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1. i To get tangent vector, we take derivative of  $(x(t), y(t))$  respect to  $t$ .

$$x'(t) = (4\cos(2\pi t) + \frac{\cos(32\pi t)}{16})' = -2\pi(4\sin(2\pi t) + \sin(32\pi t))$$

$$y'(t) = (2\sin(2\pi t) + \frac{\sin(32\pi t)}{16})' = 2\pi(2\cos(2\pi t) + \cos(32\pi t))$$

Then the tangent vector is  $(-(4\sin(2\pi t) + \sin(32\pi t)), (2\cos(2\pi t) + \cos(32\pi t)))$

- ii To get normal vector, we know that at any point normal vector is perpendicular to tangent vector; hence, normal vector is  $((2\cos(2\pi t) + \cos(32\pi t)), (4\sin(2\pi t) + \sin(32\pi t)))$  or  $(-(2\cos(2\pi t) + \cos(32\pi t)), -(4\sin(2\pi t) + \sin(32\pi t)))$ .

- iii The curve is symmetric around X-axis and symmetric around Y-axis.

We could notice that both  $x(t)$  and  $y(t)$  are periodic functions which repeat over intervals of 1 radians.

Also if a function  $f(x)$  is symmetric around X-axis means  $f(x) = -f(x)$  and is symmetric around Y-axis means  $f(x) = f(-x)$ .

Symmetric around X-axis:

First, we know that  $\cos(t) = \cos(-t)$  which means  $x(t) = x(-t)$ . Also,  $\sin(t) = -\sin(-t)$  which means  $y(t) = -y(-t)$ . Then at  $t$  and  $-t$  time, the curve has same x coordinates but opposite y coordinates; hence, the curve is symmetric around X-axis.

Symmetric around Y-axis:

We know that  $\cos(t) = -\cos(\pi - t)$  which means  $x(t) = -x(0.5 - t)$ . Also,  $\sin(t) = \sin(\pi - t)$  which means  $y(t) = y(0.5 - t)$ . Then at  $t$  and  $0.5 - t$  time, the curve has opposite x coordinates but same y coordinates; hence, the curve is symmetric around Y-axis.

- iv Since both  $x(t)$  and  $y(t)$  are periodic functions which repeat over intervals of 1 radians, and symmetric around both X-axis and Y-axis.

Then perimeter:

$$\begin{aligned} p &= 4 \int_0^{0.25} \sqrt{(x'(t))^2 + (y'(t))^2} dt \\ &= 4 \int_0^{0.25} \sqrt{(2\pi(4\sin(2\pi t) + \sin(32\pi t)))^2 + (2\pi(2\cos(2\pi t) + \cos(32\pi t)))^2} dt \end{aligned}$$

- v Define  $f(t)$  as follow:

$$f(t) = \sqrt{(2\pi(4\sin(2\pi t) + \sin(32\pi t)))^2 + (2\pi(2\cos(2\pi t) + \cos(32\pi t)))^2}$$

The way we approximate the perimeter is approximate the integral above. So we divide the interval  $[0, 0.25]$  to  $n$  sub-interval  $[x_0, x_1], [x_1, x_2] \dots [x_{n-1}, x_n]$  where  $x_0 = 0, x_n = 0.25$ . Then calculate sum,  $perimeter = 4 \sum_{i=0}^{n-1} [(f(x_{i+1}) - f(x_i))(x_{i+1} - x_i)]$ .

2. Denote  $C_1$  to be the circle with radius  $r_1$  and  $C_2$  to be the circle with radius  $r_2$  ( $r_2 > r_1$ ).

- i The area of donut is  $A = \pi(r_2)^2 - \pi(r_1)^2 = \pi((r_2)^2 - (r_1)^2)$ .

- ii There can be 0, 1, 2, 3 and 4 intersections.

- iii The distance from the centre  $(p_1)$  of the circles to line  $p(\lambda) = p_0 + \lambda \vec{d}$  is

$$distance: d = \|(p_0 - p_1) - ((p_0 - p_1) \cdot \vec{n}) \vec{n}\| \quad \text{where } \vec{n} = \frac{\vec{d}}{|\vec{d}|}$$

- (1) if  $d > r_2$ , then there is no intersection;  
 (2) if  $d = r_2$ , then there is 1 intersection, then solve the equation

$$\|(p_0 - p_1) - \lambda \vec{d}\| = r_2$$

get one solution  $\lambda_0$  and  $p(\lambda_0)$  is the location of the intersection.

- (3) if  $r_2 > d > r_1$ , then there 2 intersections, then solve the equation

$$\|(p_0 - p_1) - \lambda \vec{d}\| = r_2$$

get two solutions  $\lambda_0, \lambda_1$  and  $p(\lambda_0), p(\lambda_1)$  are the location of the intersections.

- (4) if  $d = r_1$ , then there are 3 intersections, then solve then solve the equation

$$\|(p_0 - p_1) - \lambda \vec{d}\| = r_2$$

$$\|(p_0 - p_1) - \lambda \vec{d}\| = r_1$$

get three solutions  $\lambda_0, \lambda_1, \lambda_2$  and  $p(\lambda_0), p(\lambda_1), p(\lambda_2)$  are the location of the intersections.

- (5) if  $d < r_1$ , then there are 4 intersections, then solve then solve the equation

$$\|(p_0 - p_1) - \lambda \vec{d}\| = r_2$$

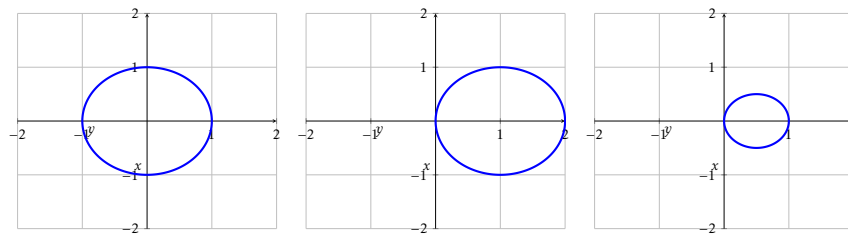
$$\|(p_0 - p_1) - \lambda \vec{d}\| = r_1$$

get three solutions  $\lambda_0, \lambda_1, \lambda_2, \lambda_3$  and  $p(\lambda_0), p(\lambda_1), p(\lambda_2), p(\lambda_3)$  are the location of the intersections.

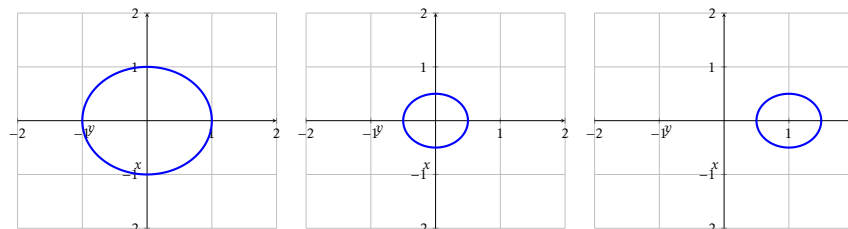
- iv If both line and donut transformed by a non-uniform scale  $(s_x, s_y)$ , then intersection won't change. Suppose the old location is  $(x, y)$ , then location after scale it will be  $(s_x x, s_y y)$ .

- v Suppose  $A(x, y)$  is a point on the donut. After scaling, it becomes  $A'(s_x x, s_y y)$ . Then  $\Delta(A'A) = (A' - A)$ , and  $\theta = \arccos\left(\frac{\overrightarrow{A'-A} \cdot \vec{d}}{|\overrightarrow{A'-A}| |\vec{d}|}\right)$ . Then if  $\pi < \theta < 2\pi$  means after scaling  $A$  is closer to the line, if  $0 < \theta < \pi$  means  $A$  is away from the line after scaling and  $\theta = 0 \vee \theta = \pi$  means the distance from  $A$  to the line remains the same.

3. (a) Translation and uniform scaling do not commute First, translate by  $(1, 0)$ , then scaled by  $(\frac{1}{2}, \frac{1}{2})$ :

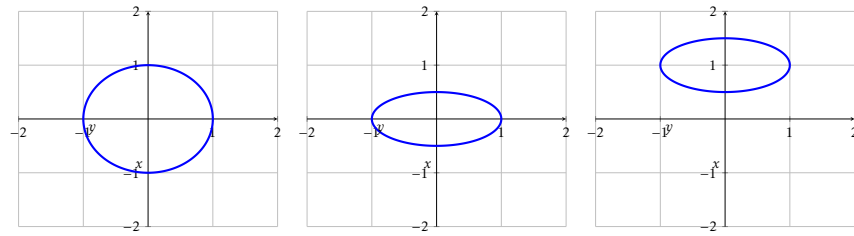


Now, apply it reversely, scaled by  $(\frac{1}{2}, \frac{1}{2})$ , then translate by  $(1, 0)$ :

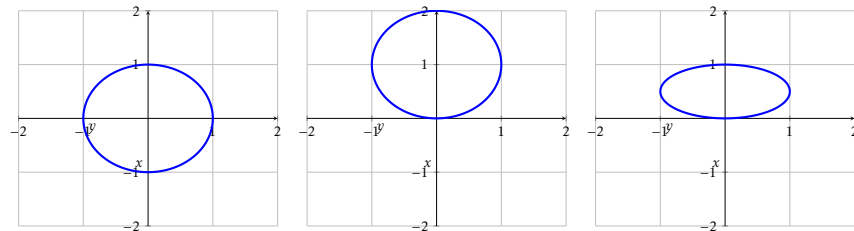


Hence, clearly translation and uniform scaling do not commute.

(b) Translation and non-uniform scaling do not commute. First we scaled by  $(1, \frac{1}{2})$ , then translate by  $(0, 1)$  :



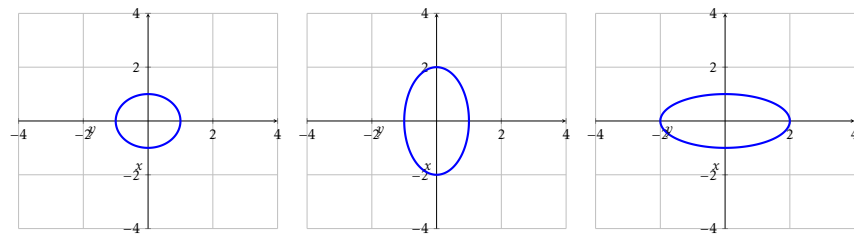
Now, we apply translation first, then scaling:



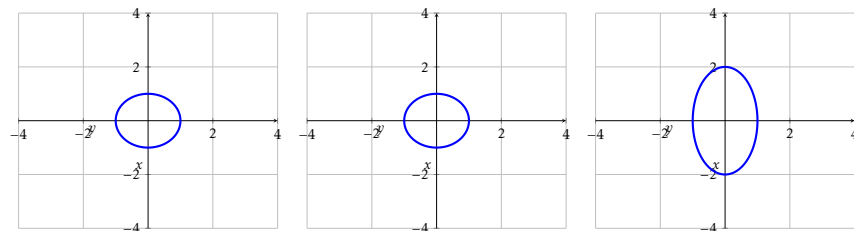
Hence, translation and non-uniform scaling do not commute.

(c) Scaling and rotation, both having the same fixed points commute.

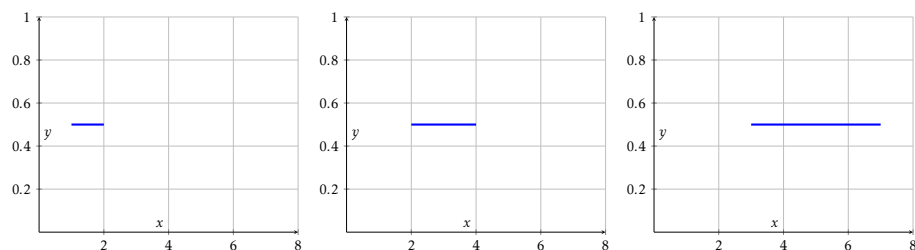
Scaling by  $(1, 2)$ , then rotating  $\frac{\pi}{2}$ :



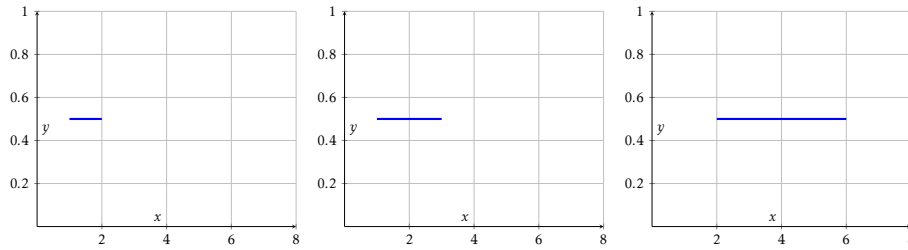
Now, rotating first then scaling



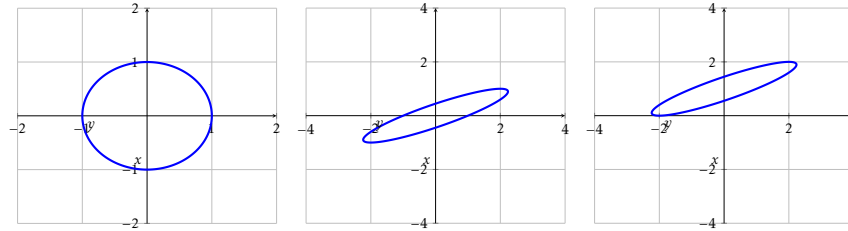
(d) Scaling and scaling, having different fixed points do not commute. First, Scaling around  $(0, 0)$  by  $(2, 0)$ , then around  $(1, 0)$  by  $(2, 0)$ :



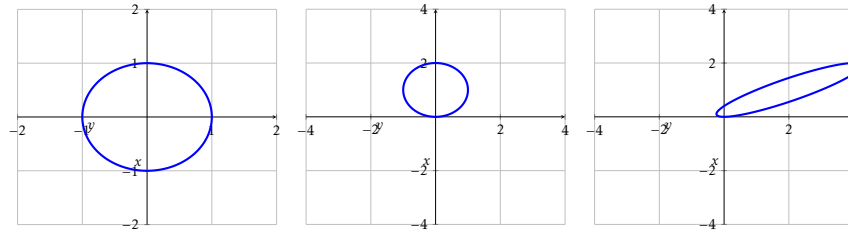
First, Scaling around  $(1, 0)$  by  $(2, 0)$ , then around  $(0, 0)$  by  $(2, 0)$  :



(e) Translation and shear do not commute. First, shearing by  $\begin{bmatrix} 1 & 2 \\ 0 & 1 \end{bmatrix}$ , then translate by  $(0, 1)$ :



Now, we first translate by  $(0, 1)$  then shearing by  $\begin{bmatrix} 1 & 2 \\ 0 & 1 \end{bmatrix}$ :



Hence, translation and shear do not commute.

4. i First we create 3 vectors  $\overrightarrow{v_0 - q}$ ,  $\overrightarrow{v_1 - q}$ ,  $\overrightarrow{v_2 - q}$  using  $v_0, v_1, v_2$  and  $q$ .

$$\theta_0 = \arccos\left(\frac{\overrightarrow{v_0 - q} \cdot \overrightarrow{v_1 - q}}{|\overrightarrow{v_0 - q}| |\overrightarrow{v_1 - q}|}\right)$$

$$\theta_1 = \arccos\left(\frac{\overrightarrow{v_0 - q} \cdot \overrightarrow{v_2 - q}}{|\overrightarrow{v_0 - q}| |\overrightarrow{v_2 - q}|}\right)$$

$$\theta_2 = \arccos\left(\frac{\overrightarrow{v_1 - q} \cdot \overrightarrow{v_2 - q}}{|\overrightarrow{v_1 - q}| |\overrightarrow{v_2 - q}|}\right)$$

Then  $q$  is inside the triangle iff  $(\theta_0 + \theta_1 + \theta_2 = 2\pi) \wedge (\theta_0 \neq \pi) \wedge (\theta_1 \neq \pi) \wedge (\theta_2 \neq \pi)$ ;

$q$  is on the triangle iff  $((v_0 = q) \vee (v_1 = q) \vee (v_2 = q)) \vee ((\theta_0 + \theta_1 + \theta_2 = 2\pi) \wedge ((\theta_0 = \pi) \vee (\theta_1 = \pi) \vee (\theta_2 = \pi)))$ ;

Otherwise,  $q$  is outside the triangle.

- ii Suppose we are given with 4 vertices  $V = \{v_0, v_1, v_2, v_3\}$  and edge set  $E = \{(v_0, v_1), (v_1, v_2), (v_2, v_3), (v_3, v_0)\}$

Define:

$$\theta_0 = \arccos\left(\frac{\overrightarrow{v_1 - v_0} \cdot \overrightarrow{v_2 - v_0}}{|\overrightarrow{v_1 - v_0}| |\overrightarrow{v_2 - v_0}|}\right) + \arccos\left(\frac{\overrightarrow{v_1 - v_0} \cdot \overrightarrow{v_3 - v_0}}{|\overrightarrow{v_1 - v_0}| |\overrightarrow{v_3 - v_0}|}\right) + \arccos\left(\frac{\overrightarrow{v_2 - v_0} \cdot \overrightarrow{v_3 - v_0}}{|\overrightarrow{v_2 - v_0}| |\overrightarrow{v_3 - v_0}|}\right)$$

$$\theta_1 = \arccos\left(\frac{\overrightarrow{v_0 - v_1} \cdot \overrightarrow{v_2 - v_1}}{|\overrightarrow{v_0 - v_1}| |\overrightarrow{v_2 - v_1}|}\right) + \arccos\left(\frac{\overrightarrow{v_0 - v_1} \cdot \overrightarrow{v_3 - v_1}}{|\overrightarrow{v_0 - v_1}| |\overrightarrow{v_3 - v_1}|}\right) + \arccos\left(\frac{\overrightarrow{v_2 - v_1} \cdot \overrightarrow{v_3 - v_1}}{|\overrightarrow{v_2 - v_1}| |\overrightarrow{v_3 - v_1}|}\right)$$

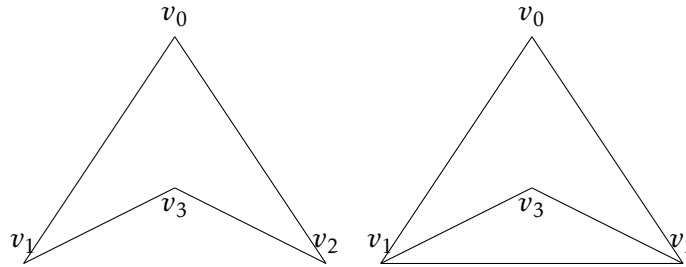
$$\theta_2 = \arccos\left(\frac{\overrightarrow{v_1 - v_2} \cdot \overrightarrow{v_3 - v_2}}{|\overrightarrow{v_1 - v_2}| |\overrightarrow{v_3 - v_2}|}\right) + \arccos\left(\frac{\overrightarrow{v_1 - v_2} \cdot \overrightarrow{v_0 - v_2}}{|\overrightarrow{v_1 - v_2}| |\overrightarrow{v_0 - v_2}|}\right) + \arccos\left(\frac{\overrightarrow{v_0 - v_2} \cdot \overrightarrow{v_3 - v_2}}{|\overrightarrow{v_0 - v_2}| |\overrightarrow{v_3 - v_2}|}\right)$$

$$\theta_3 = \arccos\left(\frac{\overrightarrow{v_1 - v_3} \cdot \overrightarrow{v_2 - v_3}}{|\overrightarrow{v_1 - v_3}| |\overrightarrow{v_2 - v_3}|}\right) + \arccos\left(\frac{\overrightarrow{v_1 - v_3} \cdot \overrightarrow{v_0 - v_3}}{|\overrightarrow{v_1 - v_3}| |\overrightarrow{v_0 - v_3}|}\right) + \arccos\left(\frac{\overrightarrow{v_0 - v_3} \cdot \overrightarrow{v_2 - v_3}}{|\overrightarrow{v_0 - v_3}| |\overrightarrow{v_2 - v_3}|}\right)$$

Check if any  $\theta_0, \theta_1, \theta_2, \theta_3$  equals  $2\pi$ , if  $\theta_x = 2\pi$  we know that quadrilateral is concave. And based on (i) we also know that  $v_x$  is inside the triangle with vertices  $V \setminus v_x$ . Then connect  $v_x, v_y$  where  $(v_y \in V \setminus v_x) \wedge ((v_x, v_y) \notin E)$ , and quadrilateral is now split into the union of two triangles.

If none of  $\theta_0, \theta_1, \theta_2, \theta_3$  equals  $2\pi$  which means the quadrilateral is convex. Then just connect one of two diagonals (i.e  $(v_0, v_2)$  or  $(v_1, v_3)$ ), the quadrilateral is now split into the union of two triangles.

- iii Suppose we are given with  $n$  vertices  $V = \{v_0, v_1, v_2, v_3, \dots, v_{n-1}\}$  and edge set  $E = \{(v_0, v_1), (v_1, v_2), (v_2, v_3), (v_3, v_4), \dots, (v_{n-2}, v_{n-1}), (v_{n-1}, v_0)\}$ . pick any vertex  $v_i$  in the vertices set  $V$  (i.e  $v_0$ ), then connect  $v_i$  to the rest of the vertices if there no edge between them.
- iv Counterexample, this algorithm won't work for concave, for example if we choose  $v_i = v_2$  in the following graph.



- v For any point  $q$ , we connect  $q$  with every vertex in the vertices set  $V$ , and define

$$\theta_i = \arccos\left(\frac{\overrightarrow{v_i - q} \cdot \overrightarrow{v_{i+1 \pmod n} - q}}{|\overrightarrow{v_i - q}| |\overrightarrow{v_{i+1 \pmod n} - q}|}\right) \quad 0 \leq i \leq n-1$$

Also, define the line function for each edge  $i$  is  $l_i$ . Then  $q$  is inside the polygon iff  $\sum_{i=0}^{n-1} \theta_i = 2\pi$  and  $q$  doesn't satisfy any line function  $l_i$ .  $q$  is on the polygon iff  $\sum_{i=0}^{n-1} \theta_i = 2\pi$  and satisfy some line function  $l_i$ . Otherwise,  $q$  is outside the polygon.