manual *

SW1 → assisted → SW2 → PARAM → seatbelt
SW1 → assisted → SW2 → PARAM → simple
SW1 → assisted → SW2 → autoland

SW1 → auto → SW2 → SW? → mission → PARAM → onboard
SW1 → auto → SW2 → SW? → mission → PARAM → offboard
SW1 → auto → SW2 → SW? → loiter
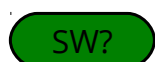SW1 → auto → SW2 → RTL

SW1   mandatory override switch (3 position)

SW2   mandatory flight / land switch (2 position)

SW?   optional mission control switch (2 position, default value if not present)

PARAM   mode depends on parameter (default value is underlined)

* multirotors: attitude stabilized,
   fixed wing: mixing of manual inputs

→ input viewpoint (SW?) → onboard
                        → ground

→ bounding (SW?) → off
                 → on

→ avoidance (SW?) → off
                  → on

→ acro (SW?) → off
             → on