

Game theory

a course for the
MSc in ICT for Internet and multimedia

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Dynamic Nash equilibria

Direct extension of the definition

NE of a dynamic game

- Going back to the normal form seems to lose the dynamic character of the problem
- Yet, it is interesting for aspects, such as the Nash equilibrium, that are inherently static!

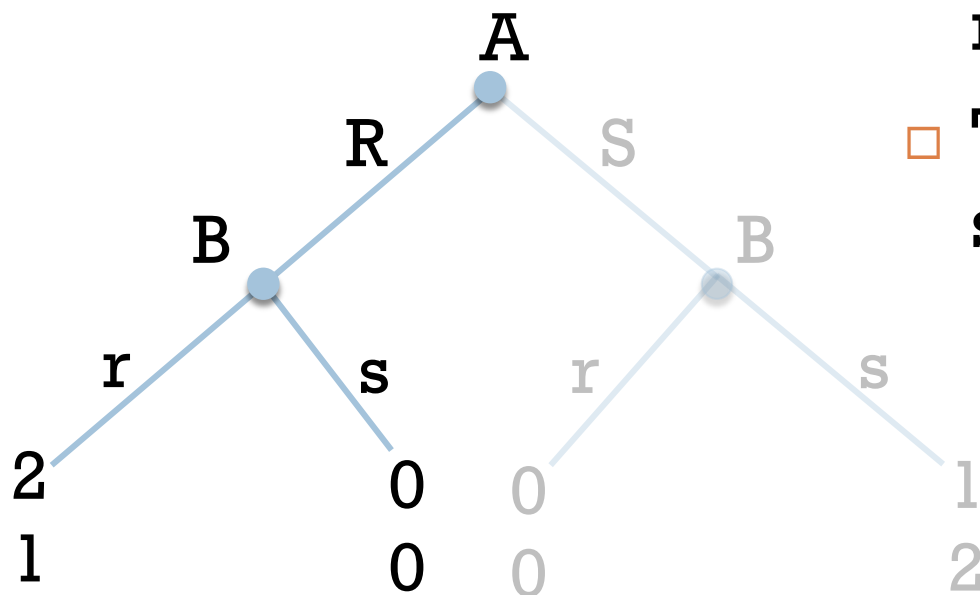
		Brian			
		rr	rs	sr	ss
Ann	R	2, 1	2, 1	0, 0	0, 0
	S	0, 0	1, 2	0, 0	1, 2

NE of a dynamic game

- For the sequential-move Battle of the Sexes, we have three (pure) NE:
 - ▣ (R, rr) : Ann plays R, Brian “always plays R”
 - ▣ (R, rs) : Ann plays R, Brian “copies Ann’s move”
 - ▣ (S, ss) : Ann plays S, Brian “always plays S”
- Remember these strategies are chosen by Brian as though he is moving first!

NE of a dynamic game

- Compare two equilibria: (R, rr) and (R, rs)
 - ▣ Are they really different?

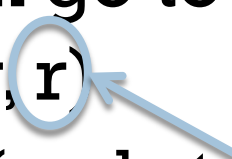


- Ann does not play S, no right-side tree
- They end up in the same outcome
 - ▣ Only part “r” of Brian strategy counts?

NE of a dynamic game

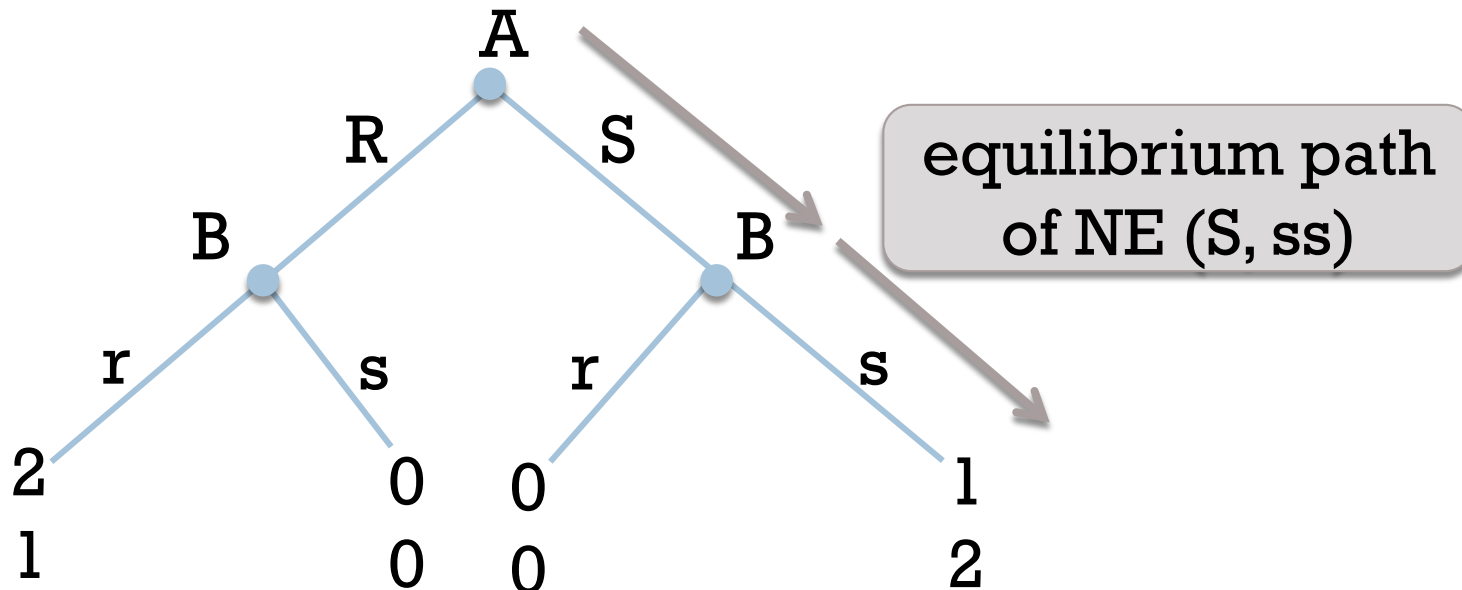
- There is indeed a difference between the two strategies: they are the same in equilibrium, but they are not identical off-equilibrium
 - ▣ Actually, when we are not in equilibrium, playing “rs” for Brian seems to be smarter (it is the strategy “do what Ann says”)
 - ▣ “rr” has a non-rational answer (r to Ann’s S): the thing is, it never comes into play!

NE of a dynamic game

- Representing situations that will not come into play is not really strange
- Remember that in 2-night Battle of the Sexes we included also strategies such as “Go to R the 1st night. If 1st outcome is Rr, then go to S the 2nd night, else go to R” = (r, s, r, r, r)
- Do we need this part of the strategy? (reply to Ss)
- The strategy demands the 1st move to be r, so Ss cannot happen. Yet, we need this specification, not for this player, but for the others!

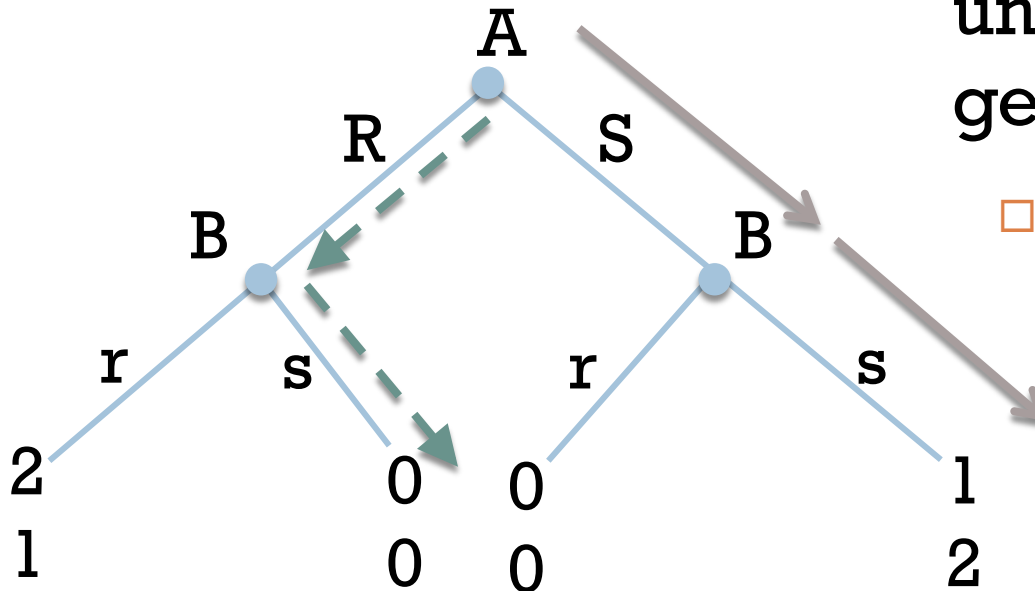
Equilibrium path

- Given a joint profile of behavioral strategies $m^* = (m_1^*, m_2^*, \dots, m_n^*)$ that is a NE, its equilibrium path contains the decision tree nodes that are reached with probability > 0



Equilibrium path

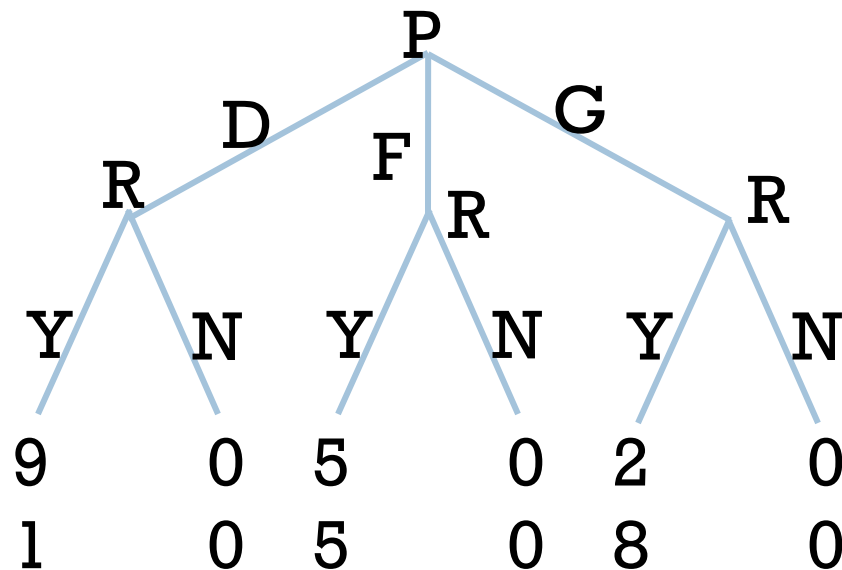
- NEs are determined by belief about what other people are doing both **on and off** the equilibrium path!
- (S, ss) is a NE since A's unilateral deviation gets "punished" by B
 - B "threatens" A
 - is this credible?



Example: Ultimatum game

- Two players share 10 candies as follows
 - ▣ Player 1 (Proposer) presents a split
 - ▣ Player 2 (Responder) decides whether to accept it
 - ▣ If Player 2 refuses, they both get nothing
- For simplicity, $A_P = \{ \text{“D”}(9-1), \text{“F”}(5-5), \text{“G”}(2-8) \}$
- Actions $A_R = \{ \text{“Y”}(\text{accept}), \text{“N”}(\text{refuse}) \}$
 - ▣ The **strategies** of R are more complex, e.g., “play Y if the offer is D or F but not G”
 - ▣ Thus, they are a triple (x_1, x_2, x_3) where $x_j = Y$ or N

Example: Ultimatum game



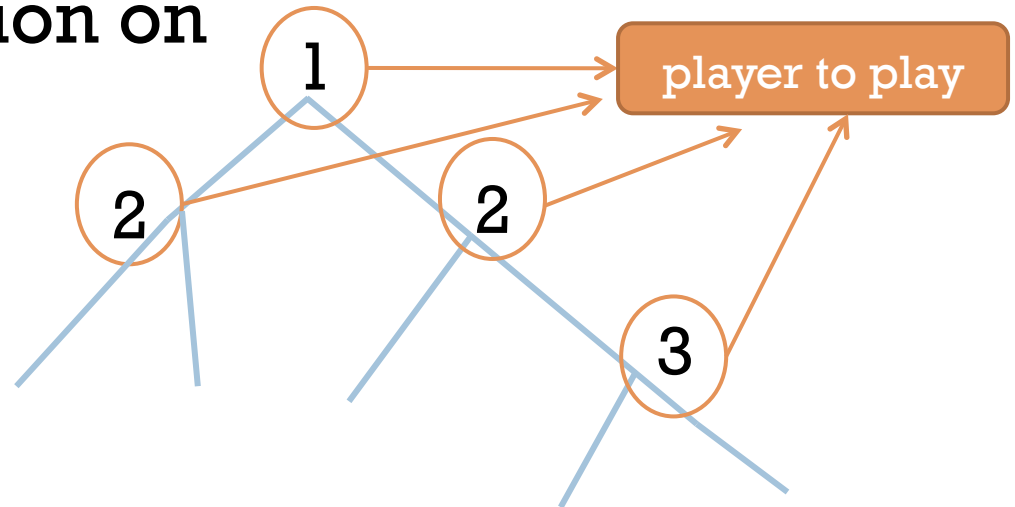
- Joint strategies “offer $x/10-x$ ” (proposer) and “refuse if P’s share is more than x ” (responder) are NEs: no player has incentive to deviate

Rationality and credibility

How to solve dynamic games

Perfect vs imperfect information

- A dynamic game with perfect information is a **sequential game** that can be represented with a regular decision tree (all the information sets are singletons)
- Players move one after another; later players have full information on previous players' choices and can exploit it



Dynamic game, perfect inf.

- This class of games can be solved by means of **backward induction**
- To see why, consider just a 2-players setup
 - ▣ Player **1** chooses action **a_1** from set A_1
 - ▣ Player **2** sees **a_1** and chooses action **$a_2 \in A_2$**
 - ▣ A_2 depends on **a_1** (the game can even end after player 1's move, if $A_2 = \{a_2^*\}$, so 2 has no choice)
 - ▣ Players receive payoffs $u_1(a_1, a_2)$ and $u_2(a_1, a_2)$

Dynamic game, perfect inf.

- We can assume that player 2 can always optimize his/her move
 - ▣ Because of **perfect** information, player 2 knows has the right information set (singleton)
 - ▣ Thanks to **complete** information, player 1 can anticipate the optimization and do the same
- Theorem (~Zermelo). Any dynamic game of perfect information has a backward induction solution that is sequentially rational; if terminal payoffs are all different, it is unique

Backward induction

- When it is his/her turn, Player 2 sees Player 1's move \mathbf{a}_1^h and solves the optimization problem

$$\max_{\mathbf{a}_2 \in A_2} u_2(\mathbf{a}_1^h, \mathbf{a}_2)$$

- Call $\mathbf{R}_2(\mathbf{a}_1^h)$ the argmax solving the problem, i.e., \mathbf{a}_2 yielding the max. Due to complete info, 1 anticipates 2's reaction and solves

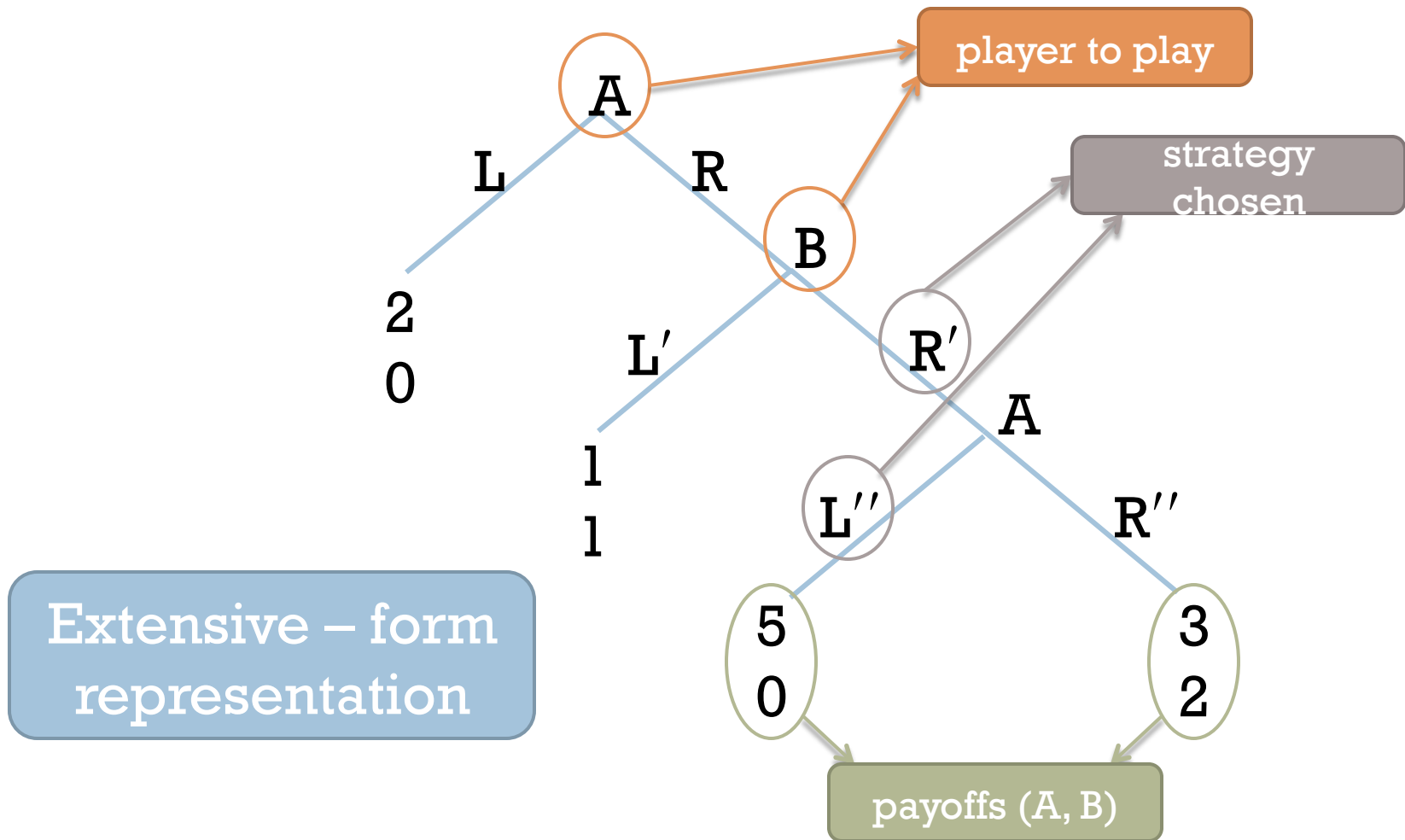
$$\max_{\mathbf{a}_1 \in A_1} u_1(\mathbf{a}_1, \mathbf{R}_2(\mathbf{a}_1))$$

- 1's solution is \mathbf{a}_1^* , the outcome is $\mathbf{a}_1^*, \mathbf{R}_2(\mathbf{a}_1^*)$
It is a **Nash equilibrium in pure strategies**

Example: Trust game

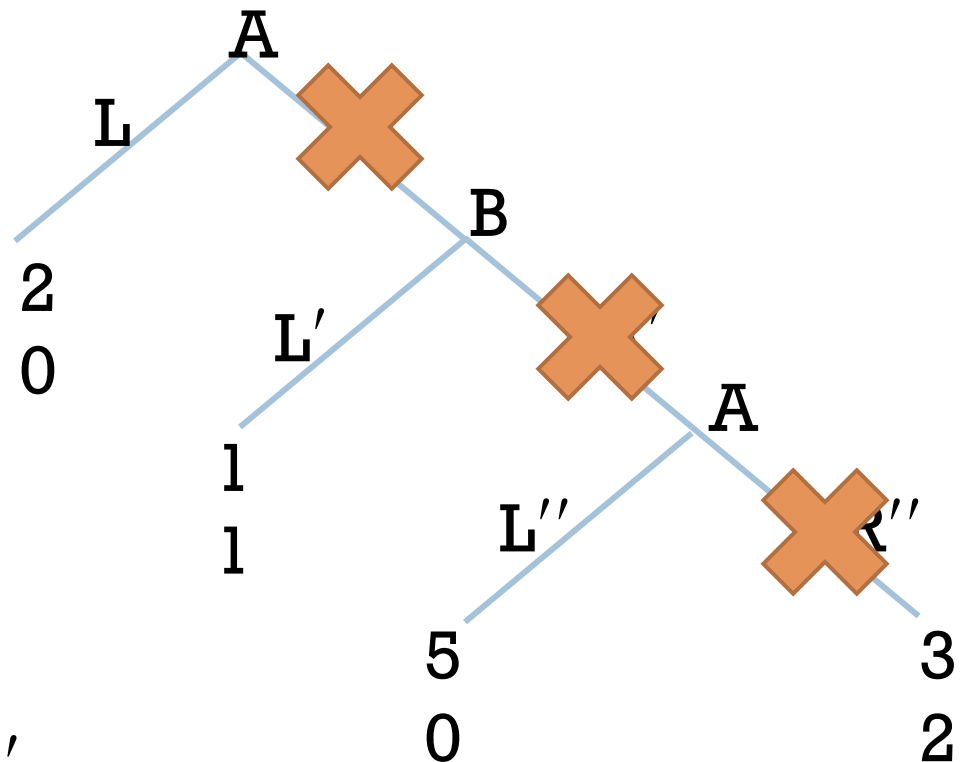
- Consider the following game
 1. A chooses either L or R. L ends the game with payoffs 2 for A and 0 for B. R gives B the right to move (step 2)
 2. B chooses either L' or R'. L' ends the game with payoffs 1 for A and 1 for B. R' gives A the right to move (step 3)
 3. A chooses either L'' or R''. Both end the game, with respective payoffs 5 or 0 for L'' and 3 or 2 for R''
- We can represent this sequence with a tree

Example: Trust game



Example: Trust game

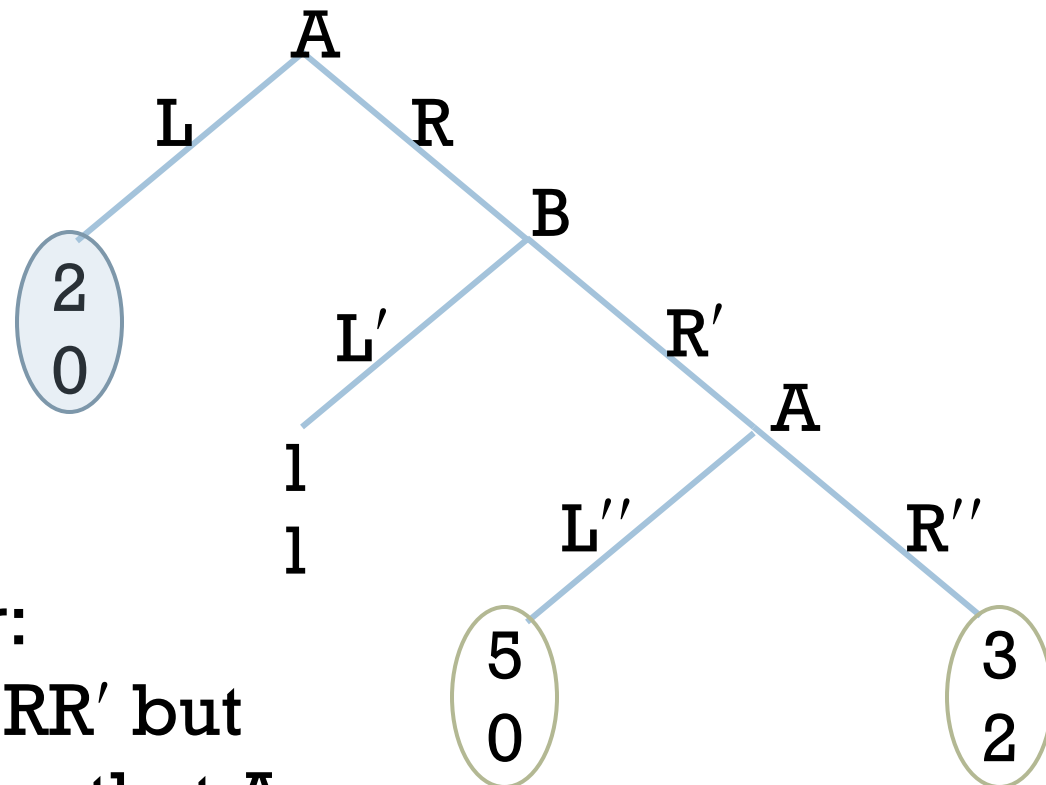
- Apply backward induction.
- A prefers L'' over R''
- Knowing R' will end up in A playing L'' , B will choose to play L'
- Knowing this, A plays L



Example: Trust game

- Payoffs: 2 and 0
 - ▣ inefficient solution (in Pareto sense)

- Rational players do not trust each other:
A can ask B to play RR' but there is no guarantee that A will play R'' (not L''), nor that B plays L' instead



Imperfect information

- Consider now a dynamic game with complete but imperfect information
- A basic model for this kind of games is
 - Players **1** and **2** choose actions **a_1** and **a_2** from sets A_1 and A_2 , respectively
 - Players **3** and **4** observe the outcome of this and choose **a_3** and **a_4** from A_3 and A_4
- Payoffs are $u_j(\mathbf{a}_1, \mathbf{a}_2, \mathbf{a}_3, \mathbf{a}_4)$ for $j = 1, 2, 3, 4$

Note: players are not necessarily distinct or all present

Imperfect information

- Use an approach akin to backward induction.
- For every choice $(\mathbf{a}_1, \mathbf{a}_2)$ of the first two players, players 3 and 4 play a Nash equilibrium $(\mathbf{a}_3^*(\mathbf{a}_1, \mathbf{a}_2), \mathbf{a}_4^*(\mathbf{a}_1, \mathbf{a}_2))$
 - ▣ Players 1 and 2 know and anticipate it, as if they play a simultaneous-move game with payoffs $u_j(\mathbf{a}_1, \mathbf{a}_2, \mathbf{a}_3^*(\mathbf{a}_1, \mathbf{a}_2), \mathbf{a}_4^*(\mathbf{a}_1, \mathbf{a}_2))$ for $j = 1, 2$
 - ▣ They take $\mathbf{a}_1^*, \mathbf{a}_2^*$ as NE of this game
- $(\mathbf{a}_1^*, \mathbf{a}_2^*, \mathbf{a}_3^*(\mathbf{a}_1^*, \mathbf{a}_2^*), \mathbf{a}_4^*(\mathbf{a}_1^*, \mathbf{a}_2^*))$ is the outcome resulting from backward induction

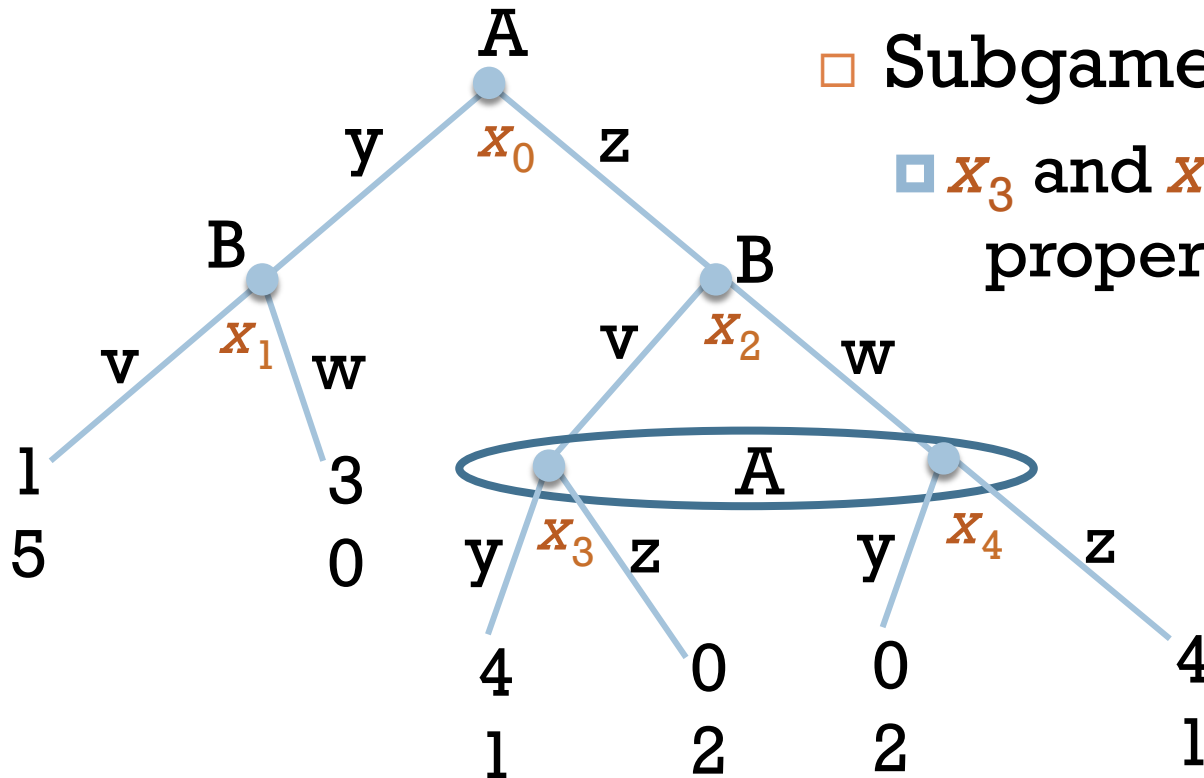
Subgame-perfect NE

Extending the Nash equilibrium concept

Subgames

- Game follows a tree: what about subtrees?
- A (proper) **subgame** \mathbf{G} contains a single node of the tree and all of its successor nodes, with the requirement: $x_j \in \mathbf{G}, x_k \in h_i(x_j) \Rightarrow x_k \in \mathbf{G}$
- All other requirements (players, payoffs, common knowledge) are left unchanged
- The whole game is a subgame of itself

Subgames



□ Subgames: x_0, x_1, x_2 .

□ x_3 and x_4 , are not proper subgames

Subgame-perfect NE

- Definition (R. Selten). A Nash equilibrium is **subgame-perfect** if the strategies chosen by the players give a NE in **every** subgame
 - ▣ It is a refinement of NE. In a subgame-perfect Nash equilibrium (SPE) the players strategies must first be a NE and then must pass an additional test
- Every finite extensive form game has an SPE
 - ▣ This means that every game, from tic-tac-toe to chess or go, has an optimal way to be played

Subgame-perfect NE

- How to prove that SPE is unique? For perfect information game with finite horizon, SPE is the outcome of backward induction
- This can be somehow extended for other dynamic games, by taking into account the **credibility** of the threats
- Credibility: Player 1 knows \mathbf{a}_1 implies response $\mathbf{R}_2(\mathbf{a}_1)$, so strategies “if \mathbf{a}_1 then $\mathbf{a}_2 \neq \mathbf{R}_2(\mathbf{a}_1)$ ” are classified as non-credible

Credibility of threats

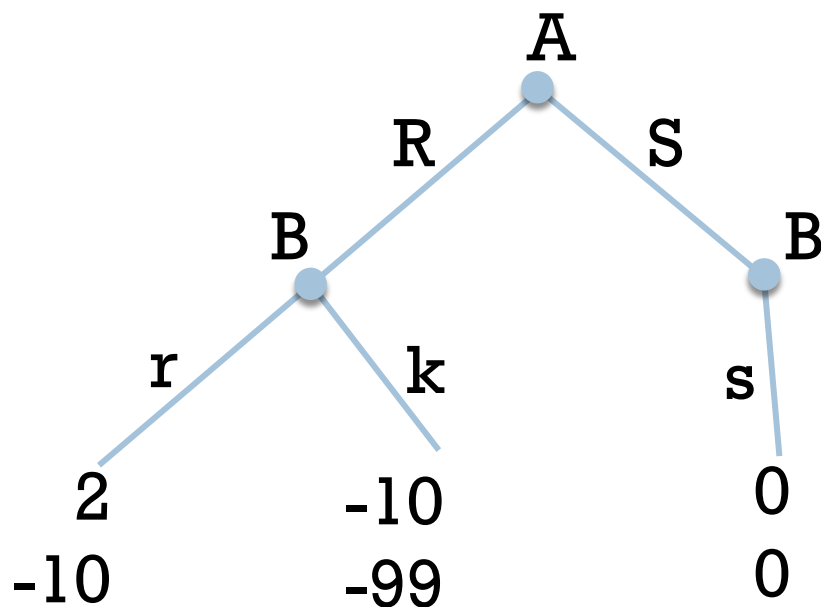
- Consider again the dynamic battle of the sexes with Ann moving first
 - ▣ Brian can play (ss) meaning that, even when Ann selects R, he goes to S
 - ▣ Ann does not believe him and decides what she prefers, knowing Brian's threat is empty
- In Hawk-and-Dove the threat to deviate from NE is non-credible (it hurts both)

Credibility of threats

- An extreme version of incredible threat
 - ▣ There is no (S)ci-fi movie at the theater, just one (R)omance movies that Brian hates
 - ▣ Now, option S means = “stay at home” that is probably the best option for Brian: if Ann chooses this, then the game ends
 - ▣ But if Ann decides to go (R), then Brian has just two options: to comply (r) or to kill himself (k)
 - ▣ Brian may consider strategy (s,k)

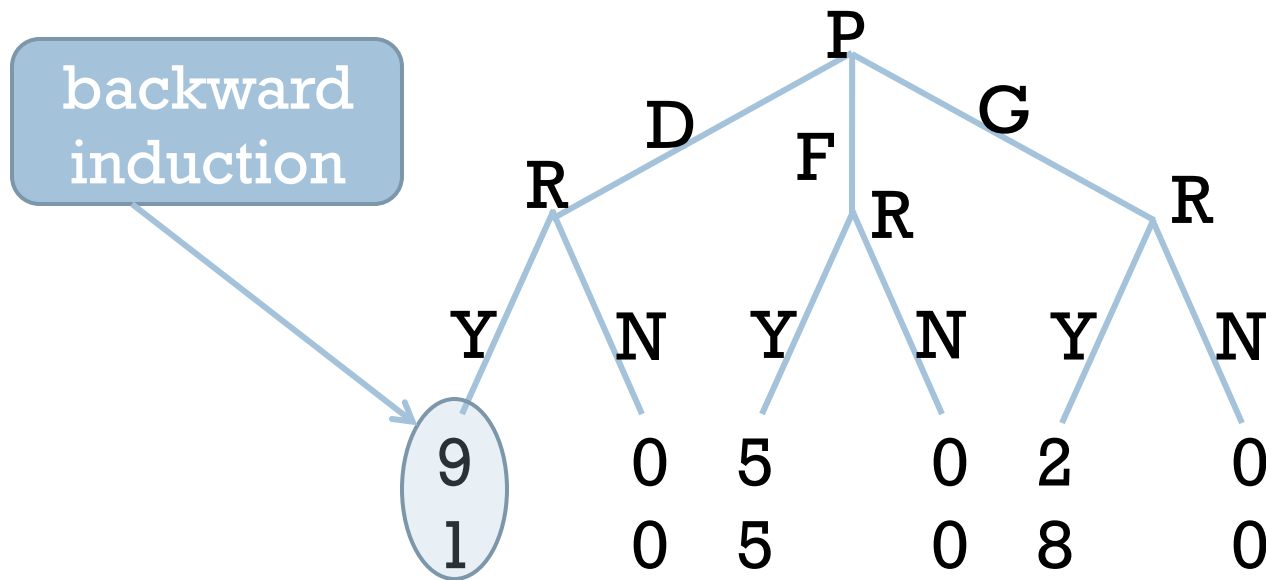
Credibility of threats

- Brian may consider strategy (k,s)
 - ▣ This means to threaten Ann to commit suicide if she insists in going to R



- Ann can be tempted to play S to avoid this
- However, B choosing k instead of r would be irrational
 - ▣ Non-credible threat!

back to Example 11



- Many NEs, **one** SPE: “P chooses D” “R accepts”
- P knows that R is better off if accepting any proposal, since it is “something” against “nothing”
- Not accepting is a non-credible threat