

# Package ‘fastmatrix’

November 11, 2021

**Type** Package

**Title** Fast Computation of some Matrices Useful in Statistics

**Version** 0.4

**Date** 2021-11-11

**Author** Felipe Osorio [aut, cre] (<<https://orcid.org/0000-0002-4675-5201>>),  
Alonso Ogueda [aut]

**Maintainer** Felipe Osorio <felipe.osorios@usm.cl>

**Description** Small set of functions to fast computation of some matrices and operations useful in statistics and econometrics. Currently, there are functions for efficient computation of duplication, commutation and symmetrizer matrices with minimal storage requirements. Some commonly used matrix decompositions (LU and LDL), basic matrix operations (for instance, Hadamard, Kronecker products and the Sherman-Morrison formula) and iterative solvers for linear systems are also available. In addition, the package includes a number of common statistical procedures such as the sweep operator, weighted mean and covariance matrix using an online algorithm, linear regression (using Cholesky, QR, SVD, sweep operator and conjugate gradients methods), ridge regression (with optimal selection of the ridge parameter considering the GCV procedure), functions to compute the multivariate skewness, kurtosis, Mahalanobis distance (checking the positive definiteness) and the Wilson-Hilferty transformation of chi squared variables. Furthermore, the package provides interfaces to C code callable by another C code from other R packages.

**Depends** R(>= 3.5.0)

**License** GPL-3

**URL** <https://faosorios.github.io/fastmatrix/>

**NeedsCompilation** yes

**LazyLoad** yes

## R topics documented:

array.mult . . . . .	3
asSymmetric . . . . .	4
bracket.prod . . . . .	5
cg . . . . .	6

comm.info . . . . .	7
comm.prod . . . . .	8
commutation . . . . .	9
cov.MSSD . . . . .	10
cov.weighted . . . . .	11
dupl.cross . . . . .	12
dupl.info . . . . .	13
dupl.prod . . . . .	14
duplication . . . . .	15
equilibrate . . . . .	16
geomean . . . . .	17
hadamard . . . . .	18
helmert . . . . .	19
is.lower.tri . . . . .	20
jacobi . . . . .	21
kronecker.prod . . . . .	22
kurtosis . . . . .	23
ldl . . . . .	24
lu . . . . .	25
lu-methods . . . . .	26
lu2inv . . . . .	27
Mahalanobis . . . . .	28
matrix.inner . . . . .	29
matrix.norm . . . . .	30
mediancenter . . . . .	31
minkowski . . . . .	32
moments . . . . .	33
ols . . . . .	34
ols.fit . . . . .	35
ols.fit-methods . . . . .	36
power.method . . . . .	37
ridge . . . . .	38
seidel . . . . .	40
sherman.morrison . . . . .	41
sweep.operator . . . . .	42
symm.info . . . . .	43
symm.prod . . . . .	44
symmetrizer . . . . .	45
vec . . . . .	46
vech . . . . .	47
whitening . . . . .	47
wilson.hilferty . . . . .	48

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array.mult	<i>Array multiplication</i>
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---

## Description

Multiplication of 3-dimensional arrays was first introduced by Bates and Watts (1980). More extensions and technical details can be found in Wei (1998).

## Usage

```
array.mult(a, b, x)
```

## Arguments

a	a numeric matrix.
b	a numeric matrix.
x	a three-dimensional array.

## Details

Let  $\mathbf{X} = (x_{tij})$  be a 3-dimensional  $n \times p \times q$  where indices  $t, i$  and  $j$  indicate face, row and column, respectively. The product  $\mathbf{Y} = \mathbf{A}\mathbf{X}\mathbf{B}$  is an  $n \times r \times s$  array, with  $\mathbf{A}$  and  $\mathbf{B}$  are  $r \times p$  and  $q \times s$  matrices respectively. The elements of  $\mathbf{Y}$  are defined as:

$$y_{tkl} = \sum_{i=1}^p \sum_{j=1}^q a_{ki} x_{tij} b_{jl}$$

## Value

array.mult returns a 3-dimensional array of dimension  $n \times r \times s$ .

## References

- Bates, D.M., Watts, D.G. (1980). Relative curvature measures of nonlinearity. *Journal of the Royal Statistical Society, Series B* **42**, 1-25.
- Wei, B.C. (1998). *Exponential Family Nonlinear Models*. Springer, New York.

## See Also

[array](#), [matrix](#), [bracket.prod](#).

**Examples**

```

x <- array(0, dim = c(2,3,3)) # 2 x 3 x 3 array
x[,,1] <- c(1,2,2,4,3,6)
x[,,2] <- c(2,4,4,8,6,12)
x[,,3] <- c(3,6,6,12,9,18)

a <- matrix(1, nrow = 2, ncol = 3)
b <- matrix(1, nrow = 3, ncol = 2)

y <- array.mult(a, b, x) # a 2 x 2 x 2 array
y

```

---

asSymmetric	<i>Force a matrix to be symmetric</i>
-------------	---------------------------------------

---

**Description**

Force a square matrix x to be symmetric

**Usage**

```
asSymmetric(x, lower = TRUE)
```

**Arguments**

x	a square matrix to be forced to be symmetric.
lower	logical, should the upper (lower) triangle be replaced with the lower (upper) triangle?

**Value**

a square symmetric matrix.

**Examples**

```

a <- matrix(1:16, ncol = 4)
isSymmetric(a) # FALSE
a <- asSymmetric(a) # copy lower triangle into upper triangle

```

---

bracket.prod	<i>Bracket product</i>
--------------	------------------------

---

### Description

Bracket product of a matrix and a 3-dimensional array.

### Usage

```
bracket.prod(a, x)
```

### Arguments

a	a numeric matrix.
x	a three-dimensional array.

### Details

Let  $\mathbf{X} = (x_{tij})$  be a 3-dimensional  $n \times p \times q$  array and  $\mathbf{A}$  an  $m \times n$  matrix, then  $\mathbf{Y} = [\mathbf{A}][\mathbf{X}]$  is called the bracket product of  $\mathbf{A}$  and  $\mathbf{X}$ , that is an  $m \times p \times q$  with elements

$$y_{tij} = \sum_{k=1}^n a_{tk} x_{kij}$$

### Value

bracket.prod returns a 3-dimensional array of dimension  $m \times p \times q$ .

### References

Wei, B.C. (1998). *Exponential Family Nonlinear Models*. Springer, New York.

### See Also

[array](#), [matrix](#), [array.mult](#).

### Examples

```
x <- array(0, dim = c(2,3,3)) # 2 x 3 x 3 array
x[, , 1] <- c(1,2,2,4,3,6)
x[, , 2] <- c(2,4,4,8,6,12)
x[, , 3] <- c(3,6,6,12,9,18)

a <- matrix(1, nrow = 3, ncol = 2)

y <- bracket.prod(a, x) # a 3 x 3 x 3 array
y
```

cg

*Solve linear systems using the conjugate gradients method***Description**

Conjugate gradients (CG) method is an iterative algorithm for solving linear systems with positive definite coefficient matrices.

**Usage**

```
cg(a, b, maxiter = 200, tol = 1e-7)
```

**Arguments**

a	a symmetric positive definite matrix containing the coefficients of the linear system.
b	a vector of right-hand sides of the linear system.
maxiter	the maximum number of iterations. Defaults to 200
tol	tolerance level for stopping iterations.

**Value**

a vector with the approximate solution, the iterations performed are returned as the attribute 'iterations'.

**Warning**

The underlying C code does not check for symmetry nor positive definiteness.

**References**

Golub, G.H., Van Loan, C.F. (1996). *Matrix Computations*, 3rd Edition. John Hopkins University Press.

Hestenes, M.R., Stiefel, E. (1952). Methods of conjugate gradients for solving linear equations. *Journal of Research of the National Bureau of Standards* **49**, 409-436.

**See Also**

[jacobi](#), [seidel](#), [solve](#)

**Examples**

```
a <- matrix(c(4,3,0,3,4,-1,0,-1,4), ncol = 3)
b <- c(24,30,-24)
z <- cg(a, b)
z # 3 iterations
```

comm.info

*Compact information to construct the commutation matrix***Description**

This function provides the minimum information required to create the commutation matrix.

The commutation matrix is a square matrix of order  $mn$  that, for an  $m \times n$  matrix  $\mathbf{A}$ , transform  $\text{vec}(\mathbf{A})$  to  $\text{vec}(\mathbf{A}^T)$ .

**Usage**

```
comm.info(m = 1, n = m, condensed = TRUE)
```

**Arguments**

m	a positive integer row dimension.
n	a positive integer column dimension.
condensed	logical. Information should be returned in compact form?

**Details**

This function returns a list containing two vectors that represent an element of the commutation matrix and is accessed by the indexes in vectors `row` and `col`. This information is used by function [comm.prod](#) to do some operations involving the commutation matrix without forming it. This information also can be obtained using function [commutation](#).

**Value**

A list containing the following elements:

row	vector of indexes, each entry represents the row index of the commutation matrix.
col	vector of indexes, each entry represents the column index of the commutation matrix. Only present if <code>condensed = FALSE</code> .
m	positive integer, row dimension.
n	positive integer, column dimension.

**References**

Magnus, J.R., Neudecker, H. (1979). The commutation matrix: some properties and applications. *The Annals of Statistics* **7**, 381-394.

**See Also**

[commutation](#), [comm.prod](#)

## Examples

```
z <- comm.info(m = 3, n = 2, condensed = FALSE)
z # where are the ones in commutation matrix of order '3,2'?

K32 <- commutation(m = 3, n = 2, matrix = TRUE)
K32 # only recommended if m and n are very small
```

---

comm.prod

---

*Matrix multiplication involving the commutation matrix*


---

## Description

Given the row and column dimension of a commutation and matrix  $x$ , performs one of the matrix-matrix operations:

- $Y = KX$ , if side = "left" and transposed = FALSE, or
- $Y = K^T X$ , if side = "left" and transposed = TRUE, or
- $Y = XK$ , if side = "right" and transposed = FALSE, or
- $Y = XK^T$ , if side = "right" and transposed = TRUE,

where  $K$  is the commutation matrix of order  $mn$ . The main aim of comm.prod is to do this matrix multiplication **without forming** the commutation matrix.

## Usage

```
comm.prod(m = 1, n = m, x = NULL, transposed = FALSE, side = "left")
```

## Arguments

m	a positive integer row dimension.
n	a positive integer column dimension.
x	numeric matrix (or vector).
transposed	logical. Commutation matrix should be transposed?
side	a string selecting if commutation matrix is pre-multiplying $x$ , that is side = "left" or post-multiplying $x$ , by using side = "right".

## Details

Underlying Fortran code only uses information provided by [comm.info](#) to performs the matrix multiplication. The commutation matrix is **never** created.

## See Also

[commutation](#)



## Examples

```
K42 <- commutation(m = 4, n = 2, matrix = TRUE)
x <- matrix(1:24, ncol = 3)
y <- K42 %*% x

z <- comm.prod(m = 4, n = 2, x) # K42 is not stored
all(z == y) # matrices y and z are equal!
```

---

commutation	<i>Commutation matrix</i>
-------------	---------------------------

---

## Description

This function returns the commutation matrix of order  $mn$  which transforms, for an  $m \times n$  matrix  $\mathbf{A}$ ,  $\text{vec}(\mathbf{A})$  to  $\text{vec}(\mathbf{A}^T)$ .

## Usage

```
commutation(m = 1, n = m, matrix = FALSE, condensed = FALSE)
```

## Arguments

<code>m</code>	a positive integer row dimension.
<code>n</code>	a positive integer column dimension.
<code>matrix</code>	a logical indicating whether the commutation matrix will be returned.
<code>condensed</code>	logical. Information should be returned in compact form?

## Details

This function is a wrapper function for the function `comm.info`. This function provides the minimum information required to create the commutation matrix. If option `matrix = FALSE` the commutation matrix is stored in two vectors containing the coordinate list of indexes for rows and columns. Option `condensed = TRUE` only returns vector of indexes for the rows of commutation matrix.

**Warning:** `matrix = TRUE` is **not** recommended, unless the order `m` **and** `n` be small. This matrix can require a huge amount of storage.

## Value

Returns an  $mn$  by  $mn$  matrix (if requested).

## References

Magnus, J.R., Neudecker, H. (1979). The commutation matrix: some properties and applications. *The Annals of Statistics* **7**, 381-394.

Magnus, J.R., Neudecker, H. (2007). *Matrix Differential Calculus with Applications in Statistics and Econometrics*, 3rd Edition. Wiley, New York.

**See Also**[comm.info](#)**Examples**

```

z <- commutation(m = 100, condensed = TRUE)
object.size(z) # 40.6 Kb of storage

z <- commutation(m = 100, condensed = FALSE)
object.size(z) # 80.7 Kb of storage

K100 <- commutation(m = 100, matrix = TRUE) # time: < 2 secs
object.size(K100) # 400 Mb of storage, do not request this matrix!

# a small example
K32 <- commutation(m = 3, n = 2, matrix = TRUE)
a <- matrix(1:6, ncol = 2)
v <- K32 %*% vec(a)
all(vec(t(a)) == as.vector(v)) # vectors are equal!

```

cov.MSSD

---

*Mean Square Successive Difference (MSSD) estimator of the covariance matrix*

---

**Description**

Returns a list containing the mean and covariance matrix of the data.

**Usage**

```
cov.MSSD(x)
```

**Arguments**

**x** a matrix or data frame. As usual, rows are observations and columns are variables.

**Details**

This procedure uses the Holmes-Mergen method using the difference between each successive pairs of observations also known as Mean Square Successive Method (MSSD) to estimate the covariance matrix.

**Value**

A list containing the following named components:

mean	an estimate for the center (mean) of the data.
cov	the estimated covariance matrix.

## References

Holmes, D.S., Mergen, A.E. (1993). Improving the performance of the  $T^2$  control chart. *Quality Engineering* **5**, 619-625.

## See Also

[cov](#) and [var](#).

## Examples

```
x <- cbind(1:10, c(1:3, 8:5, 8:10))
z0 <- cov(x)
z0
z1 <- cov.MSSD(x)
z1
```

---

cov.weighted	<i>Weighted covariance matrices</i>
--------------	-------------------------------------

---

## Description

Returns a list containing estimates of the weighted mean and covariance matrix of the data.

## Usage

```
cov.weighted(x, weights = rep(1, nrow(x)))
```

## Arguments

x	a matrix or data frame. As usual, rows are observations and columns are variables.
weights	a non-negative and non-zero vector of weights for each observation. Its length must equal the number of rows of x.

## Details

The covariance matrix is divided by the number of observations, which arise for instance, when we use the class of elliptical contoured distributions. This differs from the behaviour of function [cov.wt](#).

## Value

A list containing the following named components:

mean	an estimate for the center (mean) of the data.
cov	the estimated (weighted) covariance matrix.

## References

Clarke, M.R.B. (1971). Algorithm AS 41: Updating the sample mean and dispersion matrix. *Applied Statistics* **20**, 206-209.

## See Also

[cov.wt](#), [cov](#) and [var](#).

## Examples

```
x <- cbind(1:10, c(1:3, 8:5, 8:10))
z0 <- cov.weighted(x) # all weights are 1
D2 <- Mahalanobis(x, center = z0$mean, cov = z0$cov)
p <- ncol(x)
wts <- (p + 1) / (1 + D2) # nice weights!
z1 <- cov.weighted(x, weights = wts)
z1
```

---

dupl.cross

---

Matrix crossproduct involving the duplication matrix

---

## Description

Given the order of two duplication matrices and matrix  $x$ , this function performs the operation:  $Y = D_n^T X D_k$ , where  $D_n$  and  $D_k$  are duplication matrices of order  $n$  and  $k$ , respectively.

## Usage

```
dupl.cross(n = 1, k = n, x = NULL)
```

## Arguments

<code>n</code>	order of the duplication matrix used pre-multiplying $x$ .
<code>k</code>	order of the duplication matrix used post-multiplying $x$ . By default $k = n$ is used.
<code>x</code>	numeric matrix, this argument is required.

## Details

This function calls [dupl.prod](#) to performs the matrix multiplications required but **without forming** any duplication matrices.

## See Also

[dupl.prod](#)

## Examples

```
D2 <- duplication(n = 2, matrix = TRUE)
D3 <- duplication(n = 3, matrix = TRUE)
x <- matrix(1, nrow = 9, ncol = 4)
y <- t(D3) %*% x %*% D2

z <- dupl.cross(n = 3, k = 2, x) # D2 and D3 are not stored
all(z == y) # matrices y and z are equal!

x <- matrix(1, nrow = 9, ncol = 9)
z <- dupl.cross(n = 3, x = x) # same matrix is used to pre- and post-multiplying x
z # print result
```

---

dupl.info

*Compact information to construct the duplication matrix*


---

## Description

This function provides the minimum information required to create the duplication matrix.

## Usage

```
dupl.info(n = 1, condensed = TRUE)
```

## Arguments

n	order of the duplication matrix.
condensed	logical. Information should be returned in compact form?

## Details

This function returns a list containing two vectors that represent an element of the duplication matrix and is accessed by the indexes in vectors row and col. This information is used by function [dupl.prod](#) to do some operations involving the duplication matrix without forming it. This information also can be obtained using function [duplication](#)

## Value

A list containing the following elements:

row	vector of indexes, each entry represents the row index of the duplication matrix. Only present if condensed = FALSE.
col	vector of indexes, each entry represents the column index of the duplication matrix.
order	order of the duplication matrix.

**See Also**

[duplication](#), [dupl.prod](#)

**Examples**

```
z <- dupl.info(n = 3, condensed = FALSE)
z # where are the ones in duplication of order 3?

D3 <- duplication(n = 3, matrix = TRUE)
D3 # only recommended if n is very small
```

---

dupl.prod

---

*Matrix multiplication involving the duplication matrix*


---

**Description**

Given the order of a duplication and matrix  $x$ , performs one of the matrix-matrix operations:

- $Y = DX$ , if side = "left" and transposed = FALSE, or
- $Y = D^T X$ , if side = "left" and transposed = TRUE, or
- $Y = XD$ , if side = "right" and transposed = FALSE, or
- $Y = XD^T$ , if side = "right" and transposed = TRUE,

where  $D$  is the duplication matrix of order  $n$ . The main aim of `dupl.prod` is to do this matrix multiplication **without forming** the duplication matrix.

**Usage**

```
dupl.prod(n = 1, x, transposed = FALSE, side = "left")
```

**Arguments**

<code>n</code>	order of the duplication matrix.
<code>x</code>	numeric matrix (or vector).
<code>transposed</code>	logical. Duplication matrix should be transposed?
<code>side</code>	a string selecting if duplication matrix is pre-multiplying $x$ , that is side = "left" or post-multiplying $x$ , by using side = "right".

**Details**

Underlying C code only uses information provided by [dupl.info](#) to performs the matrix multiplication. The duplication matrix is **never** created.

**See Also**

[duplication](#)

### Examples

```
D4 <- duplication(n = 4, matrix = TRUE)
x <- matrix(1, nrow = 16, ncol = 2)
y <- crossprod(D4, x)

z <- dupl.prod(n = 4, x, transposed = TRUE) # D4 is not stored
all(z == y) # matrices y and z are equal!
```

---

duplication

*Duplication matrix*


---

### Description

This function returns the duplication matrix of order  $n$  which transforms, for a symmetric matrix  $\mathbf{A}$ ,  $\text{vech}(\mathbf{A})$  into  $\text{vec}(\mathbf{A})$ .

### Usage

```
duplication(n = 1, matrix = FALSE, condensed = FALSE)
```

### Arguments

<code>n</code>	order of the duplication matrix.
<code>matrix</code>	a logical indicating whether the duplication matrix will be returned.
<code>condensed</code>	logical. Information should be returned in compact form?.

### Details

This function is a wrapper function for the function `dupl.info`. This function provides the minimum information required to create the duplication matrix. If option `matrix = FALSE` the duplication matrix is stored in two vectors containing the coordinate list of indexes for rows and columns. Option `condensed = TRUE` only returns vector of indexes for the columns of duplication matrix.

**Warning:** `matrix = TRUE` is **not** recommended, unless the order  $n$  be small. This matrix can require a huge amount of storage.

### Value

Returns an  $n^2$  by  $n(n+1)/2$  matrix (if requested).

### References

Magnus, J.R., Neudecker, H. (1980). The elimination matrix, some lemmas and applications. *SIAM Journal on Algebraic Discrete Methods* **1**, 422-449.

Magnus, J.R., Neudecker, H. (2007). *Matrix Differential Calculus with Applications in Statistics and Econometrics*, 3rd Edition. Wiley, New York.

**See Also**

[dupl.info](#)

**Examples**

```
z <- duplication(n = 100, condensed = TRUE)
object.size(z) # 40.5 Kb of storage

z <- duplication(n = 100, condensed = FALSE)
object.size(z) # 80.6 Kb of storage

D100 <- duplication(n = 100, matrix = TRUE)
object.size(D100) # 202 Mb of storage, do not request this matrix!

# a small example
D3 <- duplication(n = 3, matrix = TRUE)
a <- matrix(c( 1, 2, 3,
              2, 3, 4,
              3, 4, 5), nrow = 3)
upper <- vech(a)
v <- D3 %%% upper
all(vec(a) == as.vector(v)) # vectors are equal!
```

---

equilibrate

*Equilibration of a rectangular or symmetric matrix*

---

**Description**

Equilibrate a rectangular or symmetric matrix using 2-norm.

**Usage**

```
equilibrate(x, scale = TRUE)
```

**Arguments**

x	a numeric matrix.
scale	a logical value, x must be scaled to norm unity?

**Value**

For scale = TRUE, the equilibrated matrix. The scalings and an approximation of the condition number, are returned as attributes "scales" and "condition". If x is a rectangular matrix, only the columns are equilibrated.



**Examples**

```

x <- matrix(c(1, 1, 1,
              1, 2, 1,
              1, 3, 1,
              1, 1,-1,
              1, 2,-1,
              1, 3,-1), ncol = 3, byrow = TRUE)
z <- equilibrate(x)
apply(z, 2, function(x) sum(x^2)) # all 1

xx <- crossprod(x)
equilibrate(xx)

```

geomean

*Geometric mean***Description**

It calculates the geometric mean using a Fused-Multiply-and-Add (FMA) compensated scheme for accurate computation of floating-point product.

**Usage**

```
geomean(x)
```

**Arguments**

**x** a numeric vector containing the sample observations.

**Details**

If **x** contains any non-positive values, **geomean** returns NA and a warning message is displayed.

The geometric mean is a measure of central tendency, which is defined as

$$G = \sqrt[n]{x_1 x_2 \dots x_n} = \left( \prod_{i=1}^n x_i \right)^{1/n}.$$

This procedure calculates the product required in the geometric mean safely using a compensated scheme as proposed by Graillat (2009).

**Value**

The geometric mean of the sample, a non-negative number.

## References

- Graillat, S. (2009). Accurate floating-point product and exponentiation. *IEEE Transactions on Computers* **58**, 994-1000.
- Oguita, T., Rump, S.M., Oishi, S. (2005). Accurate sum and dot product. *SIAM Journal on Scientific Computing* **26**, 1955-1988.

## See Also

[mean](#), [median](#).

## Examples

```
set.seed(149)
x <- rlnorm(1000)
mean(x)      # 1.68169
median(x)    # 0.99663
geomean(x)   # 1.01688
```

---

hadamard

*Hadamard product of two matrices*

---

## Description

This function returns the Hadamard or element-wise product of two matrices  $x$  and  $y$ , that have the same dimensions.

## Usage

```
hadamard(x, y = x)
```

## Arguments

$x$	a numeric matrix or vector.
$y$	a numeric matrix or vector.

## Value

A matrix with the same dimension of  $x$  (and  $y$ ) which corresponds to the element-by-element product of the two matrices.

## References

- Styan, G.P.H. (1973). Hadamard products and multivariate statistical analysis, *Linear Algebra and Its Applications* **6**, 217-240.

**Examples**

```
x <- matrix(rep(1:10, times = 5), ncol = 5)
y <- matrix(rep(1:5, each = 10), ncol = 5)
z <- hadamard(x, y)
z
```

helmert

*Helmert matrix***Description**

This function returns the Helmert matrix of order  $n$ .

**Usage**

```
helmert(n = 1)
```

**Arguments**

$n$  order of the Helmert matrix.

**Details**

A Helmert matrix of order  $n$  is a square matrix defined as

$$\mathbf{H}_n = \begin{bmatrix} 1/\sqrt{n} & 1/\sqrt{n} & 1/\sqrt{n} & \dots & 1/\sqrt{n} \\ 1/\sqrt{2} & -1/\sqrt{2} & 0 & \dots & 0 \\ 1/\sqrt{6} & 1/\sqrt{6} & -2/\sqrt{6} & \dots & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ \frac{1}{\sqrt{n(n-1)}} & \frac{1}{\sqrt{n(n-1)}} & \frac{1}{\sqrt{n(n-1)}} & \dots & -\frac{(n-1)}{\sqrt{n(n-1)}} \end{bmatrix}.$$

Helmert matrix is orthogonal and is frequently used in the analysis of variance (ANOVA).

**Value**

Returns an  $n$  by  $n$  matrix.

**References**

- Lancaster, H.O. (1965). The Helmert matrices. *The American Mathematical Monthly* **72**, 4-12.
- Gentle, J.E. (2007). *Matrix Algebra: Theory, Computations, and Applications in Statistics*. Springer, New York.

**Examples**

```

n <- 1000
set.seed(149)
x <- rnorm(n)

H <- helmert(n)
object.size(H) # 7.63 Mb of storage
K <- H[2:n,]
z <- c(K %*% x)
sum(z^2) # 933.1736

# same that
(n - 1) * var(x)

```

---

is.lower.tri	<i>Check if a matrix is lower or upper triangular</i>
--------------	---

---

**Description**

Returns TRUE if the given matrix is lower or upper triangular matrix.

**Usage**

```

is.lower.tri(x, diag = FALSE)
is.upper.tri(x, diag = FALSE)

```

**Arguments**

**x** a matrix of other R object with `length(dim(x)) == 2`.

**diag** logical. Should the diagonal be included?

**Value**

Check if a matrix is lower or upper triangular. You can also include diagonal to the check.

**See Also**

[lower.tri](#), [upper.tri](#)

**Examples**

```

x <- matrix(rnorm(10 * 3), ncol = 3)
R <- chol(crossprod(x))

is.lower.tri(R)
is.upper.tri(R)

```

---

 jacobi

 Solve linear systems using the Jacobi method
 

---

### Description

Jacobi method is an iterative algorithm for solving a system of linear equations.

### Usage

```
jacobi(a, b, start, maxiter = 200, tol = 1e-7)
```

### Arguments

<code>a</code>	a square numeric matrix containing the coefficients of the linear system.
<code>b</code>	a vector of right-hand sides of the linear system.
<code>start</code>	a vector for initial starting point.
<code>maxiter</code>	the maximum number of iterations. Defaults to 200
<code>tol</code>	tolerance level for stopping iterations.

### Details

Let  $D$ ,  $L$ , and  $U$  denote the diagonal, lower triangular and upper triangular parts of a matrix  $A$ . Jacobi's method solve the equation  $Ax = b$ , iteratively by rewriting  $Dx + (L + U)x = b$ . Assuming that  $D$  is nonsingular leads to the iteration formula

$$x^{(k+1)} = -D^{-1}(L + U)x^{(k)} + D^{-1}b$$

### Value

a vector with the approximate solution, the iterations performed are returned as the attribute 'iterations'.

### References

Golub, G.H., Van Loan, C.F. (1996). *Matrix Computations*, 3rd Edition. John Hopkins University Press.

### See Also

[seidel](#)

### Examples

```
a <- matrix(c(5,-3,2,-2,9,-1,3,1,-7), ncol = 3)
b <- c(-1,2,3)
start <- c(1,1,1)
z <- jacobi(a, b, start)
z # 15 iterations
```

---

kronecker.prod	<i>Kronecker product on matrices</i>
----------------	--------------------------------------

---

### Description

Computes the kronecker product of two matrices,  $x$  and  $y$ .

### Usage

```
kronecker.prod(x, y = x)
```

### Arguments

$x$	a numeric matrix or vector.
$y$	a numeric matrix or vector.

### Details

Let  $\mathbf{X}$  be an  $m \times n$  and  $\mathbf{Y}$  a  $p \times q$  matrix. The  $mp \times nq$  matrix defined by

$$\begin{bmatrix} x_{11}\mathbf{Y} & \dots & x_{1n}\mathbf{Y} \\ \vdots & & \vdots \\ x_{m1}\mathbf{Y} & \dots & x_{mn}\mathbf{Y} \end{bmatrix},$$

is called the *Kronecker product* of  $\mathbf{X}$  and  $\mathbf{Y}$ .

### Value

An array with dimensions  $\dim(x) * \dim(y)$ .

### References

Magnus, J.R., Neudecker, H. (2007). *Matrix Differential Calculus with Applications in Statistics and Econometrics*, 3rd Edition. Wiley, New York.

### See Also

[kronecker](#) function from base package is based on [outer](#). Our C version is slightly faster.

### Examples

```
# block diagonal matrix:
a <- diag(1:3)
b <- matrix(1:4, ncol = 2)
kronecker.prod(a, b)

# examples with vectors
ones <- rep(1, 4)
```

```

y <- 1:3
kronecker.prod(ones, y) # 12-dimensional vector
kronecker.prod(ones, t(y)) # 3 x 3 matrix

```

---

kurtosis

*Mardia's multivariate skewness and kurtosis coefficients*


---

## Description

Functions to compute measures of multivariate skewness ( $b_{1p}$ ) and kurtosis ( $b_{2p}$ ) proposed by Mardia (1970),

$$b_{1p} = \frac{1}{n^2} \sum_{i=1}^n \sum_{j=1}^n ((\mathbf{x}_i - \bar{\mathbf{x}})^T \mathbf{S}^{-1} (\mathbf{x}_j - \bar{\mathbf{x}}))^3,$$

and

$$b_{2p} = \frac{1}{n} \sum_{i=1}^n ((\mathbf{x}_i - \bar{\mathbf{x}})^T \mathbf{S}^{-1} (\mathbf{x}_i - \bar{\mathbf{x}}))^2.$$

## Usage

```
kurtosis(x)
```

```
skewness(x)
```

## Arguments

`x` matrix of data with, say,  $p$  columns.

## References

Mardia, K.V. (1970). Measures of multivariate skewness and kurtosis with applications. *Biometrika* **57**, 519-530.

Mardia, K.V., Zemroch, P.J. (1975). Algorithm AS 84: Measures of multivariate skewness and kurtosis. *Applied Statistics* **24**, 262-265.

## Examples

```

setosa <- iris[1:50,1:4]
kurtosis(setosa)
skewness(setosa)

```

---

 ldl *The LDL decomposition*


---

**Description**

Compute the LDL decomposition of a real symmetric matrix.

**Usage**

```
ldl(x)
```

**Arguments**

`x` a symmetric numeric matrix whose LDL decomposition is to be computed.

**Value**

The factorization has the form  $X = LDL^T$ , where  $D$  is a diagonal matrix and  $L$  is unitary lower triangular.

The LDL decomposition of `x` is returned as a list with components:

`lower` the unitary lower triangular factor  $L$ .  
`d` a vector containing the diagonal elements of  $D$ .

**References**

Golub, G.H., Van Loan, C.F. (1996). *Matrix Computations*, 3rd Edition. John Hopkins University Press.

**See Also**

[chol](#)

**Examples**

```
a <- matrix(c(2,-1,0,-1,2,-1,0,-1,1), ncol = 3)
z <- ldl(a)
z # information of LDL factorization

# computing det(a)
prod(z$d) # product of diagonal elements of D

# a non-positive-definite matrix
m <- matrix(c(5,-5,-5,3), ncol = 2)
try(chol(m)) # fails
ldl(m)
```



---

lu	<i>The LU factorization of a square matrix</i>
----	--

---

### Description

lu computes the LU factorization of a matrix.

### Usage

```
lu(x)
## Default S3 method:
lu(x)

## S3 method for class 'lu'
solve(a, b, ...)

is.lu(x)
```

### Arguments

x	a square numeric matrix whose LU factorization is to be computed.
a	an LU factorization of a square matrix.
b	a vector or matrix of right-hand sides of equations.
...	further arguments passed to or from other methods

### Details

The LU factorization plays an important role in many numerical procedures. In particular it is the basic method to solve the equation  $Ax = b$  for given matrix  $A$ , and vector  $b$ .

`solve.lu` is the method for `solve` for `lu` objects.

`is.lu` returns TRUE if `x` is a `list` and `inherits` from "lu".

Unsuccessful results from the underlying LAPACK code will result in an error giving a positive error code: these can only be interpreted by detailed study of the Fortran code.

### Value

The LU factorization of the matrix as computed by LAPACK. The components in the returned value correspond directly to the values returned by DGETRF.

lu	a matrix with the same dimensions as <code>x</code> . The upper triangle contains the $U$ of the decomposition and the strict lower triangle contains information on the $L$ of the factorization.
pivot	information on the pivoting strategy used during the factorization.

**Note**

To compute the determinant of a matrix (do you *really* need it?), the LU factorization is much more efficient than using eigenvalues ([eigen](#)). See [det](#).

LAPACK uses column pivoting and does not attempt to detect rank-deficient matrices.

**References**

Anderson. E., Bai, Z., Bischof, C., Blackford, S., Demmel, J., Dongarra, J., Du Croz, J., Greenbaum, A., Hammarling, S., McKenney, A. Sorensen, D. (1999). *LAPACK Users' Guide*, 3rd Edition. SIAM. (Available at [http://www.netlib.org/lapack/lug/lapack\\_lug.html](http://www.netlib.org/lapack/lug/lapack_lug.html)).

Golub, G.H., Van Loan, C.F. (1996). *Matrix Computations*, 3rd Edition. John Hopkins University Press.

**See Also**

[extractL](#), [extractU](#), [constructX](#) for reconstruction of the matrices, [lu2inv](#)

**Examples**

```
a <- matrix(c(3,2,6,17,4,18,10,-2,-12), ncol = 3)
z <- lu(a)
z # information of LU factorization

# computing det(a)
prod(diag(z$lu)) # product of diagonal elements of U

# solve linear equations
b <- matrix(1:6, ncol = 2)
solve(z, b)
```

---

lu-methods

---

*Reconstruct the L, U, or X Matrices from an LU object*


---

**Description**

Returns the original matrix from which the object was constructed or the components of the factorization.

**Usage**

```
constructX(x)
extractL(x)
extractU(x)
```

**Arguments**

x                      object representing an LU factorization. This will typically have come from a previous call to [lu](#).

**Value**

constructX returns  $X$ , the original matrix from which the lu object was constructed (because of the pivoting the  $X$  matrix is not exactly the product between  $L$  and  $U$ ).

extractL returns  $L$ . This may be pivoted.

extractU returns  $U$ .

**See Also**

[lu](#).

**Examples**

```
a <- matrix(c(10,-3,5,-7,2,-1,0,6,5), ncol = 3)
z <- lu(a)
L <- extractL(z)
L
U <- extractU(z)
U
X <- constructX(z)
all(a == X)
```

---

lu2inv

---

*Inverse from LU factorization*


---

**Description**

Invert a square matrix from its LU factorization.

**Usage**

```
lu2inv(x)
```

**Arguments**

**x** object representing an LU factorization. This will typically have come from a previous call to [lu](#).

**Value**

The inverse of the matrix whose LU factorization was given.

Unsuccessful results from the underlying LAPACK code will result in an error giving a positive error code: these can only be interpreted by detailed study of the Fortran code.

**Source**

This is an interface to the LAPACK routine DGETRI. LAPACK is from <https://www.netlib.org/lapack/> and its guide is listed in the references.

## References

Anderson. E., Bai, Z., Bischof, C., Blackford, S., Demmel, J., Dongarra, J., Du Croz, J., Greenbaum, A., Hammarling, S., McKenney, A. Sorensen, D. (1999). *LAPACK Users' Guide*, 3rd Edition. SIAM. (Available at [http://www.netlib.org/lapack/lug/lapack\\_lug.html](http://www.netlib.org/lapack/lug/lapack_lug.html)).

Golub, G.H., Van Loan, C.F. (1996). *Matrix Computations*, 3rd Edition. John Hopkins University Press.

## See Also

[lu](#), [solve](#).

## Examples

```
a <- matrix(c(3,2,6,17,4,18,10,-2,-12), ncol = 3)
z <- lu(a)
a %%% lu2inv(z)
```

---

Mahalanobis

*Mahalanobis distance*

---

## Description

Returns the squared Mahalanobis distance of all rows in  $x$  and the vector  $\mu$  = center with respect to  $\Sigma$  = cov. This is (for vector  $x$ ) defined as

$$D^2 = (x - \mu)^T \Sigma^{-1} (x - \mu)$$

## Usage

```
Mahalanobis(x, center, cov, inverted = FALSE)
```

## Arguments

<code>x</code>	vector or matrix of data. As usual, rows are observations and columns are variables.
<code>center</code>	mean vector of the distribution.
<code>cov</code>	covariance matrix ( $p \times p$ ) of the distribution, must be positive definite.
<code>inverted</code>	logical. If TRUE, cov is supposed to contain the <i>inverse</i> of the covariance matrix.

## Details

Unlike function `mahalanobis`, the covariance matrix is factorized using the Cholesky decomposition, which allows to assess if cov is positive definite. Unsuccessful results from the underlying LAPACK code will result in an error message.

## See Also

[cov](#), [mahalanobis](#)

**Examples**

```
x <- cbind(1:6, 1:3)
xbar <- colMeans(x)
S <- matrix(c(1,4,4,1), ncol = 2) # is negative definite
D2 <- mahalanobis(x, center = xbar, S)
all(D2 >= 0) # several distances are negative

## next command produces the following error:
## Covariance matrix is possibly not positive-definite
## Not run: D2 <- Mahalanobis(x, center = xbar, S)
```

matrix.inner

*Compute the inner product between two rectangular matrices***Description**

Computes the inner product between two rectangular matrices calling BLAS.

**Usage**

```
matrix.inner(x, y = x)
```

**Arguments**

x                    a numeric matrix.  
y                    a numeric matrix.

**Value**

a real value, indicating the inner product between two matrices.

**Examples**

```
x <- matrix(c(1, 1, 1,
              1, 2, 1,
              1, 3, 1,
              1, 1,-1,
              1, 2,-1,
              1, 3,-1), ncol = 3, byrow = TRUE)
y <- matrix(1, nrow = 6, ncol = 3)
matrix.inner(x, y)

# must be equal
matrix.norm(x, type = "Frobenius")^2
matrix.inner(x)
```

---

matrix.norm	<i>Compute the norm of a rectangular matrix</i>
-------------	---

---

### Description

Computes a matrix norm of `x` using LAPACK. The norm can be the one ("1") norm, the infinity ("inf") norm, the Frobenius norm, the maximum modulus ("maximum") among elements of a matrix, as determined by the value of `type`.

### Usage

```
matrix.norm(x, type = "Frobenius")
```

### Arguments

<code>x</code>	a numeric matrix.
<code>type</code>	character string, specifying the <i>type</i> of matrix norm to be computed. A character indicating the type of norm desired. "1" specifies the <b>one</b> norm, (maximum absolute column sum); "Inf" specifies the <b>infinity</b> norm (maximum absolute row sum); "Frobenius" specifies the <b>Frobenius</b> norm (the Euclidean norm of <code>x</code> treated as if it were a vector); "maximum" specifies the <b>maximum</b> modulus of all the elements in <code>x</code> .

### Details

As function `norm` in package **base**, method of `matrix.norm` calls the LAPACK function `DLANGE`.  
 Note that the 1-, Inf- and maximum norm is faster to calculate than the Frobenius one.

### Value

The matrix norm, a non-negative number.

### Examples

```
# a tiny example
x <- matrix(c(1, 1, 1,
              1, 2, 1,
              1, 3, 1,
              1, 1,-1,
              1, 2,-1,
              1, 3,-1), ncol = 3, byrow = TRUE)
matrix.norm(x, type = "Frobenius")
matrix.norm(x, type = "1")
matrix.norm(x, type = "Inf")

# an example not that small
```

```
n <- 1000
x <- .5 * diag(n) + 0.5 * matrix(1, nrow = n, ncol = n)
matrix.norm(x, type = "Frobenius")
matrix.norm(x, type = "1")
matrix.norm(x, type = "Inf")
matrix.norm(x, type = "maximum") # equal to 1
```

---

mediancenter	<i>Mediancenter</i>
--------------	---------------------

---

## Description

It calculates the mediancenter (or geometric median) of multivariate data.

## Usage

```
mediancenter(x)
```

## Arguments

x	a matrix or data frame. As usual, rows are observations and columns are variables.
---	--

## Details

The mediancenter for a sample of multivariate observations is computed using a steepest descend method combined with bisection. The mediancenter invariant to rotations of axes and is useful as a multivariate generalization of the median of univariate sample.

## Value

A list containing the following named components:

median	an estimate for the mediancenter of the data.
iter	the number of iterations performed, it is negative if a degenerate solution is found.

## References

Gower, J.C. (1974). Algorithm AS 78: The mediancentre. *Applied Statistics* **23**, 466-470.

## See Also

[cov.wt](#), [median](#).

**Examples**

```
x <- cbind(1:10, c(1:3, 8:5, 8:10))
z <- mediancenter(x)$median # degenerate solution
xbar <- colMeans(x)
plot(x, xlab = "", ylab = "")
points(x = xbar[1], y = xbar[2], pch = 16, col = "red")
points(x = z[1], y = z[2], pch = 3, col = "blue", lwd = 2)
```

---

minkowski

*Computes the p-norm of a vector*


---

**Description**

Computes a p-norm of vector x. The norm can be the one ( $p = 1$ ) norm, Euclidean ( $p = 2$ ) norm, the infinity ( $p = \text{Inf}$ ) norm. The underlying C or Fortran code is inspired on ideas of BLAS Level 1.

**Usage**

```
minkowski(x, p = 2)
```

**Arguments**

x	a numeric vector.
p	a number, specifying the <i>type</i> of norm desired. Possible values include real number greater or equal to 1, or Inf, Default value is $p = 2$ .

**Details**

Method of minkowski for  $p = \text{Inf}$  calls idamax BLAS function. For other values, C or Fortran subroutines using unrolled cycles are called.

**Value**

The vector p-norm, a non-negative number.

**Examples**

```
# a tiny example
x <- rnorm(1000)
minkowski(x, p = 1)
minkowski(x, p = 1.5)
minkowski(x, p = 2)
minkowski(x, p = Inf)

x <- x / minkowski(x)
minkowski(x, p = 2) # equal to 1
```



moments

*Central moments***Description**

It calculates up to fourth central moments (or moments about the mean), and the skewness and kurtosis coefficients using an online algorithm.

**Usage**

```
moments(x)
```

**Arguments**

`x` a numeric vector containing the sample observations.

**Details**

The  $k$ -th central moment is defined as

$$m_k = \frac{1}{n} \sum_{i=1}^n (x_i - \bar{x})^k.$$

In particular, the second central moment is the variance of the sample. The sample skewness and kurtosis are defined, respectively, as

$$b_1 = \frac{m_3}{s^3}, \quad b_2 = \frac{m_4}{s^4} - 3,$$

where  $s$  denotes the standard deviation.

**Value**

A list containing second, third and fourth central moments, and skewness and kurtosis coefficients.

**References**

Spicer, C.C. (1972). Algorithm AS 52: Calculation of power sums of deviations about the mean. *Applied Statistics* **21**, 226-227.

**See Also**

[var.](#)

**Examples**

```
set.seed(149)
x <- rnorm(1000)
z <- moments(x)
z
```

---

ols	<i>Fit linear regression model</i>
-----	------------------------------------

---

### Description

Returns an object of class "ols" that represents a linear model fit.

### Usage

```
ols(formula, data, subset, na.action, method = "qr", tol = 1e-7, maxiter = 100,
    model = FALSE, x = FALSE, y = FALSE, contrasts = NULL, ...)
```

### Arguments

formula	an object of class " <a href="#">formula</a> " (or one that can be coerced to that class): a symbolic description of the model to be fitted.
data	an optional data frame, list or environment (or object coercible by <a href="#">as.data.frame</a> to a data frame) containing the variables in the model. If not found in data, the variables are taken from <code>environment(formula)</code> , typically the environment from which <code>ols</code> is called.
subset	an optional vector specifying a subset of observations to be used in the fitting process.
na.action	a function which indicates what should happen when the data contain NAs. The default is set by the <code>na.action</code> setting of <a href="#">options</a> , and is <a href="#">na.fail</a> if that is unset.
method	the least squares fitting method to be used; the options are "cg" (conjugate gradients), "chol", "qr" (the default), "svd" and "sweep".
tol	tolerance for the conjugate gradients (gc) method. Default is <code>tol = 1e-7</code> .
maxiter	The maximum number of iterations for the conjugate gradients (gc) method. Defaults to 100.
model, x, y	logicals. If TRUE the corresponding components of the fit (the model frame, the model matrix, the response) are returned.
contrasts	an optional list. See the <code>contrasts.arg</code> of <a href="#">model.matrix.default</a> .
...	additional arguments (currently disregarded).

### Value

`ols` returns an object of class "ols".

The function summary is used to obtain and print a summary of the results. The generic accessor functions `coefficients`, `fitted.values` and `residuals` extract various useful features of the value returned by `ols`.

An object of class "ols" is a list containing at least the following components:

<code>coefficients</code>	a named vector of coefficients
---------------------------	--------------------------------

residuals	the residuals, that is response minus fitted values.
fitted.values	the fitted mean values.
RSS	the residual sum of squares.
cov.unscaled	a $p \times p$ matrix of (unscaled) covariances of the $\hat{\beta}_j, j = 1, \dots, p$ .
call	the matched call.
terms	the <a href="#">terms</a> object used.
contrasts	(only where relevant) the contrasts used.
y	if requested, the response used.
x	if requested, the model matrix used.
model	if requested (the default), the model frame used.

**See Also**

[ols.fit](#), [lm](#), [lsfit](#)

**Examples**

```
# tiny example of regression
y <- c(1, 3, 3, 2, 2, 1)
x <- matrix(c(1, 1,
              2, 1,
              3, 1,
              1,-1,
              2,-1,
              3,-1), ncol = 2, byrow = TRUE)
f0 <- ols(y ~ x) # intercept is included by default
f0 # printing results (QR method was used)

f1 <- ols(y ~ x, method = "svd") # using SVD method instead
f1
```

---

ols.fit

---

*Fitter Functions for Linear Models*


---

**Description**

This function is a *switcher* among various numerical fitting functions ([ols.fit.cg](#), [ols.fit.chol](#), [ols.fit.qr](#), [ols.fit.svd](#) and [ols.fit.sweep](#)). The argument `method` does the switching: "qr" for [ols.fit.qr](#), etc. This should usually *not* be used directly unless by experienced users.

**Usage**

```
ols.fit(x, y, method = "qr", tol = 1e-7, maxiter = 100)
```

**Arguments**

<code>x</code>	design matrix of dimension $n \times q$ .
<code>y</code>	vector of observations of length $n$ .
<code>method</code>	currently, methods "cg", "chol", "qr" (default), "svd" and "sweep" are supported.
<code>tol</code>	tolerance for the conjugate gradients (gc) method. Default is <code>tol = 1e-7</code> .
<code>maxiter</code>	The maximum number of iterations for the conjugate gradients (gc) method. Defaults to 100.

**Value**

a [list](#) with components:

<code>coefficients</code>	a named vector of coefficients
<code>residuals</code>	the residuals, that is response minus fitted values.
<code>fitted.values</code>	the fitted mean values.
<code>RSS</code>	the residual sum of squares.
<code>cov.unscaled</code>	a $p \times p$ matrix of (unscaled) covariances of the $\hat{\beta}_j, j = 1, \dots, p$ .

**See Also**

[ols.fit.cg](#), [ols.fit.chol](#), [ols.fit.qr](#), [ols.fit.svd](#), [ols.fit.sweep](#).

**Examples**

```
set.seed(151)
n <- 100
p <- 2
x <- matrix(rnorm(n * p), n, p) # no intercept!
y <- rnorm(n)
fm <- ols.fit(x = x, y = y, method = "chol")
fm
```

---

ols.fit-methods

*Fit a Linear Model*


---

**Description**

Fits a linear model, returning the bare minimum computations.

**Usage**

```
ols.fit.cg(x, y, tol = 1e-7, maxiter = 100)
ols.fit.chol(x, y)
ols.fit.qr(x, y)
ols.fit.svd(x, y)
ols.fit.sweep(x, y)
```

**Arguments**

<code>x, y</code>	numeric vectors or matrices for the predictors and the response in a linear model. Typically, but not necessarily, <code>x</code> will be constructed by one of the fitting functions.
<code>tol</code>	tolerance for the conjugate gradients (gc) method. Default is <code>tol = 1e-7</code> .
<code>maxiter</code>	The maximum number of iterations for the conjugate gradients (gc) method. Defaults to 100.

**Value**

The bare bones of an `ols` object: the coefficients, residuals, fitted values, and some information used by `summary.ols`.

**See Also**

[ols](#), [ols.fit](#), [lm](#)

**Examples**

```
set.seed(151)
n <- 100
p <- 2
x <- matrix(rnorm(n * p), n, p) # no intercept!
y <- rnorm(n)
z <- ols.fit.chol(x, y)
z
```

---

power.method

*Power method to approximate dominant eigenvalue and eigenvector*

---

**Description**

The power method seeks to determine the eigenvalue of maximum modulus, and a corresponding eigenvector.

**Usage**

```
power.method(x, only.value = FALSE, maxiter = 100, tol = 1e-8)
```

**Arguments**

<code>x</code>	a symmetric matrix.
<code>only.value</code>	if TRUE, only the dominant eigenvalue is returned, otherwise both dominant eigenvalue and eigenvector are returned.
<code>maxiter</code>	the maximum number of iterations. Defaults to 100
<code>tol</code>	a numeric tolerance.

**Value**

When `only.value` is not true, as by default, the result is a list with components "value" and "vector". Otherwise only the dominant eigenvalue is returned. The performed number of iterations to reach convergence is returned as attribute "iterations".

**See Also**

[eigen](#) for eigenvalues and eigenvectors computation.

**Examples**

```
n <- 1000
x <- .5 * diag(n) + 0.5 * matrix(1, nrow = n, ncol = n)

# dominant eigenvalue must be (n + 1) / 2
z <- power.method(x, only.value = TRUE)
```

---

ridge	<i>Ridge regression</i>
-------	-------------------------

---

**Description**

Fit a linear model by ridge regression, returning an object of class "ridge".

**Usage**

```
ridge(formula, data, subset, lambda = 1.0, method = "GCV", ngrid = 200, tol = 1e-07,
      na.action, model = FALSE, x = FALSE, y = FALSE, contrasts = NULL, ...)
```

**Arguments**

formula	an object of class " <a href="#">formula</a> " (or one that can be coerced to that class): a symbolic description of the model to be fitted.
data	an optional data frame, list or environment (or object coercible by <a href="#">as.data.frame</a> to a data frame) containing the variables in the model. If not found in data, the variables are taken from <code>environment(formula)</code> , typically the environment from which <code>ridge</code> is called.
subset	an optional vector specifying a subset of observations to be used in the fitting process.
na.action	a function which indicates what should happen when the data contain NAs. The default is set by the <code>na.action</code> setting of <a href="#">options</a> , and is <a href="#">na.fail</a> if that is unset.
lambda	a scalar or vector of ridge constants. A value of 0 corresponds to ordinary least squares.

method	the method for choosing the ridge parameter lambda. If method = "none", then lambda is 'fixed'. If method = "GCV" (the default) then the ridge parameter is chosen automatically using the generalized cross validation (GCV) criterion. For method = "grid", optimal value of lambda is selected computing the GCV criterion over a grid.
ngrid	number of elements in the grid used to compute the GCV criterion. Only required if method = "grid" and lambda is a scalar.
tol	tolerance for the optimization of the GCV criterion. Default is 1e-7.
model, x, y	logicals. If TRUE the corresponding components of the fit (the model frame, the model matrix, the response) are returned.
contrasts	an optional list. See the contrasts.arg of <a href="#">model.matrix.default</a> .
...	additional arguments to be passed to the low level regression fitting functions (not implemented).

## Details

ridge function fits in linear ridge regression **without** scaling or centering the regressors and the response. In addition, If an intercept is present in the model, its coefficient is penalized.)

## Value

A list with the following components:

dims	dimensions of model matrix.
coefficients	a named vector of coefficients.
scale	a named vector of coefficients.
fitted.values	the fitted mean values.
residuals	the residuals, that is response minus fitted values.
RSS	the residual sum of squares.
edf	the effective number of parameters.
GCV	vector (if method = "grid") of GCV values.
HKB	HKB estimate of the ridge constant.
LW	LW estimate of the ridge constant.
lambda	vector (if method = "grid") of lambda values.
optimal	value of lambda with the minimum GCV (only relevant if method = "grid").
call	the matched call.
terms	the <a href="#">terms</a> object used.
contrasts	(only where relevant) the contrasts used.
y	if requested, the response used.
x	if requested, the model matrix used.
model	if requested, the model frame used.

## References

- Golub, G.H., Heath, M., Wahba, G. (1979). Generalized cross-validation as a method for choosing a good ridge parameter. *Technometrics* **21**, 215-223.
- Hoerl, A.E., Kennard, R.W., Baldwin, K.F. (1975). Ridge regression: Some simulations. *Communication in Statistics* **4**, 105-123.
- Hoerl, A.E., Kennard, R.W. (1970). Ridge regression: Biased estimation of nonorthogonal problems. *Technometrics* **12**, 55-67.
- Lawless, J.F., Wang, P. (1976). A simulation study of ridge and other regression estimators. *Communications in Statistics* **5**, 307-323.

## See Also

[lm](#), [ols](#)

## Examples

```
z <- ridge(GNP.deflator ~ ., data = longley, lambda = 4, method = "grid")
z # ridge regression on a grid over seq(0, 4, length = 200)

z <- ridge(GNP.deflator ~ ., data = longley)
z # ridge parameter selected using GCV (default)
```

---

seidel

---

Solve linear systems using the Gauss-Seidel method

---

## Description

Gauss-Seidel method is an iterative algorithm for solving a system of linear equations.

## Usage

```
seidel(a, b, start, maxiter = 200, tol = 1e-7)
```

## Arguments

a	a square numeric matrix containing the coefficients of the linear system.
b	a vector of right-hand sides of the linear system.
start	a vector for initial starting point.
maxiter	the maximum number of iterations. Defaults to 200
tol	tolerance level for stopping iterations.

## Details

Let  $D$ ,  $L$ , and  $U$  denote the diagonal, lower triangular and upper triangular parts of a matrix  $A$ . Gauss-Seidel method solve the equation  $Ax = b$ , iteratively by rewriting  $(L + D)x + Ux = b$ . Assuming that  $L + D$  is nonsingular leads to the iteration formula

$$x^{(k+1)} = -(L + D)^{-1}Ux^{(k)} + (L + D)^{-1}b$$



## Value

a vector with the approximate solution, the iterations performed are returned as the attribute 'iterations'.

## References

Golub, G.H., Van Loan, C.F. (1996). *Matrix Computations*, 3rd Edition. John Hopkins University Press.

## See Also

[jacobi](#)

## Examples

```
a <- matrix(c(5,-3,2,-2,9,-1,3,1,-7), ncol = 3)
b <- c(-1,2,3)
start <- c(1,1,1)
z <- seidel(a, b, start)
z # 10 iterations
```

---

sherman.morrison	<i>Sherman-Morrison formula</i>
------------------	---------------------------------

---

## Description

The Sherman-Morrison formula gives a convenient expression for the inverse of the rank 1 update  $(\mathbf{A} + \mathbf{b}\mathbf{d}^T)$  where  $\mathbf{A}$  is a  $n \times n$  matrix and  $\mathbf{b}, \mathbf{d}$  are  $n$ -dimensional vectors. Thus

$$(\mathbf{A} + \mathbf{b}\mathbf{d}^T)^{-1} = \mathbf{A}^{-1} - \frac{\mathbf{A}^{-1}\mathbf{b}\mathbf{d}^T\mathbf{A}^{-1}}{1 + \mathbf{d}^T\mathbf{A}^{-1}\mathbf{b}}.$$

## Usage

```
sherman.morrison(a, b, d = b, inverted = FALSE)
```

## Arguments

a	a numeric matrix.
b	a numeric vector.
d	a numeric vector.
inverted	logical. If TRUE, a is supposed to contain its <i>inverse</i> .

## Details

Method of sherman.morrison calls BLAS level 2 subroutines DGEMV and DGER for computational efficiency.

**Value**

a square matrix of the same order as a.

**Examples**

```
n <- 10
ones <- rep(1, n)
a <- 0.5 * diag(n)
z <- sherman.morrison(a, ones, 0.5 * ones)
z
```

---

sweep.operator

*Gauss-Jordan sweep operator for symmetric matrices*


---

**Description**

Perform the sweep operation (or reverse sweep) on the diagonal elements of a symmetric matrix.

**Usage**

```
sweep.operator(x, k = 1, reverse = FALSE)
```

**Arguments**

x	a symmetric matrix.
k	elements (if k is vector) of the diagonal which will be swept.
reverse	logical. If reverse = TRUE the reverse sweep is performed.

**Details**

The symmetric sweep operator is a powerful tool in computational statistics with uses in stepwise regression, conditional multivariate normal distributions, MANOVA, and more.

**Value**

a square matrix of the same order as x.

**References**

Goodnight, J.H. (1979). A tutorial on the SWEEP operator. *The American Statistician* **33**, 149-158.

**Examples**

```
# tiny example of regression, last column contains 'y'
xy <- matrix(c(1, 1, 1, 1,
               1, 2, 1, 3,
               1, 3, 1, 3,
               1, 1,-1, 2,
               1, 2,-1, 2,
               1, 3,-1, 1), ncol = 4, byrow = TRUE)
z <- crossprod(xy)
z <- sweep.operator(z, k = 1:3)
cf <- z[1:3,4] # regression coefficients
RSS <- z[4,4] # residual sum of squares

# an example not that small
x <- matrix(rnorm(1000 * 100), ncol = 100)
xx <- crossprod(x)
z <- sweep.operator(xx, k = 1)
```

symm.info

*Compact information to construct the symmetrizer matrix***Description**

This function provides the information required to create the symmetrizer matrix.

**Usage**

```
symm.info(n = 1)
```

**Arguments**

**n** order of the symmetrizer matrix.

**Details**

This function returns a list containing vectors that represent an element of the symmetrizer matrix and is accessed by the indexes in vectors `row`, `col` and values contained in `val`. This information is used by function [symm.prod](#) to do some operations involving the symmetrizer matrix without forming it. This information also can be obtained using function [symmetrizer](#).

**Value**

A list containing the following elements:

<code>row</code>	vector of indexes, each entry represents the row index of the symmetrizer matrix.
<code>col</code>	vector of indexes, each entry represents the column index of the symmetrizer matrix.
<code>val</code>	vector of values, each entry represents the value of the symmetrizer matrix at element given by row and col indexes.
<code>order</code>	order of the symmetrizer matrix.

**See Also**

[symmetrizer](#), [symm.prod](#)

**Examples**

```
z <- symm.info(n = 3)
z # elements in symmetrizer matrix of order 3

N3 <- symmetrizer(n = 3, matrix = TRUE)
N3 # only recommended if n is very small
```

---

symm.prod

*Matrix multiplication involving the symmetrizer matrix*

---

**Description**

Given the order of a symmetrizer and matrix  $x$ , performs one of the matrix-matrix operations:

- $Y = NX$ , if `side = "left"`, or
- $Y = XN$ , if `side = "right"`,

where  $N$  is the symmetrizer matrix of order  $n$ . The main aim of `symm.prod` is to do this matrix multiplication **without forming** the symmetrizer matrix.

**Usage**

```
symm.prod(n = 1, x = NULL, side = "left")
```

**Arguments**

<code>n</code>	order of the symmetrizer matrix.
<code>x</code>	numeric matrix (or vector).
<code>side</code>	a string selecting if symmetrizer matrix is pre-multiplying $x$ , that is <code>side = "left"</code> or post-multiplying $x$ , by using <code>side = "right"</code> .

**Details**

Underlying C code only uses information provided by [symm.info](#) to performs the matrix multiplication. The symmetrizer matrix is **never** created.

**See Also**

[symmetrizer](#)

### Examples

```
N4 <- symmetrizer(n = 4, matrix = TRUE)
x <- matrix(1:32, ncol = 2)
y <- N4 %%% x

z <- symm.prod(n = 4, x) # N4 is not stored
all(z == y) # matrices y and z are equal!
```

---

symmetrizer

*Symmetrizer matrix*


---

### Description

This function returns the symmetrizer matrix of order  $n$  which transforms, for every  $n \times n$  matrix  $\mathbf{A}$ ,  $\text{vec}(\mathbf{A})$  into  $\text{vec}((\mathbf{A} + \mathbf{A}^T)/2)$ .

### Usage

```
symmetrizer(n = 1, matrix = FALSE)
```

### Arguments

<code>n</code>	order of the symmetrizer matrix.
<code>matrix</code>	a logical indicating whether the symmetrizer matrix will be returned.

### Details

This function is a wrapper function for the function `symm.info`. This function provides the information required to create the symmetrizer matrix. If option `matrix = FALSE` the symmetrizer matrix is stored in three vectors containing the coordinate list of indexes for rows, columns and the values.

**Warning:** `matrix = TRUE` is **not** recommended, unless the order `n` be small. This matrix can require a huge amount of storage.

### Value

Returns an  $n^2$  by  $n^2$  matrix (if requested).

### References

Abadir, K.M., Magnus, J.R. (2005). *Matrix Algebra*. Cambridge University Press.

Magnus, J.R., Neudecker, H. (2007). *Matrix Differential Calculus with Applications in Statistics and Econometrics*, 3rd Edition. Wiley, New York.

### See Also

[symm.info](#)

### Examples

```
z <- symmetrizer(n = 100)
object.size(z) # 319 Kb of storage

N100 <- symmetrizer(n = 100, matrix = TRUE) # time: < 2 secs
object.size(N100) # 800 Mb of storage, do not request this matrix!

# a small example
N3 <- symmetrizer(n = 3, matrix = TRUE)
a <- matrix(rep(c(2,4,6), each = 3), ncol = 3)
a
b <- 0.5 * (a + t(a))
b
v <- N3 %**% vec(a)
all(vec(b) == as.vector(v)) # vectors are equal!
```

---

vec

---

*Vectorization of a matrix*


---

### Description

This function returns a vector obtained by stacking the columns of  $x$

### Usage

```
vec(x)
```

### Arguments

$x$                       a numeric matrix.

### Value

Let  $x$  be a  $n$  by  $m$  matrix, then  $\text{vec}(x)$  is a  $nm$ -dimensional vector.

### Examples

```
x <- matrix(rep(1:10, each = 10), ncol = 10)
x
y <- vec(x)
y
```

---

vech	<i>Vectorization the lower triangular part of a square matrix</i>
------	---

---

**Description**

This function returns a vector obtained by stacking the lower triangular part of a square matrix.

**Usage**

```
vech(x)
```

**Arguments**

`x` a square matrix.

**Value**

Let  $x$  be a  $n$  by  $n$  matrix, then `vech(x)` is a  $n(n+1)/2$ -dimensional vector.

**Examples**

```
x <- matrix(rep(1:10, each = 10), ncol = 10)
x
y <- vech(x)
y
```

---

whitening	<i>Whitening transformation</i>
-----------	---------------------------------

---

**Description**

Applies the whitening transformation to a data matrix based on the Cholesky decomposition of the empirical covariance matrix.

**Usage**

```
whitening(x, Scatter = NULL)
```

**Arguments**

`x` vector or matrix of data with, say,  $p$  columns.

`Scatter` covariance (or scatter) matrix ( $p \times p$ ) of the distribution, must be positive definite. If NULL, the covariance matrix is estimated from the data.

**Value**

Returns the whitened data matrix  $Z = XW^T$ , where

$$W^T W = S^{-1},$$

with  $S$  the empirical covariance matrix.

**References**

Kessy, A., Lewin, A., Strimmer, K. (2018). Optimal whitening and decorrelation. *The American Statistician* **72**, 309-314.

**Examples**

```
x <- iris[,1:4]
species <- iris[,5]
pairs(x, col = species) # plot of Iris

# whitened data
z <- whitening(x)
pairs(z, col = species) # plot of
```

---

wilson.hilferty

*Wilson-Hilferty transformation*


---

**Description**

Returns the Wilson-Hilferty transformation of random variables with chi-squared distribution.

**Usage**

```
wilson.hilferty(x)
```

**Arguments**

$x$  vector or matrix of data with, say,  $p$  columns.

**Details**

Let  $F = D^2/p$  be a random variable, where  $D^2$  denotes the squared Mahalanobis distance defined as

$$D^2 = (\mathbf{x} - \boldsymbol{\mu})^T \boldsymbol{\Sigma}^{-1} (\mathbf{x} - \boldsymbol{\mu})$$

Thus the Wilson-Hilferty transformation is given by

$$z = \frac{F^{1/3} - (1 - \frac{2}{9p})}{(\frac{2}{9p})^{1/2}}$$

and  $z$  is approximately distributed as a standard normal distribution. This is useful, for instance, in the construction of QQ-plots.



**References**

Wilson, E.B., and Hilferty, M.M. (1931). The distribution of chi-square. *Proceedings of the National Academy of Sciences of the United States of America* **17**, 684-688.

**See Also**

[cov](#), [Mahalanobis](#)

**Examples**

```
x <- iris[,1:4]
z <- wilson.hilferty(x)
par(pty = "s")
qqnorm(z, main = "Transformed distances Q-Q plot")
abline(c(0,1), col = "red", lwd = 2, lty = 2)
```

# Index

## \* algebra

- array.mult, 3
- bracket.prod, 5
- cg, 6
- comm.prod, 8
- commutation, 9
- dupl.cross, 12
- dupl.prod, 14
- duplication, 15
- equilibrate, 16
- hadamard, 18
- helmert, 19
- jacobi, 21
- ldl, 24
- lu, 25
- lu-methods, 26
- lu2inv, 27
- power.method, 37
- seidel, 40
- sherman.morrison, 41
- sweep.operator, 42
- symm.prod, 44
- symmetrizer, 45

## \* array

- array.mult, 3
- asSymmetric, 4
- bracket.prod, 5
- cg, 6
- comm.info, 7
- comm.prod, 8
- commutation, 9
- dupl.cross, 12
- dupl.info, 13
- dupl.prod, 14
- duplication, 15
- equilibrate, 16
- hadamard, 18
- helmert, 19
- is.lower.tri, 20

- jacobi, 21
- kronecker.prod, 22
- ldl, 24
- lu, 25
- lu-methods, 26
- lu2inv, 27
- matrix.inner, 29
- matrix.norm, 30
- ols.fit, 35
- ols.fit-methods, 36
- power.method, 37
- seidel, 40
- sherman.morrison, 41
- sweep.operator, 42
- symm.info, 43
- symm.prod, 44
- symmetrizer, 45
- vec, 46
- vech, 47

## \* math

- matrix.inner, 29
- matrix.norm, 30
- minkowski, 32

## \* models

- ridge, 38

## \* multivariate

- cov.MSSD, 10
- cov.weighted, 11
- kurtosis, 23
- Mahalanobis, 28
- mediancenter, 31
- whitening, 47
- wilson.hilferty, 48

## \* regression

- ols, 34
- ols.fit, 35
- ols.fit-methods, 36

## \* univar

- geomean, 17

- moments, 33
- array, 3, 5
- array.mult, 3, 5
- as.data.frame, 34, 38
- asSymmetric, 4
- bracket.prod, 3, 5
- cg, 6
- chol, 24
- class, 34
- comm.info, 7, 8, 10
- comm.prod, 7, 8
- commutation, 7, 8, 9
- constructX, 26
- constructX (lu-methods), 26
- cov, 11, 12, 28, 49
- cov.MSSD, 10
- cov.weighted, 11
- cov.wt, 11, 12, 31
- det, 26
- dupl.cross, 12
- dupl.info, 13, 14, 16
- dupl.prod, 12–14, 14
- duplication, 13, 14, 15
- eigen, 26, 38
- equilibrate, 16
- extractL, 26
- extractL (lu-methods), 26
- extractU, 26
- extractU (lu-methods), 26
- formula, 34, 38
- geomean, 17
- hadamard, 18
- helmert, 19
- inherits, 25
- is.lower.tri, 20
- is.lu (lu), 25
- is.upper.tri (is.lower.tri), 20
- jacobi, 6, 21, 41
- kronecker, 22
- kronecker.prod, 22
- kurtosis, 23
- ldl, 24
- list, 25, 36
- lm, 35, 37, 40
- lower.tri, 20
- lsfit, 35
- lu, 25, 26–28
- lu-methods, 26
- lu2inv, 26, 27
- Mahalanobis, 28, 49
- mahalanobis, 28
- matrix, 3, 5
- matrix.inner, 29
- matrix.norm, 30
- mean, 18
- median, 18, 31
- mediancenter, 31
- minkowski, 32
- model.matrix.default, 34, 39
- moments, 33
- na.fail, 34, 38
- ols, 34, 37, 40
- ols.fit, 35, 35, 37
- ols.fit-methods, 36
- ols.fit.cg, 35, 36
- ols.fit.cg (ols.fit-methods), 36
- ols.fit.chol, 35, 36
- ols.fit.chol (ols.fit-methods), 36
- ols.fit.qr, 35, 36
- ols.fit.qr (ols.fit-methods), 36
- ols.fit.svd, 35, 36
- ols.fit.svd (ols.fit-methods), 36
- ols.fit.sweep, 35, 36
- ols.fit.sweep (ols.fit-methods), 36
- options, 34, 38
- outer, 22
- power.method, 37
- ridge, 38
- seidel, 6, 21, 40
- sherman.morrison, 41
- skewness (kurtosis), 23
- solve, 6, 25, 28
- solve.lu (lu), 25

sweep.operator, [42](#)  
symm.info, [43](#), [44](#), [45](#)  
symm.prod, [43](#), [44](#), [44](#)  
symmetrizer, [43](#), [44](#), [45](#)  
  
terms, [35](#), [39](#)  
  
upper.tri, [20](#)  
  
var, [11](#), [12](#), [33](#)  
vec, [46](#)  
vech, [47](#)  
  
whitening, [47](#)  
wilson.hilferty, [48](#)