Markov Chain Monte Carlo methods

Stat 580: Statistical Computing

- Theme: Black White
 - Printable version

General information

- A series of random variables $\{Y_i, i = 1, ..., n\}$ has the Markov property if the conditional distribution of Y_i , given all the previous observations $Y_1, ..., Y_{i-1}$ depends only on Y_{i-1} .
- In these two slides, we assume that the state space is countable for ease of exposition.
- If Y_i has a discrete sample space (state space), this is the same as $P(Y_i = k | Y_1, Y_2, \dots, Y_{i-1}) = P(Y_i = k | Y_{i-1} = j) = P_{jk}$, where P_{jk} is the probability that the variable "jumps" from state j to state k, known as transition probability.
- We only focus on the homogeneous case when P_{jk} does not depend on i.
- Transition matrix $P = \{P_{jk}\}$
- $\{Y_1, ...\}$ is called a Markov chain, characterized by P.

General information

- If *P* possesses the following properties:
 - 1. Irreducibility: the Markov chain is not made up of smaller cycles
 - 2. Aperiodicity: $P(X_j = k | X_0 = k) > 0$ and $P(X_{j+1} = k | X_0 = k) > 0$
 - 3. Recurrence: the Markov chain returns to its original state with probability 1.
- Then a stationary distribution (limiting equilibrium distribution) exists, denoted as π or f.

Weather example

In the summer, each day in Ames is either sunny or rainy. A sunny day is followed by another sunny day with probability 0.7, whereas a rainy day is followed by a sunny day with probability 0.4. It rains on Monday (M). Make weather forecasts for Tuesday (T), Wednesday (W), and Thursday (H), using a homogeneous Markov chain model.

- Forecast for Tuesday (one-step transition) P(T sunny | M rainy) = 0.4 P(T rainy | M rainy) = 0.6
- Forecast for Wednesday (two-step transition): e.g., P(W sunny | M rainy) = P(W sunny | T rainy, M rainy)P(T rainy | M rainy) + P(W sunny | T sunny, M rainy)P(T sunny | M rainy) = (0.4)(0.6) + (0.7)(0.4) = 0.52

Weather example

- let "sunny" and "rainy" be state 1 and 2 respectively.
- Using matrix notation,
 - the transition matrix

$$P = \begin{pmatrix} 0.7 & 0.3 \\ 0.4 & 0.6 \end{pmatrix}$$

- Forecast for Tuesday (one-step transition): second row of P
 - \circ can be regarded as (0, 1)**P**
- Forecast for Wednesday (two-step transition): second row of P^2
 - \circ can be regarded as $(0, 1)P^2$

Weather example

Forecast for 14 days later:

$$\mathbf{P}^{14} = \begin{pmatrix} 0.5714286 & 0.4285714 \\ 0.5714285 & 0.4285715 \end{pmatrix}$$

Forecast for 30 days later:

$$\mathbf{P}^{30} \simeq \begin{pmatrix} 0.5714286 & 0.4285714 \\ 0.5714286 & 0.4285714 \end{pmatrix} = \begin{pmatrix} 4/7 & 3/7 \\ 4/7 & 3/7 \end{pmatrix}$$

Note that

$$(p, 1-p)$$
 $\begin{pmatrix} 4/7 & 3/7 \\ 4/7 & 3/7 \end{pmatrix} = (4/7, 3/7)$

• no matter what the starting distribution (p, 1 - p) is, the distribution after long time converge to $\pi = (4/7, 3/7)$ (stationary distribution)

Markov Chain Monte Carlo

- often, the goal is to generate a series of observations whose stationary distribution π (or f) is proportional to the unnormalized posterior distribution (mainly for Bayesian methods)
- these observations are correlated, so we may need to "skip every *m* observations" to get an (approximate) *iid* sample
- also, it will take some time for the chain to reach its equilibrium state, so throw away the first e.g. 10000 observations (known as burn-in).

Gibbs sampling

- goal: sample from joint distribution
- applicable when the conditional distributions of variables (given others) can be easily constructed (and sampled) from
- basic form for three components: for i = 1, ..., n, do
 - Generate X_i from $f(x|y = Y_{i-1}, z = Z_{i-1})$.
 - Generate Y_i from $f(y|x = X_i, z = Z_{i-1})$.
 - Generate Z_i from $f(z|x=X_i,y=Y_i)$.
- then the triple (X_i, Y_i, Z_i) forms a Markov chain whose stationary distribution is the joint distribution of X, Y, Z
- note that any or all of the three components (X, Y, Z) may be multivariate

Example

Suppose we are trying to simulate from $f(x, y) = \binom{n}{x} y^{x+n-1} (1-y)^{n-x+\beta-1}$, where x is an integer from 0 to n, and $y \in [0, 1]$.

- $f(x|y) \propto \binom{n}{x} y^x (1-y)^{n-x}$, which is Binomial(n, y).
- $f(y|x) \propto y^{x+\alpha-1}(1-y)^{n-x+\beta-1}$, which is Beta $(x+\alpha, n+\beta)$.
- To use Gibbs sampling, for i = 1, ..., n, do
 - 1. generate Y_i from $f(y|x = X_{i-1})$
 - 2. generate X_i from $f(x|y = Y_i)$

Metropolis-Hastings algorithm

- a dependent version of the rejection algorithm (depend on previous draw)
- target stationary distribution f(x)
- need a proposal distribution with density q(y|x)
- The algorithm: Choose X_0 . The algorithm generates X_i , for $i=1,\ldots,$, as follows.
 - 1. Generate Y_i from $q(y|X=x_{i-1})$ and U_i from Unif(0, 1).
 - 2. Evaluate $r(X_{i-1}, Y_i)$ where

$$r(x, y) = \min \left\{ \frac{f(y)q(x|y)}{f(x)q(y|x)}, 1 \right\}.$$

3. If $U_i \le r(X_{i-1}, Y_i)$, then set $X_i = Y_i$. If not, then set $X_i = X_{i-1}$.

Metropolis-Hastings algorithm

- If we only know the density f(x) up to a constant c (i.e., f(x) = cp(x)), we can still use Metropolis-Hastings.
- Common choices for q(y|x) is $\mathcal{N}(x,b^2)$ for some b>0. In this case, q is symmetric, i.e., q(y|x)=q(x|y), and r simplifies to

$$r(x, y) = \min \left\{ \frac{f(y_i)}{f(x_{i-1})}, 1 \right\}.$$

• X_i can be a vector of random variables, or other object like a tree structured "data point".

Example

Let $f(x) = \frac{1}{\pi(1+x^2)}$ be the distribution we are trying to generate from (Cauchy distribution).

- Take q(y|x) as $\mathcal{N}(x, b^2)$. So $r(x, y) = \min\left\{\frac{f(y)}{f(x)}, 1\right\} = \min\left\{\frac{1 + x^2}{1 + y^2}, 1\right\}$
- The algorithm is:
 - 1. Draw $Y_i \sim \mathcal{N}(X_{i-1}, b^2)$.
 - 2. Set

$$X_i = \begin{cases} Y_i & \text{with probability } r(X_{i-1}, Y_i), \\ X_{i-1} & \text{with probability } 1 - r(X_{i-1}, Y_i). \end{cases}$$

Example

- If b is small (e.g., b=0.1), the chain takes small steps and does not "explore" much of the sample space.
- If b is too small, the chain will be highly correlated.
- If b is large (e.g., b = 10), the proposals (Y_i) are often far in the tails, making r small and hence we often reject the proposal.
- For this example b = 1 is about the right choice.

- Let p(x, y) be the probability of making a transition from x to y.
- Our goal is to show that f(x) in the algorithm satisfies $f(x) = \int f(y)p(y,x)dy$, which implies f(x) is a stationary distribution of the chain.
- Consider two points *x* and *y*. Either:

$$f(x)q(y|x) < f(y)q(x|y),$$

or

$$f(x)q(y|x) > f(y)q(x|y).$$

We ignore ties, which happen with probability 0 for continuous distributions.

• Without loss of generality, assume that f(x)q(y|x) > f(y)q(x|y). Then,

$$r(x, y) = \frac{f(y)}{f(x)} \frac{q(x|y)}{q(y|x)}$$

and

$$r(y, x) = 1$$

since we have assumed already (WLOG) that the numerator is larger than the denominator.

SO

• p(x, y) is the probability of jumping from x to y, which happens in two stages. We first generate y and then we must accept it. Mathematically,

$$p(x, y) = \underbrace{q(y|x)}_{\text{probability of generating } y} \cdot \underbrace{r(x, y)}_{\text{probability of accepting}}$$

$$= q(y|x) \frac{f(y)}{f(x)} \frac{q(x|y)}{q(y|x)}$$

$$= \frac{f(y)}{f(x)} q(x|y),$$

f(x)p(x, y) = f(y)q(x|y).

• Similarly,

and therefore,
$$f(x)p(x,y) = q(x|y),$$

$$f(x)p(x,y) = f(y)p(y,x)$$

$$\Rightarrow \qquad \int f(x)p(x,y)dy = \int f(y)p(y,x)dy$$

$$\Rightarrow \qquad f(x) \int p(x,y)dy = \int f(y)p(y,x)dy$$

$$\Rightarrow \qquad f(x) = \int f(y)p(y,x)dy$$