

# MAT-466: Estimación en GLM

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## Función de log-verosimilitud

Para  $Y_1, \dots, Y_n$  siguiendo un GLM tenemos que

$$\begin{aligned}\ell(\boldsymbol{\psi}) &= \sum_{i=1}^n \log f(y_i; \theta_i, \phi) \\ &= \sum_{i=1}^n \{\phi(y_i \theta_i - b(\theta_i)) + c(y_i; \phi)\} \\ &= \phi \sum_{i=1}^n (y_i \theta_i - b(\theta_i)) + \sum_{i=1}^n c(y_i; \phi),\end{aligned}$$

donde  $\boldsymbol{\psi} = (\boldsymbol{\beta}^\top, \phi)^\top$ .

### Observación:

Debemos destacar que  $\boldsymbol{\beta}$  y  $\phi$  son parametros ortogonales, y por tanto la inferencia puede ser realizada de manera independiente.



## Función score

Para GLM la función score  $U(\beta) = \dot{\ell}(\beta)$  adopta la forma:

$$\begin{aligned}\frac{\partial \ell(\psi)}{\partial \beta} &= \phi \sum_{i=1}^n \left\{ Y_i \frac{d\theta_i}{d\mu_i} \frac{d\mu_i}{d\eta_i} \frac{\partial \eta_i}{\partial \beta} - \frac{db(\theta_i)}{d\theta_i} \frac{d\theta_i}{d\mu_i} \frac{d\mu_i}{d\eta_i} \frac{\partial \eta_i}{\partial \beta} \right\} \\&= \phi \sum_{i=1}^n \left\{ Y_i - \frac{db(\theta_i)}{d\theta_i} \right\} \frac{d\theta_i}{d\mu_i} \frac{d\mu_i}{d\eta_i} \frac{\partial \eta_i}{\partial \beta} \\&= \phi \sum_{i=1}^n (Y_i - b'(\theta_i)) \left\{ \frac{d\mu_i}{d\theta_i} \right\}^{-1} \frac{d\mu_i}{d\eta_i} \frac{\partial \eta_i}{\partial \beta} \\&= \phi \sum_{i=1}^n (Y_i - \mu_i) V(\mu_i)^{-1} \frac{d\mu_i}{d\eta_i} \mathbf{x}_i \\&= \phi \sum_{i=1}^n \omega_i^{1/2} \frac{(Y_i - \mu_i)}{\sqrt{V_i}} \mathbf{x}_i,\end{aligned}$$

donde  $\omega_i = (d\mu_i/d\eta_i)^2/V_i$  y  $V_i = V(\mu_i)$ , para  $i = 1, \dots, n$ .



## Función score

Una manera mucho más compacta de escribir la función score en GLM es:

$$U(\beta) = \phi \mathbf{X}^\top \mathbf{W}^{1/2} \mathbf{V}^{-1/2} (\mathbf{Y} - \boldsymbol{\mu}),$$

donde  $\mathbf{W} = \text{diag}(\omega_1, \dots, \omega_n)$ ,  $\mathbf{V} = \text{diag}(V_1, \dots, V_n)$  y  $\mathbf{Y} = (Y_1, \dots, Y_n)^\top$ .

Vamos a suponer que  $\mathbf{X}$  es matriz de rango completo cuya  $i$ -ésima fila es dada por  $\mathbf{x}_i^\top$ , para  $i = 1, \dots, n$ . Además,  $\boldsymbol{\mu} = (\mu_1, \dots, \mu_n)^\top$  con  $\mu_i = \mu_i(\beta)$ .



## Matriz de información de Fisher

La matriz Hessiana en GLM es dada por:

$$\begin{aligned}\frac{\partial^2 \ell(\boldsymbol{\psi})}{\partial \boldsymbol{\beta} \partial \boldsymbol{\beta}^\top} &= \phi \sum_{i=1}^n (Y_i - \mu_i) \frac{d^2 \theta_i}{d \mu_i^2} \left( \frac{d \mu_i}{d \eta_i} \right)^2 \mathbf{x}_i \mathbf{x}_i^\top \\ &\quad + \phi \sum_{i=1}^n (Y_i - \mu_i) \frac{d \theta_i}{d \mu_i} \left( \frac{d^2 \mu_i}{d \eta_i^2} \right)^2 \mathbf{x}_i \mathbf{x}_i^\top \\ &\quad - \phi \sum_{i=1}^n \frac{d \theta_i}{d \mu_i} \left( \frac{d \mu_i}{d \eta_i} \right)^2 \mathbf{x}_i \mathbf{x}_i^\top\end{aligned}$$

De este modo, la matriz de información de Fisher asume la forma,

$$\mathcal{F}(\boldsymbol{\beta}) = \mathbb{E} \left\{ - \frac{\partial^2 \ell(\boldsymbol{\psi})}{\partial \boldsymbol{\beta} \partial \boldsymbol{\beta}^\top} \right\} = \phi \sum_{i=1}^n \frac{(d \mu_i / d \eta_i)^2}{V_i} \mathbf{x}_i \mathbf{x}_i^\top = \phi \mathbf{X}^\top \mathbf{W} \mathbf{X}.$$



# Algoritmo Fisher-scoring en GLM

El [algoritmo Fisher-scoring](#) para  $\beta$  es dado por:

$$\beta^{(r+1)} = \beta^{(r)} + \mathcal{F}^{-1}(\beta^{(r)})U(\beta^{(r)}),$$

y para el caso de GLM, adopta la forma:

$$\begin{aligned}\beta^{(r+1)} &= \beta^{(r)} + (\mathbf{X}^\top \mathbf{W}^{(r)} \mathbf{X})^{-1} \mathbf{X}^\top \mathbf{W}^{(r)1/2} \mathbf{V}^{(r)-1/2} (\mathbf{Y} - \boldsymbol{\mu}^{(r)}) \\ &= (\mathbf{X}^\top \mathbf{W}^{(r)} \mathbf{X})^{-1} \mathbf{X}^\top \mathbf{W}^{(r)} \mathbf{X} \beta^{(r)} \\ &\quad + (\mathbf{X}^\top \mathbf{W}^{(r)} \mathbf{X})^{-1} \mathbf{X}^\top \mathbf{W}^{(r)1/2} \mathbf{V}^{(r)-1/2} (\mathbf{Y} - \boldsymbol{\mu}^{(r)}) \\ &= (\mathbf{X}^\top \mathbf{W}^{(r)} \mathbf{X})^{-1} \mathbf{X}^\top \mathbf{W}^{(r)} \mathbf{Z}^{(r)},\end{aligned}$$

donde

$$\mathbf{Z} = \boldsymbol{\eta} + \mathbf{W}^{-1/2} \mathbf{V}^{-1/2} (\mathbf{Y} - \boldsymbol{\mu}),$$

denota la [respuesta de trabajo](#).



Tenemos que la función score asociada a  $\phi$ , adopta la forma:

$$U(\phi) = \frac{\partial \ell(\psi)}{\partial \phi} = \sum_{i=1}^n (y_i \theta_i - b(\theta_i)) + \sum_{i=1}^n c'(y_i; \phi),$$

mientras que la información de Fisher, es dada por

$$\mathcal{F}(\phi) = - \sum_{i=1}^n \mathbb{E}\{c''(Y_i; \phi)\}.$$

De este modo, podemos considerar el procedimiento de estimación:

$$\phi^{(r+1)} = \phi^{(r)} + \frac{U(\phi^{(r)})}{\mathcal{F}(\phi^{(r)})}, \quad r = 0, 1, \dots$$

Alternativamente, podemos resolver la ecuación  $U(\phi) = 0$ , obteniendo

$$\sum_{i=1}^n c'(y_i; \hat{\phi}) = \frac{1}{2} D(\mathbf{y}; \hat{\boldsymbol{\mu}}) - \sum_{i=1}^n (y_i \hat{\theta}_i - b(\hat{\theta}_i)).$$



## Casos particulares: Modelo normal

Es fácil notar que

$$c'(y_i; \phi) = \frac{1}{2\phi} - \frac{y_i^2}{2}, \quad c''(y_i; \phi) = -\frac{1}{2\phi^2}.$$

Así,  $\mathcal{F}(\phi) = n/(2\phi^2)$ . Evidentemente,

$$\begin{aligned} U(\phi) &= \sum_{i=1}^n \left( y_i \mu_i - \frac{\mu_i^2}{2} \right) + \sum_{i=1}^n \left( \frac{1}{2\phi} - \frac{y_i^2}{2} \right) \\ &= -\frac{1}{2} \sum_{i=1}^n (y_i^2 - 2y_i \mu_i + \mu_i^2) + \frac{n}{2\phi}, \end{aligned}$$

desde  $U(\phi) = 0$ , sigue que

$$\hat{\phi}^{-1} = \frac{1}{n} \sum_{i=1}^n (y_i - \hat{\mu}_i)^2.$$





## Casos particulares: Modelo normal inversa

Tenemos,

$$c'(y_i; \phi) = \frac{1}{2\phi} - \frac{y_i^2}{2}, \quad c''(y_i; \phi) = -\frac{1}{2\phi^2}.$$

y portanto,  $\mathcal{F}(\phi) = n/(2\phi^2)$ . De este modo,

$$U(\phi) = \sum_{i=1}^n \left( \frac{1}{\mu_i} - \frac{y_i}{2\mu_i^2} \right) + \sum_{i=1}^n \left( \frac{1}{2\phi} - \frac{y_i^2}{2} \right).$$

Evidentemente, desde  $U(\phi) = 0$  obtenemos

$$\hat{\phi}^{-1} = \frac{1}{n} \sum_{i=1}^n (y_i - \hat{\mu}_i)^2.$$



## Casos particulares: Modelo Gama

Es este caso

$$c'(y_i; \phi) = \log y_i + \log \phi + 1 - \psi(\phi), \quad c''(y_i; \phi) = \frac{1}{\phi} - \psi'(\phi),$$

donde  $\psi(z) = \Gamma'(z)/\Gamma(z)$  denota la función digama. De ahí que

$$2\{\log \hat{\phi} - \psi(\hat{\phi})\} = \frac{1}{n} D(\mathbf{y}; \hat{\boldsymbol{\mu}}).$$

Usando la aproximación

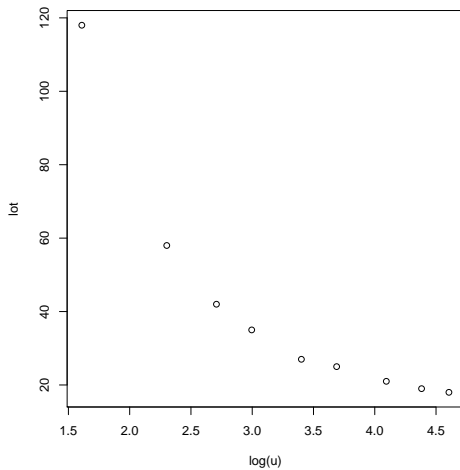
$$\psi(\phi) \approx \log \phi - \frac{1}{2\phi} - \frac{1}{12\phi^2},$$

lleva a

$$\hat{\phi} \approx \frac{1 + \sqrt{1 + 2\bar{D}/3}}{2\bar{D}}, \quad \bar{D} = \frac{1}{n} D(\mathbf{y}; \hat{\boldsymbol{\mu}}).$$



# Datos de coagulación



Conjunto de datos: Coagulación inducida por dos lotes de tromboplastina.

```
clotting <- data.frame(  
+   u = c(5,10,15,20,30,40,60,80,100),  
+   lot = c(118,58,42,35,27,25,21,19,18))
```

Exploramos el conjunto de datos por medio del gráfico:

```
> plot(lot ~ log(u), data = clotting)
```



## Datos de coagulación de la sangre

```
> fit <- glm(lot ~ log(u), data = clotting, family = Gamma)
> summary(fit)

Call:
glm(formula = lot ~ log(u), family = Gamma, data = clotting)

Deviance Residuals:
    Min       1Q   Median       3Q      Max
-0.04008  -0.03756  -0.02637   0.02905   0.08641

Coefficients:
            Estimate Std. Error t value Pr(>|t|)
(Intercept) -0.0165544   0.0009275  -17.85 4.28e-07 ***
log(u)       0.0153431   0.0004150   36.98 2.75e-09 ***
---
Signif. codes:  0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1

(Dispersion parameter for Gamma family taken to be 0.002446059)

Null deviance: 3.51283  on 8  degrees of freedom
Residual deviance: 0.01673  on 7  degrees of freedom
AIC: 37.99

Number of Fisher Scoring iterations: 3
```

