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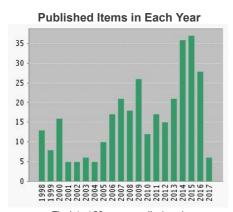
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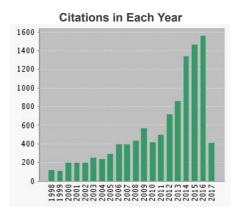
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2.	NEURAL-NET ROBOT CONTROLLER WITH GUARANTEED TRACKING PERFORMANCE  By: LEWIS, FL; LIU, K; YESILDIREK, A IEEE TRANSACTIONS ON NEURAL NETWORKS Volume: 6 Issue: 3 Pages: 703-715 Published: MAY 1995	9	18	14	12	5	329	14.30
3.	Control of a nonholonomic mobile robot using neural networks  By: Fierro, R; Lewis, FL  IEEE TRANSACTIONS ON NEURAL NETWORKS Volume: 9 Issue: 4  Pages: 589-600 Published: JUL 1998	28	27	27	19	3	310	15.50
4.	Optimal Design for Synchronization of Cooperative Systems: State Feedback, Observer and Output Feedback By: Zhang, Hongwei; Lewis, Frank L.; Das, Abhijit IEEE TRANSACTIONS ON AUTOMATIC CONTROL Volume: 56 Issue: 8 Pages: 1948-1952 Published: AUG 2011	47	62	80	64	18	289	41.29
5.	Nearly optimal control laws for nonlinear systems with saturating actuators using a neural network HJB approach  By: Abu-Khalaf, M; Lewis, FL  AUTOMATICA Volume: 41 Issue: 5 Pages: 779-791 Published: MAY 2005	32	48	45	40	10	264	20.31

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6.	Discrete-time nonlinear HJB solution using approximate dynamic programming: Convergence proof  By: Al-Tamimi, Asma; Lewis, Frank L.; Abu-Khalaf, Murad IEEE TRANSACTIONS ON SYSTEMS MAN AND CYBERNETICS PART B- CYBERNETICS Volume: 38 Issue: 4 Pages: 943-949 Published: AUG 2008	36	54	48	38	7	261	26.10	
7.	Reinforcement Learning and Adaptive Dynamic Programming for Feedback Control  By: Lewis, Frank L.; Vrabie, Draguna IEEE CIRCUITS AND SYSTEMS MAGAZINE Volume: 9 Issue: 3 Pages: 32-50 Published: 2009	34	60	44	47	9	243	27.00	
8.	Online actor-critic algorithm to solve the continuous-time infinite horizon optimal control problem  By: Vamvoudakis, Kyriakos G.; Lewis, Frank L.  AUTOMATICA Volume: 46 Issue: 5 Pages: 878-888 Published: MAY 2010	35	58	45	41	13	230	28.75	
9.	FEEDBACK LINEARIZATION USING NEURAL NETWORKS  By: YESILDIREK, A; LEWIS, FL AUTOMATICA Volume: 31 Issue: 11 Pages: 1659-1664 Published: NOV 1995	5	8	10	10	3	220	9.57	
10.	Distributed adaptive control for synchronization of unknown nonlinear networked systems  By: Das, Abhijit; Lewis, Frank L.  AUTOMATICA Volume: 46 Issue: 12 Pages: 2014-2021 Published: DEC 2010	32	52	50	54	11	219	27.38	
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