## Using formalism to design secure systems

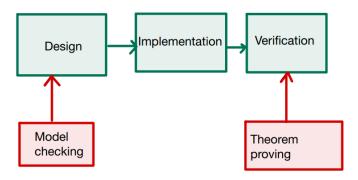
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## Agenda

- What are formal methods
- ► How to formalize systems
- Several examples from literature
- One real world example
- Conclusion

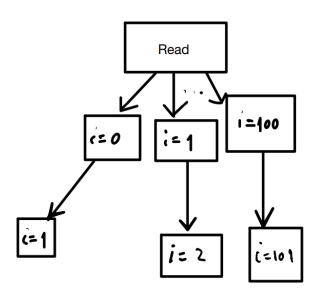
#### **Process**



```
int main() {
    int i = readInteger();
    i++;
    return 0;
}
```

# How to model this simple program formally as state machine?

## State diagram



— Module simple\_increment\_sm —

#### Extends TLC, Integers

variables  $i,\ pc$ 

$$init \stackrel{\Delta}{=} i = 0 \land pc = \text{``start''}$$

$$next \stackrel{\triangle}{=} IF \ pc = "start" \ THEN$$

$$(i' \in 0..1000) \land (pc' = \text{``middle''})$$
  
ELSE IF  $pc = \text{``middle''}$  THEN

$$(i'=i+1) \wedge (pc'=\text{"done"})$$

 $(i = i + 1) \land (pc = dolle)$ ELSE FALSE

# **Two-phase commit**

```
— MODULE twoPhase — —
EXTENDS TIC
CONSTANT RM
VARIABLE rmState
VARIABLES tmState, tmPrepared, msgs
Messages = [type : {"prepared"}, rm : RM] \setminus cup
    [type : {"commit", "abort"}]
TPTvpeOK ==
    /\ rmState \in [RM -> {"working", "prepared",
        "committed", "aborted"}]
    /\ tmState \in {"init", "done"}
    /\ tmPrepared \subseteq RM
    /\ msgs \subseteq Messages
```

```
TPRecvPrepared(r) ==
   /\ tmState = "init"
   /\ [type |-> "prepared", rm |-> r] \in msgs
   /\ tmPrepared' = tmPrepared \cup {r}
   /\ UNCHANGED << tmState, msgs, rmState >>
```

```
TMCommit ==
    /\ tmState = "init"
    /\ \A r \in RM : r \in tmPrepared
    /\ msgs' = msgs \cup {[type |-> "commit"]}
    / tmState ' = "done"
    /\ UNCHANGED <<rmState, tmPrepared >>
TMAbort ==
    /\ tmState = "init"
    /\ tmState '="done"
    /\ \ E \ r \ in \ RM : rmState[r] = "aborted"
    // msgs' = msgs \cup {[type |-> "abort"]}
    /\setminus tmPrepared '=\{\}
    /\ UNCHANGED <<rmState>>
```

```
RMPrepare(r) = 
    /\ rmState[r] = "working"
    /\ msgs' = msgs \cup
        \{[rm \mid -> r, type \mid -> "prepared"]\}
    /\ rmState ' = [rmState
        EXCEPT ![r] = "prepared"]
    /\ UNCHANGED <<tmPrepared, tmState>>
RMAbort(r) =
    /\ rmState[r] = "working"
    /\ rmState' = [rmState
        \mathsf{EXCEPT} ! [r] = "aborted"]
    /\ UNCHANGED
        <<tmPrepared, tmState, msgs>>
```

#### PlusCal

- ► A little more progreammer-friendly
- ▶ We specify processes and TLC will check all behaviours

### Simple clock

- ➤ We start from anywhere between 1 and 12 (including 1 and 12)
- in every iteration, we increase by one
- when we reach 12, we reset back to 1
- ► We also state that "x will be eventually one"

### Real world example - health monitor

- ▶ We have several nodes (lets say nodes are 1, 2 and 3)
- Every node can reboot and recover later on
- Every node has one instance of service called "replicator"
- ► When node is down, its replicator instance gets transferred to another node which is up
- When we detect that replicato instance is stuck, we kill it and restart it
- We state that eventually if replicator is stuck, this will lead to either it being killed or recovered by itself

```
▼ 14: Orchestrator in heartbeat >>

  ▶ alive (1)
    killed (0)
 ▶ pc (4) M
                            (0 :> "RebootNode" @@ 1 :> "NodeDown" @@ 2 :> "NodeDown" ...
 ▶ replOwner (3)
 ▶ replStuck (3)
                            <<TRUE, TRUE, FALSE>>

▼ 15: RestartReplicator in heartbeat >>

  ■ alive (1)
    killed (0)
                            (0 :> "RebootNode" @@ 1 :> "NodeDown" @@ 2 :> "NodeDown" ...
  ▶ pc (4) M
 ▶ replOwner (3)
<<2, 3, 3>>
 ▶ replStuck (3)
                            <<TRUE, TRUE, FALSE>>

▼ 16: RebootNode in heartbeat >>

  ■ alive (1)
    killed (0)
 ▶ pc (4) M
                            (0:> "Orchestrator" @@ 1:> "NodeDown" @@ 2:> "NodeDown" ...
 ▶ replOwner (3)
 ▶ replStuck (3)
                            <<TRUE, TRUE, FALSE>>

▼ 17: Orchestrator in heartbeat >>

  ▶ alive (1)
    killed (0)
 ▶ pc (4) M
                            (0:> "RebootNode" @@ 1:> "NodeDown" @@ 2:> "NodeDown" ...
 ▶ replOwner (3)
                   <<2.3.3>>
 ▶ replStuck (3)
                             <<TRUE, TRUE, FALSE>>
▼ 18: P in heartbeat >>
 ▶ alive (1)
    killed (0)
 ▶ pc (4) M
                            (0 :> "RebootNode" @@ 1 :> "NodeDown" @@ 2 :> "NodeDown" ...
 ▶ replOwner (3)
                             <<2.3.3>>
                             <<TRUE, TRUE, FALSE>>
▶ 15: Back to state >>
```

Checking heartbeat.tla / heartbeat.cfg

Success: Fingerprint collision probability: 4.4E-11

Start: 13:23:48 (Jul 4), end: 13:23:55 (Jul 4)

#### States

00:00:00				
00:00:03	13	36 691	9 543	2 062
00:00:05	21	69 801	14 637	
00:00:06	21	69 801	14 637	

#### Coverage

			Distinct
	ACTION		
heartbeat			
heartbeat		11 895	5 256
heartbeat	<u>CheckIfStuck</u>	11 004	4 365
heartbeat	<u>RestartReplicator</u>	15 465	570
heartbeat	<u>NodeDown</u>		C
heartbeat	<u>Orchestrator</u>	9 894	2 964
heartbeat		7 245	208
heartbeat	<u>MakeReplicatorStuck</u>	14 637	1 273
heartbeat	<u>Terminating</u>		C

#### Conclusion

- Formal specification can help us reason about systems and communicate better in teams
- ► There are tools to help us formally specify systems and to check its validity
- ▶ More granular we go, more validation we get

# Gossip session