

Graph Algorithms

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Graphs

A **graph** is a set of **vertices** that are pairwise connected by **edges**.

We distinguish between **directed** and **undirected** graphs.

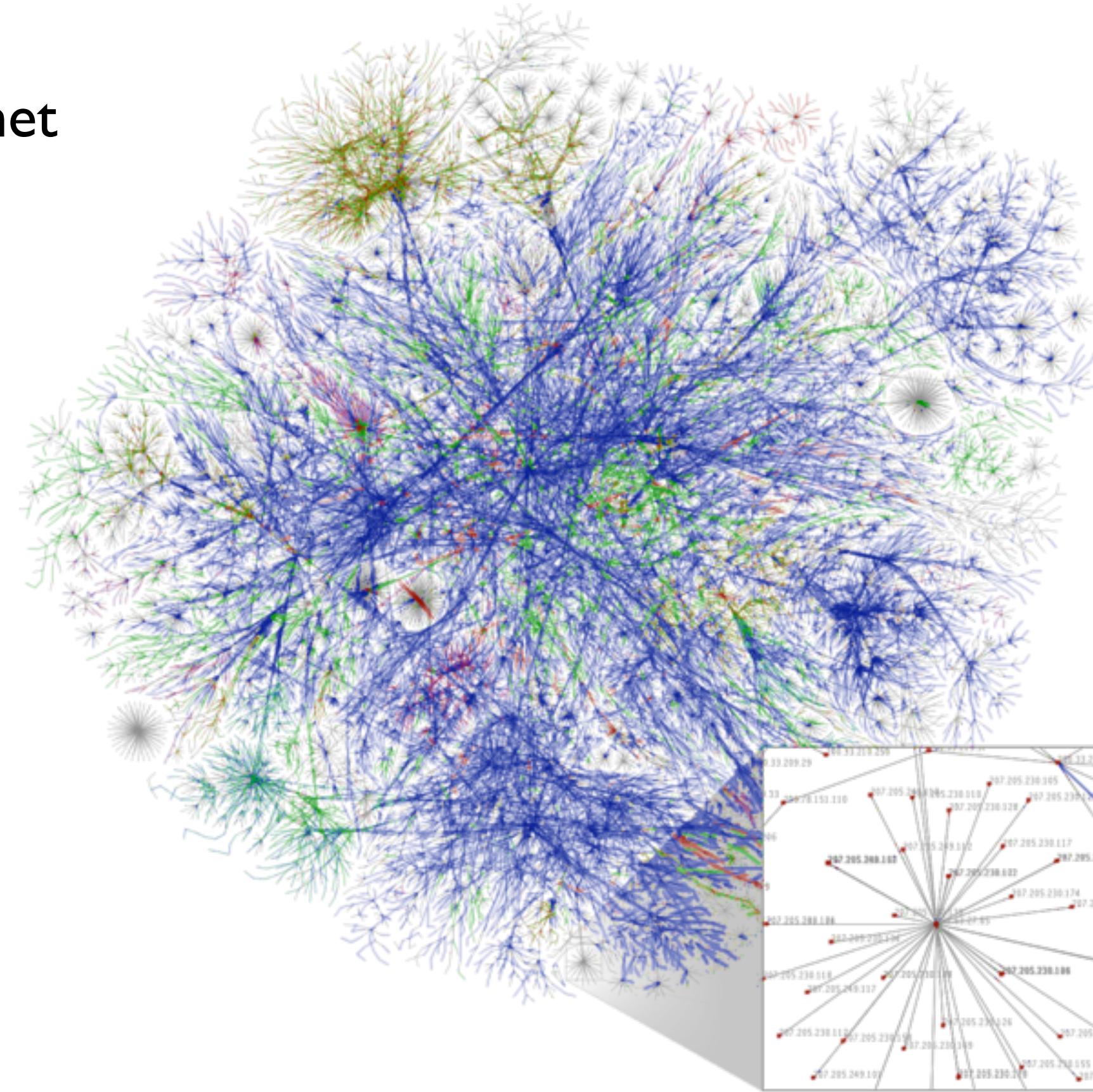
Why are we interested in graphs?

- ⦿ Graphs are a very useful abstraction
- ⦿ Graphs have many interesting applications
- ⦿ Thousands of graph algorithms are known

Versatile Abstraction

Application	Vertices	Edges
Traffic	Intersections	Roads
Social Network	People	Friendship
Internet	Class C network	Connection
Game	Board Position	Legal Move
Erdos number	People	Coauthored Paper
CMOS Circuits	FET, Vdd, Vss, I/O	Wires
Financial	Stock, Currency	Transactions
Programs	Procedures	Procedure Call f->g

The Internet



Undirected Graphs

An undirected graph is a pair $G=(V,E)$, where

- V is a finite set
- E is a subset of $\{ e \mid e \subseteq V, |e|=2 \}$.

The elements in V are called **vertices**.

Elements in E are called **edges**, e.g. $e=\{u,v\}$, written $e=(u,v)$.

Self-loops are not allowed for undirected graphs, $e \neq \{u,u\} = \{u\}$.

Directed Graphs

An directed graph is a pair $G=(V,E)$, where

- V is a finite set
- E is a subset of $V \times V$

The set of edges does not need to be symmetric.

Thus, if (u,v) is an edge, then (v,u) does not need to be an edge.

We illustrate a directed edge often by an arrow $u \rightarrow v$.

Graph Terminology

If $e=(u,v)$ is an edge in a graph, then v is called adjacent to u .

For undirected graphs, adjacency is a symmetric relation.

The edge e is said to be incident to u and v .

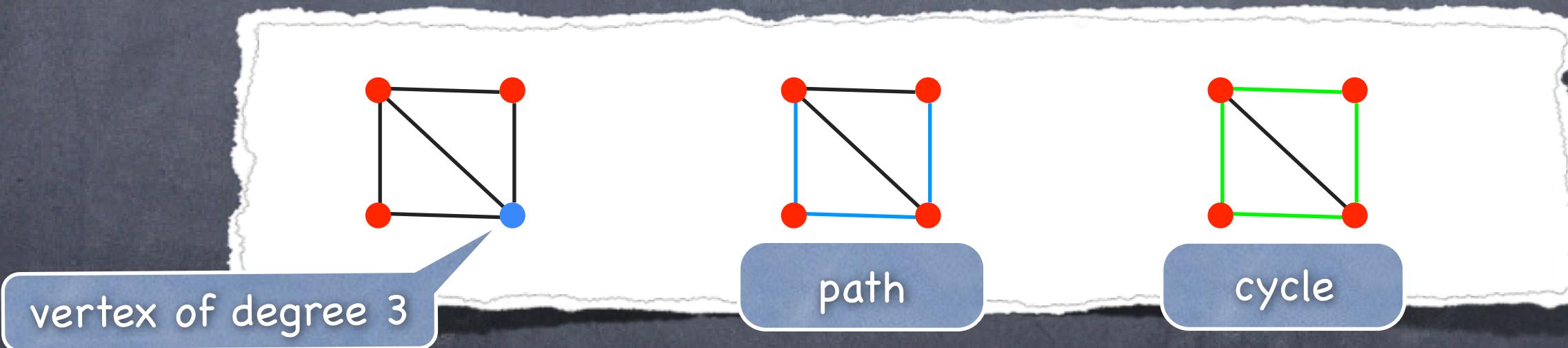
The number of edges incident to a vertex is called the degree of the vertex.

Graph Terminology

A **path** is a sequence of vertices that are connected by edges.

A **cycle** is a path whose first and last vertices are the same.

Two vertices are **connected** if and only if there is a path between them.



Breadth-First Search

Breadth First Search (BFS)

Input: A graph $G = (V,E)$ and source node s in V

mark all nodes v in V as unvisited

mark source node s as visited

`enq(Q,s) // first-in first-out queue Q`

`while (Q is not empty) {`

`u := deq(Q);`

`for each unvisited neighbor v of u {`

`mark v as visited; enq(Q, v);`

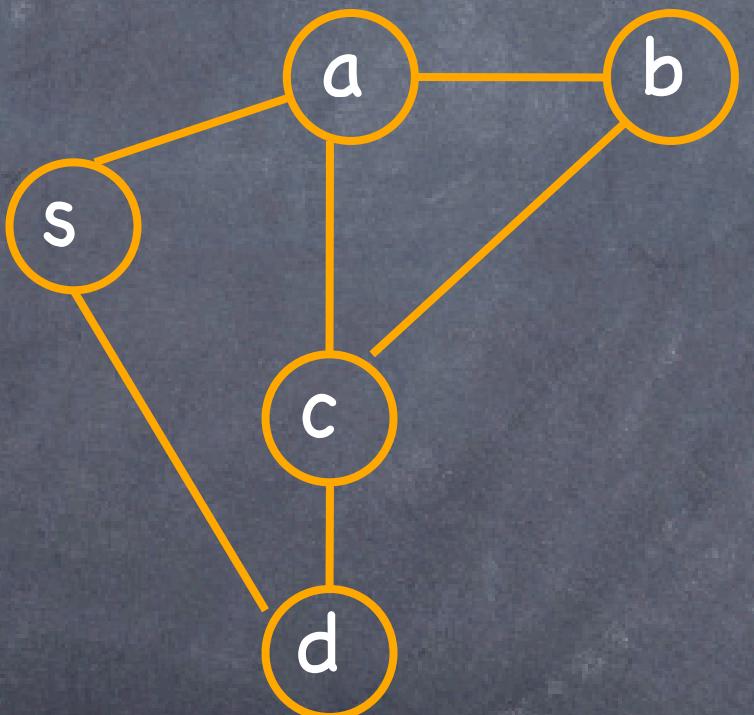
`}`

`}`

Example

demo-bfs

BFS Example



Visit the nodes in the order:

s

a, d

b, c

BFS Tree

We can make a spanning tree rooted at the source node s by remembering the parent of each node.

Breadth First Search (BFS)

Input: A graph $G = (V,E)$ and source node s in V

mark all nodes v in V as unvisited; set $\text{parent}[v] := \text{nil}$ for all v in V

mark source node s as visited; $\text{parent}[s] := s$;

$\text{enq}(Q,s)$ // first-in first-out queue Q

while (Q is not empty) {

$u := \text{deq}(Q)$;

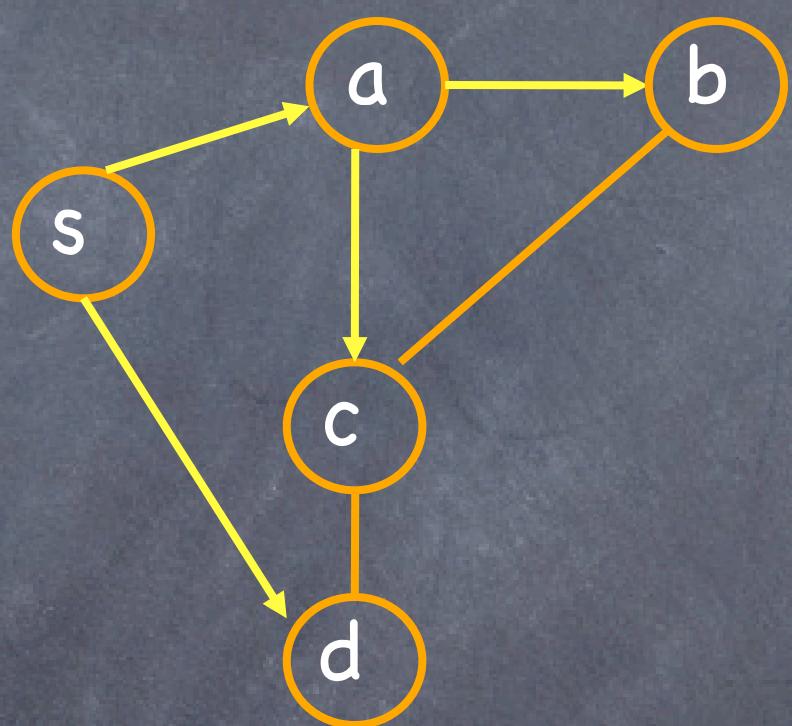
 for each unvisited neighbor v of u {

 mark v as visited; $\text{enq}(Q,v)$; $\text{parent}[v] := u$

 }

}

BFS Tree Example



BFS Trees

The BFS tree is in general **not unique** for a given graph. It depends on the order in which neighboring nodes are processed.

BFS Numbering

During the breadth-first search, assign to each node v its distance $d[v]$ from the source.

Breadth First Search (BFS)

Input: A graph $G = (V,E)$ and source node s in V

mark all nodes v in V as unvisited; set $\text{parent}[v] := \text{nil}$; $d[v] = \infty$ for all v in V

mark source node s as visited; $\text{parent}[s] := s$; $d[s] = 0$

$\text{enq}(Q,s)$ // first-in first-out queue Q

while (Q is not empty) {

$u := \text{deq}(Q);$

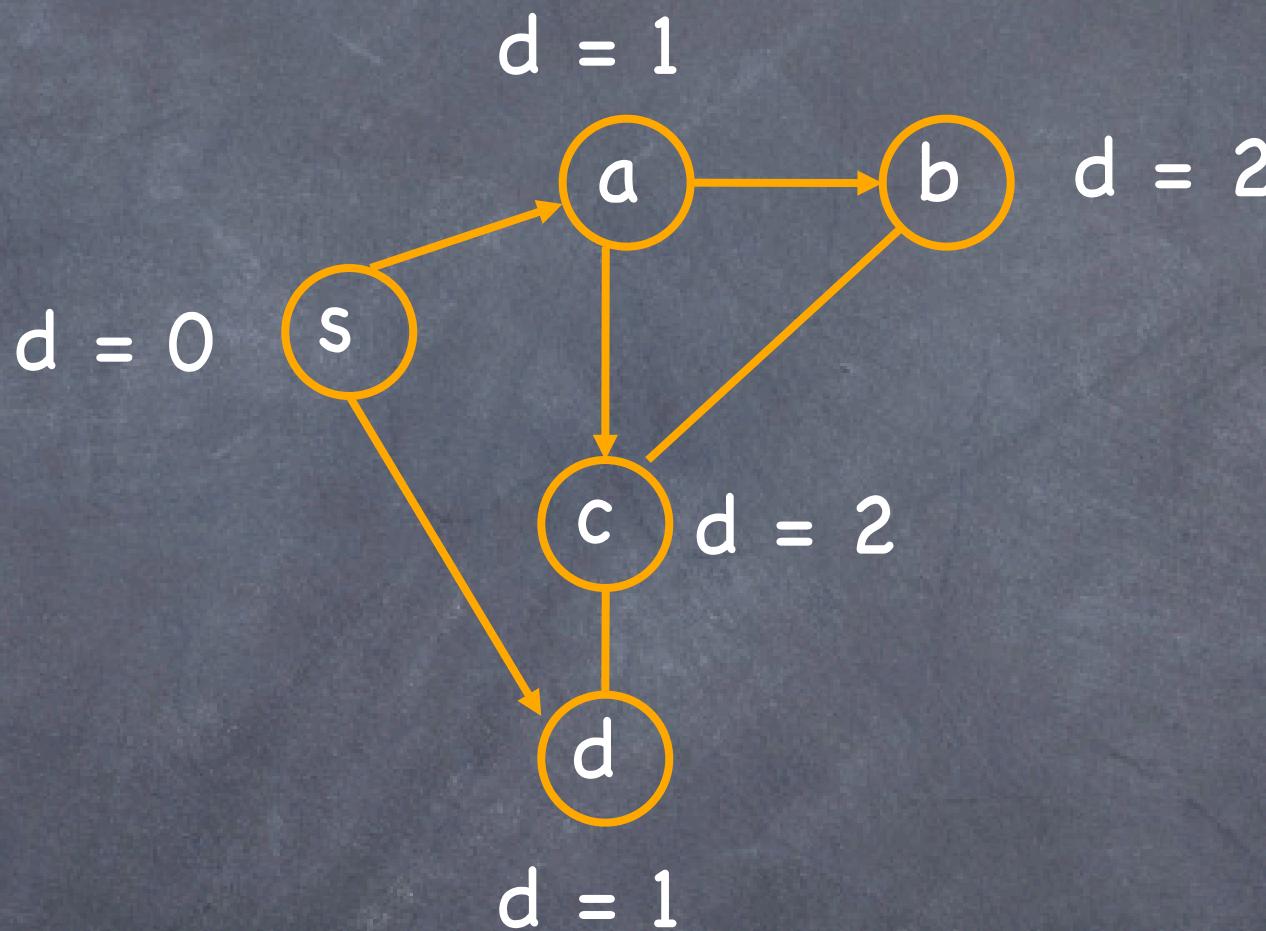
 for each unvisited neighbor v of u {

 mark v as visited; $\text{enq}(Q,v)$; $\text{parent}[v] := u$; $d[v] = d[u]+1$

 }

}

BFS Numbering Example



Shortest Path Tree

Theorem: The BFS algorithm

- visits all and only nodes reachable from s
- for all nodes v sets $d[v]$ to the shortest path distance from s to v
- sets parent variables to form a shortest path tree

Proof Ideas

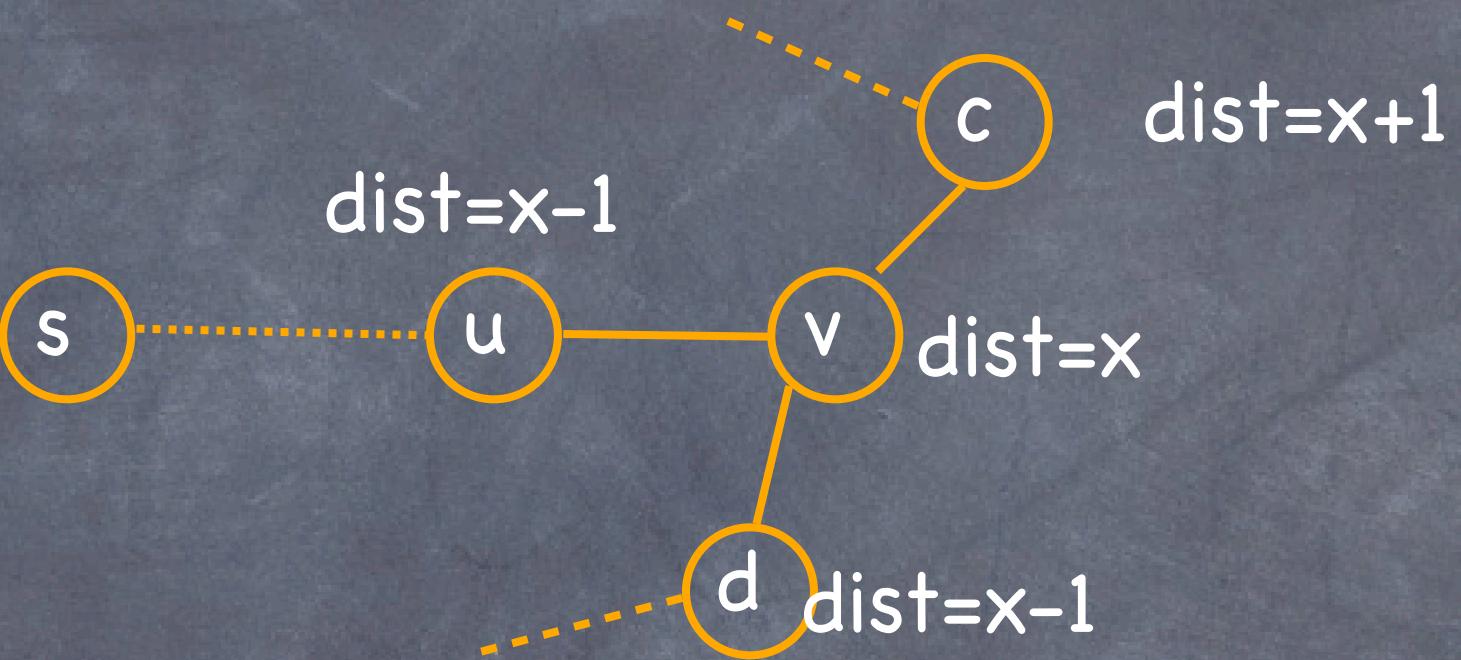
We use induction on the distance from the source node s to show that a node v at distance x from s has correct $d[v]$.

Basis: Distance 0. $d[s]$ is set to 0.

Induction: Assume that all nodes u at distance $x-1$ from s satisfy $d[u]=x-1$. Our goal is to show that every node v at distance x satisfies $d[v]=x$ as well.

Since v is at distance x , it has at least one neighbor at distance $x-1$. Let u be the first of these neighbors that is enqueued.

Proof Ideas



A key property of shortest path distances: If v has distance x ,

- ⦿ it must have a neighbor with distance $x-1$,
- ⦿ no neighbor has distance less than $x-1$, and
- ⦿ no neighbor has distance more than $x+1$

Proof Ideas

Claim: When the node u is dequeued, then v is still unvisited.

Indeed, this follows from behavior of the queue and the fact that d never underestimates the distance.

By induction, $d[u] = x-1$.

When v is enqueued, $d[v]$ is set to $d[u] + 1 = x$.

BFS Running Time

Initialization of each node takes $O(V)$ time

Every node is enqueued once and dequeued once, taking $O(V)$ time

When a node is dequeued, all its neighbors are checked to see if they are unvisited, taking time proportional to number of neighbors of the node, and summing to $O(E)$ over all iterations

Total time is $O(V+E)$

Credits

In the preparation of these slides, I got inspired by slides by Robert Sedgewick. The slides on BFS are based on slides by Jennifer Welch.