

INP7079233 - BIG DATA COMPUTING 2023-2024 (prof. Pietracaprina and Silvestri)

[Home](#) / [My courses](#) / [2023-IN2547-003PD-2023-INP7079233-G2GR2](#) / [Homework 1](#) / [Assignment of Homework 1 \(deadline: April 12\)](#)

Assignment of Homework 1 (deadline: April 12)

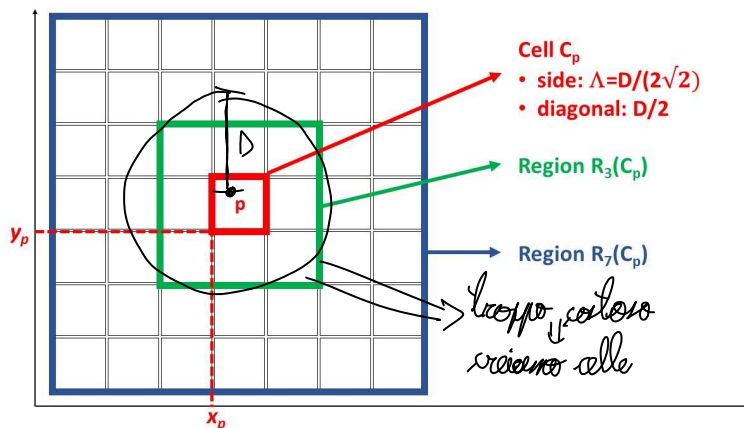
The purpose of the first homework is to get acquainted with Spark and with its use to implement MapReduce algorithms. In preparation for the homework, you must set up your environment following the instructions given in Moodle Exam, in the same section as this page. After the set up is complete, test it using the WordCountExample program (Java or Python), and familiarize with the Spark methods it uses. The Introduction to Programming in Spark may turn out useful to this purpose.

OUTLIER DETECTION. In the homework, you must implement and compare exact and approximate algorithms to detect outliers in a large dataset. Outlier (or anomaly) detection is a fundamental task in data analysis but it is often very expensive from a computational point of view. We will use the following definition of outlier. Let S be a set of N points from some metric space and, for each $p \in S$ let $B_S(p, r)$ denote the set of points of S at distance at most r from p . For given parameters $M, D > 0$, an (M, D) -outlier (w.r.t. S) is a point $p \in S$ such that $|B_S(p, D)| \leq M$. The problem that we want to study is the following: given S, M , and D , mark each point $p \in S$ as outlier, if it is an (M, D) -outlier, and non-outlier otherwise. For simplicity, we will consider inputs $S \subset \mathbb{R}^2$ and the standard Euclidean distance.

Exact Algorithm. The problem can be solved straightforwardly, by computing all $N(N-1)/2$ pairwise distances among the points, but, unfortunately, this strategy is impractical for very large N .

Approximate Algorithm. This algorithm is a simple adaptation of an algorithm presented in Edwin M. Knorr, Raymond T. Ng, V. Tucakov: *Distance-Based Outliers: Algorithms and Applications*, VLDB J. 8(3-4): 237-253 (2000). Consider \mathbb{R}^2 partitioned into square cells of side $\Lambda = D/(2\sqrt{2})$ (whose diagonal length is $D/2$). For each such cell C , we use an identifier defined by the pair of indices (i, j) , with $i, j \in \mathbb{Z}$, where $i \cdot \Lambda$ and $j \cdot \Lambda$ are the real coordinates of C 's bottom-left corner. For a point $p = (x_p, y_p) \in C$ we define (see also picture below):

- C_p = cell where p resides, i.e., $C_p = (i, j)$ with $i = \lfloor x_p/\Lambda \rfloor$ and $j = \lfloor y_p/\Lambda \rfloor$.
- $R_3(C_p)$ = 3x3 grid of cells with C_p in the middle.
- $R_7(C_p)$ = 7x7 grid of cells with C_p in the middle.



OUTLIER: $|B(p, r) \cap S| \leq M$
dato S input set, $|S| \leq n$
Brute force: calcolo tutte distanze
($O(n^2)$)

Define also:

- $N_3(C_p)$ = number of points in $R_3(C_p) \cap S$.
- $N_7(C_p)$ = number of points in $R_7(C_p) \cap S$.

soluzione approx: \bar{n} , no, incerto

almeno 1 punto in $B(p, D)$

It is easy to verify that if $N_3(C_p) > M$, then p is a non-outlier, while if $N_7(C_p) \leq M$, then p is surely an outlier. Instead, if $N_3(C_p) \leq M$ and $N_7(C_p) > M$, then p can be outlier or non-outlier, and we call *uncertain*. Observe that if an uncertain point is a true outlier, it can be regarded as a "mild" outlier, in the sense that it has more than M points within distance at most $2D$.

The homework aims at comparing the exact and approximate algorithms in terms of accuracy in detecting the true outliers and running time.

DATA FORMAT. To implement the algorithms assume that each point p is represented through its coordinates (x_p, y_p) , where each coordinate is a float, and that set S is given in input as a file, where each row contains one point stored with the coordinates separated by comma (','). Assume also that all points are distinct.

TASK for HW1:

1) Write a method/function **ExactOutliers** which implements the Exact algorithm, through standard sequential code which does not use RDDs. Specifically, **ExactOutliers** takes as input a list of points (ArrayList in Java, or a list in Python) and parameters D (float), M , K (integers), and must compute and print the following information.

- The number of (D, M) -outliers.
- The first K outliers points p in non-decreasing order of $|B_S(p, D)|$, one point per line. (If there are less than K outlier, it prints all of them.)

2) Write a method/function **MRApproxOutliers** which implements the above approximate algorithm. Specifically, **MRApproxOutliers** must take as input an RDD of points and parameters D (float), M , K (integers), and can assume that the RDD is already subdivided into a suitable number of partitions. **MRApproxOutliers** consists of two main steps. **Step A** transforms the input RDD into an RDD whose elements corresponds to the non-empty cells and, contain, for each cell, its identifier (i, j) and the number of points of S that it contains. The computation must be done by exploiting the Spark partitions, *without gathering together all points of a cell* (which could be too many). **Step B** transforms the RDD of cells, resulting from Step A, by attaching to each element, relative to a non-empty cell C , the values $|N_3(C)|$ and $|N_7(C)|$, as additional info. To this purpose, you can assume that the total number of non-empty cells is small with respect to the capacity of each executor's memory. **MRApproxOutliers** must eventually compute and print

- The number of sure (D, M) -outliers.
- The number of uncertain points.
- For the first K non-empty cells, in non-decreasing order of $|N_3(C)|$, their identifiers and value of $|N_3(C)|$, one line per cell. (If there are less than K non-empty cells, it prints the information for all of them.)

3) Write a program GxxxHW1.java (for Java users) or **GxxxHW1.py** (for Python users), where xxx is your 3-digit group number (e.g., 004 or 045), which receives in input, as command-line arguments, a path to the file storing the input points, a float D , and 3 integers M , K , L , and does the following:

- Prints the command-line arguments and stores D , M , K , L into suitable variables.
- Reads the input points into an RDD of strings (called **rawData**) and transform it into an RDD of points (called **inputPoints**), represented as pairs of integers subdivided into L partitions.
- Prints the total number of points.
- Only if the number of points is at most 200000:
 - Downloads the points into a list called **listOfPoints**
 - Executes **ExactOutliers** with parameters **listOfPoints**, (D) , M and K . The execution will print the information specified above.
 - Prints **ExactOutliers**' running time.
- In all cases:
 - Executes **MRApproxOutliers** with parameters **inputPoints**, (D) , M and K . The execution will print the information specified above.
 - Prints **MRApproxOutliers**' running time.

File **OutputFormat.txt (TO BE ADDED)** shows you how to format your output. Make sure that your program complies with this format.

4) Test your program using the datasets that we provide in the same section as this page, together with the outputs of our program on the datasets.

SUBMISSION INSTRUCTIONS. Each group must submit the file containing its program (**GxxxHW1.java** or **GxxxHW1.py**). Only one student per group must submit the file in Moodle Exam using the link provided in the Homework 1 section. Make sure that your code is free from compiling/run-time errors and that you use the file/variable names in the homework description, otherwise your score will be penalized.

If you have questions about the assignment, contact the teaching assistants (TAs) by email to bdc-course@dei.unipd.it. The subject of the email must be "**HW1 - Group xxx**", where xxx is your group ID. If needed, a zoom meeting between the TAs and the group will be organized.

Last modified: Monday, 18 March 2024, 3:10 PM

◀ [sentence_small.txt](#) (file that can be used with WordCountExample Java and Python codes)

Jump to...

[TestN15-input](#) (small input for testing, input size N=15) ▶

You are logged in as FANTIN LUCA (Log out)
2023-IN2547-003PD-2023-INP7079233-G2GR2

Data retention summary