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Papers

2017

Conference papers

<u>Incremental Cross-Modality Deep Learning for Pedestrian Recognition</u>
Danut Ovidiu Pop, Alexandrina Rogozan, Fawzi Nashashibi, Abdelaziz Bensrhair *IV'17 – IEEE Intelligent Vehicles Symposium*, Jun 2017, Redondo Beach, CA, United States



Fusion of Stereo Vision for Pedestrian Recognition using Convolutional Neural Networks

Danut Ovidiu Pop, Alexandrina Rogozan, Fawzi Nashashibi, Abdelaziz Bensrhair

ESANN 2017 – 25th European Symposium on Artificial Neural Networks, Computational Intelligence and Machine Learning, Apr 2017, Bruges, Belgium



Indoor Intelligent Vehicle localization using WiFi Received Signal Strength Indicator
Nguyen Dinh-Van, Fawzi Nashashibi, Nguyen Thanh-Huong, Eric Castelli
3rd IEEE MTT-S International Conference on Microwaves for Intelligent Mobility 2017, Mar 2017, Nagoya,
Japan



Fast Distributed Agreements and Safety-Critical Scenarios in VANETs

Gérard Le Lann

2017 IEEE International Conference on Computing, Networking and Communications, Jan 2017, Santa Clara, CA, United States. IEEE ComSoc, 2017 IEEE International Conference on Computing, Networking and Communications pp.7, 2017, 2017 IEEE International Conference on Computing, Networking and Communications



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Shape Matching By Part Alignment Using Extended Chordal Axis Transform

Zahraa Yasseen, Anne Verroust-Blondet, Ahmad Nasri

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A Markovian Analysis of IEEE 802.11 Broadcast Transmission Networks with Buffering

Guy Fayolle, Paul Muhlethaler

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A Review of Motion Planning Techniques for Automated Vehicles

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Analysis of Large-Scale Traffic Dynamics in an Urban Transportation Network Using Non-Negative Tensor Factorization

Yufei Han, Fabien Moutarde

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Pioneering driverless electric vehicles in Europe: the City Automated Transport System (CATS)

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Zahraa Yasseen, Anne Verroust-Blondet, Ahmad Nasri

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Latent binary MRF for online reconstruction of large scale systems

Victorin Martin, Jean-Marc Lasgouttes, Cyril Furtlehner

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Fusion of Perception and V2P Communication Systems for Safety of Vulnerable Road Users

Pierre Merdrignac, Oyunchimeg Shagdar, Fawzi Nashashibi

IEEE Transactions on Intelligent Transportation Systems, IEEE, 2016



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Automated Global Planner for Cybernetic Transportation Systems

Myriam Vaca Recalde, Jose Emilio Traver, Vicente Milanés, Joshué Pérez, David Gonzalez Bautista, Fawzi Nashashibi

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Real-time planning for adjacent consecutive intersections

Fernando Garrido, David Gonzalez Bautista, Vicente Milanés, Joshué Pérez, Fawzi Nashashibi 19th International IEEE Conference on Intelligent Transportation Systems – ITSC 2016, Nov 2016, Rio de Janeiro, Brazil. Intelligent Transportation Systems Conference 2016



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Speed Profile Generation based on Quintic Bezier Curves for Enhanced Passenger Comfort

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Using Fractional Calculus for Cooperative Car-Following Control

Carlos Flores, Vicente Milanés, Fawzi Nashashibi

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Comparison of Spatial Aloha and CSMA using Simple Stochastic Geometry Models for 1D and 2D Networks Nadjib Achir, Younes Bouchaala, Paul Muhlethaler, Oyunchimeg Shagdar

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Miguel Romero, Angel De Madrid, C Mañoso, V Milanés

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Automatic parking and platooning for electric vehicles redistribution in a car-sharing application

Mohamed Marouf, Evangeline Pollard, Fawzi Nashashibi

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Automatic vehicle perpendicular parking design using saturated control

Plamen Petrov, Fawzi Nashashibi

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Jean-Marc Lasgouttes

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Emergent Behaviors and Traffic Density among Heuristically-Driven Intelligent Vehicles using V2V

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Priority-based coordination of autonomous and legacy vehicles at intersection

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Low-Speed Cooperative Car-Following Fuzzy Controller for Cybernetic Transport Systems

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