

MAD 350

Project : Application of Measure Theory in Finance

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Some Nice Properties

Capturing Information Flow in Financial Markets

- Structure of a σ -algebra is specially suited to model information

Definition 1. A family \mathbb{X} of subsets of a set X is said to be a σ -algebra in case :

- i) \emptyset, X belong to \mathbb{X} .
- ii) If A belongs to \mathbb{X} , then A^c belongs to \mathbb{X} .
- iii) If (A_n) is a sequence of sets in \mathbb{X} , then the union $\bigcup_{n=1}^{\infty} A_n \in \mathbb{X}$.

An ordered pair (X, \mathbb{X}) consisting of a set X and a σ -algebra \mathbb{X} is called a *measurable space*.

- Let the set of all outcomes of a random experiment be the set Ω , and let ω be a particular outcome
- We have some information, which may or may not us in evaluating ω
- If we know, for a set A , whether the eventual ω lies in it or not, then it is said to be *resolved*

- i) \emptyset, X are always resolved.
- ii) If A is resolved then A^c is also resolved.
- iii) If (A_n) is a sequence of resolved sets, then the union $\bigcup_{n=1}^{\infty} A_n$ is also resolved.

Capturing Information Flow in Financial Markets

Definition 5. Let Ω be a non-empty set. Let T be a fixed positive number, and assume that for each $t \in [0, T]$ there is an associated σ -algebra $\mathcal{F}(t)$. Assume further that if $s \leq t$, then $\mathcal{F}(s) \subseteq \mathcal{F}(t)$. Then the collection of σ -algebras, $\mathcal{F}(t)$, $0 \leq t \leq T$, is called a *filtration*.

- When we get to time t , we will know for each set in $\mathcal{F}(t)$ whether the eventual ω lies in that set or not.
- In mathematical finance, a filtration represents the information available up to and including each time t , and is more and more precise (the set of measurable events is staying the same or increasing) as more information from the evolution of the stock price becomes available.
- Knowing the value of $S(\omega)$, does give us some information
- Resolves every set of the form $\{\omega : S(\omega) \text{ belongs to } B, \text{ where } B \text{ of } \mathcal{B}(R)\}$.
- Information provided by S is captured by $\sigma(S)$. *

Definition 8. Let Ω be a nonempty sample space equipped with a filtration $\mathcal{F}(t), 0 \leq t \leq T$. Let $S(t)$ be a collection of random variables indexed by $t \in [0, T]$. We say this collection of random variables is an *adapted stochastic process* if, for each t , the random variable $S(t)$ is $\mathcal{F}(t)$ -measurable.

- Introduce the notion of stochastic processes for asset prices, portfolio processes, and wealth process (value of a portfolio), and these are adapted to a filtration that we regard as a model of the flow of public information.

Towards Conditional Expectation

In general, there are three cases that arise when we have a random variable S and a σ -algebra \mathcal{G} :

1. The information contained in the \mathcal{G} is sufficient to determine the value of S . In this case, S is \mathcal{G} -measurable.
2. The information contained in \mathcal{G} gives us no clue about the value of S . In this case, we say that S is *independent* of \mathcal{G} .
3. The information contained in \mathcal{G} is not sufficient to evaluate S , but we can get some estimate of S based on the information in \mathcal{G} .

Definition 2. Let (Ω, \mathcal{F}, P) be a probability space, let \mathcal{G} be a *sub- σ -algebra* of \mathcal{F} , and let S be a random variable that is either nonnegative or integrable. The conditional expectation of S given \mathcal{G} , denoted by $\mathbb{E}[S|\mathcal{G}]$, is any random variable that satisfies:

- 1) (Measurability) $\mathbb{E}[S|\mathcal{G}]$ is \mathcal{G} -measurable, and
- 2) (Partial Averaging)

$$\int_C \mathbb{E}[S|\mathcal{G}] dP = \int_C S dP \text{ for all } C \in \mathcal{G}$$

- But does it exist?
- Proof by Radon – Nikodym Theorem
- Can also prove other properties.

Alternative View

- Closest approximation to a random variable S if we restrict ourselves to random variables belonging to some smaller σ -algebra . (sub- σ -algebra)

Definition 7. Let $\mathcal{G} \subseteq \mathcal{F}$ be σ -algebras and S be a random variable on (Ω, \mathcal{F}, P) . Assume $E[S^2] < \infty$. Then the conditional expectation is an almost surely unique \mathcal{G} -measurable Y_G such that $E[(S - Y_G)^2] = \inf_Z E[(S - Z)^2]$, where the infimum is over all \mathcal{G} -measurable random variables. Note: We denote the minimizing Y_G by $E[S|\mathcal{G}]$.

- Claim 1 : The Y_G in Definition 7 satisfies, for each $C \in \mathcal{G}$, :

$$\int_C Y_G dP = \int_C S dP$$

- Claim 2 : If $\mathcal{G} = \{ \emptyset, \Omega \}$, then $Y_G = E[S]$
- Claim 3 : If $\mathcal{G} = \{ \Omega, A, A^c, \emptyset \}$, for some event A . then

$$Y_G = \begin{cases} E[SI_A]/P(A) & \text{for } \omega \in A \\ E[SI_{A^c}]/P(A^c) & \text{for } \omega \in A^c \end{cases}$$

- Claim 4 : If \mathcal{G} is generated by a finite partition $\{A_1, A_2, \dots, A_N\}$, then :

$$Y_g = \sum_{i=1}^n c_i I_{A_i}(\omega) \quad \text{where } c_i = E[SI_{A_i}]/P(A_i)$$

A Topological Approach (Hilbert Spaces)

- Two ways of looking at the same general, more abstract concept of Conditional Expectation
- Existence of Conditional Expectation arises as a direct consequences of the special structure of Hilbert Spaces

Theorem 14. *If $1 \leq p < \infty$, then the space \mathcal{L}^p is a complete normed linear space (Banach) under the norm*

$$\|S\|_p = \left\{ \int |S|^p \right\}^{\frac{1}{p}}$$

Proof: Robert G. Bartle. *The Elements of Integration and Lebesgue Measure*. Theorem 6.14. Pg 69. ■

Lemma 16. *L_2 spaces are Hilbert Spaces with the inner product being defined by :*

$$\langle X, Y \rangle = \int_C XY dP \text{ or } \mathbb{E}[XY]$$

Theorem 15. *Hilbert Space Projection Theorem. For every point x in a Hilbert space H and every closed convex set $C \subset H$, there exists a unique point z_0 for which $\|x - z\|$ is minimized over C . This is, in particular, true for any closed subspace M of H . In that case, a necessary and sufficient condition for y is that the vector $x - y$ be orthogonal to M .⁴*

A Topological Approach (Hilbert Spaces)

- Proof of Existence of Conditional Expectation by Hilbert Space Projection Theorem

Thus, the Conditional Expectation is :

- the best approximation of S
 - the function in the sub- σ -algebra G closest to S , where the distance is given by the L_2 norm
 - the orthogonal projection of S onto G .
- can extend to all non- negative random variables
 - can extend all integrable random variables

The special structure of the L_2 Hilbert Space (one-to-one correspondence between closed subspaces and orthogonal projections) and σ -algebras allow us to model public information in such a way that we can estimate any random variable (like future Stock Price) , whose Lebesgue Integral exists.

Some Useful Properties

- **Linearity of Conditional Expectation:** If X and Y are integrable random variables and c_1 and c_2 are constants, then :

$$E[(c_1X + c_2Y) | G] = c_1E[X | G] + c_2E[Y | G]$$

- **Taking out what is known :** If X and Y are integrable random variables, XY is integrable, and X is G -measurable, then :

$$E[XY | G] = XE[Y | G]$$

- **Iterated Conditioning :** If H is a sub- σ -algebra of G , and X is an integrable random variable, then :

$$E[E[X | G] | H] = E[X | H]$$

- **Independence :** If X is integrable and independent of G , then:

$$E[X | G] = E[X]$$

References

1. Robert G. Bartle. The Elements of Integration and Lebesgue Measure (Wiley Classics Library Edition 1995)
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