Competitive Programming Algorithms

Extracted from CP3 and December Algorithmics IOI Training Resources

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1 Data Structures

1.1 Stack

```
1 stack < int > s;
2 s.push(1); s.push(2); s.push(3);
3 while (!s.empty()) {
4    cout << s.top() << endl;
5    s.pop();
6 } // prints 3 2 1</pre>
```

1.2 Sets

A set will contain only distinct elements. O(log n) insert, delete, search.

1.3 Maps

Associative maps: get a value by a unique key. Like a set (unique key) with data attached. O(log n) insert, delete, search

1.4 Bitmasks

- 1. To set/turn on the j-th item (0-based indexing) of the set, use the bitwise OR operation $S \mid = (1 << j)$.
- 2. To check if the j-th item of the set is on, use the bitwise AND operation T = S & (1 << j). If T = 0, then the j-th item of the set is off. If T != 0 (to be precise, T = (1 << J)), then the j-th item of the set is on.

3. To clear/turn off the j-th item of the set, use the bitwise AND operation.

```
S \&= (1 << j) // is the bitwise NOT operation
```

4. To toggle the j-th item of the set, use the bitwise XOR operation

```
S = (1 << j)
```

- 5. To get the value of the least significant bit that is on (first from the right), use T = (S & (-S)).
- 6. To turn on all bits in a set of size n, use S = (1 << n) 1.

1.5 Union-Find Disjoint Sets

```
1 class UnionFind{
      private: vi p, rank;
2
3
      public:
4
           UnionFind(int N) {
               rank.assign(N,0); p.assign(N,0);
5
               for (int i = 0; i < N; i++) p[i] = i;
6
7
8
           int findSet(int i){
9
               return (p[i] = i)? i : (p[i] = findSet(p[i]));
10
11
           bool isSameSet(int i, int j){
               return findSet(i) == findSet(j);
12
13
           void unionSet(int i, int j){
14
15
               if (!isSameSet(i,j)){
16
                   int x = findSet(i), y = findSet(j);
17
                   if(rank[x] > rank[y]) p[y] = x;
18
                   else{
                       p[x] = y;
19
20
                       if(rank[x] = rank[y]) rank[y]++;
21 }}};
```

1.6 Fenwick Trees

1.6.1 Implementation theory

Querying To query the range from 1 to i, add the buckets at position:

```
p_0 = i,

p_1 = p_0 - \text{ size of bucket } p_0,

p_2 = p_1 - \text{ size of bucket } p_1, etc

Subtract size of bucket until 0
```

Updating To update, the ranges that contain i are:

```
\begin{aligned} p_0 &= i, \\ p_1 &= p_0 + \text{ size of bucket } p_0 \\ p_2 &= p_1 + \text{ size of bucket } p_1, etc \end{aligned}
```

```
1 long long ft [N + 1]; // note: Fenwick tree must be 1-indexed.
2 int ls(int x) { return x & (-x); }
3
4 void fenwick_update(int p, long long v){
5     for (; p <= N; p += ls(p)) ft [p] += v;
6 }
7
8 long long fenwick_query(int p){
9     long long sum = 0;
10     for (; p; p -= ls(p)) sum += ft [p];
11     return sum;
12 }</pre>
```

2 Sorts

```
sort, O(n \log n) - sorts entire array stable_sort, O(n \log n) - keeps original order between equal elements partial_sort, O(n \log k) - sorts the k smallest entries
```

3 Conversions

```
1 string stlstr = "hello";
2 printf("%s", stlstr.c_str());
3
4 char cstr[] = "world";
5 cout << string(cstr) << endl;</pre>
```

4 Dynamic Programming

4.1 2D-Maxsum

For every pair of rows (eg. x1, x2):

- Sum each column between them (inclusive) into an 1D- array
 - Use W columns of 1D static sum
 - Or 2D static sum works too
- Perform 1D-Maxsum on this array

Complexity: $O(H^2W)$

```
1 int G[H+1][W+1], S[H+1][W+1], ans; /* 1-indexed */
2 /* W rows of 1D Static Sum */
3 for (int i = 1; i <= H; i++)
      for (int j = 1; j \le W; j++)
5
           S[i][j] = S[i-1][j] + G[i][j];
6 for (int x1 = 1; x1 \ll H; x1++) {
      for (int x2 = x1; x2 \ll H; x2++) {
7
           int cursum = S[x2][1] - S[x1-1][1];
8
           for (int y = 2; y \le W; y++) {
9
               cursum += max(cursum, 0) + S[x2][y] - S[x1-1][y];
10
11
               ans = max(cursum, ans);
12
           }
      }
13
14 }
```

4.2 Lowest Common Substring

To recover LCS: start from lcs[N][M] and work backwards.

```
1 int lcs[1001][1001], A[1001], B[1001]; // A and B are 1-indexed here
2 for (int i = 0; i <= N; ++i) {
3     for (int j = 0; j <= M; ++j) {
4         if (i == 0 || j == 0) lcs[i][j] = 0;
5         if (A[i] == B[j]) lcs[i][j] = 1 + lcs[i - 1][j - 1];
6         else lcs[i][j] = max(lcs[i][j - 1], lcs[i - 1][j]);
7     }
8 }</pre>
```

5 Graphs

5.1 Topological Sort

```
1 void dfs(int vertex_id) {
       if (visited[vertex_id]) return;
2
3
       visited [vertex_id] = true;
      for (auto i: adjList[vertex_id]) {
4
5
           dfs(i);
6
7
      topo.push_back(vertex_id);
8 }
9
10 for (int i = 0; i < V; ++i)
      if (!visited[i]) dfs(i);
11
12
13 reverse (topo.begin(), topo.end());
```

5.2 Kruskal's

```
1 vector < pair < int, ii > > EdgeList; // (weight, two vertices) of the edge
2 for (int i = 0; i < E; i++){
       scanf("%d_{d_{w}}d_{d_{w}}d_{u}, \&u, \&v, \&w);
4
       EdgeList.push_back(make_pair(w, ii(u, v)));
5 }
6 sort (EdgeList.begin(), EdgeList.end());
8 \text{ int } \text{mst\_cost} = 0;
9 UnionFind UF(V);
10 for (int i = 0; i < E; i++){
11
       pair < int , ii > front = EdgeList[i];
       if (!UF.isSameSet(front.second.first, front.second.second)){
12
           mst_cost += front.first;
13
           UF. unionSet (front.second.first, front.second.second);
14
15
|16| // note: number of disjoint sets must eventually be 1 for a valid MST
| 17 printf("MST_cost_=_%d", mst_cost);
```

5.3 Dijkstra's

 $O((V+E)\log V)$, best for weighted graphs, works for negative weights (slower), unable to detect negative cycle.

```
1 vi dist (V, INF); dist [s] = 0; // INF = 1B to avoid overflow
2 priority_queue<ii, vector<ii>, greater<ii>> pq; pq.push(ii(0,s));
3 while (!pq.empty()) {
      ii front = pq.top(); pq.pop();
4
      int d = front.first , u = front.second;
5
6
      if(d > dist[u]) continue;
7
      for(int j = 0; j < (int) AdjList[u]. size(); j++){
8
           ii v = AdjList[u][j];
9
           if(dist[u] + v.second < dist[v.first])
               dist[v.first] = dist[u] + v.second;
10
11
              pq.push(ii(dist[v.first],v.first));
12
          }
13
      }
|14|
```

5.4 Bellman Ford's

O(VE), works for negative weight.

```
1 vi dist(V, INF); dist[s] = 0;
2 \text{ for } (\text{int } i = 0; i < V - 1; i++)
                                           // relax all E edges V-1 times
      for (int u = 0; u < V; u++){
3
4
           for (int j = 0; j < (int) AdjList[u]. size(); <math>j++){
                ii v = AdjList[u][j];
5
               dist[v.first] = min(dist[v.first], dist[u] + v.second);
6
7
           } //relax
      }
8
9 }
```

5.5 Floyd Warshall's

 $V \le 400$

```
1 // inside int main()
2 // precondition: AdjMat [i] [j] contains the weight of edge (i,j)
3 // or INF (1B) if there is no such edge
4 // AdjMat is a 32-bit signed integer array
5 for (int k = 0; k < V; k++) // remember that loop order is k->i->j
6     for (int i = 0; i < V; i++)
7         for (int j = 0; j < V; j++)
8         AdjMat [i][j] = min(AdjMat [i][j] , AdjMat [i][j] + AdjMat[k][j]);</pre>
```

6 Mathematics

6.1 Modular Arithmetic

```
a \equiv b(modm) \leftrightarrow a - b \equiv 0(modm),

k * m \equiv 0(modm),

a * c \equiv b * c(modm) \leftrightarrow a \equiv b(modm)
```

if m and c are coprime because of Euclid's lemma: If a prime divides the product of two numbers, it must divide at least one of those numbers.

6.2 Fast Exponentiation

```
1 int fastExp(ll base, ll p){
       if (p==0) return 1;
      else if(p==1) return base;
3
      else {
4
5
           11 res = fastExp(base, p/2);
6
           res *= res;
           res %= MOD;
7
8
           if(p\%2==1) res *= base\%MOD;
           return res%MOD;
9
10
11 }
```

6.3 GCD

Euclid's algorithm, O(log N) time.

```
1 ll gcd(ll a, ll b){
2     if(b == 0) return a;
3     if(a > b) return gcd(b, a%b);
4     if(b > a) return gcd(b, a);
5 }
```

6.4 LCM

$$lcm(m,n) = \frac{|m \cdot n|}{gcd(m,n)}$$

LCM can also be found by merging the prime decompositions of both m and n.

6.5 Sieve of Eratosthenes

```
1 ll sieveSize;
2 \text{ bitset} < 10000010 > \text{ bs};
3 vi primes; // list of primes
5 void sieve(ll upperbound) { // create list of primes in [0..upperbound]
      sieveSize = upperbound + 1; // add 1 to include upperbound
6
      bs.set(); // set all bits to 1
7
      bs[0] = bs[1] = 0; // except index 0 and 1
8
9
      for(ll i = 2; i \le sieveSize; i++) if (bs[i]) {
           // cross out multiples of i starting from i * i
10
11
           for (ll j = i * i; j \le sieveSize; j += i) bs[j] = 0;
           primes.push_back(i);
12
13 }}
14
15 bool isPrime(ll N){
      if (N <= sieveSize) return bs[N];
16
17
      for(int i = 0; i < (int)primes.size(); i++)
18
           if (N % primes [i] == 0) return false; // a good enough deterministic prime tester
      return true;
19
20 }
      // only works for N \le (last prime in vi "primes")^2
21
22 int main(){
      sieve (10000000);
23
24
       printf("%d\n", isPrime(2147483647)); // return true
      printf("%d\n", isPrime(136117223861)); // return false
25
26 }
```