

# Game theory

a course for the  
MSc in ICT for Internet and multimedia

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# Dynamic Nash equilibria

Direct extension of the definition

# NE of a dynamic game

- Going back to the normal form seems to lose the dynamic character of the problem
- Yet, it is interesting for aspects, such as the Nash equilibrium, that are inherently static!

		Brian			
		rr	rs	sr	ss
Ann	R	2, 1	2, 1	0, 0	0, 0
	S	0, 0	1, 2	0, 0	1, 2

# NE of a dynamic game

- For the sequential-move Battle of the Sexes, we have three (pure) NE:
  - (R,rr): Ann plays R, Brian “always plays R”
  - (R,rs): Ann plays R, Brian “copies Ann’s move”
  - (S,ss): Ann plays S, Brian “always plays S”
- Remember these strategies are chosen by Brian as though he is moving first!

# NE of a dynamic game

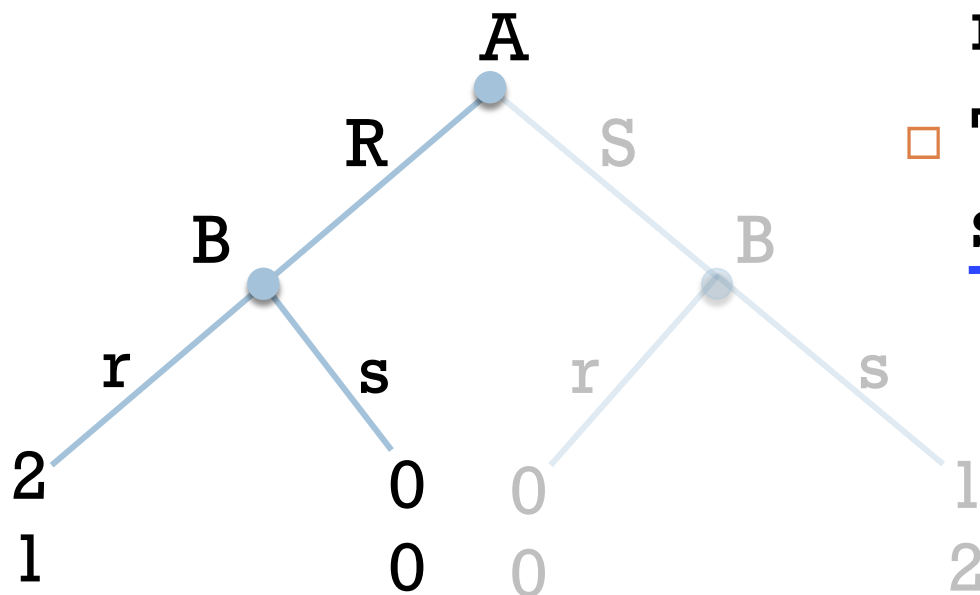
□ Compare two equilibria:  $(R, rr)$  and  $(R, rs)$

▣ Are they really different?

□ Ann does not play S, no right-side tree

□ They end up in the same outcome

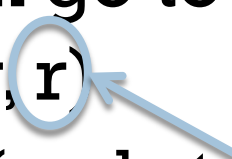
▣ Only part “r” of Brian strategy counts?



# NE of a dynamic game

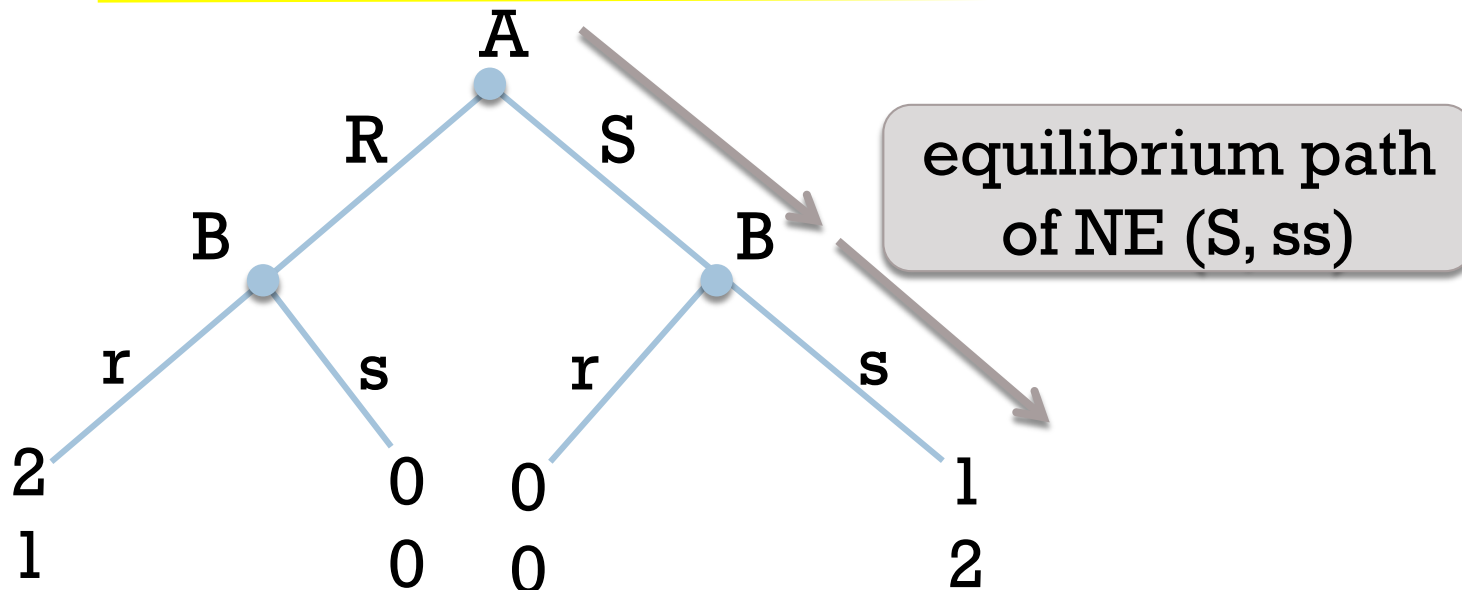
- There is indeed a difference between the two strategies: they are the same in equilibrium, but they are not identical off-equilibrium
  - ▣ Actually, when we are not in equilibrium, playing “rs” for Brian seems to be smarter (it is the strategy “do what Ann says”)
  - ▣ “rr” has a non-rational answer (r to Ann’s S): the thing is, it never comes into play!

# NE of a dynamic game

- Representing situations that will not come into play is not really strange
- Remember that in 2-night Battle of the Sexes we included also strategies such as “Go to R the 1<sup>st</sup> night. If 1<sup>st</sup> outcome is Rr, then go to S the 2<sup>nd</sup> night, else go to R” = (r, s, r, r, r)
- Do we need this part of the strategy? (reply to Ss)
- The strategy demands the 1<sup>st</sup> move to be r, so Ss cannot happen. Yet, we need this specification, not for this player, but for the others!

# Equilibrium path

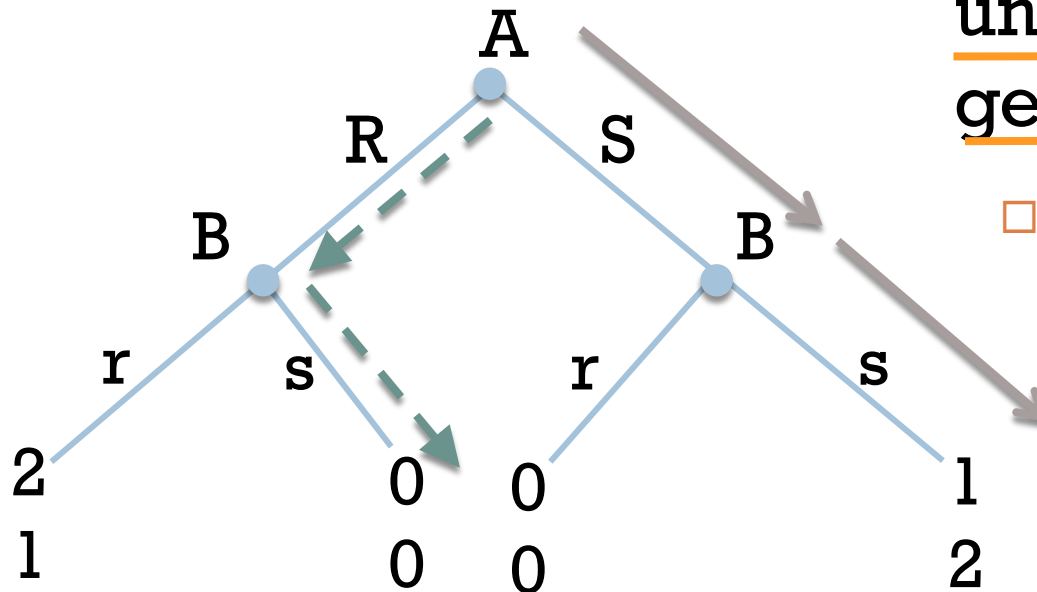
- Given a joint profile of behavioral strategies  $m^* = (m_1^*, m_2^*, \dots, m_n^*)$  that is a NE, its equilibrium path contains the decision tree nodes that are reached with probability  $> 0$





# Equilibrium path

- NEs are determined by belief about what other people are doing both on and off the equilibrium path!

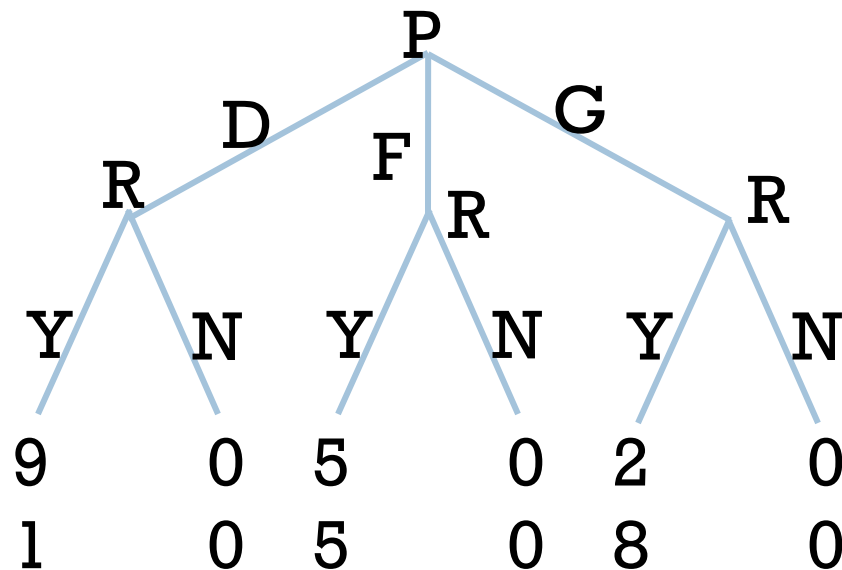


- (S, ss) is a NE since A's unilateral deviation gets "punished" by B
- B "threatens" A
  - is this credible?

# Example: Ultimatum game

- Two players share 10 candies as follows
  - ▣ Player 1 (Proposer) presents a split
  - ▣ Player 2 (Responder) decides whether to accept it
  - ▣ If Player 2 refuses, they both get nothing
- For simplicity,  $A_P = \{“D”(9-1), “F”(5-5), “G”(2-8)\}$
- Actions  $A_R = \{“Y”(accept), “N”(refuse)\}$ 
  - ▣ The **strategies** of R are more complex, e.g., “play Y if the offer is D or F but not G”
  - ▣ Thus, they are a triple  $(x_1, x_2, x_3)$  where  $x_j = Y$  or N

# Example: Ultimatum game



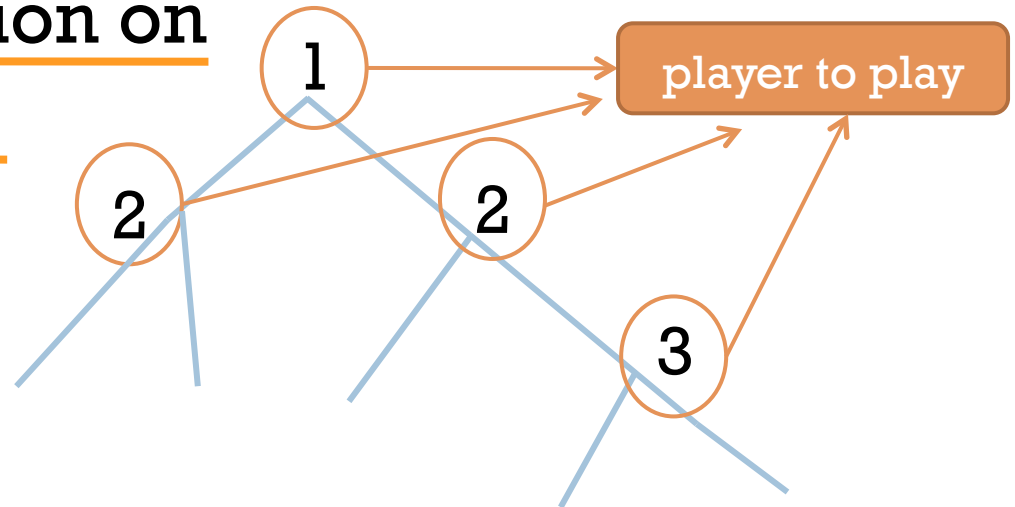
- Joint strategies “offer  $x/10-x$ ” (proposer) and “refuse if P’s share is more than  $x$ ” (responder) are NEs: no player has incentive to deviate

# Rationality and credibility

How to solve dynamic games

# Perfect vs imperfect information

- A dynamic game with perfect information is a sequential game that can be represented with a regular decision tree (all the information sets are singletons)
- Players move one after another; later players have full information on previous players' choices and can exploit it



# Dynamic game, perfect inf.

- This class of games can be solved by means of **backward induction**
- To see why, consider just a 2-players setup
  - Player **1** chooses action  $a_1$  from set  $A_1$
  - Player **2** sees  $a_1$  and chooses action  $a_2 \in A_2$
  - $A_2$  depends on  $a_1$  (the game can even end after player 1's move, if  $A_2 = \{a_2^*\}$ , so 2 has no choice)
  - Players receive payoffs  $u_1(a_1, a_2)$  and  $u_2(a_1, a_2)$

# Dynamic game, perfect inf.

- We can assume that player 2 can always optimize his/her move
  - ▣ Because of perfect information, player 2 knows has the right information set (singleton)
  - ▣ Thanks to complete information, player 1 can anticipate the optimization and do the same
- Theorem (~Zermelo). Any dynamic game of perfect information has a backward induction solution that is sequentially rational; if terminal payoffs are all different, it is unique

# Backward induction

- When it is his/her turn, Player 2 sees Player 1's move  $\mathbf{a}_1^h$  and solves the optimization problem

$$\max_{\mathbf{a}_2 \in A_2} u_2(\mathbf{a}_1^h, \mathbf{a}_2)$$

- Call  $\mathbf{R}_2(\mathbf{a}_1^h)$  the argmax solving the problem, i.e.,  $\mathbf{a}_2$  yielding the max. Due to complete info, 1 anticipates 2's reaction and solves

$$\max_{\mathbf{a}_1 \in A_1} u_1(\mathbf{a}_1, \mathbf{R}_2(\mathbf{a}_1))$$

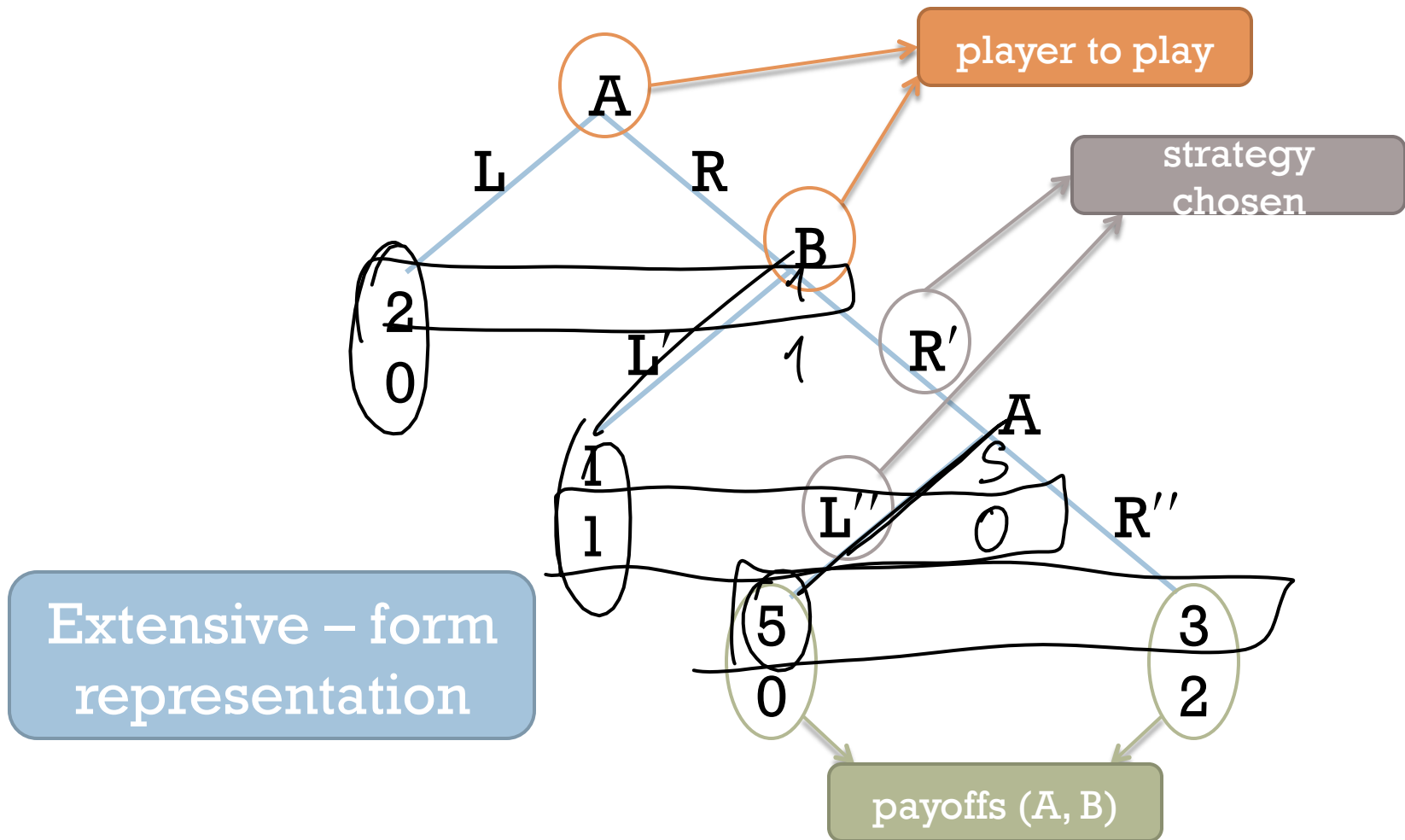
- 1's solution is  $\mathbf{a}_1^*$ , the outcome is  $\mathbf{a}_1^*, \mathbf{R}_2(\mathbf{a}_1^*)$   
It is a **Nash equilibrium in pure strategies**



# Example: Trust game

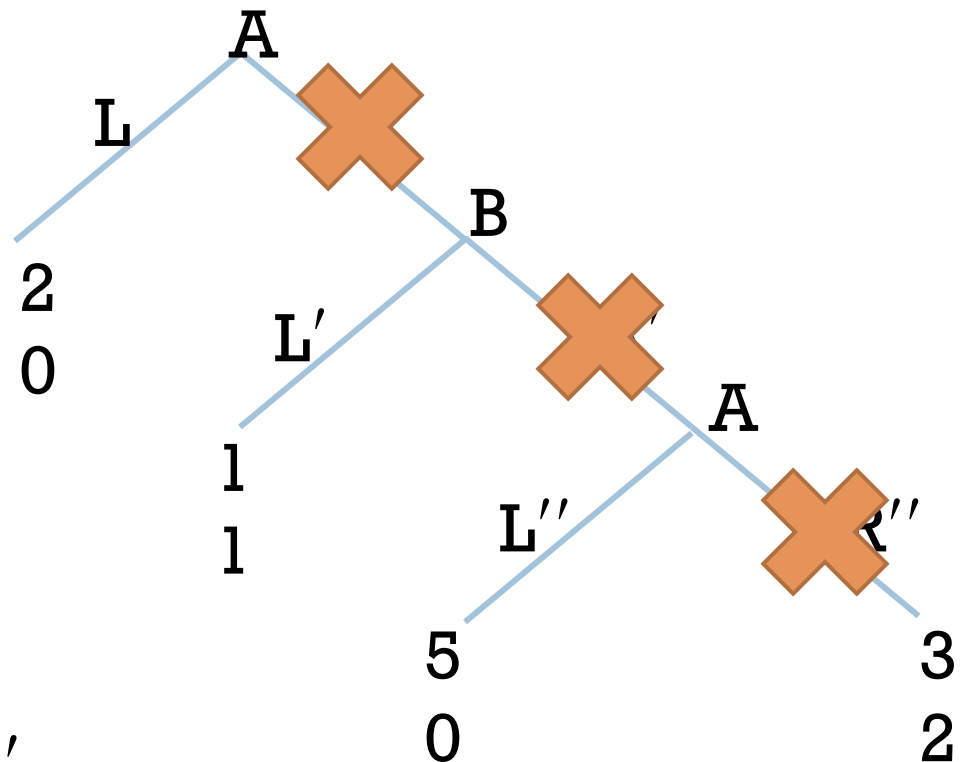
- Consider the following game
  1. A chooses either L or R. L ends the game with payoffs 2 for A and 0 for B. R gives B the right to move (step 2)
  2. B chooses either L' or R'. L' ends the game with payoffs 1 for A and 1 for B. R' gives A the right to move (step 3)
  3. A chooses either L'' or R''. Both end the game, with respective payoffs 5 or 0 for L'' and 3 or 2 for R''
- We can represent this sequence with a tree

# Example: Trust game



# Example: Trust game

- Apply backward induction.
- A prefers  $L''$  over  $R''$
- Knowing  $R'$  will end up in A playing  $L''$ , B will choose to play  $L'$
- Knowing this, A plays  $L$

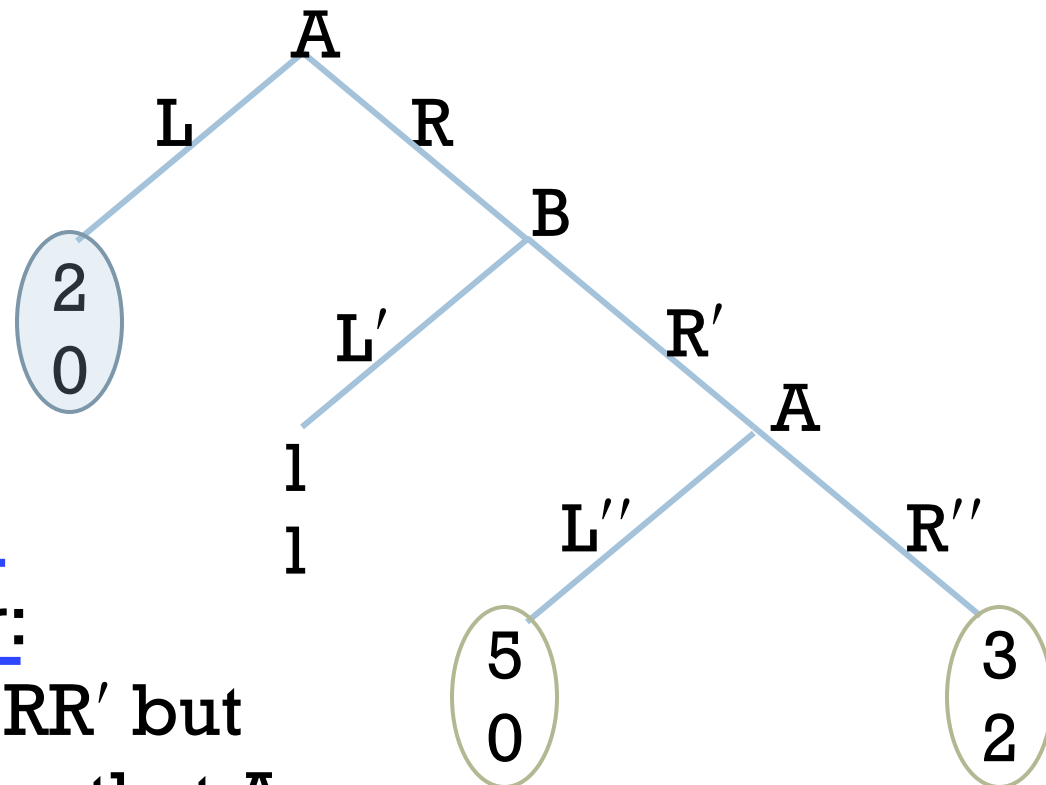


# Example: Trust game

- Payoffs: 2 and 0
  - inefficient solution  
(in Pareto sense)

- Rational players do not trust each other:

A can ask B to play  $RR'$  but there is no guarantee that A will play  $R''$  (not  $L''$ ), nor that B plays  $L'$  instead



# Imperfect information

- Consider now a dynamic game with complete but imperfect information
- A basic model for this kind of games is
  - Players 1 and 2 choose actions  $a_1$  and  $a_2$  from sets  $A_1$  and  $A_2$ , respectively
  - Players 3 and 4 observe the outcome of this and choose  $a_3$  and  $a_4$  from  $A_3$  and  $A_4$
- Payoffs are  $u_j(a_1, a_2, a_3, a_4)$  for  $j = 1, 2, 3, 4$

**Note:** players are not necessarily distinct or all present

# Imperfect information

- Use an approach akin to backward induction.
- For every choice  $(\mathbf{a}_1, \mathbf{a}_2)$  of the first two players, players 3 and 4 play a Nash equilibrium  $(\mathbf{a}_3^*(\mathbf{a}_1, \mathbf{a}_2), \mathbf{a}_4^*(\mathbf{a}_1, \mathbf{a}_2))$
- Players 1 and 2 know and anticipate it, as if they play a simultaneous-move game with payoffs  $u_j(\mathbf{a}_1, \mathbf{a}_2, \mathbf{a}_3^*(\mathbf{a}_1, \mathbf{a}_2), \mathbf{a}_4^*(\mathbf{a}_1, \mathbf{a}_2))$  for  $j = 1, 2$
- They take  $\mathbf{a}_1^*, \mathbf{a}_2^*$  as NE of this game
- $(\mathbf{a}_1^*, \mathbf{a}_2^*, \mathbf{a}_3^*(\mathbf{a}_1^*, \mathbf{a}_2^*), \mathbf{a}_4^*(\mathbf{a}_1^*, \mathbf{a}_2^*))$  is the outcome resulting from backward induction

# Subgame-perfect NE

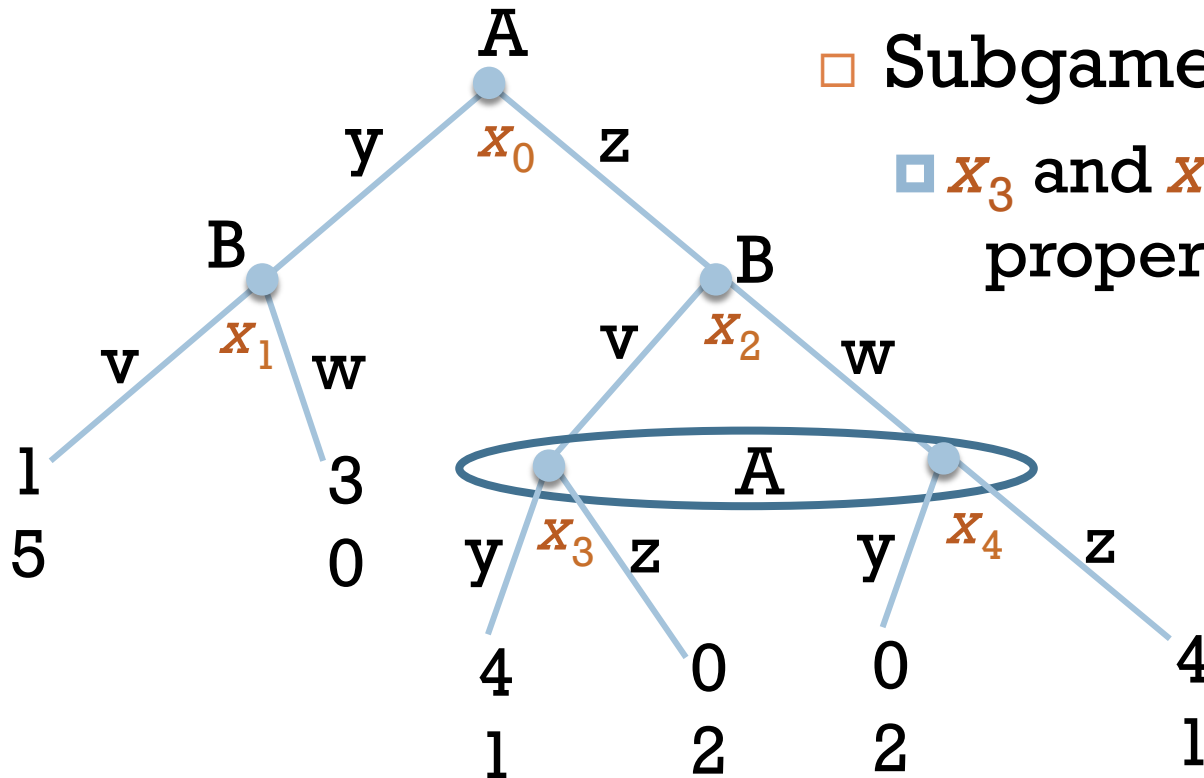
Extending the Nash equilibrium concept

# Subgames

- Game follows a tree: what about subtrees?
- A (proper) **subgame** **G** contains a single node of the tree and all of its successor nodes, with the requirement:  $x_i \in \mathbf{G}, x_k \in h_i(x_i) \Rightarrow x_k \in \mathbf{G}$
- All other requirements (players, payoffs, common knowledge) are left unchanged
- The whole game is a subgame of itself



# Subgames



□ Subgames:  $x_0, x_1, x_2$ .

□  $x_3$  and  $x_4$ , are not proper subgames

# Subgame-perfect NE

- Definition (R. Selten). A Nash equilibrium is **subgame-perfect** if the strategies chosen by the players give a NE in **every** subgame
  - ▣ It is a refinement of NE. In a subgame-perfect Nash equilibrium (SPE) the players strategies must first be a NE and then must pass an additional test
- Every finite extensive form game has an SPE
  - ▣ This means that every game, from tic-tac-toe to chess or go, has an optimal way to be played

# Subgame-perfect NE

- How to prove that SPE is unique? For perfect information game with finite horizon, SPE is the outcome of backward induction
- This can be somehow extended for other dynamic games, by taking into account the **credibility** of the threats
- Credibility: Player 1 knows  $a_1$  implies response  $R_2(a_1)$ , so strategies “if  $a_1$  then  $a_2 \neq R_2(a_1)$ ” are classified as non-credible

# Credibility of threats

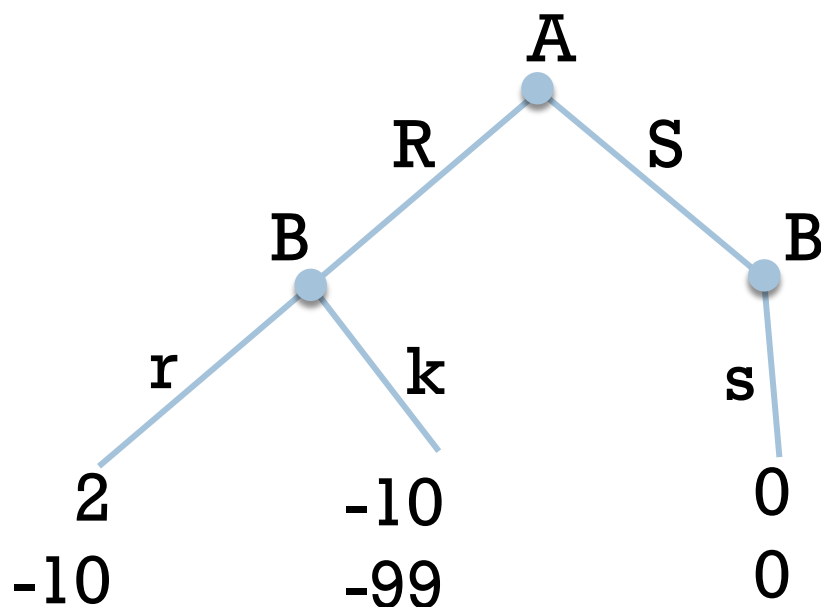
- Consider again the dynamic battle of the sexes with Ann moving first
  - ▣ Brian can play (ss) meaning that, even when Ann selects R, he goes to S
  - ▣ Ann does not believe him and decides what she prefers, knowing Brian's threat is empty
- In Hawk-and-Dove the threat to deviate from NE is non-credible (it hurts both)

# Credibility of threats

- An extreme version of incredible threat
  - ▣ There is no (S)ci-fi movie at the theater, just one (R)omance movies that Brian hates
  - ▣ Now, option S means = “stay at home” that is probably the best option for Brian: if Ann chooses this, then the game ends
  - ▣ But if Ann decides to go (R), then Brian has just two options: to comply (r) or to kill himself (k)
  - ▣ Brian may consider strategy (s,k)

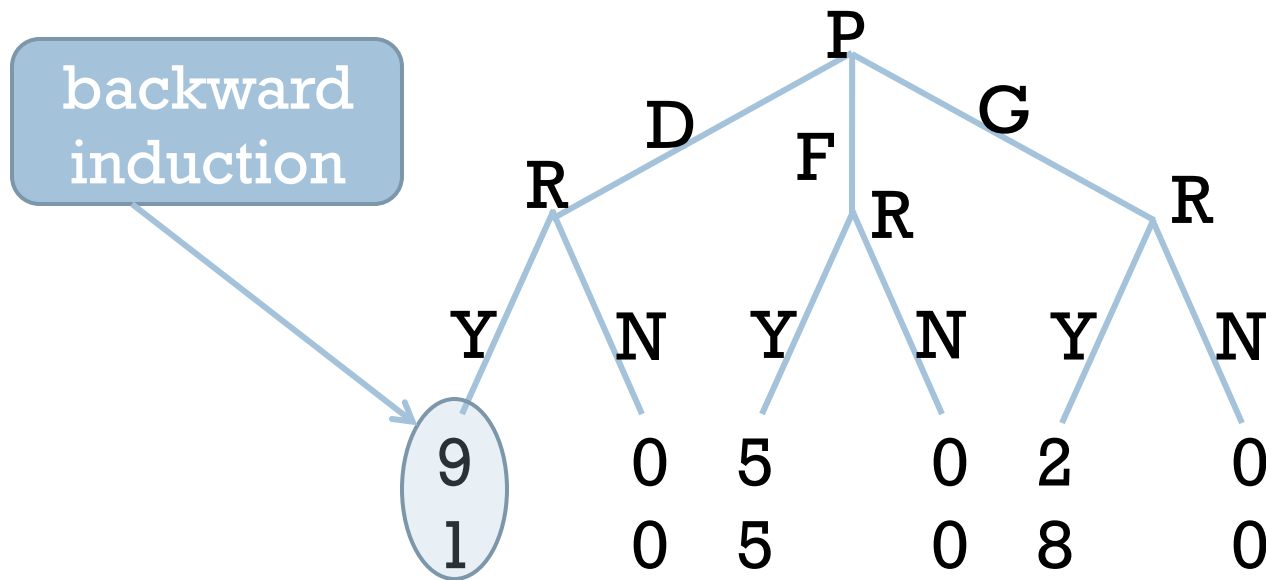
# Credibility of threats

- Brian may consider strategy (k,s)
  - ▣ This means to threaten Ann to commit suicide if she insists in going to R



- Ann can be tempted to play S to avoid this
- However, B choosing k instead of r would be irrational
  - ▣ Non-credible threat!

# back to Example 11



- Many NEs, **one** SPE: “P chooses D” “R accepts”
- P knows that R is better off if accepting any proposal, since it is “something” against “nothing”
- Not accepting is a non-credible threat