k \in out} \left(i + e_{\scriptscriptstyle P} + e_{\scriptscriptstyle K}\right)_k W_k$$

#### Importance of the Second Law

- Any analysis of Energy Transformation Systems (ETS) must include the Second Law of Thermodynamics
- This is not because the second law is necessary to determine the flow and temperature fields (for that purpose the first law is used)
- Second law helps to strive after systems with high thermodynamic efficiency, meaning minimum generation of entropy, or minimum destruction of available work (exergy)
- The second law quantifies the real-life fact that all processes are irreversible and supports the applied field of entropy generation minimization

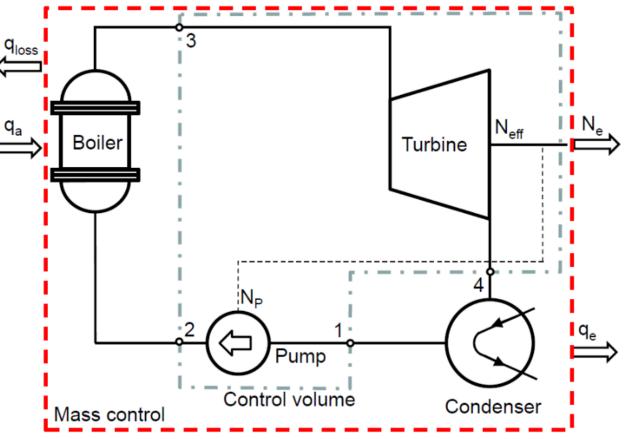
#### Entropy Analysis (1)

For system shown in the picture, we can write mass, energy and entropy balances.

For that purpose we will use the control volume as indicated in the picture.

The control volume has two inflow ports: (3) and (1) and two outflow ports: (2) and (4).

The mass, energy and entropy carried to the system through port 1 per unit time is  $W_1$ ,  $W_1i_1$ ,  $W_1s_1$ 



The entropy decrease per unit time due to heat loss  $q_{loss}$  is  $(dS/dt)_{loss}$  and entropy increase per unit time inside the control volume is  $(dS/dt)_{gen}$ 

# Entropy Analysis (2)

Mass conservation applied to the control volume gives:

$$W_3 - W_4 + W_1 - W_2 = 0$$

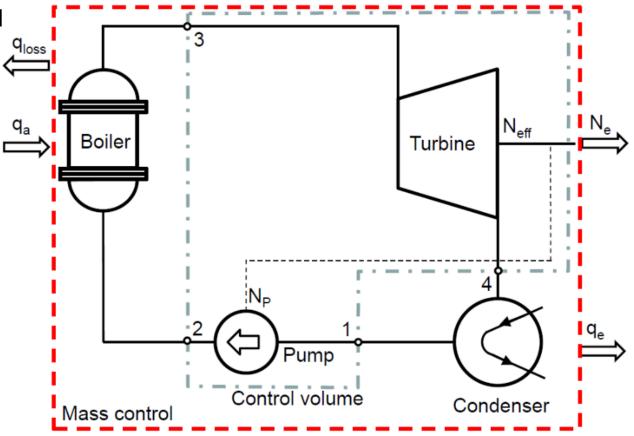
This equation is satisfied automatically since:

$$W_3 = W_4 = W_1 = W_2$$

Energy conservation gives:

$$q_a + q_{loss} + q_e - N_e = 0,$$

where  $q_a = W_3 i_3 - W_2 i_2$ (added heat) and  $q_e = W_1 i_1 - W_4 i_4$  (extracted heat).  $q_{loss} < 0$  represents systems' thermal losses



Entropy balance for the control volume reads:

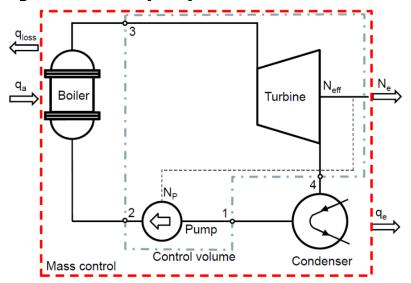
$$W_3s_3-W_2s_2+W_1s_1-W_4s_4+(dS/dt)_{loss}+(dS/dt)_{gen}=0$$

### Entropy Analysis (3)

(1) Thus, the following entropy balance is obtained:

$$W_b\left(s_3 - s_2\right) + W_c\left(s_1 - s_4\right) + \left(\frac{dS}{dt}\right)_{loss} + \left(\frac{dS}{dt}\right)_{gen} = 0$$

here we note that  $W_3 = W_2 = W_b$  (flow through the boiler) and  $W_4 = W_1 = W_c$  (flow through the condenser). At steady state operation they are equal:  $W_b = W_c$ .



(2) From the energy balance we have:

$$W_b(i_3 - i_2) = q_a \Longrightarrow W_b = \frac{q_a}{(i_3 - i_2)}$$

$$W_c(i_1 - i_4) = q_e \Longrightarrow W_c = \frac{q_e}{(i_1 - i_4)}$$

(3) Combining the energy and entropy equations yields:

$$q_{a} \frac{s_{3} - s_{2}}{i_{3} - i_{2}} + q_{e} \frac{s_{1} - s_{4}}{i_{1} - i_{4}} + \left(\frac{dS}{dt}\right)_{loss} + \left(\frac{dS}{dt}\right)_{gen} = 0$$

#### Entropy Analysis (4)

(1) Now the entropy balance is as follows:

$$q_a \frac{s_3 - s_2}{i_3 - i_2} + q_e \frac{s_1 - s_4}{i_1 - i_4} + \left(\frac{dS}{dt}\right)_{loss} + \left(\frac{dS}{dt}\right)_{gen} = 0$$

We define the average thermodynamic temperature for heat addition in the boiler as:

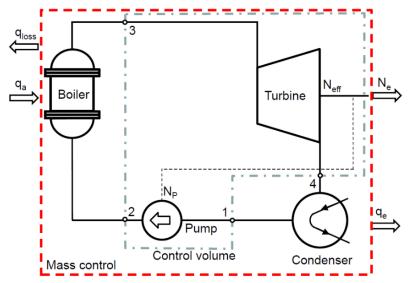
$$\overline{T}_a = \left| \frac{i_3 - i_2}{s_3 - s_2} \right|$$

and for heat extraction in the condenser as:

$$\overline{T}_e = \left| rac{i_4 - i_1}{s_4 - s_1} \right|$$

(2) The entropy balance is now:

$$\frac{q_a}{\overline{T}_a} + \frac{q_e}{\overline{T}_e} + \left(\frac{dS}{dt}\right)_{loss} + \left(\frac{dS}{dt}\right)_{gen} = 0$$



(3) We repeat here the energy conservation:

$$q_a + q_e + q_{loss} - N_e = 0$$

or:

$$q_e = -q_a - q_{loss} + N_e$$

#### Entropy Analysis (5)

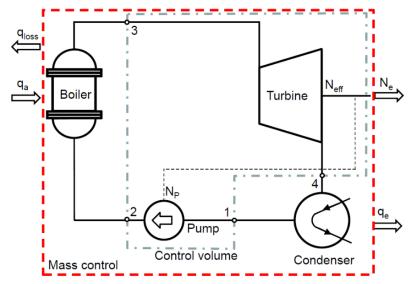
(1) We combine now the energy conservation equation with the entropy balance equation:

$$\frac{q_a}{\overline{T}_a} + \frac{q_e}{\overline{T}_e} + \left(\frac{dS}{dt}\right)_{loss} + \left(\frac{dS}{dt}\right)_{gen} = 0$$

$$q_e = -q_a - q_{loss} + N_e$$

and we get:

$$\frac{q_a}{\overline{T}_a} - \frac{q_a}{\overline{T}_e} - \frac{q_{loss}}{\overline{T}_e} + \frac{N_e}{\overline{T}_e} + \left(\frac{dS}{dt}\right)_{loss} + \left(\frac{dS}{dt}\right)_{gen} = 0$$



This gives the following expression for the extracted power:

$$N_{e} = q_{a} \left( 1 - \frac{\overline{T}_{e}}{\overline{T}_{a}} \right) + q_{loss} - \overline{T}_{e} \left( \frac{dS}{dt} \right)_{loss} - \overline{T}_{e} \left( \frac{dS}{dt} \right)_{gen}$$

note that  $q_{loss} < 0$ 

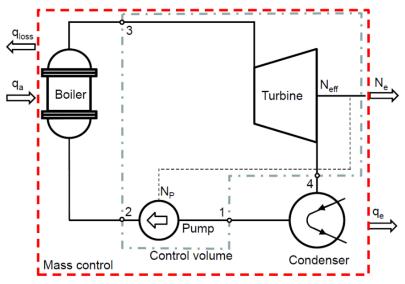
# **Entropy Analysis (6)**

We have obtained the following expression for the extracted power:

$$N_e = q_a \left( 1 - \frac{\overline{T}_e}{\overline{T}_a} \right)$$

Carnot heat engine power

$$-iggl[ \overline{T_e} iggl( rac{dS}{dt} iggr)_{loss} - q_{loss} iggr]$$
 Power loss due to heat loss



$$-\overline{T}_{e}\left(\frac{dS}{dt}\right)_{gen}$$

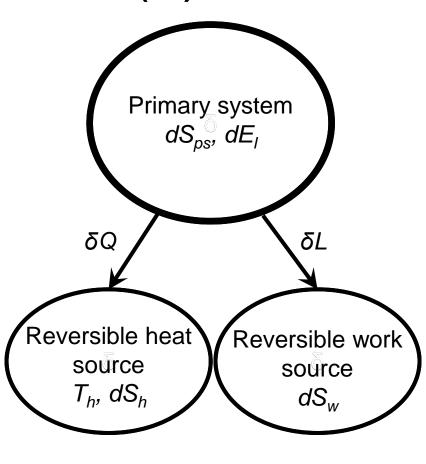
Power loss due to entropy generation

Since the two last terms on the right-hand side of the equation are negative, they all deteriorate the over-all system efficiency

#### Maximum Work (1)

 For a given finite thermodynamic cycle the maximum work can be determined from the first and second law of thermodynamics

 The derivation of the maximum work was first given by Gibbs who considered a primary system connected to reversible heat and reversible work sources



#### Maximum Work (2)

First law of thermodynamics for the primary system:

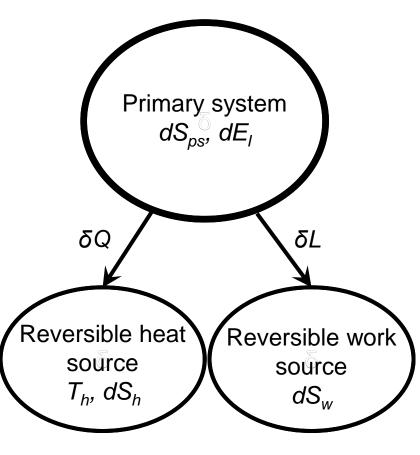
$$dE_I = \delta Q - \delta L$$

An internal energy change  $dE_l$  is equal to a heat exchanged with the RHS,  $\delta Q$ , minus a work exchanged with RWS,  $\delta L$ 

Second law of thermodynamics says:

$$dS_h + dS_w + dS_{ps} \ge 0$$

The sum of entropy changes in the primary system and sources is non-negative



### Maximum Work (3)

Reversibility of the work source dictates:

$$dS_w = 0$$

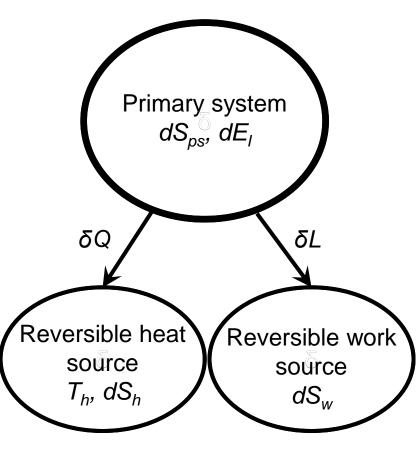
Reversibility of the heat source gives:

$$-\delta Q = T_h dS_h$$

Using the above in the 1st and 2nd law

gives 
$$-\frac{dE_I + \delta L}{T_h} + dS_{ps} \ge 0$$

or 
$$\delta L \leq T_h dS_{ps} - dE_I$$

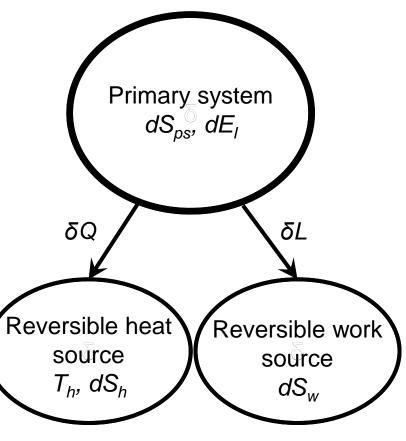


#### Maximum Work (4)

When the primary system is reversible the equality will hold and the work will be a maximum:

$$\delta L_{\text{max}} = T_h dS_{ps} - dE_I$$

The above equation states that the maximum (positive) work can be obtained from a system whose internal energy drops (then  $dE_I$ <0) reduced by  $T_h dS_{ps}$  (note that  $T_h dS_{ps}$ <0 when  $\delta Q$ <0).



The maximum work principle gives explicit prove that it is not possible to use internal energy entirely to perform work. The maximum work = internal energy drop reduced by  $T_h dS_{ps}$ , where  $dS_{ps} < 0$ , when  $\delta Q < 0$ 

#### Maximum Work (5)

The derived maximum work principle is as follows:

$$\delta L_{\text{max}} = T_h dS_{ps} - dE_I$$

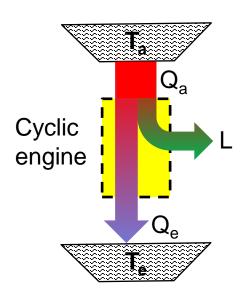
 We can integrate the above equations between two states (1) and (2):

$$L_{\text{max}} = \int_{1}^{2} \delta L_{\text{max}} = E_{I1} - E_{I2} - T_{h} \left( S_{ps1} - S_{ps2} \right)$$

 It should be noted that this expression is not valid for cyclic processes where states (1) and (2) are identical

#### Maximum Work (6)

 To derive an expression for the maximum work in a cyclic process, we assume a model as follows:

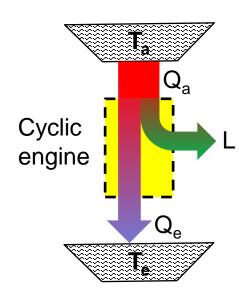


The engine operates between two heat reservoirs with temperatures  $T_a$ , from which, during a single cycle, heat  $Q_a$  is added to the system, and a reservoir with temperature  $T_e$ , to which heat  $Q_e$ , extracted from the system, is deposited. The engine delivers work L.

We will investigate what is the maximum work that can be delivered by the engine.

#### Maximum Work (7)

Note that from the point of view of the cyclic engine,  $Q_a > 0$  (system gains heat), L > 0 (according to convention work delivered by a system is positive) and  $Q_e < 0$  (system loses heat).



The first law for the engine operating during one cycle is as follows

$$\Delta E_I = Q_a + Q_e - L = 0$$

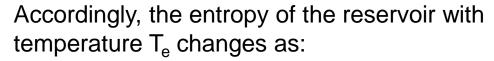
From which, we have:

$$L = Q_a + Q_e$$

#### Maximum Work (8)

The reservoir with temperature  $T_a$  loses heat  $Q_{Ra} = -Q_a < 0$  and its entropy changes as:

$$\Delta S_a = \frac{Q_{Ra}}{T_a} = -\frac{Q_a}{T_a} < 0$$



$$\Delta S_e = \frac{Q_{Re}}{T_e} = -\frac{Q_e}{T_a} > 0$$

Since the engine works in a cycle, the change of entropy  $\Delta S_{Engine} = 0$ for the engine itself is zero:

$$\Delta S_{Engine} = 0$$

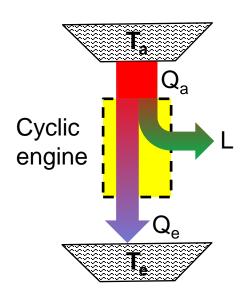
The total entropy change becomes: 
$$\Delta S_{total} = \Delta S_a + \Delta S_e = \frac{Q_{Ra}}{T_a} + \frac{Q_{Re}}{T_e} > 0$$

### Maximum Work (9)

#### Summarizing:

From the 1st law we have:

$$L = Q_a + Q_e$$



The 2<sup>nd</sup> law:

$$-\frac{Q_a}{T_a} - \frac{Q_e}{T_e} > 0$$

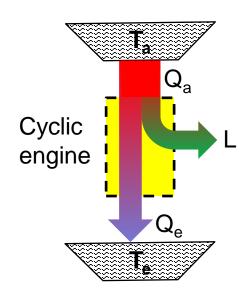
Combining the two expressions yields:

$$-\frac{Q_a}{T_a} - \frac{L - Q_a}{T_e} > 0 \quad \text{or} \qquad Q_a \left( 1 - \frac{T_e}{T_a} \right) - L > 0$$

#### Maximum Work (10)

Thus for a cyclic engine the following limitation is valid:

$$L < Q_a \left( 1 - \frac{T_e}{T_a} \right) = Q_a \eta_C \text{ where } \eta_C \equiv \left( 1 - \frac{T_e}{T_a} \right)$$



The obtained result indicates that only a fraction of the heat added to a cyclic engine can be converted into work.

The maximum work in a cyclic engine is thus:

$$L_{\text{max}} = Q_a \eta_C$$

where  $\eta_C$  is the Carnot cycle efficiency

### Exergy (1)

- Deriving the expression for the maximum work we noticed that only a fraction of the system energy is available (has potential) to do useful work
- Energy that is available to be used is called exergy, or sometime, available energy
- Determining exergy was the first goal of thermodynamics
- Application of exergy analyses in chemical plants was partially responsible for its huge grow in 20<sup>th</sup> century

### Exergy (2)

- The fundamental difference between energy and exergy is that energy is conserved, whereas exergy is not
- From 1<sup>st</sup> law, energy input and output will always balance
- Exergy output will not balance the exergy input for real processes since a fraction of the exergy input will be destroyed according to the 2<sup>nd</sup> law

## Exergy (3)

- An energy efficiency or first law efficiency will determine the most efficient process, where as little as possible of the input energy is wasted
- An exergy efficiency or second law efficiency will determine the most efficient process, where as little as possible of the <u>available work</u>, from a given <u>input of</u> <u>available work</u>, will be destroyed

#### Exergy (4)

The thermal exergy B<sub>th</sub> is defined as

$$B_{th} = E_I + p_0 V - T_0 S - \underbrace{\sum_{i} \mu_{i0} n_i}_{\text{available energy}}$$

$$\underbrace{\sum_{\text{internal energy available physical energy}}_{\text{available physical energy}} - \underbrace{\sum_{i} \mu_{i0} n_i}_{\text{available chemical energy}}$$

• For a mass stream penetrating a control volume boundary, it is convenient to partition the (total) exergy time rate  $\dot{B}$  as

$$\dot{B} = \dot{B}_{k} + \dot{B}_{p} + \dot{B}_{th} = W \left( \frac{U^{2}}{2} + gh + b_{th} \right)$$
kinetic potential thermal exergy exergy

• here U – absolute mean speed, h – center-of-mass elevation,  $b_{th}$  – specific thermal exergy

#### Exergy (5)

Additionally, the thermal exergy is partitioned as

$$\dot{B}_{th} = \dot{B}_{ph} + \dot{B}_{ch} = W \left( b_{ph} + b_{ch} \right)$$
physical chemical exergy

Chemical exergy only changes when chemical reactions take place (e.g. fuel combustion)

where the physical exergy can be found as

$$\dot{B}_{ph} = Wb_{ph} = W\left(i_{ph} - T_{0}s_{ph}\right) = W\left[i - i_{0} - T_{0}\left(s - s_{0}\right)\right]$$

• where  $i_{ph}$ ,  $s_{ph}$  – specific physical enthalpy and entropy (calculated in reference to ambient),  $i_0$ ,  $s_0$  – specific enthalpy and entropy at ambient pressure and temperature

### Exergy (6)

 For an ideal gas, the specific physical exergy is obtained as

$$b_{ph} = c_p \left( T - T_0 - T_0 \ln \frac{T}{T_0} \right) + RT_0 \ln \frac{p}{p_0}$$

• where  $c_p$  is the specific heat at constant pressure, R is the specific gas constant, T,  $T_0$  is the actual and ambient temperature and p,  $p_0$  is the actual and ambient pressure

# Exergy (7)

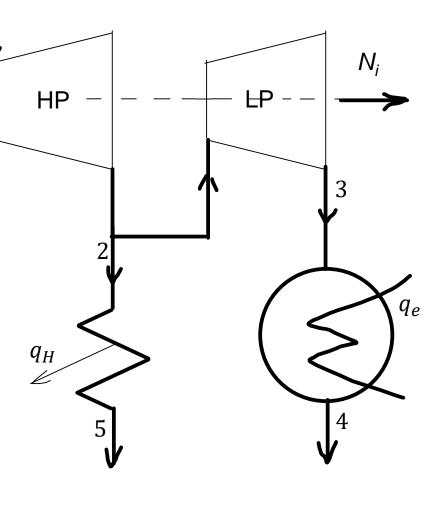
Consider a system as shown in the figure

 Working fluid flows in through inlet 1 with mass flow rate W<sub>1</sub>

 Thus the system gains exergy per unit time given as:

$$\dot{B}_{1} = W_{1} \left[ i_{1} - i_{0} - T_{0} \left( s_{1} - s_{0} \right) \right]$$

• here  $i_1$ ,  $s_1$  – specific enthalpy and entropy at inlet 1,  $i_0$ ,  $s_0$  – working fluid's specific enthalpy and entropy at ambient pressure  $p_0$  and temperature  $T_0$ , respectively



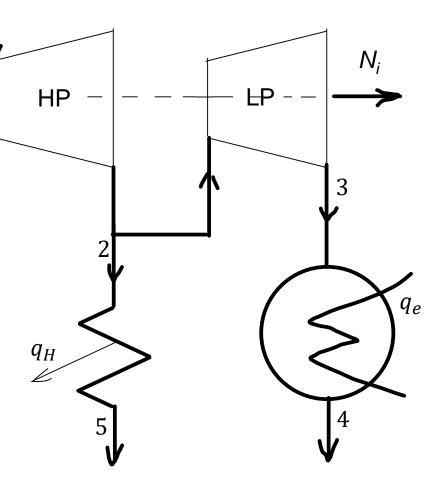
# Exergy (8)

- Similarly, working fluid flows out through outlets 4 and 5 with mass flow rates W<sub>4</sub> and W<sub>5</sub>, respectively
- Thus the system loses exergy per unit time given as:

$$\dot{B}_{4} = W_{4} \left[ i_{4} - i_{0} - T_{0} \left( s_{4} - s_{0} \right) \right]$$

$$\dot{B}_{5} = W_{5} \left[ i_{5} - i_{0} - T_{0} \left( s_{5} - s_{0} \right) \right]$$

• here  $i_4$ ,  $s_4$  – specific enthalpy and entropy at outlet 4,  $T_0$ ambient temperature, etc



# Exergy (9)

• There is also loss of exergy due to heat sinks. For example, if thermal power  $q_H$  is leaving the system at temperature  $T_H$ , the exergy loss is

$$\dot{B}_H = q_H \, \frac{T_H - T_0}{T_H} \quad \text{ NOTE: if } T_H = T_0, \\ \text{then } B_H = 0$$

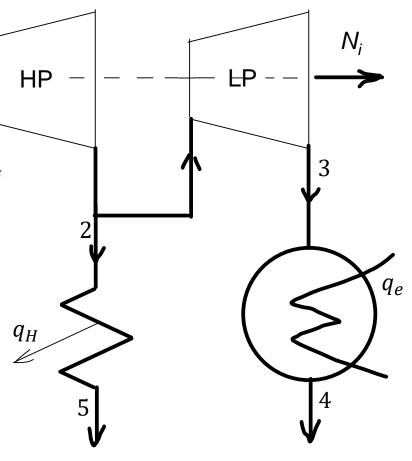
 Note that this exergy loss corresponds to the Carnot engine power working with heat q<sub>H</sub> at high temperature T<sub>H</sub> and low temperature T<sub>0</sub>

# Exergy (10)

 The general rule for the exergy balance in an open system is as follows

$$B_{a} = \Delta B_{sys} + B_{e} + L + \Delta B_{sources} + \delta B_{int-loss}$$

- B<sub>a</sub> exergy of added material
- B<sub>e</sub> exergy of extracted material
- $\Delta B_{\text{sys}}$  system exergy change
- ΔB<sub>source</sub> exergy change due to heat sources/sinks
- $\delta B_{int-loss}$  internal exergy loss
- L work performed by the system

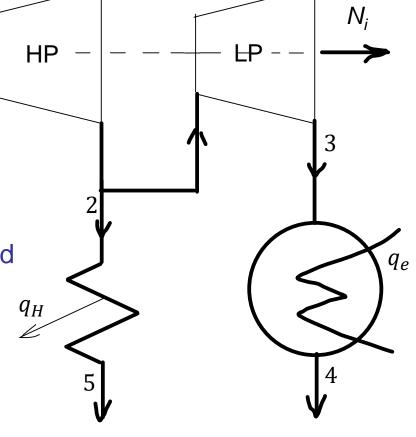


## Exergy (11)

 For steady-state conditions the system exergy will not change, and internal exergy losses can be found as

$$\delta B_{int\text{-}loss} = B_a - B_e - L - \Delta B_{sources}$$

 thus the exergy losses are obtained as a difference between exergy added (B<sub>a</sub>) and exergy leaving the system with working fluid (B<sub>e</sub>), as work (L) and as heat (ΔB<sub>sources</sub>)



# Exergy (12)

 Expressed as time-rate loss of exergy, we have

$$\delta \dot{B}_{int\text{-}loss} = \dot{B}_a - \dot{B}_e - N - \Delta \dot{B}_{sources}$$

where

$$\dot{B}_a = W_a \left[ i_a - i_0 - T_0 \left( s_a - s_0 \right) \right]$$

$$\dot{B}_{e} = W_{e} \left[ i_{e} - i_{0} - T_{0} \left( s_{e} - s_{0} \right) \right]$$

$$\Delta \dot{B}_{sources} = q_{sources} \frac{T_{sources} - T_0}{T_{sources}}$$

