

# Fanzhe Lyu

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## EDUCATION

**Georgia Institute of Technology**, Atlanta, GA  
Major: Electrical Engineering

Expected Graduate: May. 2020  
**GPA: 4.0**

## EXPERIENCE

### ECE tutoring

**August 2017 –**

- Working as an IEEE tutor and Tutoring Intro to Digital Design in ECE department

### IVA Lab

#### Undergraduate Researcher

**August 2017 –**

- Working at undergraduate researcher at Vision-based navigation team
- Researching extended-local vision-based navigation

### ESTUN Robotics, Co, Ltd.

#### Application Software Engineering Intern

**May 2017 – July 2017**

- Designed alert system and archive system in a remote monitoring system for manufacturing robots and deployed devices used for internetworking in the system
- Designed a data manipulation software debugging tool for debugging data in PLC
- Prototyped future IOT device for robot cloud
- Tested robot cloud codes from outsourcing company
- Configured networking used for robot show
- Demonstrated basic usage of ROS and possibilities to migrate functions to ROS

## PROJECTS

### ModJbus (An Open Source Java Modbus-TCP Library) (On-Going)

- Designing a Modbus-TCP Library in Java
- Aiming at better performance than existing library
- Avoiding flaws of design which exists in existing library
- Adding more utilities and tools useful for data manipulation

### ModbusPP (An Open Source C++ Modbus-TCP Library)

- Designed a Modbus-TCP Library in C++
- Inspired by lib-modbus but accommodated C++'s OO Design and stream programming
- Designed useful utilities for data manipulation and type conversion from Socket Stream
- Achieved Better Readability, lighter weight

### V-Plate (A robot waiter)

- Made a Raspberry Pi based robot waiter and supporting voice recognizing Android App
- Developed server-side program on controller to listen data from phone and translate into GPIO digital signal to control the behavior of the robot

### A Voice-Controlled Game

- Designed a Voice-Controlled Game using Python and Cocos2d
- Used the python library to analyze the volume of the microphone input and then change the graphic output of controlled figure

### Adaptable Robotic Gripper

- Entered final round of the Hack-A-Thing Competition (2016)
- Built a robotic gripper that can adapt to most of objects, from hard to soft, and harsh to fragile
- Designed and built whole Electrical Part and Controlling Part of the robotic gripper

### Smart Eco-Friendly Green House

- Built a IOT Solar-energy powered greenhouse in high school
- Designed a computer-based automatic control of Electricity, and circulation of air and water
- Promoted technology application on protecting environment in school

## SKILLS/INTERESTS

- Coding:** Python, MATLAB, Java, C++, C, Pascal, VB. NET, Arduino, mbed, Assembly
- Framework:** Flask, ROS, OpenCV
- Electrical:** Digital System Design, FPGA w/ VHDL, KiCAD
- Language:** English, Mandarin, German
- Hobbies:** Soccer, Guitar, Percussion, Piano, Bass, Rubik's Cube