$$Z = \begin{bmatrix} 0.4 \\ 0.8 \end{bmatrix}$$

Since with our his should also have 2. channels.

$$h_1 = \begin{bmatrix} 0.38 & 1.4 \\ 0.96 & 1.06 \end{bmatrix}$$
 $h_2 = \begin{bmatrix} 0.7 & 1.54 \\ 1.60 & 1.06 \end{bmatrix}$

because the filter is 3x3x2, We need to pad 2 pixel of o at each edge.

$$C_{1} = ConV2D(h_{1}, w_{1}) \begin{cases} 0.114 & 0.572 & 0.636 & 0.28 \\ 0.134 & 0.528 & 1.634 & 6.552 \\ 0.286 & (.63 & 1.436 & 0.246 \\ 0.48 & 0.914 & 0.52 & 0.106 \end{cases} \begin{cases} 0.21 & 0.602 & 0.658 & 0.77 \\ 0.626 & 1.58 & 0.63 & 0.992 \\ 0.744 & 0.664 & 1.734 & 0.626 \\ 0.972 & 0.798 & 0.143 & 0.212 \end{cases}$$

After adding pias,

$$h_1 = 0$$
 $h_2 = 1$ h_2

Given TA's policy, except I index from o.

$$M = W_2 H_2 + b_2 = 11.9786.$$

$$P(y=0) = \hat{y} = P(m)$$

$$= 0.999.$$

Q2.

pcy=0) means the input H2 offered by
the generation network. To maximiz the discriminator.
the loss function is:

Negativo log likehihood because we want to use gradient descent.

2.1 Gradient of prediction: Vy

$$\nabla \hat{y} = \frac{\lambda^{-1} \circ g \hat{y}}{\lambda^{2}} = -\frac{1}{\hat{y}} = -\frac{1}$$

2.2 Gradient of Hz: VHa.

$$\nabla_{H_2} = \frac{\partial m}{\partial H_2} \frac{\partial \hat{y}}{\partial m} \nabla \hat{y}$$

$$= W_2 \hat{y} (1 - \hat{y}) \nabla \hat{y}.$$

2.3 Gradient of hz: Thz

$$\nabla h_{1} = \left[\nabla H_{2} CO \cdots \nabla H_{2} [3] \right]$$

$$\nabla H_{2} [4]$$

$$\vdots$$

$$\nabla H_{2} [12] \cdots \nabla H_{2} [15]$$

$$2.4 Gradient of w, $2 \nabla w$,$$

$$H_{b} = C_{1} h_{1}^{1} + C_{2} h_{1}^{2} + b_{1} \Rightarrow h_{1} = C(H_{b} - b_{1}).$$
where C_{1} is a 4×16 . matrix, which is based on $w_{1}^{1} = \begin{bmatrix} a_{0} & 0_{1} & 0_{1} \\ a_{0} & 0_{1} & 0_{1} \\ a_{0} & 0_{1} & 0_{1} \end{bmatrix}$

$$C_{1} = \begin{bmatrix} w_{1}^{1} D_{1} g_{1}^{1} w_{1}^{1} J_{1} w_{1}^{1} J_{1} g_{2}^{1} g_{2}^{1} g_{1}^{1} g_{1}^{1} g_{2}^{1} g_{$$

$$\nabla_{G_{1}} = \frac{\partial H_{2}}{\partial C_{1}} \nabla H_{2}.$$

$$= \frac{16}{5} \frac{\partial H_{2} \Gamma_{1}}{\partial C_{1}} \nabla H_{2} \Gamma_{1}.$$

$$= \frac{16}{5} \left[\frac{\partial H_{2} \Gamma_{1}}{\partial C_{1}}, \dots, \frac{\partial H_{2} \Gamma_{1}}{\partial C_{1}} \right]. \text{ This } \Gamma_{1}.$$

$$= \frac{16}{5} \left[\frac{\partial H_{2} \Gamma_{1}}{\partial C_{1}}, \dots, \frac{\partial H_{2} \Gamma_{1}}{\partial C_{1}} \right]. \text{ This } \Gamma_{1}.$$

Whe. 2CIEJI is the column of C.

 $\nabla W_{1}^{\dagger} [0, 0] = \nabla C_{1} [0, 0] + \nabla C_{1} [1, 1] + \nabla C_{1} [2, 4] + \nabla C_{1} [3, 5]$ $\nabla W_{1}^{\dagger} [0, 1] = \nabla C_{1} [0, 1] + \nabla C_{1} [1, 2] + \nabla C_{1} [2, 4] + \nabla C_{1} [2, 6]$ $\nabla W_{1}^{\dagger} [0, 2] = \nabla C_{1} [0, 2] + \nabla C_{1} [1, 3] + \nabla C_{1} [2, 6] + \nabla C_{1} [2, 6]$ $\nabla W_{1}^{\dagger} [1, 0] = \nabla C_{1} [0, 4] + \nabla C_{1} [1, 3] + \nabla C_{1} [2, 6] + \nabla C_{1} [2, 6]$ $\nabla W_{1}^{\dagger} [1, 1] = \nabla C_{1} [0, 4] + \nabla C_{1} [1, 6] + \nabla C_{1} [1, 6] + \nabla C_{1} [2, 6] + \nabla C_{1} [2, 10]$ $\nabla W_{1}^{\dagger} [1, 1] = \nabla C_{1} [0, 6] + \nabla C_{1} [1, 7] + \nabla C_{1} [1, 2] + \nabla C_{1} [2, 10] + \nabla C_{1} [2, 11]$ $\nabla W_{1}^{\dagger} [1, 2] = \nabla C_{1} [0, 6] + \nabla C_{1} [1, 7] + \nabla C_{1} [2, 10] + \nabla C_{1} [2, 13] + \nabla C_{1} [2, 13]$ $\nabla W_{1}^{\dagger} [2, 2] = \nabla C_{1} [0, 7] + \nabla C_{1} [1, 10] + \nabla C_{1} [2, 13] + \nabla C_{1} [2, 14]$ $\nabla W_{1}^{\dagger} [2, 2] = \nabla C_{1} [0, 7] + \nabla C_{1} [1, 1] + \nabla C_{1} [2, 14] + \nabla C_{1} [2, 14]$

This is the gradient matrix of. u_i' : $\nabla w_i'$ we can also use the same method to got: ∇w_i^2 So $\nabla w_i = [\nabla w_i'], \nabla w_i^2]$

2.5 Gradient of h_1 $H_2 = C_1 h_1^2 + C_2 h_1^2 + b_1$ $\nabla h_1^2 = \frac{\partial H_{\partial}}{\partial h_1^2} \nabla H_2$ $\nabla h_1^3 = \frac{\partial H_{\partial}}{\partial h_1^3} \nabla H_2$

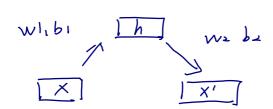
2.6 Gradient of ho. $h_1 = \text{reshape(ho)}$: $\nabla h_0 = \left[\frac{1}{\sqrt{h_1^2}} \right]$

a.7. Gradient of No ho = Pelu (woz, + bo)

$$\frac{\partial h_{o}Li]}{\partial w_{o}L8JLi} \frac{\partial h_{o}Li]}{\partial w_{o}L8JLi}$$

$$\frac{\partial h_{o}Li]}{\partial w_{o}LjJLi} = \begin{cases} 2^{T}, & z=j & h_{o}LiJ > 0. \\ 0, & \text{otherwise.} \end{cases}$$

Q2. Auto Encoder.



$$\begin{cases} h = \text{Pelu}(w_i^T x + b_i) \\ \chi' = \sigma(w_i^T h + b_i) \end{cases}$$

$$w'_i w'' = \text{arg min}_{w'_i w'_j = 1} \sum_{j=1}^{N} c \chi_j - \chi_{ij}^{-j} \partial_{x_i}.$$

Perine the gradient for wie wa.

Find Gradient for
$$x': \nabla x'$$

$$\nabla x' = \begin{bmatrix} 2(x_{EN}] - x'_{EN}] \\ \vdots \\ 2(x_{EN}] - x'_{EN} \end{bmatrix}$$

a.a Gradient for $w_2 : \nabla w_2$. $Z_2 = w_2^T h + b_2$ $\chi' = \sigma(2)$

$$X \in \mathbb{R}^{N \times 1}$$
 $W_1 \in \mathbb{R}^{N \times M}$
 $W_1 \in \mathbb{R}^{M \times 1}$
 $W_2 \in \mathbb{R}^{M \times N}$
 $W_2 \in \mathbb{R}^{M \times N}$
 $W_2 \in \mathbb{R}^{M \times N}$

Fach.
$$\frac{\partial z_2 \tau i J}{\partial w_2 \tau J \xi j J} = \begin{cases} h & \text{if } \tilde{t} = \tilde{j} \\ 0, & \text{other wise.} \end{cases}$$

2.3 Gradient of h: vh.

$$\nabla h = \frac{\partial z_2}{\partial h} \cdot \frac{\partial x'}{\partial z_2} \nabla x'$$

$$= W_2 \cdot x'(1-x') \nabla x'$$

2.4 Gradient of W,:

$$\nabla W_1 = \frac{3h}{3WI} \nabla h$$

Each
$$\frac{\partial h \bar{L}i]}{\partial w_i} = \frac{\partial h \bar{L}i]}{\partial w_i \bar{L}i \bar{J} \bar{L}i \bar{J}} \dots \frac{\partial h \bar{L}i \bar{J}}{\partial w_i \bar{L}i \bar{J} \bar{L}i \bar{J}} \dots \frac{\partial h \bar{L}i \bar{J}}{\partial w_i \bar{L}i \bar{J} \bar{L}i \bar{J}} \dots \frac{\partial h \bar{L}i \bar{J}}{\partial w_i \bar{L}i \bar{J} \bar{L}i \bar{J}} \dots \frac{\partial h \bar{L}i \bar{J}}{\partial w_i \bar{L}i \bar{J} \bar{L}i \bar{J}} \dots \frac{\partial h \bar{L}i \bar{J}}{\partial w_i \bar{L}i \bar{J} \bar{L}i \bar{J}} \dots \frac{\partial h \bar{L}i \bar{J}}{\partial w_i \bar{L}i \bar{J} \bar{L}i \bar{J}} \dots \frac{\partial h \bar{L}i \bar{J}}{\partial w_i \bar{L}i \bar{J} \bar{L}i \bar{J}} \dots \frac{\partial h \bar{L}i \bar{J}}{\partial w_i \bar{L}i \bar{J} \bar{L}i \bar{J}} \dots \frac{\partial h \bar{L}i \bar{J}}{\partial w_i \bar{L}i \bar{J} \bar{L}i \bar{J}} \dots \frac{\partial h \bar{L}i \bar{J}}{\partial w_i \bar{L}i \bar{J} \bar{L}i \bar{J}} \dots \frac{\partial h \bar{L}i \bar{J}}{\partial w_i \bar{L}i \bar{J} \bar{L}i \bar{J}} \dots \frac{\partial h \bar{L}i \bar{J}}{\partial w_i \bar{L}i \bar{J} \bar{L}i \bar{J}} \dots \frac{\partial h \bar{L}i \bar{J}}{\partial w_i \bar{L}i \bar{J} \bar{L}i \bar{J}} \dots \frac{\partial h \bar{L}i \bar{J}}{\partial w_i \bar{L}i \bar{J} \bar{L}i \bar{J}} \dots \frac{\partial h \bar{L}i \bar{J}}{\partial w_i \bar{L}i \bar{J} \bar{L}i \bar{J}} \dots \frac{\partial h \bar{L}i \bar{J}}{\partial w_i \bar{L}i \bar{J} \bar{L}i \bar{J}} \dots \frac{\partial h \bar{L}i \bar{J}}{\partial w_i \bar{L}i \bar{J}i \bar{J}} \dots \frac{\partial h \bar{L}i \bar{J}}{\partial w_i \bar{L}i \bar{J}i \bar{J}} \dots \frac{\partial h \bar{L}i \bar{J}}{\partial w_i \bar{L}i \bar{J}i \bar{J}} \dots \frac{\partial h \bar{L}i \bar{J}}{\partial w_i \bar{L}i \bar{J}i \bar{J}} \dots \frac{\partial h \bar{L}i \bar{J}}{\partial w_i \bar{L}i \bar{J}i \bar{J}} \dots \frac{\partial h \bar{L}i \bar{J}}{\partial w_i \bar{L}i \bar{J}i \bar{J}} \dots \frac{\partial h \bar{L}i \bar{J}}{\partial w_i \bar{L}i \bar{J}i \bar{J}} \dots \frac{\partial h \bar{L}i \bar{J}}{\partial w_i \bar{L}i \bar{J}i \bar{J}} \dots \frac{\partial h \bar{L}i \bar{J}}{\partial w_i \bar{L}i \bar{J}i \bar{J}} \dots \frac{\partial h \bar{L}i \bar{J}}{\partial w_i \bar{L}i \bar{J}i \bar{J}} \dots \frac{\partial h \bar{L}i \bar{J}}{\partial w_i \bar{L}i \bar{J}i \bar{J}} \dots \frac{\partial h \bar{L}i \bar{J}}{\partial w_i \bar{L}i \bar{J}i \bar{J}} \dots \frac{\partial h \bar{L}i \bar{J}}{\partial w_i \bar{L}i \bar{J}i \bar{J}} \dots \frac{\partial h \bar{L}i \bar{J}}{\partial w_i \bar{L}i \bar{J}i \bar{J}} \dots \frac{\partial h \bar{L}i \bar{J}}{\partial w_i \bar{L}i \bar{J}i \bar{J}} \dots \frac{\partial h \bar{L}i \bar{J}}{\partial w_i \bar{L}i \bar{J}i \bar{J}} \dots \frac{\partial h \bar{L}i \bar{J}}{\partial w_i \bar{L}i \bar{J}i \bar{J}} \dots \frac{\partial h \bar{L}i \bar{J}}{\partial w_i \bar{L}i \bar{J}i \bar{J}} \dots \frac{\partial h \bar{L}i \bar{J}}{\partial w_i \bar{L}i \bar{J}i \bar{J}} \dots \frac{\partial h \bar{L}i \bar{J}}{\partial w_i \bar{L}i \bar{J}i \bar{J}} \dots \frac{\partial h \bar{L}i \bar{J}}{\partial w_i \bar{L}i \bar{J}i \bar{J}} \dots \frac{\partial h \bar{L}i \bar{J}}{\partial w_i \bar{L}i \bar{J}i \bar{J}} \dots \frac{\partial h \bar{L}i \bar{J}}{\partial w_i \bar{L}i \bar{J}i \bar{J}} \dots \frac{\partial h \bar{L}i \bar{J}}{\partial w_i \bar{L}i \bar{J}i \bar{J}i \bar{J}i \bar{J}} \dots \frac{\partial h \bar{L}i \bar{J}}{\partial w_i \bar{L}i \bar{J}i \bar{J}i$$