

10-708 Recitation 3 - Monte Carlo Markov Chain

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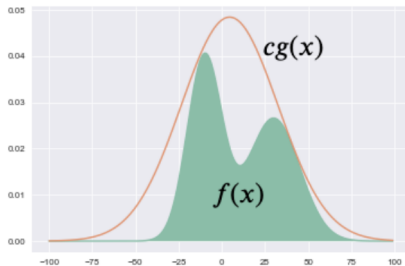
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Homework Overview

Rejection Sampling

Rejection Sampling (HW2 Q5)

- ▶ Problem: you have some hard to sample distribution f (target distribution), and an easy to sample distribution g (proposal distribution)
- ▶ Rejection sampling algorithm: Choose c large enough such that $\forall x, f(x) \leq cg(x)$.
 - ▶ Generate sample x from g
 - ▶ Generate sample $u \sim \text{Unif}(0, 1)$
 - ▶ Accept if $u \leq \frac{f(x)}{cg(x)}$



- ▶ Good when g is close to h and therefore c is small

Rejection Sampling (HW2 Q5)

Illustration for proposal distribution S and target distribution D in Q5:



$$D = \{(x, y) : (x/2)^2 + y^2 \leq 1\}$$

$$S = \{(x, y) : -2 \leq x \leq 2, -1 \leq y \leq 1\}$$

Markov Chains

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- ▶ Let T denote the transition matrix of a Markov chain.

Definition (Stationary Distribution)

A distribution π is stationary if $\pi \mathbf{T} = \pi$.

- ▶ When does a *unique* stationary distribution exist?

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- ▶ When does a *unique* stationary distribution exist?
- ▶ Sufficient conditions:
 1. Irreducibility: transition graph is connected, able to reach any state from any other state eventually
 2. Aperiodicity: random walk doesn't get trapped in cycles, i.e. there exists some n where eventually there is positive probability of being in all states after n steps

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- ▶ When does a *unique* stationary distribution exist?
- ▶ Sufficient conditions:
 1. Irreducibility: transition graph is connected, able to reach any state from any other state eventually
 2. Aperiodicity: random walk doesn't get trapped in cycles, i.e there exists some n where eventually there is positive probability of being in all states after n steps
- ▶ When is π a stationary distribution? Sufficient condition: π satisfies detailed balance:

$$\pi_i T_{ij} = \pi_j T_{ji} \quad \forall (i, j).$$

Monte Carlo Markov Chain

Monte Carlo Markov Chain

- ▶ Importance sampling may work in low dimensions, but becomes inefficient in high dimensions (ratio of volumes grow exponentially, always rejecting)
- ▶ Idea: construct a Markov Chain on the state space whose stationary distribution is the target distribution

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Example

For Ising models, the Markov Chain will move around state space $\{0, 1\}^n$.

After reaching stationary distribution, proportion of time spent in some state $\mathbf{x} \in \{0, 1\}^n$ proportionate to $p(\mathbf{x})$, so sampling from the Markov Chain is like sampling from p

- ▶ Question: How to determine \mathbf{T} ?

Metropolis-Hastings (HW2 Programming)

Main idea:

- ▶ Suppose we have some easy to sample proposal distribution (also called transition kernel) $q(i, j)$, and we are in state j
- ▶ At each step, we sample a proposal i with probability $q(i, j)$
- ▶ Be clever about deciding the probability to accept the proposal
- ▶ The Markov Chain will eventually reach a stationary distribution

Algorithm:

$$\Pr(X_n = j | X_{n-1} = i) =$$

- 1., from state i go to state j with prob. $q(i, j)$
- 2., $\begin{cases} \text{with prob } 1 - \alpha(i, j) \text{ go back to state } i, \\ \text{with prob } \alpha(i, j) \text{ stay in state } j. \end{cases}$

where

$$\alpha(i, j) = \min\left(\frac{\pi_j q(j, i)}{\pi_i q(i, j)}, 1\right) = \min\left(\frac{b(j) q(j, i)}{b(i) q(i, j)}, 1\right).$$

Gibbs Sampling (HW2 Programming)

- ▶ Downside with Metropolis-Hastings: need to come up with a proposal distribution q , and acceptance rate may be low
- ▶ Gibbs sampling always accepts, and is a special case of MH

Algorithm:

Repeat:

Let current state be $\mathbf{x} = (x_1, x_2, \dots, x_n)$

Pick $i \in [n]$ uniformly at random.

Sample $x \sim P(X_i = x | \mathbf{x}_{-i})$

Update state to $\mathbf{y} = (x_1, x_2, \dots, x_{i-1}, x, x_{i+1}, \dots, x_n)$

Why is $x \sim P(X_i = x | \mathbf{x}_{-i})$ easy to sample? You will show this in the HW.

HW2 Programming Hints

- ▶ The neighbors of node (i,j) are just its vertical and horizontal neighbors on the $n \times n$ grid
- ▶ In the setup of this problem, there is double counting of the edges. In general, whether there is double counting or not is a matter of convention and does not affect any of our results.

Linear Algebra Refresher

Linear Algebra Refresher and Hints (Q6, Q8)

- ▶ Let A be any matrix. v is an eigenvector of A if $Av = \lambda v$ for some $\lambda \in \mathbb{R}$. λ is called the eigenvalue associated with v .
- ▶ Vectors u, v are orthogonal when $\langle u, v \rangle = 0$
- ▶ A matrix U is orthogonal when all its rows are pairwise orthogonal, and all its columns are pairwise orthogonal
- ▶ For a square orthogonal matrix U , $UU^T = U^T U = I$
- ▶ The operator norm of a matrix A is defined as:

$$\|A\|_2 = \sup_{x \neq 0} \frac{\|Ax\|_2}{\|x\|_2}.$$

Linear Algebra Refresher and Hints (Q6, Q8)

Properties of a $n \times n$ **symmetric** matrix A :

- ▶ Exhibits an eigendecomposition:

$$A = UDU^T = \sum_{i=1}^n \lambda_i \underbrace{v_i v_i^T}_{n \times n}$$

where U orthogonal, $D = \text{diag}(\lambda_1, \dots, \lambda_n)$, λ_i eigenvalues, v_i eigenvector of unit norm corresponding to λ_i .

- ▶ All eigenvectors v_i are orthogonal:

$$\langle v_i, v_j \rangle = 0 \quad \forall i \neq j$$

- ▶ The largest eigenvalue λ_1 of A is given by

$$\lambda_1 = \max_{\|x\|_2=1} x^T A x.$$

- ▶ The second largest eigenvalue λ_2 is given by

$$\lambda_2 = \max_{\|x\|_2=1, \langle x, v_1 \rangle=0} x^T A x.$$

Markov Chain Mixing Times

Markov Chain Mixing Times (HW2 Q8)

- ▶ In theory:

$$\lim_{t \rightarrow \infty} \mathbf{T}^t \mathbf{x} = \boldsymbol{\pi}. \quad (1)$$

- ▶ In practice: how long does it take for my Markov Chain to reach a stationary distribution?

Reach means:

$$\|\mathbf{T}^k \mathbf{x} - \boldsymbol{\pi}\|_{TV} < 1/4 \quad (2)$$

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- ▶ Linear algebraic view: you will learn how to bound the mixing time in terms of the difference between the two largest eigenvalues in magnitude of \mathbf{T}

Markov Chain Mixing Times (HW2 Q8)

High level overview:

- ▶ For a connected d -regular transition matrix \mathbf{T} , you will show its largest eigenvalue is 1
- ▶ Let λ_{\max} denote the next largest eigenvalue. You will show that the number of steps k required to mix is

$$k \geq \frac{\log n}{1 - \lambda_{\max}}.$$

- ▶ Asymptotically, $1 - \lambda_{\max}$ could be $O(1)$ (clique), $O(1/n)$, $O(1/n^2)$ (cycle), etc, so mixing time could vary a lot.

Markov Chain Mixing Times (HW2 Q8)

- ▶ $S \subseteq V$ set of vertices in the graph, $E(S, \bar{S})$: set of edges that are cut between the two partitions S and \bar{S} .
- ▶ Conductance of a cut S :

$$\Phi(S) = \frac{|E(S, \bar{S})|}{d \cdot |S|}, \quad (3)$$

- ▶ Conductance of the graph represented by \mathbf{T} :

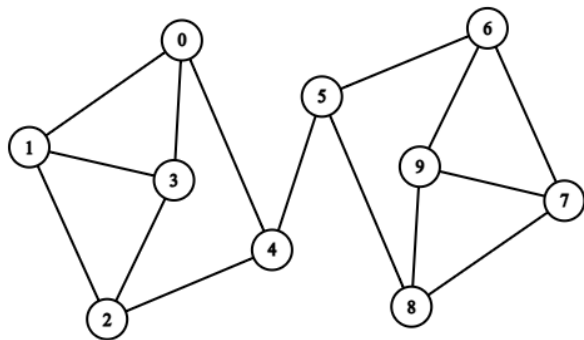
$$\Phi_{\mathbf{T}} = \min_{S, |S| \leq |\bar{S}|} \frac{|E(S, \bar{S})|}{d \cdot |S|}. \quad (4)$$

- ▶ ☹ Let's do some examples!

Markov Chain Mixing Times (HW2 Q8)

Conductance of a cut S :

$$\Phi(S) = \frac{|E(S, \bar{S})|}{d \cdot |S|}, \quad (5)$$

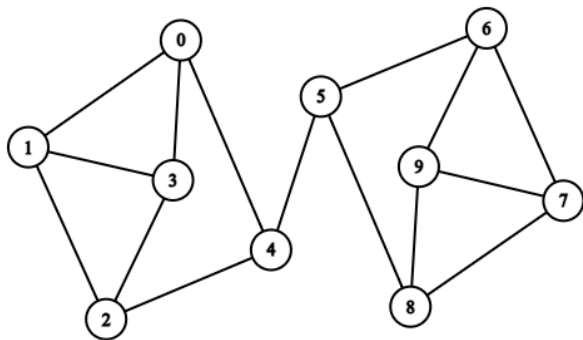


What is $\Phi(\{1, 2\})$?

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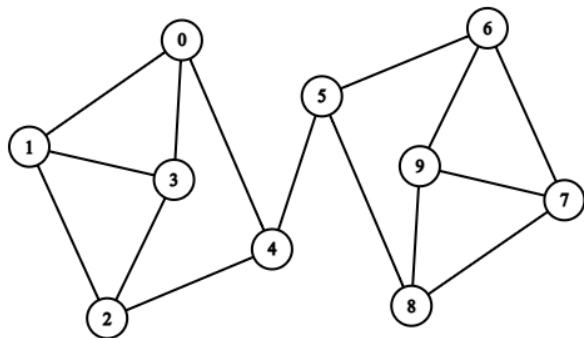


What is $\Phi(\{1, 2\})$? **Ans: 1/2**

Markov Chain Mixing Times (HW2 Q8)

Conductance of the entire graph:

$$\Phi_T = \min_{S, |S| \leq |\bar{S}|} \frac{|E(S, \bar{S})|}{d \cdot |S|}. \quad (6)$$

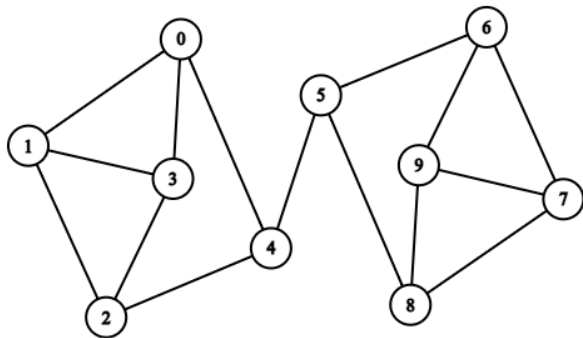


What is Φ_T ?

Markov Chain Mixing Times (HW2 Q8)

Conductance of the entire graph:

$$\Phi_T = \min_{S, |S| \leq |\bar{S}|} \frac{|E(S, \bar{S})|}{d \cdot |S|}. \quad (6)$$



What is Φ_T ? Take everything on the left side, 1/15

Markov Chain Mixing Times (HW2 Q8)

High level overview, continued:

- ▶ In practice, hard to find/characterize $1 - \lambda_{\max}$ for a family of graphs
- ▶ You will use the conductance $\Phi_{\mathbf{T}}$ of the graph represented by \mathbf{T} , and use it to bound $1 - \lambda_{\max}$. You will prove the LHS of the following result:

$$\frac{1 - \lambda_{\max}}{2} \leq \Phi_{\mathbf{T}} \leq \sqrt{2 \cdot (1 - \lambda_{\max})}$$

Markov Chain Mixing Times (HW2 Q8)

Other hints:

- ▶ We only consider graphs that are connected, d -regular, and distribute transition probabilities uniformly among its neighbors. This implies that \mathbf{T} is symmetric.
- ▶ Q8(a): After you show that $\lambda_1 = 1$ and $v_1 = \frac{1}{\sqrt{n}}\vec{1}$, this fact is very important and will be used many times
- ▶ Q8(h): When relaxing from discrete to continuous constraints, the solution can only get better, i.e

$$\min_{x \in \{0,1\}^n} f(x) \geq \min_{x \in \mathbb{R}^n} f(x)$$

- ▶ Lots of hints included in problem 😊

Homework Overview

What's Next?

- ▶ You have learnt enough material to do Q1-Q5, Q8, and B.1(a) and B.1(b) of the programming homework
- ▶ Next week we will cover annealed importance sampling and Hamiltonian Monte Carlo, and you will have everything you need
- ▶ Start early 😊

*Thank you for coming to recitation and good luck
on the homework!*