

# Rust network programming: Futures and gRPC

Presented by  
[shentaining@pingcap.com](mailto:shentaining@pingcap.com)



# About me

- 沈泰宁
- R&D Engineer @ PingCAP/TiKV
- Maintainer
  - tikv
  - grpc-rs
  - rust-prometheus
  - ...



# Agenda

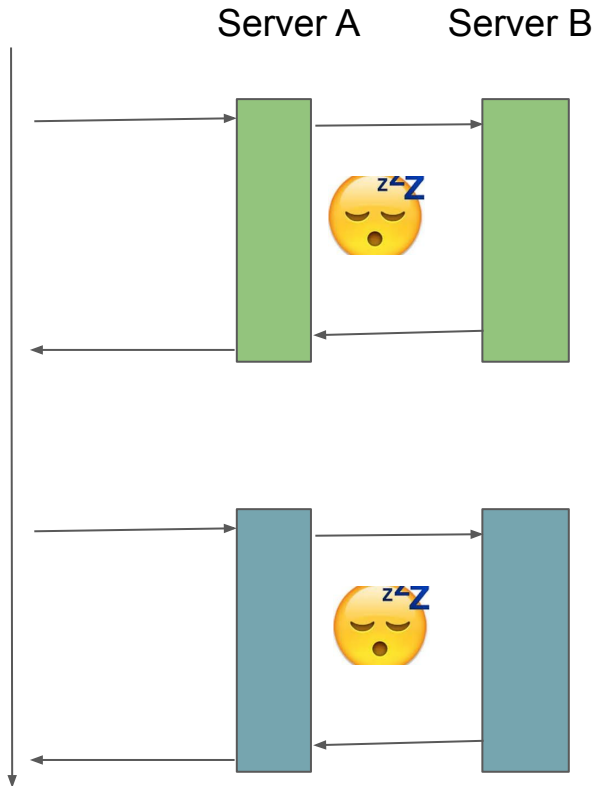
- Async programming
- Futures
- gRPC
- Combine Futures and gRPC



# Part I - Async programming



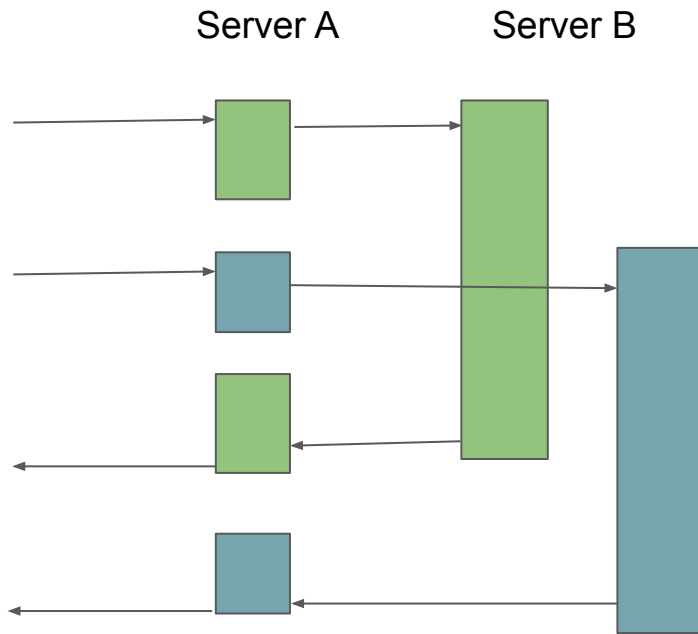
# Why Sync?



- Pros
  - Simple
  - High effective for low load service
  - Use multi threads for concurrency
- Cons
  - Block
  - Thread is heavy and wastes resources.
  - Switching thread is inefficient



# Why Async?



- Pros.
  - No blocking
  - High performance
- Cons
  - Logic is split
  - Complex



# Callback Hell?

```
let r = Arc::new(AtomicU8::new());
do_async_a(|a| {
  do_async_b(|b| {
    do_finish(|res| {
      r.set(res);
    })
  })
})
```



# Coroutine Make It Easy

- C++: boost coroutine, libco, etc...
- Python: yield, greenlet, etc...
- Golang: Goroutine

For Golang:

```
go func(ch: channel) {  
    // do something  
    ch <- res  
}(ch)  
r := <- ch
```





## Part II - Future



# FUTURES RS

Zero-cost asynchronous programming in Rust

<https://github.com/rust-lang-nursery/futures-rs>



# The Ergonomic Way

```
let future_count = do_async_a()  
    .then(|res| do_async_b(res))  
    .then(|res| do_finish(res));  
let r = future_count.wait().unwrap();
```

```
let r = Arc::new(AtomicU8::new());  
do_async_a(|a| {  
    do_async_b(|b| {  
        do_finish(|res| {  
            r.set(res);  
        })  
    })  
})
```



# Under the Hood

```
pub trait Future {  
    type Item;  
    type Error;  
    // Query this future to see if its value has become available.  
    fn poll(&mut self) -> Result<Async<Self::Item>, Self::Error>;  
    // Block the current thread until this future is resolved.  
    fn wait() -> result::Result<Self::Item, Self::Error> {  
        loop { self.poll(); return if it ready or error }  
    }  
}  
  
pub enum Async<T> {  
    Ready(T),  
    NotReady,  
}
```



# Examples

```
let f = ok::<u32, u32>(1);  
assert_eq!(f.wait().unwrap(), 1);
```

```
let mut f = empty::<u32, u32>();  
assert_eq!(f.poll(), Ok(Async::NotReady));
```

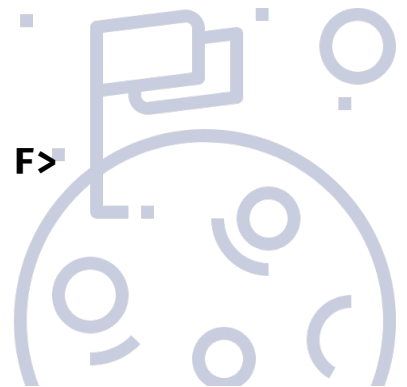
<https://play.rust-lang.org/?edition=2018&gist=bf84b6eedd25603686a0714b063b9024>



# Combinator

```
let future = do_async_a()  
    .then(|res| do_async_b(res))  
    .then(|res| do_finish(res));
```

```
trait Future {  
    fn then<F, B>(self, f: F) -> Then<Self, B, F>  
    where  
        F: FnOnce(Result<Self::Item, Self::Error>) -> B,  
        B: IntoFuture { ... }  
  
    fn map<F, U>(self, f: F) -> Map<Self, F>  
    where  
        F: FnOnce(Self::Item) -> U { ... }  
    ...  
}
```



# Synchronization

- oneshot
  - Single producer/Single consumer
- mpsc
  - Multi producers/Single consumer

```
let (tx, rx) = oneshot::channel::<u32>();
thread::spawn(move || {
    thread::sleep_ms(3000);
    tx.send(1).unwrap();
});
assert_eq!(rx.map(|x| x + 1).wait().unwrap(), 2);
```



# Stream

```
pub trait Stream {  
    type Item;  
    type Error;  
    // Attempt to pull out the next value of this stream.  
    // Ready(Some) means next value is on the stream  
    // Ready(None) means the stream is finished  
    fn poll(&mut self) -> Result<Async<Option<Self::Item>, Self::Error>>;  
}
```





# Sink

```
pub trait Sink {  
    type SinkItem;  
    type SinkError;  
    fn start_send(self, item: Self::SinkItem)  
        -> StartSend<Self::SinkItem, Self::SinkError>;  
    fn poll_complete(&mut self) -> Result<Async<()>, Self::SinkError>;  
    fn close(&mut self) -> Result<Async<()>, Self::SinkError>;  
}
```



# Task

- If the future is not ready?

```
let handle = task::current();
```

- If the event of interest occurs?

```
handle.notify();
```

- What to do after notify?

```
executor.poll(f);
```



# Part III - gRPC



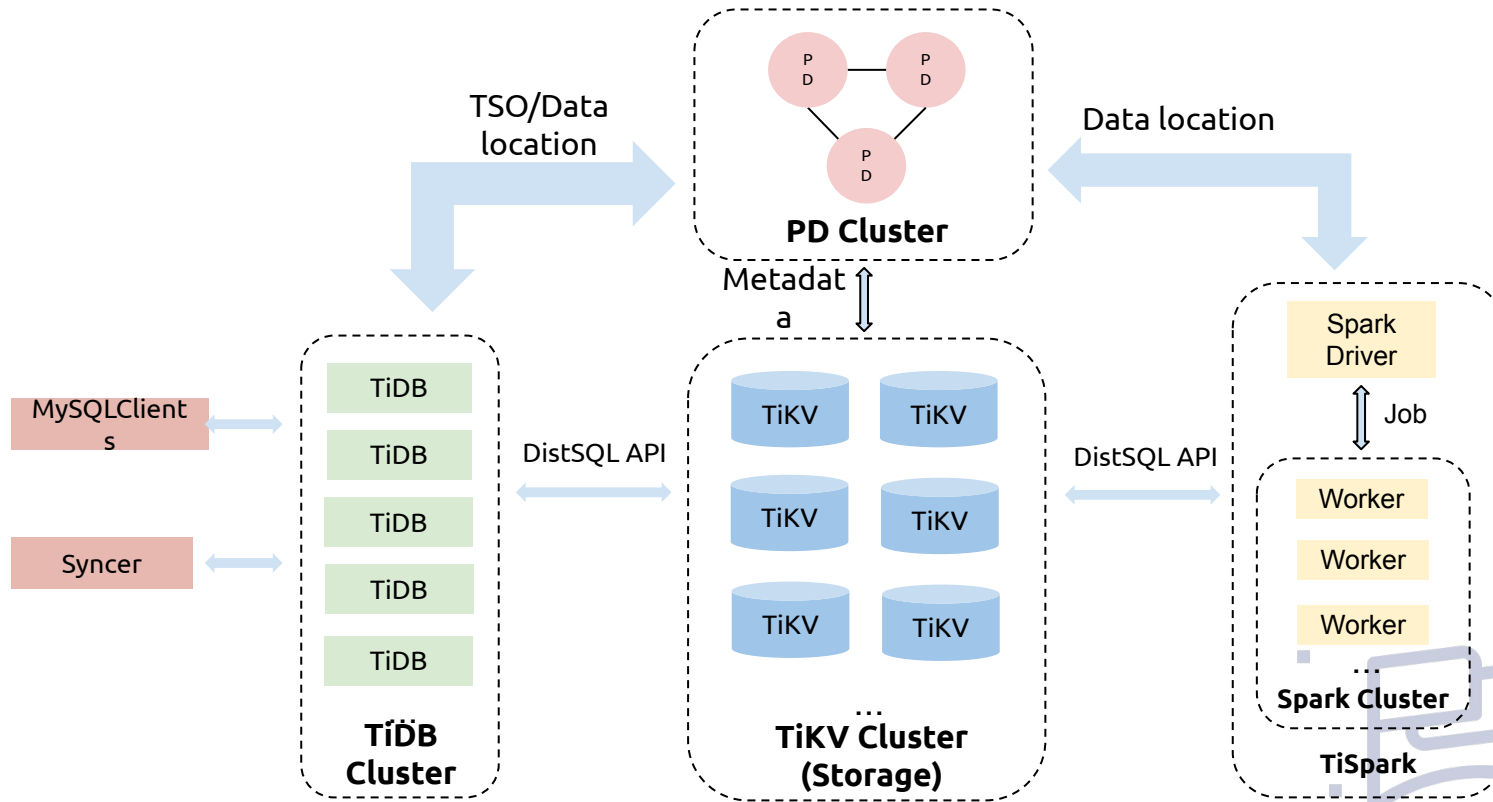


A high-performance, open-source universal  
RPC framework

<https://grpc.io/>



# gRPC in TiDB?



# Why

- Protobuf
- Widely used
- Supported by many languages
- Benefit from HTTP/2
- Rich interfaces



# HTTP/2

- Binary protocol
- Multiplexing
- Priority
- Flow Control
- HPACK



# C gRPC Key Concept

- Call: RPC call, Unary, Client, Server and Duplex streaming
- Channel: Connection
- Server: Server to register the service
- Completion Queue: Drive RPC





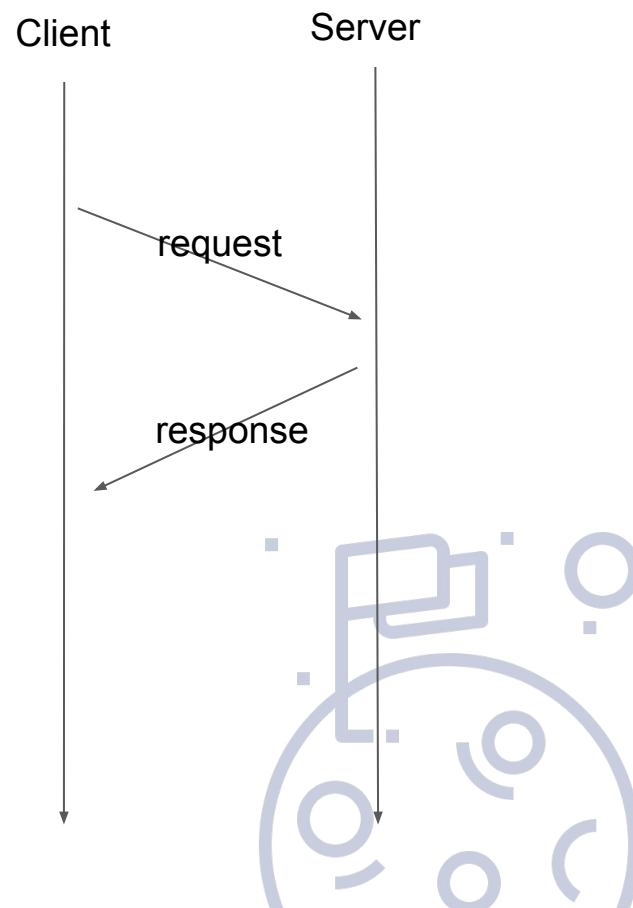
# Workflow

- Create completion queue
- Create client channel
- Create a call from the channel
- Start operations in batch of the call with a **tag**
- **Poll** completion queue to perform the call and return the event contains a **tag**
- Use tag to do something...



# Unary

- Client sends request
- Server replies response



# Unary: Pseudo Flow

> Client

```
let future = unary(service, method, request);
```

```
let response = future.wait();
```

> Server

```
fn on_unary(context, request, response_sink) {
```

```
    context.spawn(|| {
```

```
        // do something with request
```

```
        response_sink.send(response)
```

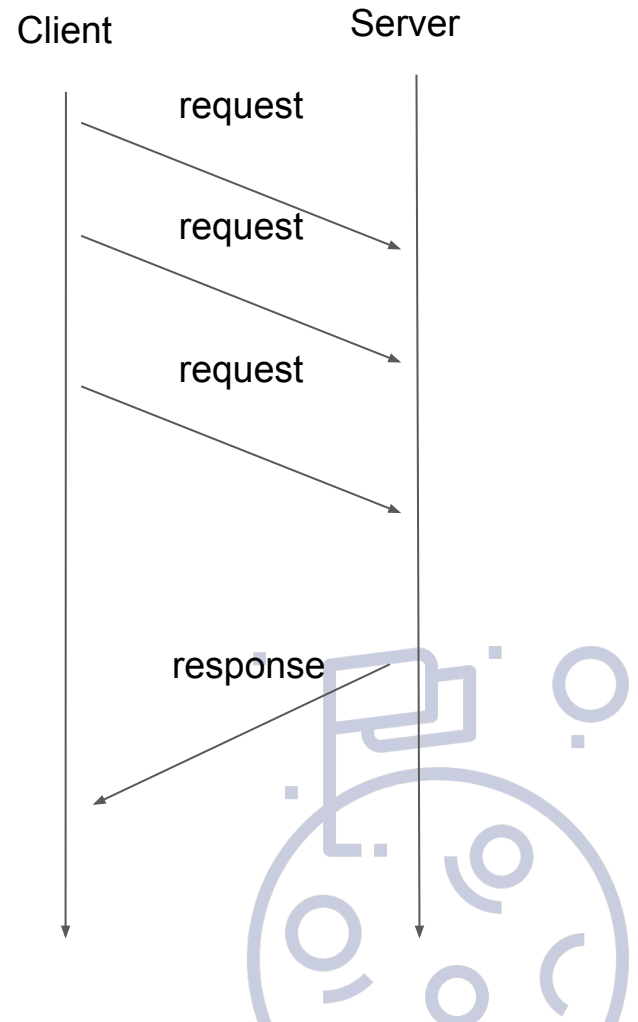
```
    });
```

```
}
```



# Client Streaming

- Client sends request 1
- .....
- Client sends request N
- Server replies response



# Client Streaming: Pseudo Flow

> Client

```
let (mut sink, resp) = client_streaming(service, method);  
loop { sink = sink.send(request).wait().unwrap(); }  
let response = resp.wait();
```

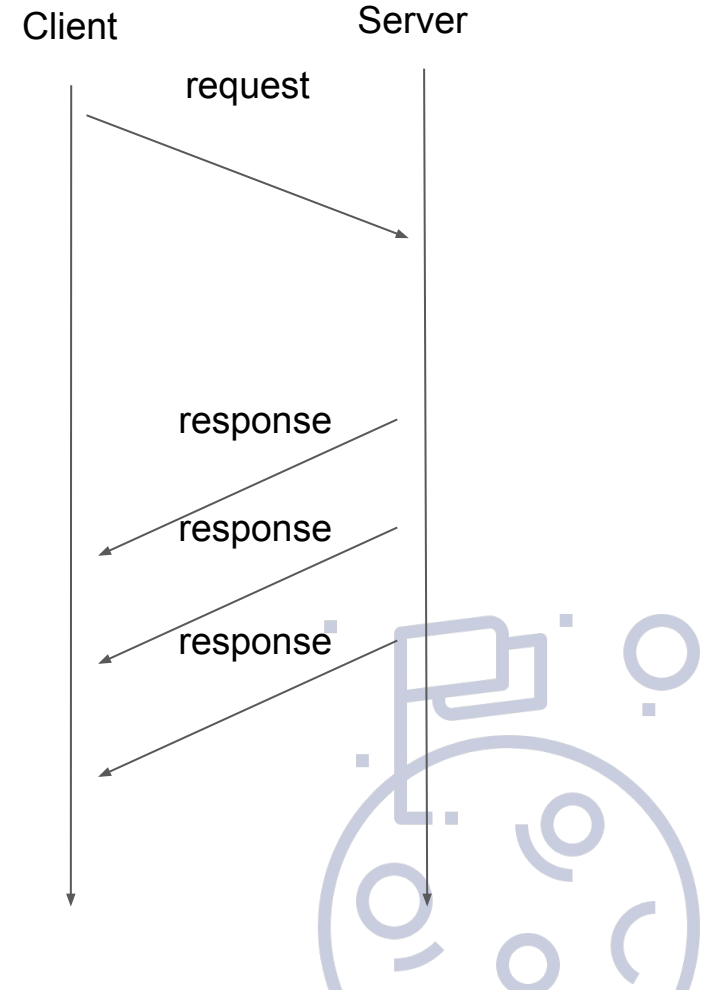
> Server

```
fn on_client_streaming(context, request_stream, response_sink) {  
    context.spawn(request_stream  
        .for_each(|request| { /* .. */ })  
        .and_then(|res| { response_sink.send(res) }));  
}
```



# Server Streaming

- Client sends request 1
- Server replies response 1
- .....
- Server replies response N



# Server Streaming: Pseudo Flow

> Client

```
let resp_stream = server_streaming(service, method, request);  
resp_stream.for_each(|response| { /* */ }).wait();
```

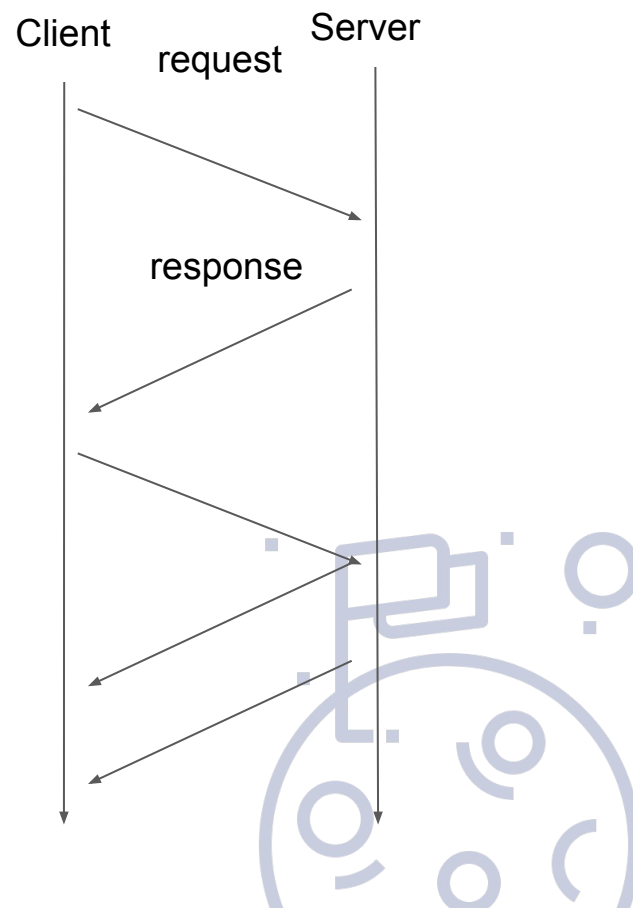
> Server

```
fn on_server_streaming(context, request, response_sink) {  
    let future = response_sink.send_all(responses);  
    context.spawn(future);  
}
```



# Duplex Streaming

- Client sends request 1
- Server replies response 1
- .....
- Client sends request N
- Server replies response N





# Duplex Streaming: Pseudo Flow

> Client

```
let (sink, stream) = duplex_streaming(service, method);  
sink.send_all(requests);  
stream.for_each(|response| { /* */ });
```

> Server

```
fn on_duplex_streaming(context, request_stream, response_sink) {  
    context.spawn(response_sink.send_all(request_stream))  
}
```



# Part V - Unary Implementation



# Client Unary

```
let call = channel.create_call();  
let (resp_future, tag) = CallTag::batch_pair();  
// create a tag and let gRPC manages its lifetime  
let tag_box = Box::new(tag);  
let tag_ptr = Box::into_raw(tag_box) as _;  
channel.start_batch(call, tag_ptr);
```



# Unary Future

```
fn poll(&mut self) -> Poll<T, Error> {  
    let guard = self.inner.lock();  
    if let Some(res) = guard.result.take() {  
        let r = try!(res);  
        return Ok(Async::Ready(r));  
    }  
    // Has not been finished yet, Add notification hook  
    if guard.task.is_none() {  
        || !guard.task.as_ref().unwrap().will_notify_current() {  
            guard.task = task::current();  
        }  
    }  
    Ok(Async::NotReady)  
}
```



# Resolve Future

> Completion Queue:

```
let e = cq.next();  
// Get the tag from gRPC again  
let tag: Box<CallTag> = unsafe {  
  Box::from_raw(e.tag as _) } ;  
tag.resolve(&cq, e.success != 0);
```

> Resolve:

```
let task = {  
  let mut guard = self.inner.lock();  
  guard.set_result(res)  
  guard.task.take()  
};  
task.map(|t| t.notify());
```





<https://github.com/pingcap/tidb>



[https://github.com/tikv/tikv/](https://github.com/tikv/tikv)



<https://github.com/pingcap/grpc-rs>



# Thank You !

