

MAT8034: Machine Learning

Support Vector Machines

Fang Kong

https://fangkongx.github.io/Teaching/MAT8034/Spring2025/index.html

Outline

- Support vector machines
 - Intuition: margins
 - Problem definition
 - Functional and geometric margins
 - The optimal margin classifier
 - Regularization and the non-separable case

Intuition: margins

The confidence of predictions

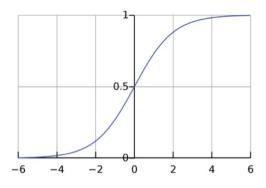
Recall in the logistic regression

- Predict the probability $p(y = 1 | x; \theta)$ using $h_{\theta}(x) = g(\theta^{T}x)$
- Predict the label y = 1 if $h_{\theta}(x) > 0.5$
- Predict the label y = 0 otherwise

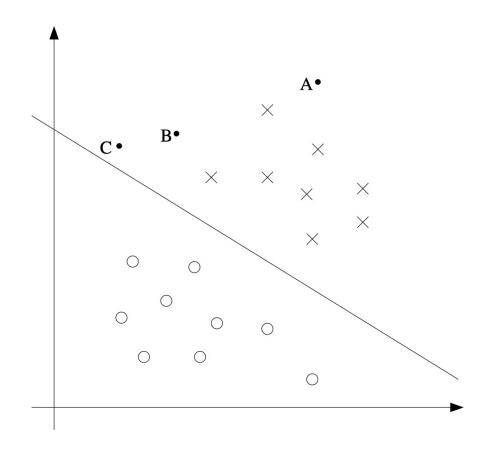








Illustration



Confidence of the prediction: A>B>C

The confidence of predictions

- We have a good model if the θ satisfies
 - When y = 1, $\theta^T x \gg 0$
 - When y = 0, $\theta^{\mathsf{T}} x \ll 0$

This reflects a very confident (and correct) set of classifications

 Our objective: introduce the functional margins (confidence) to evaluate the performance

New formulation of classification

Formulation

- To better evaluate the sigh of the label
 - Label $y \in \{-1,1\}$
- Linear classifier (based on parameter w, b)

$$h_{w,b}(x) = g(w^T x + b)$$

- b plays the role of previous θ_0 , w plays the role of previous $[\theta_1, \theta_2, \dots, \theta_d]$
- Activation function
 - $g(z) = 1 \text{ if } z \ge 0$
 - g(z) = 0 otherwise
- Difference from logistic regression: do not predict the probability

Functional and geometric margins

Functional margin

Define the functional margin w.r.t. training example i

$$\hat{\gamma}^{(i)} = y^{(i)}(w^T x^{(i)} + b)$$

- Intuition: to make the margin larger
 - When $y^i = 1$, hope $w^T x^i + b$ to be a large positive number
 - When $y^i = -1$, hope $w^T x^i + b$ to be a large negative number
 - If $\hat{\gamma}^i > 0$: prediction is correct

A large functional margin represents a confident and a correct prediction.

Functional margin

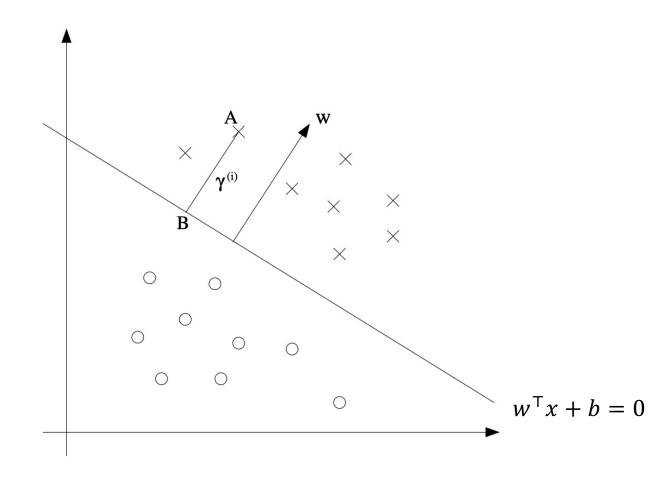
- Given the training set $S = \{(x^1, y^1), (x^2, y^2), ..., (x^n, y^n)\}$
- Define the functional margin w.r.t. training set

$$\hat{\gamma} = \min_{i=1,\dots,n} \hat{\gamma}^{(i)}$$

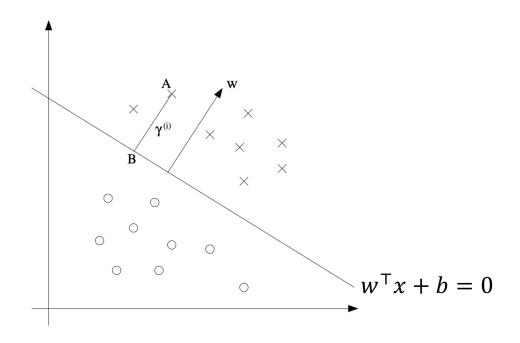
Limitation

- If we replace w, b with 2w, 2b
 - The prediction $g(w^Tx^i + b)$ does not change (since the sigh does not change
 - \blacksquare But the function margin changes $\ \hat{\gamma}^{(i)} = y^{(i)}(w^Tx^{(i)} + b)$
- From this view, optimizing the functional margin changes anything meaningful

Improvement: geometric margins



Improvement: geometric margins



How to compute the function margin?

$$w^{T}\left(x^{(i)} - \gamma^{(i)}\frac{w}{||w||}\right) + b = 0.$$

$$\gamma^{(i)} = \frac{w^T x^{(i)} + b}{||w||} = \left(\frac{w}{||w||}\right)^T x^{(i)} + \frac{b}{||w||}$$

Geometric margins: formal definition

• For any training example (x^i, y^i)

$$\gamma^{(i)} = y^{(i)} \left(\left(\frac{w}{||w||} \right)^T x^{(i)} + \frac{b}{||w||} \right)$$

• If ||w|| = 1, the function margin equals to geometric margin

■ Finally, given training set $S = \{(x^1, y^1), (x^2, y^2), \dots, (x^n, y^n)\}$ $\gamma = \min_{i=1,\dots,n} \gamma^{(i)}$

The optimal margin classifier

The optimization objective

- Given a training set that is linearly separable
- How to achieve the maximum geometric margin

$$\max_{\gamma,w,b} \quad \gamma$$
s.t.
$$y^{(i)}(w^Tx^{(i)}+b) \ge \gamma, \quad i=1,\ldots,n$$

$$||w||=1.$$

Using optimization algorithm to solve it

- But ...
 - $\|w\|=1$ is a non-convex constraint, no standard optimization algorithm

Transforming the problem

New form

$$\max_{\hat{\gamma}, w, b} \frac{\hat{\gamma}}{||w||}$$
s.t. $y^{(i)}(w^T x^{(i)} + b) \ge \hat{\gamma}, \quad i = 1, \dots, n$

• ||w|| is a non-convex

Keep going

- Recall that scaling constraint on w and b without changing anything on prediction but influences the margin
- We can scale w and b to ensure $\hat{\gamma}=1$

- Then maximizing $\frac{\widehat{\gamma}}{\|w\|}$ equivalents to minimizing $\frac{1}{2}\|w\|^2$
- New problem

$$\min_{w,b} \quad \frac{1}{2} ||w||^2$$

s.t. $y^{(i)}(w^T x^{(i)} + b) \ge 1, \quad i = 1, \dots, n$

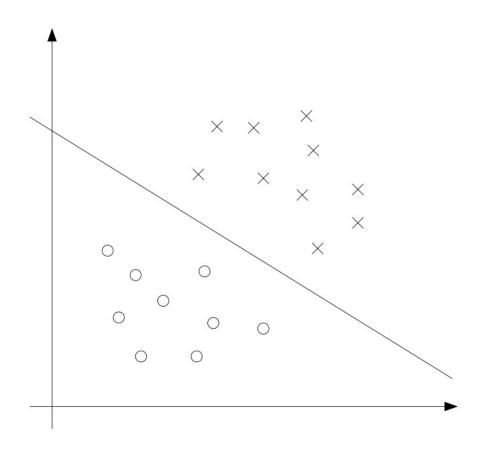
Quadradic convex objective

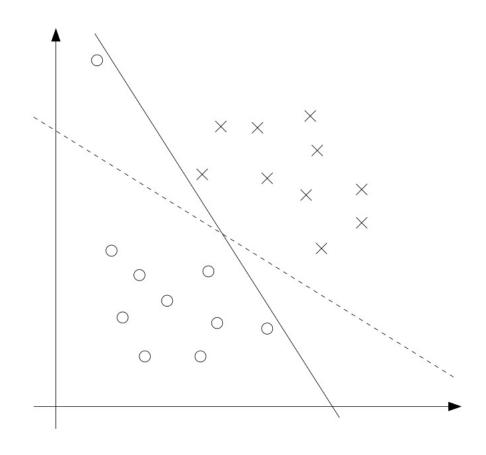
Linear constraint

The dual form and extension using kernel tricks are omitted

Regularization and the non-separable case

What happens if the data is non-separable





Solution

 To make the algorithm work for non-linearly separable datasets as well as be less sensitive to outliers

$$\min_{\gamma,w,b} \frac{1}{2} ||w||^2 + C \sum_{i=1}^n \xi_i$$
s.t. $y^{(i)}(w^T x^{(i)} + b) \ge 1 - \xi_i, i = 1, \dots, n$

$$\xi_i \ge 0, i = 1, \dots, n.$$

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