# Package 'fastmatrix'

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<b>Γitle</b> Fast Computation of some Matrices Useful in Statistics
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Description Small set of functions designed to speed up the computation of certain matrix operations that are commonly used in statistics and econometrics. It provides efficient implementations for the computation of several structured matrices, matrix decompositions and statistical procedures, many of which have minimal memory overhead. Furthermore, the package provides interfaces to C code callable by another C code from other R packages.
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## **Description**

Small set of functions designed to speed up the computation of certain matrix operations that are commonly used in statistics and econometrics. It provides efficient implementations for the computation of several structured matrices, matrix decompositions and statistical procedures, many of which have minimal memory overhead. Furthermore, the package provides interfaces to C code callable by another C code from other R packages.

## Details

The **fastmatrix** package provides functions to the efficient construction of *duplication*, *commutation* and *symmetrizer* matrices with minimal storage requeriments. Common matrix decompositions (e.g. LU, LDL), rank-1 updates (e.g. Cholesky update), iterative solvers for linear systems and other linear algebra utilities, as well as basic matrix operations, such as Hadamard (elementwise) and Kronecker products, the Sherman-Morrison formula and the power method. The package also offers several statistical procedures, namely: the sweep operator, weighted mean and covariance (using online algorithms), ordinary least squares via multiple strategies (Cholesky, QR, SVD, sweep and conjugate gradients), ridge regression (with procedures for selecting the ridge parameter), omnibus tests for univariate normality, multivariate skewness and kurtosis measures, Mahalanobis distance (with positive-definiteness checks), Wilson-Hilferty transformation of gamma variables (useful, for instance, for goodness-of-fit of multivariate normal data), and some random number generators. Finally, the package provides interfaces for code written in C, enabling other R packages (or userwritten C code) to access the C routines in the **fastmatrix** package.

## Author(s)

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4 array.mult

array.mult

Array multiplication

# Description

Multiplication of 3-dimensional arrays was first introduced by Bates and Watts (1980). More extensions and technical details can be found in Wei (1998).

## Usage

```
array.mult(a, b, x)
```

#### Arguments

a numeric matrix.

b a numeric matrix.

x a three-dimensional array.

## **Details**

Let  $X = (x_{tij})$  be a 3-dimensional  $n \times p \times q$  where indices t, i and j indicate face, row and column, respectively. The product Y = AXB is an  $n \times r \times s$  array, with A and B are  $r \times p$  and  $q \times s$  matrices respectively. The elements of Y are defined as:

$$y_{tkl} = \sum_{i=1}^{p} \sum_{j=1}^{q} a_{ki} x_{tij} b_{jl}$$

#### Value

array.mult returns a 3-dimensional array of dimension  $n \times r \times s$ .

# References

Bates, D.M., Watts, D.G. (1980). Relative curvature measures of nonlinearity. *Journal of the Royal Statistical Society, Series B* **42**, 1-25.

Wei, B.C. (1998). Exponential Family Nonlinear Models. Springer, New York.

## See Also

array, matrix, bracket.prod.

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## **Examples**

```
x <- array(0, dim = c(2,3,3)) # 2 x 3 x 3 array
x[,,1] <- c(1,2,2,4,3,6)
x[,,2] <- c(2,4,4,8,6,12)
x[,,3] <- c(3,6,6,12,9,18)

a <- matrix(1, nrow = 2, ncol = 3)
b <- matrix(1, nrow = 3, ncol = 2)

y <- array.mult(a, b, x) # a 2 x 2 x 2 array
y</pre>
```

 ${\it asSymmetric}$ 

Force a matrix to be symmetric

# **Description**

Force a square matrix X to be symmetric

# Usage

```
asSymmetric(x, lower = TRUE)
```

# Arguments

x a square matrix to be forced to be symmetric.

lower logical, should the upper (lower) triangle be replaced with the lower (upper) triangle?

## Value

a square symmetric matrix.

```
a <- matrix(1:16, ncol = 4)
isSymmetric(a) # FALSE
a <- asSymmetric(a) # copy lower triangle into upper triangle</pre>
```

6 bezier

bezier

Computation of Bezier curve

#### **Description**

Computes the Bezier curve based on n+1 control points using the De Casteljau's method.

## Usage

```
bezier(x, y, ngrid = 200)
```

## Arguments

x, y vector giving the coordinates of the control points. Missing values are deleted.

ngrid number of elements in the grid used to compute the smoother.

#### **Details**

Given  $p_0, p_1, \dots, p_n$  control points the Bezier curve is given by B(t) defined as

$$B(t) = \begin{pmatrix} x(t) \\ y(t) \end{pmatrix} = \sum_{k=0}^{n} \binom{n}{k} t^{k} (1-t)^{k} \boldsymbol{p}_{k}$$

where  $t \in [0, 1]$ . To evaluate the Bezier curve the De Casteljau's method is used.

## Value

A list containing xgrid and ygrid elements used to plot the Bezier curve.

```
# a tiny example
x <- c(1.0, 0.25, 1.25, 2.5, 4.00, 5.0)
y <- c(0.5, 2.00, 3.75, 4.0, 3.25, 1.0)
plot(x, y, type = "o")
z <- bezier(x, y, ngrid = 50)
lines(z$xgrid, z$ygrid, lwd = 2, lty = 2, col = "red")
# other simple example
x <- c(4,6,4,5,6,7)
y <- 1:6
plot(x, y, type = "o")
z <- bezier(x, y, ngrid = 50)
lines(z$xgrid, z$ygrid, lwd = 2, lty = 2, col = "red")</pre>
```

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bracket.prod

Bracket product

## **Description**

Bracket product of a matrix and a 3-dimensional array.

## Usage

```
bracket.prod(a, x)
```

## Arguments

a numeric matrix.

x a three-dimensional array.

#### **Details**

Let  $X = (x_{tij})$  be a 3-dimensional  $n \times p \times q$  array and A an  $m \times n$  matrix, then Y = [A][X] is called the bracket product of A and X, that is an  $m \times p \times q$  with elements

$$y_{tij} = \sum_{k=1}^{n} a_{tk} x_{kij}$$

#### Value

bracket.prod returns a 3-dimensional array of dimension  $m \times p \times q$ .

#### References

Wei, B.C. (1998). Exponential Family Nonlinear Models. Springer, New York.

## See Also

```
array, matrix, array.mult.
```

```
x \leftarrow array(0, dim = c(2,3,3)) \# 2 x 3 x 3 array x[,,1] \leftarrow c(1,2,2,4,3,6) x[,,2] \leftarrow c(2,4,4,8,6,12) x[,,3] \leftarrow c(3,6,6,12,9,18)
a \leftarrow arrix(1, nrow = 3, ncol = 2)
y \leftarrow bracket.prod(a, x) \# a 3 x 3 x 3 array y
```

8 ccc

ссс	Lin's concordance correlation coefficient	

# Description

Calculates Lin's concordance correlation coefficient for evaluating the degree of agreement between measurements generated by two different methods.

# Usage

```
ccc(x, data, method = "z-transform", level = 0.95, equal.means = FALSE,
    ustat = TRUE, subset, na.action)
```

# Arguments

х	a formula or a numeric matrix or an object that can be coerced to a numeric matrix.
data	an optional data frame (or similar: see model.frame), used only if x is a formula. By default the variables are taken from environment(formula).
method	a character string, indicating the method for the computation of the required confidence interval. Options available are "z-transform" or "asymp" (see details in Lin, 1989, 2000).
level	the confidence level required, must be a single number between 0 and 1 (by default $95\%$ ).
equal.means	logical, should the means of the measuring devices be considered equal? In which case the restricted estimation is carried out under this assumption.
ustat	logical, should the concordance correlation coefficient be estimated using $U$ -statistics?
subset	an optional expression indicating the subset of the rows of data that should be used in the fitting process.
na.action	a function that indicates what should happen when the data contain NAs.

#### Value

A list with class 'ccc' containing the following named components:

call	a list containing an image of the ccc call that produced the object.
x	data.frame used in the estimation process.
ccc	estimate of the concordance correlation coefficient.
var.ccc	asymptotic variance of the concordance correlation coefficient estimate.
accuracy	estimate of the accuracy (or bias) coefficient that measures how far the best-fit line deviates from a line at 45 degrees. No deviation from the 45 degree line occurs when accuracy $= 1$ .
precision	estimate of the precision (or Pearson correlation) coefficient.

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shifts list with the location and scale shifts. Z-transformation parameter estimate. asymptotic variance of the Z-transformation parameter estimate. var.z confint confidence interval for the Lin's concordance correlation coefficient. bland a data frame with two columns containing the average of each pair of measurements, and difference between the measurements. the estimated mean vector. center the estimated covariance matrix. cov available only if ustat = TRUE, in which case this element corresponds to a list ustat containing the following elements rhoc, var. rhoc, ustat, and cov. available only if equal.means = TRUE, in which case this element corresponds Restricted to a list containing the following elements ccc, accuracy, precision, shifts, center, and cov.

#### References

Bland, J., Altman, D. (1986). Statistical methods for assessing agreement between two methods of clinical measurement. *The Lancet* **327**, 307-310.

King, T.S., Chinchilli, V.M. (2001). A generalized concordance correlation coefficient for continuous and categorical data. *Statistics in Medicine* **20**, 2131-2147.

King, T.S., Chinchilli, V.M. (2001). Robust estimators of the concordance correlation coefficient. *Journal of Biopharmaceutical Statistics* **11**, 83-105.

Lin, L. (1989). A concordance correlation coefficient to evaluate reproducibility. *Biometrics* **45**, 255-268.

Lin, L. (2000). A note on the concordance correlation coefficient. *Biometrics* **56**, 324-325.

Vallejos, R., Osorio, F., Ferrer, C. (2025+). A new coefficient to measure agreement between two continuous variables. Working paper.

10 cg

```
# ccc(x = ~ Mini + Large, data = x, method = "asymp")
#
# Coefficients:
# estimate variance accuracy precision
# 0.9427 0.0008 0.9994 0.9433
#
# Asymptotic 95% confidence interval:
# CCC SE lower upper
# 0.9427 0.0286 0.8867 0.9988
```

cg

Solve linear systems using the conjugate gradients method

# Description

Conjugate gradients (CG) method is an iterative algorithm for solving linear systems with positive definite coefficient matrices.

## Usage

```
cg(a, b, maxiter = 200, tol = 1e-7)
```

#### **Arguments**

a	a symmetric positive definite matrix containing the coefficients of the linear system.
b	a vector of right-hand sides of the linear system.
maxiter	the maximum number of iterations. Defaults to 200
tol	tolerance level for stopping iterations.

## Value

a vector with the approximate solution, the iterations performed are returned as the attribute 'iterations'.

#### Warning

The underlying C code does not check for symmetry nor positive definitiveness.

## References

Golub, G.H., Van Loan, C.F. (1996). *Matrix Computations*, 3rd Edition. John Hopkins University Press.

Hestenes, M.R., Stiefel, E. (1952). Methods of conjugate gradients for solving linear equations. *Journal of Research of the National Bureau of Standards* **49**, 409-436.

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#### See Also

```
jacobi, seidel, solve
```

## **Examples**

```
a <- matrix(c(4,3,0,3,4,-1,0,-1,4), ncol = 3)
b <- c(24,30,-24)
z <- cg(a, b)
z # converged in 3 iterations</pre>
```

cholupdate

Rank 1 update to Cholesky factorization

## **Description**

function cholupdate returns the upper triangular Cholesky factor of  $A + xx^T$ , where R is the original Cholesky factor of  $A = R^T R$ , with x a column vector of appropriate dimension.

## Usage

```
cholupdate(r, x)
```

## **Arguments**

- r a upper triangular matrix, the Cholesky factor of matrix a.
- x vector defining the rank one update.

#### References

Golub, G.H., Van Loan, C.F. (2013). *Matrix Computations*, 4th Edition. John Hopkins University Press.

# See Also

chol

```
a <- matrix(c(1,1,1,1,2,3,1,3,6), ncol = 3)
r <- chol(a)
x <- c(0,0,1)
b <- a + outer(x,x)
r1 <- cholupdate(r, x)
r1
all(r1 == chol(b)) # TRUE</pre>
```

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circulant

Form a symmetric circulant matrix

## **Description**

Forms a symmetric circulant matrix using a backwards shift of its first column

# Usage

```
circulant(x)
```

## Arguments

Χ

the first column to form the circulant matrix.

#### Value

A symmetric circulant matrix.

# **Examples**

```
x <- c(2,3,5,7,11,13)
circulant(x)
```

comm.info

Compact information to construct the commutation matrix

## **Description**

This function provides the minimum information required to create the commutation matrix.

The commutation matrix is a square matrix of order mn that, for an  $m \times n$  matrix A, transform vec(A) to  $vec(A^T)$ .

## Usage

```
comm.info(m = 1, n = m, condensed = TRUE)
```

## **Arguments**

a positive integer row dimension.

n a positive integer column dimension.

condensed logical. Information should be returned in compact form?

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#### **Details**

This function returns a list containing two vectors that represent an element of the commutation matrix and is accessed by the indexes in vectors row and col. This information is used by function comm.prod to do some operations involving the commutation matrix without forming it. This information also can be obtained using function commutation.

#### Value

A list containing the following elements:

row	vector of indexes, each entry represents the row index of the commutation matrix.
col	vector of indexes, each entry represents the column index of the commutation matrix. Only present if condensed = $FALSE$ .
m	positive integer, row dimension.
n	positive integer, column dimension.

#### References

Magnus, J.R., Neudecker, H. (1979). The commutation matrix: some properties and applications. *The Annals of Statistics* **7**, 381-394.

#### See Also

```
commutation, comm.prod
```

## **Examples**

```
z <- comm.info(m = 3, n = 2, condensed = FALSE)
z # where are the ones in commutation matrix of order '3,2'?

K32 <- commutation(m = 3, n = 2, matrix = TRUE)

K32 # only recommended if m and n are very small</pre>
```

comm.prod

Matrix multiplication envolving the commutation matrix

#### **Description**

Given the row and column dimensions of a commutation matrix K of order mn and a conformable matrix x, performs one of the matrix-matrix operations:

```
• Y=KX, if side = "left" and transposed = FALSE, or
• Y=K^TX, if side = "left" and transposed = TRUE, or
• Y=XK, if side = "right" and transposed = FALSE, or
• Y=XK^T, if side = "right" and transposed = TRUE.
```

The main aim of comm. prod is to do this matrix multiplication without forming the commutation matrix.

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#### Usage

```
comm.prod(m = 1, n = m, x = NULL, transposed = FALSE, side = "left")
```

## **Arguments**

m a positive integer row dimension.n a positive integer column dimension.

x numeric matrix (or vector).

transposed logical. Commutation matrix should be transposed?

side a string selecting if commutation matrix is pre-multiplying x, that is side =

"left" or post-multiplying x, by using side = "right".

#### **Details**

Underlying Fortran code only uses information provided by comm.info to performs the matrix multiplication. The commutation matrix is **never** created.

#### See Also

commutation

## **Examples**

```
K42 <- commutation(m = 4, n = 2, matrix = TRUE) x <- matrix(1:24, ncol = 3) y <- K42 %*% x z <- comm.prod(m = 4, n = 2, x) # K42 is not stored all(z == y) # matrices y and z are equal!
```

commutation

Commutation matrix

# **Description**

This function returns the commutation matrix of order mn which transforms, for an  $m \times n$  matrix A, vec(A) to  $vec(A^T)$ .

#### **Usage**

```
commutation(m = 1, n = m, matrix = FALSE, condensed = FALSE)
```

## Arguments

m a positive integer row dimension.n a positive integer column dimension.

matrix a logical indicating whether the commutation matrix will be returned.

condensed logical. Information should be returned in compact form?

corAR1

#### **Details**

This function is a wrapper function for the function comm.info. This function provides the minimum information required to create the commutation matrix. If option matrix = FALSE the commutation matrix is stored in two vectors containing the coordinate list of indexes for rows and columns. Option condensed = TRUE only returns vector of indexes for the rows of commutation matrix.

**Warning:** matrix = TRUE is **not** recommended, unless the order m **and** n be small. This matrix can require a huge amount of storage.

#### Value

Returns an mn by mn matrix (if requested).

#### References

Magnus, J.R., Neudecker, H. (1979). The commutation matrix: some properties and applications. *The Annals of Statistics* **7**, 381-394.

Magnus, J.R., Neudecker, H. (2007). *Matrix Differential Calculus with Applications in Statistics and Econometrics*, 3rd Edition. Wiley, New York.

#### See Also

```
comm.info
```

#### **Examples**

```
z <- commutation(m = 100, condensed = TRUE)
object.size(z) # 40.6 Kb of storage

z <- commutation(m = 100, condensed = FALSE)
object.size(z) # 80.7 Kb of storage

K100 <- commutation(m = 100, matrix = TRUE) # time: < 2 secs
object.size(K100) # 400 Mb of storage, do not request this matrix!

# a small example
K32 <- commutation(m = 3, n = 2, matrix = TRUE)
a <- matrix(1:6, ncol = 2)
v <- K32 %*% vec(a)
all(vec(t(a)) == as.vector(v)) # vectors are equal!</pre>
```

corAR1

AR(1) correlation structure

#### **Description**

This function is a constructor for the corAR1 correlation matrix representing an autocorrelation structure of order 1.

16 corCS

#### Usage

```
corAR1(rho, p = 2)
```

# **Arguments**

rho the value of the lag 1 autocorrelation, which must be between -1 and 1.

p dimension of the requested correlation matrix.

#### Value

Returns a p by p matrix.

## **Examples**

```
R < - corAR1(rho = 0.8, p = 5)
```

corCS

Compound symmetry correlation structure

## **Description**

This function is a constructor for the corCS correlation matrix representing a compound symmetry structure corresponding to uniform correlation.

## Usage

```
corCS(rho, p = 2)
```

# Arguments

rho the value of the correlation between any two correlated observations, which must

be between -1 and 1.

p dimension of the requested correlation matrix.

## Value

Returns a p by p matrix.

```
R < - corCS(rho = 0.8, p = 5)
```

cov.MSSD 17

cov.MSSD

Mean Square Successive Difference (MSSD) estimator of the covariance matrix

## **Description**

Returns a list containing the mean and covariance matrix of the data.

## Usage

```
cov.MSSD(x)
```

#### **Arguments**

Х

a matrix or data frame. As usual, rows are observations and columns are variables.

#### **Details**

This procedure uses the Holmes-Mergen method using the difference between each successive pairs of observations also known as Mean Square Successive Method (MSSD) to estimate the covariance matrix, which is given by

$$m{S}_{HD} = rac{1}{2(n-1)} \sum_{i=2}^{n} (m{x}_i - m{x}_{i-1}) (m{x}_i - m{x}_{i-1})^T.$$

#### Value

A list containing the following named components:

mean an estimate for the center (mean) of the data.

cov the estimated covariance matrix.

## References

Holmes, D.S., Mergen, A.E. (1993). Improving the performance of the  $T^2$  control chart. *Quality Engineering* 5, 619-625.

#### See Also

cov and var.

```
x <- cbind(1:10, c(1:3, 8:5, 8:10))
z0 <- cov(x)
z0
z1 <- cov.MSSD(x)
71</pre>
```

18 cov.weighted

cov.weighted

Weighted covariance matrices

## **Description**

Returns a list containing estimates of the weighted mean and covariance matrix of the data.

#### Usage

```
cov.weighted(x, weights = rep(1, nrow(x)))
```

#### **Arguments**

x a matrix or data frame. As usual, rows are observations and columns are vari-

ables.

weights a non-negative and non-zero vector of weights for each observation. Its length

must equal the number of rows of x.

#### **Details**

The covariance matrix is divided by the number of observations, which arise for instance, when we use the class of elliptical contoured distributions. Thus,

$$W_n = \sum_{i=1}^n w_i, \quad \overline{x}_n = \frac{1}{W_n} \sum_{i=1}^n w_i x_i \quad S_n = \frac{1}{n} \sum_{i=1}^n w_i (x_i - \overline{x}_n) (x_i - \overline{x}_n)^T.$$

This differs from the behaviour of function cov.wt.

#### Value

A list containing the following named components:

mean an estimate for the center (mean) of the data.

cov the estimated (weighted) covariance matrix.

#### References

Clarke, M.R.B. (1971). Algorithm AS 41: Updating the sample mean and dispersion matrix. *Applied Statistics* **20**, 206-209.

#### See Also

cov.wt, cov and var.

dupl.cross 19

## **Examples**

```
x <- cbind(1:10, c(1:3, 8:5, 8:10))
z0 <- cov.weighted(x) # all weights are 1
D2 <- Mahalanobis(x, center = z0$mean, cov = z0$cov)
p <- ncol(x)
wts <- (p + 1) / (1 + D2) # nice weights!
z1 <- cov.weighted(x, weights = wts)
z1</pre>
```

dupl.cross

Matrix crossproduct envolving the duplication matrix

## **Description**

Given the order of two duplication matrices and a conformable matrix X, this function performs the operation:  $Y = D_n^T X D_k$ , where  $D_n$  and  $D_k$  are duplication matrices of order n and k, respectively.

#### Usage

```
dupl.cross(n = 1, k = n, x = NULL)
```

## Arguments

- n order of the duplication matrix used pre-multiplying x.
- k order of the duplication matrix used post-multiplying x. By default k = n is used.
- x numeric matrix, this argument is required.

#### **Details**

This function calls dupl.prod to performs the matrix multiplications required but without forming any duplication matrices.

#### See Also

```
dupl.prod
```

```
D2 <- duplication(n = 2, matrix = TRUE)
D3 <- duplication(n = 3, matrix = TRUE)
x <- matrix(1, nrow = 9, ncol = 4)
y <- t(D3) %*% x %*% D2

z <- dupl.cross(n = 3, k = 2, x) # D2 and D3 are not stored
all(z == y) # matrices y and z are equal!

x <- matrix(1, nrow = 9, ncol = 9)
z <- dupl.cross(n = 3, x = x) # same matrix is used to pre- and post-multiplying x z # print result</pre>
```

20 dupl.info

dupl.i	nfo	Compact i

Compact information to construct the duplication matrix

# **Description**

This function provides the minimum information required to create the duplication matrix.

## Usage

```
dupl.info(n = 1, condensed = TRUE)
```

## **Arguments**

n order of the duplication matrix.

condensed logical. Information should be returned in compact form?

#### **Details**

This function returns a list containing two vectors that represent an element of the duplication matrix and is accessed by the indexes in vectors row and col. This information is used by function dupl.prod to do some operations involving the duplication matrix without forming it. This information also can be obtained using function duplication

#### Value

A list containing the following elements:

row vector of indexes, each entry represents the row index of the duplication matrix.

Only present if condensed = FALSE.

col vector of indexes, each entry represents the column index of the duplication

matrix.

order of the duplication matrix.

#### See Also

```
duplication, dupl.prod
```

```
z <- dupl.info(n = 3, condensed = FALSE)
z # where are the ones in duplication of order 3?

D3 <- duplication(n = 3, matrix = TRUE)
D3 # only recommended if n is very small</pre>
```

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dupl.prod

Matrix multiplication envolving the duplication matrix

## **Description**

Given the order of a duplication and a conformable matrix X, performs one of the matrix-matrix operations:

```
• m{Y} = m{D}m{X}, if side = "left" and transposed = FALSE, or • m{Y} = m{D}^Tm{X}, if side = "left" and transposed = TRUE, or
```

ullet  $oldsymbol{Y}=oldsymbol{X}oldsymbol{D},$  if side = "right" and transposed = FALSE, or

•  $oldsymbol{Y} = oldsymbol{X} oldsymbol{D}^T$ , if side = "right" and transposed = TRUE,

where D is the duplication matrix of order n. The main aim of dupl.prod is to do this matrix multiplication without forming the duplication matrix.

#### Usage

```
dupl.prod(n = 1, x, transposed = FALSE, side = "left")
```

## **Arguments**

n order of the duplication matrix.

x numeric matrix (or vector).

transposed logical. Duplication matrix should be transposed?

side a string selecting if duplication matrix is pre-multiplying x, that is side = "left" or post-multiplying x, by using side = "right".

#### **Details**

Underlying C code only uses information provided by dupl.info to performs the matrix multiplication. The duplication matrix is **never** created.

#### See Also

duplication

```
D4 <- duplication(n = 4, matrix = TRUE)
x <- matrix(1, nrow = 16, ncol = 2)
y <- crossprod(D4, x)

z <- dupl.prod(n = 4, x, transposed = TRUE) # D4 is not stored
all(z == y) # matrices y and z are equal!</pre>
```

22 duplication

duplication
-------------

Duplication matrix

# **Description**

This function returns the duplication matrix of order n which transforms, for a symmetric matrix A, vech(A) into vec(A).

## Usage

```
duplication(n = 1, matrix = FALSE, condensed = FALSE)
```

## **Arguments**

n order of the duplication matrix.

matrix a logical indicating whether the duplication matrix will be returned.

condensed logical. Information should be returned in compact form?.

#### **Details**

This function is a wrapper function for the function dupl.info. This function provides the minimum information required to create the duplication matrix. If option matrix = FALSE the duplication matrix is stored in two vectors containing the coordinate list of indexes for rows and columns. Option condensed = TRUE only returns vector of indexes for the columns of duplication matrix.

**Warning:** matrix = TRUE is **not** recommended, unless the order n be small. This matrix can require a huge amount of storage.

#### Value

```
Returns an n^2 by n(n+1)/2 matrix (if requested).
```

## References

Magnus, J.R., Neudecker, H. (1980). The elimination matrix, some lemmas and applications. *SIAM Journal on Algebraic Discrete Methods* **1**, 422-449.

Magnus, J.R., Neudecker, H. (2007). *Matrix Differential Calculus with Applications in Statistics and Econometrics*, 3rd Edition. Wiley, New York.

#### See Also

```
dupl.info
```

equilibrate 23

## **Examples**

equilibrate

Equilibration of a rectangular or symmetric matrix

# Description

Equilibrate a rectangular or symmetric matrix using 2-norm.

## Usage

```
equilibrate(x, scale = TRUE)
```

# Arguments

```
x a numeric matrix.
scale a logical value, x must be scaled to norm unity?
```

#### Value

For scale = TRUE, the equilibrated matrix. The scalings and an approximation of the condition number, are returned as attributes "scales" and "condition". If  $\boldsymbol{X}$  is a rectangular matrix, only the columns are equilibrated.

24 floyd

```
z <- equilibrate(x)
apply(z, 2, function(x) sum(x^2)) # all 1
xx <- crossprod(x)
equilibrate(xx)</pre>
```

floyd

Find the shortest paths in a directed graph

# Description

The Floyd-Warshall algorithm finds all shortest paths (if exist) in a directed graph.

# Usage

floyd(x)

## **Arguments**

Х

adjacency matrix of a directed graph. (i, j)-entry represents the weight (cost) of the edge from i to j if one exists and  $\infty$  otherwise.

## Value

Returns a list with final costs and the shortest path between two nodes.

## References

Floyd, R.W. (1962). Algorithm 97: Shortest Path. Communications of the ACM 5 (6), 345.

frank 25

frank

Frank matrix

## **Description**

This function returns the Frank matrix of order n.

# Usage

```
frank(n = 1)
```

# Arguments

n

order of the Frank matrix.

#### **Details**

A Frank matrix of order n is a square matrix  $\mathbf{F}_n = (f_{ij})$  defined as

$$f_{ij} = \begin{cases} n - j + 1, & i \le j, \\ n - j, & i = j + 1, \\ 0, & i \ge j + 2 \end{cases}$$

## Value

Returns an n by n matrix.

#### References

Frank, W.L. (1958). Computing eigenvalues of complex matrices by determinant evaluation and by methods of Danilewski and Wielandt. *Journal of the Society for Industrial and Applied Mathematics* **6**, 378-392.

```
F5 <- frank(n = 5)
det(F5) # equals 1
```

26 geomean

geomean

Geometric mean

## Description

It calculates the geometric mean using a Fused-Multiply-and-Add (FMA) compensated scheme for accurate computation of floating-point product.

## Usage

```
geomean(x)
```

# **Arguments**

Χ

a numeric vector containing the sample observations.

#### **Details**

If x contains any non-positive values, geomean returns NA and a warning message is displayed.

The geometric mean is a measure of central tendency, which is defined as

$$G = \sqrt[n]{x_1 x_2 \dots x_n} = \left(\prod_{i=1}^n x_i\right)^{1/n}.$$

This procedure calculates the product required in the geometric mean safely using a compensated scheme as proposed by Graillat (2009).

## Value

The geometric mean of the sample, a non-negative number.

#### References

Graillat, S. (2009). Accurate floating-point product and exponentiation. *IEEE Transactions on Computers* **58**, 994-1000.

Oguita, T., Rump, S.M., Oishi, S. (2005). Accurate sum and dot product. *SIAM Journal on Scientific Computing* **26**, 1955-1988.

#### See Also

```
mean, median.
```

```
set.seed(149)
x <- rlnorm(1000)
mean(x) # 1.68169
median(x) # 0.99663
geomean(x) # 1.01688</pre>
```

hadamard 27

hadamard

Hadamard product of two matrices

## **Description**

This function returns the Hadamard or element-wise product of two matrices X and Y, that have the same dimensions.

## Usage

```
hadamard(x, y = x)
```

## **Arguments**

```
x a numeric matrix or vector.
y a numeric matrix or vector.
```

#### Value

A matrix with the same dimension of X (and Y) which corresponds to the element-by-element product of the two matrices.

## References

Styan, G.P.H. (1973). Hadamard products and multivariate statistical analysis, *Linear Algebra and Its Applications* **6**, 217-240.

## **Examples**

```
x <- matrix(rep(1:10, times = 5), ncol = 5)
y <- matrix(rep(1:5, each = 10), ncol = 5)
z <- hadamard(x, y)
z</pre>
```

hankel

Form a symmetric Hankel matrix

## **Description**

Forms a symmetric Hankel matrix of order n from the values in vector  $\boldsymbol{x}$  and optionally the vector  $\boldsymbol{y}$ .

## Usage

```
hankel(x, y = NULL)
```

28 harris.test

## **Arguments**

x the first column to form the Hankel matrix.

y the last column of the Hankel matrix. If y is not provided only its first n skew diagonals are formed and the remaining elements are zeros. Otherwise, it is

assumed that  $x_n = y_1$ , and the first entry of vector y is discarded.

#### Value

A symmetric Hankel matrix of order n.

## **Examples**

```
x <- 1:4
y <- c(4,6,8,10)
# H4
hankel(x)
# H({1,2,3,4},{4,6,8,10})
hankel(x, y)</pre>
```

harris.test

Test for variance homogeneity of correlated variables

## **Description**

Performs large-sample methods for testing equality of  $p \ge 2$  correlated variables.

## Usage

```
harris.test(x, test = "Wald")
```

#### **Arguments**

x a matrix or data frame. As usual, rows are observations and columns are vari-

ables.

test test statistic to be used. One of "Wald" (default), "log", "robust" or "log-robust".

#### Value

A list of class 'harris.test' with the following elements:

statistic value of the statistic, i.e. the value of either Wald test, using the log-transformation,

or distribution-robust versions of the test (robust and log-robust).

parameter the degrees of freedom for the test statistic, which is chi-square distributed.

p.value the p-value for the test.

estimate the estimated covariance matrix.

method a character string indicating what type of test was performed.

helmert 29

#### References

Harris, P. (1985). Testing the variance homogeneity of correlated variables. *Biometrika* **72**, 103-107

#### **Examples**

```
x <- iris[,1:4]
z <- harris.test(x, test = "robust")
</pre>
```

helmert

Helmert matrix

## **Description**

This function returns the Helmert matrix of order n.

## Usage

$$helmert(n = 1)$$

#### **Arguments**

n

order of the Helmert matrix.

## **Details**

A Helmert matrix of order n is a square matrix defined as

$$\boldsymbol{H}_{n} = \begin{bmatrix} 1/\sqrt{n} & 1/\sqrt{n} & 1/\sqrt{n} & \dots & 1/\sqrt{n} \\ 1/\sqrt{2} & -1/\sqrt{2} & 0 & \dots & 0 \\ 1/\sqrt{6} & 1/\sqrt{6} & -2/\sqrt{6} & \dots & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ \frac{1}{\sqrt{n(n-1)}} & \frac{1}{\sqrt{n(n-1)}} & \frac{1}{\sqrt{n(n-1)}} & \dots & -\frac{(n-1)}{\sqrt{n(n-1)}} \end{bmatrix}.$$

Helmert matrix is orthogonal and is frequently used in the analysis of variance (ANOVA).

## Value

Returns an n by n matrix.

## References

Lancaster, H.O. (1965). The Helmert matrices. *The American Mathematical Monthly* **72**, 4-12. Gentle, J.E. (2007). *Matrix Algebra: Theory, Computations, and Applications in Statistics*. Springer, New York.

is.lower.tri

#### **Examples**

```
n <- 1000
set.seed(149)
x <- rnorm(n)

H <- helmert(n)
object.size(H) # 7.63 Mb of storage
K <- H[2:n,]
z <- c(K %*% x)
sum(z^2) # 933.1736

# same that
(n - 1) * var(x)</pre>
```

is.lower.tri

Check if a matrix is lower or upper triangular

# **Description**

Returns TRUE if the given matrix is lower or upper triangular matrix.

## Usage

```
is.lower.tri(x, diag = FALSE)
is.upper.tri(x, diag = FALSE)
```

# Arguments

```
x a matrix of other R object with length(dim(x)) = 2. diag logical. Should the diagonal be included?
```

# Value

Check if a matrix is lower or upper triangular. You can also include diagonal to the check.

## See Also

```
lower.tri, upper.tri
```

```
x <- matrix(rnorm(10 * 3), ncol = 3)
R <- chol(crossprod(x))
is.lower.tri(R)
is.upper.tri(R)</pre>
```

jacobi 31

jacobi

Solve linear systems using the Jacobi method

#### **Description**

Jacobi method is an iterative algorithm for solving a system of linear equations.

#### Usage

```
jacobi(a, b, start, maxiter = 200, tol = 1e-7)
```

## **Arguments**

a a square numeric matrix containing the coefficients of the linear system.

b a vector of right-hand sides of the linear system.

start a vector for initial starting point.

maxiter the maximum number of iterations. Defaults to 200

tol tolerance level for stopping iterations.

#### **Details**

Let D, L, and U denote the diagonal, lower triangular and upper triangular parts of a matrix A. Jacobi's method solve the equation Ax = b, iteratively by rewriting Dx + (L + U)x = b. Assuming that D is nonsingular leads to the iteration formula

$$x^{(k+1)} = -D^{-1}(L+U)x^{(k)} + D^{-1}b$$

#### Value

a vector with the approximate solution, the iterations performed are returned as the attribute 'iterations'.

#### References

Golub, G.H., Van Loan, C.F. (1996). *Matrix Computations*, 3rd Edition. John Hopkins University Press.

## See Also

seidel

```
a <- matrix(c(5,-3,2,-2,9,-1,3,1,-7), ncol = 3)
b <- c(-1,2,3)
start <- c(1,1,1)
z <- jacobi(a, b, start)
z # converged in 15 iterations</pre>
```

32 JarqueBera.test

JarqueBera	toct
Jaruuebera	. test

Jarque-Bera test for univariate normality

#### **Description**

Performs an omnibus test for univariate normality.

## Usage

```
JarqueBera.test(x, test = "DH")
```

#### **Arguments**

x a numeric vector containing the sample observations.

test statistic to be used. One of "DH" (Doornik-Hansen, the default), "JB"

(Jarque-Bera), "robust" (robust modification by Gel and Gastwirth), "ALM"

(Adjusted Lagrange multiplier).

#### Value

A list of class 'JarqueBera.test' with the following elements:

statistic value of the statistic, i.e. the value of either Doornik-Hansen, Jarque-Bera, or

Adjusted Lagrange multiplier test.

parameter the degrees of freedom for the test statistic, which is chi-square distributed.

p.value the p-value for the test.

skewness the estimated skewness coefficient.
kurtosis the estimated kurtosis coefficient.

method a character string indicating what type of test was performed.

# References

Doornik, J.A., Hansen, H. (2008). An omnibus test for univariate and multivariate normality. *Oxford Bulletin of Economics and Statistics* **70**, 927-939.

Gel, Y.R., Gastwirth, J.L. (2008). A robust modification of the Jarque-Bera test of normality. *Economics Letters* **99**, 30-32.

Jarque, C.M., Bera, A.K. (1980). Efficient tests for normality, homoscedasticity and serial independence of regression residuals. *Economics Letters* **6**, 255-259.

Urzua, C.M. (1996). On the correct use of omnibus tests for normality. *Economics Letters* **53**, 247-251.

kronecker.prod 33

# **Examples**

```
set.seed(149)
x <- rnorm(100)
z <- JarqueBera.test(x, test = "DH")
z
set.seed(173)
x <- runif(100)
z <- JarqueBera.test(x, test = "DH")
z</pre>
```

kronecker.prod

Kronecker product on matrices

## **Description**

Computes the kronecker product of two matrices, X and Y.

#### Usage

```
kronecker.prod(x, y = x)
```

## **Arguments**

x a numeric matrix or vector.

y a numeric matrix or vector.

## **Details**

Let X be an  $m \times n$  and Y a  $p \times q$  matrix. The  $mp \times nq$  matrix defined by

$$\left[\begin{array}{ccc} x_{11}Y & \dots & x_{1n}Y \\ \vdots & & \vdots \\ x_{m1}Y & \dots & x_{mn}Y \end{array}\right],$$

is called the  $Kronecker\ product$  of X and Y.

## Value

An array with dimensions dim(x) \* dim(y).

#### References

Magnus, J.R., Neudecker, H. (2007). *Matrix Differential Calculus with Applications in Statistics and Econometrics*, 3rd Edition. Wiley, New York.

## See Also

kronecker function from base package is based on outer. Our C version is slightly faster.

34 krylov

#### **Examples**

```
# block diagonal matrix:
a <- diag(1:3)
b <- matrix(1:4, ncol = 2)
kronecker.prod(a, b)

# examples with vectors
ones <- rep(1, 4)
y <- 1:3
kronecker.prod(ones, y) # 12-dimensional vector
kronecker.prod(ones, t(y)) # 3 x 3 matrix</pre>
```

krylov

Computes a Krylov matrix

# Description

Given A an n by n real matrix and an n-vector b, this function constructs the Krylov matrix K, where

$$\boldsymbol{K} = [\boldsymbol{b}, \boldsymbol{A}\boldsymbol{b}, \dots, \boldsymbol{A}^{m-1}\boldsymbol{b}].$$

## Usage

```
krylov(a, b, m = ncol(a))
```

## **Arguments**

a a numeric square matrix of order n by n for which the Krylov matrix is to be computed.

b a numeric vector of length n.

m length of the Krylov sequence.

#### Value

Returns an n by m matrix.

```
a <- matrix(c(1, 3, 2, -5, 1, 7, 1, 5, -4), ncol = 3, byrow = TRUE) b <- c(1, 1, 1) k <- krylov(a, b, m = 4) k
```

kurtosis 35

kurtosis

Mardia's multivariate skewness and kurtosis coefficients

## **Description**

Functions to compute measures of multivariate skewness  $(b_{1p})$  and kurtosis  $(b_{2p})$  proposed by Mardia (1970).

$$b_{1p} = \frac{1}{n^2} \sum_{i=1}^n \sum_{j=1}^n ((\boldsymbol{x}_i - \overline{\boldsymbol{x}})^T \boldsymbol{S}^{-1} (\boldsymbol{x}_j - \overline{\boldsymbol{x}}))^3,$$

and

$$b_{2p} = \frac{1}{n} \sum_{i=1}^{n} ((\boldsymbol{x}_i - \overline{\boldsymbol{x}})^T \boldsymbol{S}^{-1} (\boldsymbol{x}_i - \overline{\boldsymbol{x}}))^2.$$

# Usage

kurtosis(x)

skewness(x)

# **Arguments**

Х

matrix of data with, say, p columns.

#### References

Mardia, K.V. (1970). Measures of multivariate skewness and kurtosis with applications. *Biometrika* **57**, 519-530.

Mardia, K.V., Zemroch, P.J. (1975). Algorithm AS 84: Measures of multivariate skewness and kurtosis. *Applied Statistics* **24**, 262-265.

```
setosa <- iris[1:50,1:4]
kurtosis(setosa)
skewness(setosa)</pre>
```

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ldl

The LDL decomposition

## Description

Compute the LDL decomposition of a real symmetric matrix.

## Usage

ldl(x)

## **Arguments**

Χ

a symmetric numeric matrix whose LDL decomposition is to be computed.

#### Value

The factorization has the form  $X = LDL^T$ , where D is a diagonal matrix and L is unitary lower triangular.

The LDL decomposition of x is returned as a list with components:

lower the unitary lower triangular factor  $m{L}$ .

d a vector containing the diagonal elements of D.

#### References

Golub, G.H., Van Loan, C.F. (1996). *Matrix Computations*, 3rd Edition. John Hopkins University Press.

## See Also

chol

```
a <- matrix(c(2,-1,0,-1,2,-1,0,-1,1), ncol = 3)
z <- ldl(a)
z # information of LDL factorization

# computing det(a)
prod(z$d) # product of diagonal elements of D

# a non-positive-definite matrix
m <- matrix(c(5,-5,-5,3), ncol = 2)
try(chol(m)) # fails
ldl(m)</pre>
```

*Iu* 37

lu

The LU factorization of a square matrix

### Description

lu computes the LU factorization of a matrix.

# Usage

```
lu(x)
## Default S3 method:
lu(x)
## S3 method for class 'lu'
solve(a, b, ...)
is.lu(x)
```

# **Arguments**

x a square numeric matrix whose LU factorization is to be computed.

a an LU factorization of a square matrix.

b a vector or matrix of right-hand sides of equations.

... further arguments passed to or from other methods

#### **Details**

The LU factorization plays an important role in many numerical procedures. In particular it is the basic method to solve the equation Ax = b for given matrix A, and vector b.

```
solve.lu is the method for solve for lu objects.
```

```
is.lu returns TRUE if x is a list and inherits from "lu".
```

Unsuccessful results from the underlying LAPACK code will result in an error giving a positive error code: these can only be interpreted by detailed study of the Fortran code.

### Value

The LU factorization of the matrix as computed by LAPACK. The components in the returned value correspond directly to the values returned by DGETRF.

lu a matrix with the same dimensions as x. The upper triangle contains the U of

the decomposition and the strict lower triangle contains information on the  $m{L}$  of

the factorization.

pivot information on the pivoting strategy used during the factorization.

38 lu-methods

#### Note

To compute the determinant of a matrix (do you *really* need it?), the LU factorization is much more efficient than using eigenvalues (eigen). See det.

LAPACK uses column pivoting and does not attempt to detect rank-deficient matrices.

#### References

Anderson. E., Bai, Z., Bischof, C., Blackford, S., Demmel, J., Dongarra, J., Du Croz, J., Greenbaum, A., Hammarling, S., McKenney, A. Sorensen, D. (1999). *LAPACK Users' Guide*, 3rd Edition. SIAM.

Golub, G.H., Van Loan, C.F. (1996). *Matrix Computations*, 3rd Edition. John Hopkins University Press.

### See Also

extractL, extractU, constructX for reconstruction of the matrices, lu2inv

### **Examples**

```
a <- matrix(c(3,2,6,17,4,18,10,-2,-12), ncol = 3)
z <- lu(a)
z # information of LU factorization

# computing det(a)
prod(diag(z$lu)) # product of diagonal elements of U

# solve linear equations
b <- matrix(1:6, ncol = 2)
solve(z, b)</pre>
```

lu-methods

Reconstruct the L, U, or X matrices from an LU object

### **Description**

Returns the original matrix from which the object was constructed or the components of the factorization.

# Usage

```
constructX(x)
extractL(x)
extractU(x)
```

### **Arguments**

x object representing an LU factorization. This will typically have come from a previous call to lu.

lu2inv 39

# Value

construct X returns X, the original matrix from which the lu object was constructed (because of the pivoting the X matrix is not exactly the product between L and U).

```
extractL returns L. This may be pivoted.
```

extractU returns  $oldsymbol{U}$ .

### See Also

lu.

### **Examples**

```
a <- matrix(c(10,-3,5,-7,2,-1,0,6,5), ncol = 3)
z <- lu(a)
L <- extractL(z)
L
U <- extractU(z)
U
X <- constructX(z)
all(a == X)</pre>
```

lu2inv

 $Inverse\ from\ LU\ factorization$ 

### **Description**

Invert a square matrix from its LU factorization.

### Usage

```
lu2inv(x)
```

# Arguments

Χ

object representing an LU factorization. This will typically have come from a previous call to lu.

### Value

The inverse of the matrix whose LU factorization was given.

Unsuccessful results from the underlying LAPACK code will result in an error giving a positive error code: these can only be interpreted by detailed study of the Fortran code.

### **Source**

This is an interface to the LAPACK routine DGETRI. LAPACK is from https://netlib.org/lapack/ and its guide is listed in the references.

40 Mahalanobis

#### References

Anderson. E., Bai, Z., Bischof, C., Blackford, S., Demmel, J., Dongarra, J., Du Croz, J., Greenbaum, A., Hammarling, S., McKenney, A. Sorensen, D. (1999). *LAPACK Users' Guide*, 3rd Edition. SIAM.

Golub, G.H., Van Loan, C.F. (1996). *Matrix Computations*, 3rd Edition. John Hopkins University Press.

#### See Also

lu, solve.

### **Examples**

```
a <- matrix(c(3,2,6,17,4,18,10,-2,-12), ncol = 3)
z <- lu(a)
a %*% lu2inv(z)</pre>
```

Mahalanobis

Mahalanobis distance

# **Description**

Returns the squared Mahalanobis distance of all rows in x and the vector  $\mu$  = center with respect to  $\Sigma$  = cov. This is (for vector x) defined as

$$D^2 = (\boldsymbol{x} - \boldsymbol{\mu})^T \boldsymbol{\Sigma}^{-1} (\boldsymbol{x} - \boldsymbol{\mu})$$

#### Usage

Mahalanobis(x, center, cov, inverted = FALSE)

# **Arguments**

x vector or matrix of data. As usual, rows are observations and columns are vari-

ables.

center mean vector of the distribution.

cov covariance matrix  $(p \times p)$  of the distribution, must be positive definite.

inverted logical. If TRUE, cov is supposed to contain the *inverse* of the covariance matrix.

# Details

Unlike function mahalanobis, the covariance matrix is factorized using the Cholesky decomposition, which allows to assess if cov is positive definite. Unsuccessful results from the underlying LAPACK code will result in an error message.

### See Also

cov, mahalanobis

mardia.test 41

### **Examples**

```
x <- cbind(1:6, 1:3)
xbar <- colMeans(x)
S <- matrix(c(1,4,4,1), ncol = 2) # is negative definite
D2 <- mahalanobis(x, center = xbar, S)
all(D2 >= 0) # several distances are negative
## next command produces the following error:
## Covariance matrix is possibly not positive-definite
## Not run: D2 <- Mahalanobis(x, center = xbar, S)</pre>
```

mardia.test

Mardia test for multivariate normality

# **Description**

Performs Mardia's tests to assess multivariate normality based on the multivariate skewness and kurtosis coefficients.

# Usage

```
mardia.test(x)
```

### **Arguments**

x matrix of data with, say, p columns.

### Value

A list of class 'Mardia.test' with the following elements:

skewness a list containing the statistic, the degrees of freedom (parameter), the p. value

for the test and the estimated skewness coefficient.

kurtosis a list containig the statistic, the p. value for the test and the estimated kurtosis

coefficient.

# References

Mardia, K.V. (1970). Measures of multivariate skewness and kurtosis with applications. *Biometrika* **57**, 519-530.

Mardia, K.V. (1974). Applications of some measures of multivariate skewness and kurtosis in testing normality and robustness studies. *Sankhya* **36**, 115-128.

42 matrix.fun

### **Examples**

```
setosa <- iris[1:50,1:4]
z <- mardia.test(setosa)
z

set.seed(149)
Sigma <- matrix(c(10,3,3,2), ncol = 2)
x <- rmnorm(n = 300, Sigma = Sigma)
z <- mardia.test(x)
z</pre>
```

matrix.fun

Evaluate a matrix function

# **Description**

This function computes the matrix function F = f(A) where A is upper triangular by applying a Parlett recurrence.

### Usage

```
matrix.fun(a, FUN = "log")
```

# **Arguments**

a an upper triangular matrix.

FUN the function to be applied, by default "log".

### **Details**

The used-defined function FUN is evaluated at the triangular matrix argument. This function can be used in conjunction with Schur decomposition to evaluate the function of a matrix.

#### References

Higham, N.J. (1986). Functions of Matrices: Theory and Computation. Society for Industrial and Applied Mathematics, Philadelphia.

```
a <- matrix(c(1,2,3,0,3,4,0,0,5), ncol = 3, byrow = TRUE)
fnc <- function(x) (1 + x) / x
f <- matrix.fun(a, FUN = fnc)
f

a <- matrix(c(-49,24,-64,31), ncol = 2, byrow = TRUE)
z <- schur(a)
m <- z$m</pre>
```

matrix.inner 43

```
u <- z$vectors
m <- matrix.fun(m, FUN = exp)
u %*% m %*% t(u) # exp(a)</pre>
```

matrix.inner

Compute the inner product between two rectangular matrices

# Description

Computes the inner product between two rectangular matrices calling BLAS.

# Usage

```
matrix.inner(x, y = x)
```

# Arguments

x a numeric matrix.

y a numeric matrix.

#### Value

a real value, indicating the inner product between two matrices.

44 matrix.norm

matrix.norm

Compute the norm of a rectangular matrix

# **Description**

Computes a matrix norm of x using LAPACK. The norm can be the one ("1") norm, the infinity ("inf") norm, the Frobenius norm, the maximum modulus ("maximum") among elements of a matrix, as determined by the value of type.

# Usage

```
matrix.norm(x, type = "Frobenius")
```

### **Arguments**

x a numeric matrix.

type character string, specifying the *type* of matrix norm to be computed. A character

indicating the type of norm desired.

"1" specifies the **one** norm, (maximum absolute column sum);

"Inf" specifies the **inf**inity norm (maximum absolute row sum);
"Frobenius" specifies the **Frobenius** norm (the Euclidean norm of x treated

as if it were a vector);

"maximum" specifies the **maximum** modulus of all the elements in x.

#### **Details**

As function norm in package base, method of matrix.norm calls the LAPACK function DLANGE.

Note that the 1-, Inf- and maximum norm is faster to calculate than the Frobenius one.

### Value

The matrix norm, a non-negative number.

matrix.polynomial 45

```
n <- 1000
x <- .5 * diag(n) + 0.5 * matrix(1, nrow = n, ncol = n)
matrix.norm(x, type = "Frobenius")
matrix.norm(x, type = "1")
matrix.norm(x, type = "Inf")
matrix.norm(x, type = "maximum") # equal to 1
```

matrix.polynomial

Evaluates a real general matrix polynomial

# Description

Given  $c_0, c_1, \ldots, c_n$  coefficients of the polynomial and A an n by n matrix. This function computes the matrix polynomial

$$oldsymbol{B} = \sum_{k=0}^n c_k oldsymbol{A}^k,$$

using Horner's scheme, where  $A^0 = I$  is the n by n identity matrix.

# Usage

```
matrix.polynomial(a, coef = rep(1, power + 1), power = length(coef))
```

### **Arguments**

power

a	a numeric square matrix of order $n$ by $n$ for which the polinomial is to be computed.
coef	numeric vector containing the coefficients of the polinomial in order of increasing power.

a numeric exponent (which is forced to be an integer). If provided, coef is a vector of all ones. If the exponent is zero, the identity matrix is returned.

# Value

Returns an n by n matrix.

```
a <- matrix(c(1, 3, 2, -5, 1, 7, 1, 5, -4), ncol = 3, byrow = TRUE)
cf <- c(3, 1, 2)
b <- matrix.polynomial(a, cf)
b # 3 * diag(3) + a + 2 * a %*% a
b <- matrix.polynomial(a, power = 2)
b # diag(3) + a + a %*% a</pre>
```

46 matrix.sqrt

matrix.sqrt	Matrix square root
matrix.sqrt	маттх squa

### **Description**

This function computes a square root of an  $n \times n$  matrix A.

### Usage

```
matrix.sqrt(a, method = "DB", maxiter = 50, tol = 1e-8)
```

# **Arguments**

a a square matrix.

method the procedure used to obtain the square root. If method = "DB" (the default) the

matrix square root is obtained using a Newton's method. If method = "schur"

the Schur decomposition is considered.

maxiter the maximum number of iterations. Defaults to 50

tol a numeric tolerance.

#### **Details**

A square root of a square matrix A is obtained by solving the equation  $X^2 = A$ , considering the Newton iteration proposed by Denman and Beavers (1976), or alternatively is based on the Schur decomposition.

#### References

Denman, E.D., Beavers, A.N. (1976). The matrix sign function and computations in systems. *Applied Mathematics and Computation* **2**, 63-94.

Higham, N.J. (1986). Newton's method for the matrix square root. *Mathematics of Computation* **46**, 537-549.

Higham, N.J. (1986). Functions of Matrices: Theory and Computation. Society for Industrial and Applied Mathematics, Philadelphia.

```
a <- matrix(c(35,17,3,17,46,11,3,11,12), ncol = 3)
root <- matrix.sqrt(a) # 8 iterations

# just checking
root %*% root

root <- matrix.sqrt(a, method = "schur")</pre>
```

mchol 47

mcho1

The modified Cholesky factorization

# **Description**

Compute the Cholesky factorization of a real symmetric but not necessarily positive definite matrix.

# Usage

```
mchol(x)
```

### **Arguments**

Χ

a symmetric but not necessarily positive definite matrix to be factored.

### Value

The lower triangular factor of modified Cholesky decomposition, i.e., the matrix L such that  $X + E = LL^T$ , where E is a nonnegative diagonal matrix that is zero if X es sufficiently positive definite.

# References

```
Gill, P.E., Murray, W., Wright, M.H. (1981). Practical Optimization. Academic Press, London. Nocedal, J., Wright, S.J. (1999). Numerical Optimization. Springer, New York.
```

# See Also

```
chol, ldl
```

```
# a non-positive-definite matrix
a <- matrix(c(4,2,1,2,6,3,1,3,-.004), ncol = 3)
try(chol(a)) # fails
z <- mchol(a)
z # triangular factor

# modified 'a' matrix
tcrossprod(z)</pre>
```

48 mediancenter

mediancenter

Mediancenter

# **Description**

It calculates the mediancenter (or geometric median) of multivariate data.

# Usage

```
mediancenter(x)
```

#### **Arguments**

Х

a matrix or data frame. As usual, rows are observations and columns are variables.

### **Details**

The mediancenter for a sample of multivariate observations is computed using a steepest descend method combined with bisection. The mediancenter invariant to rotations of axes and is useful as a multivariate generalization of the median of univariate sample.

### Value

A list containing the following named components:

median an estimate for the mediancenter of the data.

iter the number of iterations performed, it is negative if a degenerate solution is

found.

# References

Gower, J.C. (1974). Algorithm AS 78: The mediancentre. Applied Statistics 23, 466-470.

#### See Also

```
cov.wt, median.
```

```
x <- cbind(1:10, c(1:3, 8:5, 8:10))
z <- mediancenter(x)$median # degenerate solution
xbar <- colMeans(x)
plot(x, xlab = "", ylab = "")
points(x = xbar[1], y = xbar[2], pch = 16, col = "red")
points(x = z[1], y = z[2], pch = 3, col = "blue", lwd = 2)</pre>
```

minkowski 49

minkowski

Computes the p-norm of a vector

# Description

Computes a p-norm of vector x. The norm can be the one (p=1) norm, Euclidean (p=2) norm, the infinity (p= Inf) norm. The underlying C or Fortran code is inspired on ideas of BLAS Level 1.

# Usage

```
minkowski(x, p = 2)
```

# **Arguments**

x a numeric vector.

p a number, specifying the *type* of norm desired. Possible values include real number greater or equal to 1, or Inf, Default value is p = 2.

# **Details**

Method of minkowski for p = Inf calls idamax BLAS function. For other values, C or Fortran subroutines using unrolled cycles are called.

# Value

The vector p-norm, a non-negative number.

```
# a tiny example
x <- rnorm(1000)
minkowski(x, p = 1)
minkowski(x, p = 1.5)
minkowski(x, p = 2)
minkowski(x, p = Inf)

x <- x / minkowski(x)
minkowski(x, p = 2) # equal to 1</pre>
```

50 moments

moments

Central moments

### **Description**

It calculates up to fourth central moments (or moments about the mean), and the skewness and kurtosis coefficients using an online algorithm.

# Usage

moments(x)

# **Arguments**

Χ

a numeric vector containing the sample observations.

### **Details**

The k-th central moment is defined as

$$m_k = \frac{1}{n} \sum_{i=1}^n (x_i - \overline{x})^k.$$

In particular, the second central moment is the variance of the sample. The sample skewness and kurtosis are defined, respectively, as

$$b_1 = \frac{m_3}{m_2^{3/2}}, \qquad b_2 = \frac{m_4}{m_2^2}.$$

#### Value

A list containing second, third and fourth central moments, and skewness and kurtosis coefficients.

# References

Spicer, C.C. (1972). Algorithm AS 52: Calculation of power sums of deviations about the mean. *Applied Statistics* **21**, 226-227.

#### See Also

var.

```
set.seed(149)
x <- rnorm(1000)
z <- moments(x)
z</pre>
```

ols 51

ols	Fit linear regression model	

# **Description**

Returns an object of class "ols" that represents a linear model fit.

# Usage

```
ols(formula, data, subset, na.action, method = "qr", tol = 1e-7, maxiter = 100, x = FALSE, y = FALSE, contrasts = NULL, ...)
```

### **Arguments**

formula	an object of class "formula" (or one that can be coerced to that class): a symbolic description of the model to be fitted.
data	an optional data frame, list or environment (or object coercible by as.data.frame to a data frame) containing the variables in the model. If not found in data, the variables are taken from environment (formula), typically the environment from which ols is called.
subset	an optional vector specifying a subset of observations to be used in the fitting process.
na.action	a function which indicates what should happen when the data contain NAs. The default is set by the na.action setting of options, and is na.fail if that is unset.
method	the least squares fitting method to be used; the options are "cg" (conjugate gradients), "chol", "qr" (the default), "svd" and "sweep".
tol	tolerance for the conjugate gradients (gc) method. Default is tol = 1e-7.
maxiter	The maximum number of iterations for the conjugate gradients (gc) method. Defaults to 100.
x, y	logicals. If TRUE the corresponding components of the fit (the model matrix, the response) are returned.
contrasts	an optional list. See the contrasts.arg of model.matrix.default.
	additional arguments (currently disregarded).

# Value

ols returns an object of class "ols".

The function summary is used to obtain and print a summary of the results. The generic accessor functions coefficients, fitted.values and residuals extract various useful features of the value returned by ols.

An object of class "ols" is a list containing at least the following components:

```
coefficients a named vector of coefficients
```

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```
residuals
                    the residuals, that is response minus fitted values.
fitted.values
                   the fitted mean values.
RSS
                   the residual sum of squares.
                   a p \times p matrix of (unscaled) covariances of the \hat{\beta}_j, j = 1, \dots, p.
cov.unscaled
call
                   the matched call.
                    the terms object used.
terms
                    (only where relevant) the contrasts used.
contrasts
                   if requested, the response used.
                   if requested, the model matrix used.
Χ
mode1
                   if requested (the default), the model frame used.
```

# See Also

```
ols.fit, lm, lsfit
```

### **Examples**

ols.fit

Fitter functions for linear models

### **Description**

This function is a *switcher* among various numerical fitting functions (ols.fit.cg, ols.fit.chol, ols.fit.qr, ols.fit.svd and ols.fit.sweep). The argument method does the switching: "qr" for ols.fit.qr, etc. This should usually *not* be used directly unless by experienced users.

# Usage

```
ols.fit(x, y, method = "qr", tol = 1e-7, maxiter = 100)
```

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# **Arguments**

X	design matrix of dimension $n \times q$ .
у	vector of observations of length $n$ .
method	currently, methods "cg", "chol", "qr" (default), "svd" and "sweep" are supported.
tol	tolerance for the conjugate gradients (gc) method. Default is tol = 1e-7.
maxiter	The maximum number of iterations for the conjugate gradients (gc) method.

Defaults to 100.

### Value

```
a list with components:
```

### See Also

```
ols.fit.cg, ols.fit.chol, ols.fit.qr, ols.fit.svd, ols.fit.sweep.
```

### **Examples**

```
set.seed(151)
n <- 100
p <- 2
x <- matrix(rnorm(n * p), n, p) # no intercept!
y <- rnorm(n)
fm <- ols.fit(x = x, y = y, method = "chol")
fm</pre>
```

ols.fit-methods

Fit a linear model

# **Description**

Fits a linear model, returning the bare minimum computations.

# Usage

```
ols.fit.cg(x, y, tol = 1e-7, maxiter = 100)
ols.fit.chol(x, y)
ols.fit.qr(x, y)
ols.fit.svd(x, y)
ols.fit.sweep(x, y)
```

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# Arguments

x, y	numeric vectors or matrices for the predictors and the response in a linear model. Typically, but not necessarily, x will be constructed by one of the fitting functions.
tol	tolerance for the conjugate gradients (gc) method. Default is tol = 1e-7.
maxiter	The maximum number of iterations for the conjugate gradients (gc) method. Defaults to 100.

### Value

The bare bones of an ols object: the coefficients, residuals, fitted values, and some information used by summary.ols.

### See Also

```
ols, ols.fit, lm
```

### **Examples**

```
set.seed(151)
n <- 100
p <- 2
x <- matrix(rnorm(n * p), n, p) # no intercept!
y <- rnorm(n)
z <- ols.fit.chol(x, y)</pre>
```

power.method

Power method to approximate dominant eigenvalue and eigenvector

# Description

The power method seeks to determine the eigenvalue of maximum modulus, and a corresponding eigenvector.

# Usage

```
power.method(x, only.value = FALSE, maxiter = 100, tol = 1e-8)
```

# **Arguments**

x a symmetric matrix.

only.value if TRUE, only the dominant eigenvalue is returned, otherwise both dominant

eigenvalue and eigenvector are returned.

maxiter the maximum number of iterations. Defaults to 100

tol a numeric tolerance.

rball 55

# Value

When only value is not true, as by default, the result is a list with components "value" and "vector". Otherwise only the dominan eigenvalue is returned. The performed number of iterations to reach convergence is returned as attribute "iterations".

#### See Also

eigen for eigenvalues and eigenvectors computation.

# **Examples**

```
n <- 1000

x <- .5 * diag(n) + 0.5 * matrix(1, nrow = n, ncol = n)

# dominant eigenvalue must be (n + 1) / 2

z <- power.method(x, only.value = TRUE)
```

rball

Generation of deviates uniformly distributed in a unitary ball

# Description

Random vector generation uniformly in the unitary ball.

# Usage

```
rball(n = 1, p = 2)
```

### **Arguments**

n the number of samples requested dimension of the unitary sphere

### **Details**

The function rball is an interface to C routines, which make calls to subroutines from BLAS.

# Value

If n = 1 a p-dimensional vector, otherwise a matrix of n rows of random vectors.

#### References

Hormann, W., Leydold, J., Derflinger, G. (2004). *Automatic Nonuniform Random Variate Generation*. Springer, New York.

### See Also

runif

56 ridge

# **Examples**

```
# generate the sample
z <- rball(n = 500)

# scatterplot of a random sample of 500 points uniformly distributed
# in the unitary ball
par(pty = "s")
plot(z, xlab = "x", ylab = "y")
title("500 points in the ball", font.main = 1)</pre>
```

ridge

Ridge regression

# **Description**

Fit a linear model by ridge regression, returning an object of class "ridge".

# Usage

```
ridge(formula, data, subset, lambda = 1.0, method = "GCV", ngrid = 200, tol = 1e-07,
   maxiter = 50, na.action, x = FALSE, y = FALSE, contrasts = NULL, ...)
```

# **Arguments**

formula	an object of class "formula" (or one that can be coerced to that class): a symbolic description of the model to be fitted.
data	an optional data frame, list or environment (or object coercible by as.data.frame to a data frame) containing the variables in the model. If not found in data, the variables are taken from environment(formula), typically the environment from which ridge is called.
subset	an optional vector specifying a subset of observations to be used in the fitting process.
na.action	a function which indicates what should happen when the data contain NAs. The default is set by the na.action setting of options, and is na.fail if that is unset.
lambda	a scalar or vector of ridge constants. A value of 0 corresponds to ordinary least squares.
method	the method for choosing the ridge parameter lambda. If method = "none", then lambda is 'fixed'. If method = "GCV" (the default) then the ridge parameter is chosen automatically using the generalized cross validation (GCV) criterion. For method = "grid", optimal value of lambda is selected computing the GCV criterion over a grid. If method = "MSE" the optimal ridge parameter is selected minimizing the mean squared estimation error criterion, this is the ORPS1 subroutine by Lee (1987).
ngrid	number of elements in the grid used to compute the GCV criterion. Only required if method = "grid" and lambda is a scalar.

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tol tolerance for the optimization of the GCV criterion. Default is 1e-7.

maxiter maximum number of iterations. The default is 50.

x, y logicals. If TRUE the corresponding components of the fit (the model matrix, the

response) are returned.

contrasts an optional list. See the contrasts.arg of model.matrix.default.

.. additional arguments to be passed to the low level regression fitting functions

(not implemented).

### **Details**

ridge function fits in linear ridge regression **without** scaling or centering the regressors and the response. In addition, If an intercept is present in the model, its coefficient is penalized.

#### Value

A list with the following components:

dims dimensions of model matrix.

coefficients a named vector of coefficients.
scale a named vector of coefficients.

fitted.values the fitted mean values.

residuals the residuals, that is response minus fitted values.

RSS the residual sum of squares.

edf the effective number of parameters.

GCV vector (if method = "grid") of GCV values.

HKB HKB estimate of the ridge constant.

LW LW estimate of the ridge constant.

lambda vector (if method = "grid") of lambda values; otherwise, for methods method

= "none", "GCV" or "MSE", the value of ridge parameter used by the algorithm.

optimal value of lambda with the minimum GCV (only relevant if method = "grid").

iterations number of iterations performed by the algorithm (only relevant if method =

"MSE").

call the matched call.

terms the terms object used.

contrasts (only where relevant) the contrasts used.

y if requested, the response used.

x if requested, the model matrix used.

model if requested, the model frame used.

58 rmnorm

### References

Golub, G.H., Heath, M., Wahba, G. (1979). Generalized cross-validation as a method for choosing a good ridge parameter. *Technometrics* **21**, 215-223.

Hoerl, A.E., Kennard, R.W., Baldwin, K.F. (1975). Ridge regression: Some simulations. *Communication in Statistics* **4**, 105-123.

Hoerl, A.E., Kennard, R.W. (1970). Ridge regression: Biased estimation of nonorthogonal problems. *Technometrics* **12**, 55-67.

Lawless, J.F., Wang, P. (1976). A simulation study of ridge and other regression estimators. *Communications in Statistics* **5**, 307-323.

Lee, T.S (1987). Algorithm AS 223: Optimum ridge parameter selection. *Applied Statistics* **36**, 112-118.

#### See Also

1m, ols

### **Examples**

```
z <- ridge(GNP.deflator ~ ., data = longley, lambda = 4, method = "grid")
z # ridge regression on a grid over seq(0, 4, length = 200)
z <- ridge(GNP.deflator ~ ., data = longley)
z # ridge parameter selected using GCV (default)</pre>
```

rmnorm

Multivariate normal random deviates

### **Description**

Random number generation from the multivariate normal (Gaussian) distribution.

# Usage

```
rmnorm(n = 1, mean = rep(0, nrow(Sigma)), Sigma = diag(length(mean)))
```

### **Arguments**

n the number of samples requested

mean a vector giving the means of each variable

Sigma a positive-definite covariance matrix

#### **Details**

The function rmnorm is an interface to C routines, which make calls to subroutines from LAPACK. The matrix decomposition is internally done using the Cholesky decomposition. If Sigma is not non-negative definite then there will be a warning message.

rsphere 59

# Value

If n = 1 a vector of the same length as mean, otherwise a matrix of n rows of random vectors.

#### References

Devroye, L. (1986). Non-Uniform Random Variate Generation. Springer-Verlag, New York.

### See Also

rnorm

### **Examples**

```
# covariance parameters
Sigma <- matrix(c(10,3,3,2), ncol = 2)
Sigma

# generate the sample
y <- rmnorm(n = 1000, Sigma = Sigma)
var(y)

# scatterplot of a random bivariate normal sample with mean
# vector zero and covariance matrix 'Sigma'
par(pty = "s")
plot(y, xlab = "", ylab = "")
title("bivariate normal sample", font.main = 1)

# QQ-plot of transformed distances
z <- WH.normal(y)
par(pty = "s")
qqnorm(z, main = "Transformed distances QQ-plot")
abline(c(0,1), col = "red", lwd = 2, lty = 2)</pre>
```

rsphere

Generation of deviates uniformly located on a spherical surface

# Description

Random vector generation uniformly on the sphere.

# Usage

```
rsphere(n = 1, p = 2)
```

# **Arguments**

n the number of samples requested dimension of the unitary sphere

60 scaled.condition

### **Details**

The function rsphere is an interface to C routines, which make calls to subroutines from BLAS.

#### Value

If n = 1 a p-dimensional vector, otherwise a matrix of n rows of random vectors.

#### References

Devroye, L. (1986). Non-Uniform Random Variate Generation. Springer-Verlag, New York.

# See Also

runif

### **Examples**

```
# generate the sample
z <- rsphere(n = 200)

# scatterplot of a random sample of 200 points uniformly distributed
# on the unit circle
par(pty = "s")
plot(z, xlab = "x", ylab = "y")
title("200 points on the circle", font.main = 1)</pre>
```

scaled.condition

Scaled condition number

### **Description**

Compute the scaled condition number of a rectangular matrix.

# Usage

```
scaled.condition(x, scales = FALSE)
```

# **Arguments**

x a numeric rectangular matrix.

scales a logical value indicating whether the scaling factors that allow balancing the columns of x should be returned by the function.

columns of x should be returned by the function

### Value

The columns of a rectangular matrix X are equilibrated (but not centered), then the scaled condition number is computed following the guidelines of Belsley (1990). If requested, the column scalings are returned as the attribute 'scales'.

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### References

Belsley, D.A. (1990). Conditioning Diagnostics: Collinearity and Weak Data in Regression. Wiley, New York.

# **Examples**

schur

The Schur decomposition of a square matrix

# **Description**

schur computes the Schur decomposition of an  $n \times n$  real matrix A.

### Usage

```
schur(x, vectors = TRUE)
```

# **Arguments**

x a square numeric matrix to be decomposed.

vectors logical, if TRUE (the default), then Schur vectors are returned.

#### **Details**

For an  $n \times n$  real matrix A, the Schur decomposition is given by,

$$A = QMQ^T$$

where Q is an orthogonal matrix and M is a quasi-upper triangular matrix. The column vectors Q (if requested) are the Schur vectors of A, and M is the Schur form of A.

Unsuccessful results from the underlying LAPACK code will result in an error giving a error code: these can only be interpreted by detailed study of the Fortran code.

62 seidel

#### Value

The Schur decomposition of the matrix as computed by LAPACK. The components in the returned value correspond directly to the values returned by DGEES.

m a matrix with the same dimensions as X. The upper triangle contains the M

matrix of the decomposition.

values a vector containing the n eigenvalues of X, these values are not ordered.

vectors an  $n \times n$  matrix whose columns contain the eigenvectors of X, only available

if it is requested.

#### References

Anderson. E., Bai, Z., Bischof, C., Blackford, S., Demmel, J., Dongarra, J., Du Croz, J., Greenbaum, A., Hammarling, S., McKenney, A. Sorensen, D. (1999). *LAPACK Users' Guide*, 3rd Edition. SIAM.

Golub, G.H., Van Loan, C.F. (1996). *Matrix Computations*, 3rd Edition. John Hopkins University Press.

### **Examples**

```
a <- matrix(c(7,12,-2,-3), ncol = 2)
z <- schur(a)
z # information of Schur decomposition

x <- matrix(c(0,0,1,2,1,0,2,2,1), ncol = 3)
z <- schur(x)
z # complex eigenvalues</pre>
```

seidel

Solve linear systems using the Gauss-Seidel method

# **Description**

Gauss-Seidel method is an iterative algorithm for solving a system of linear equations.

### Usage

```
seidel(a, b, start, maxiter = 200, tol = 1e-7)
```

# **Arguments**

a square numeric matrix containing the coefficients of the linear system.

b a vector of right-hand sides of the linear system.

start a vector for initial starting point.

maxiter the maximum number of iterations. Defaults to 200

tol tolerance level for stopping iterations.

sherman.morrison 63

### **Details**

Let D, L, and U denote the diagonal, lower triangular and upper triangular parts of a matrix A. Gauss-Seidel method solve the equation Ax = b, iteratively by rewriting (L + D)x + Ux = b. Assuming that L + D is nonsingular leads to the iteration formula

$$x^{(k+1)} = -(L+D)^{-1}Ux^{(k)} + (L+D)^{-1}b$$

### Value

a vector with the approximate solution, the iterations performed are returned as the attribute 'iterations'.

#### References

Golub, G.H., Van Loan, C.F. (1996). *Matrix Computations*, 3rd Edition. John Hopkins University Press.

#### See Also

jacobi

### **Examples**

```
a <- matrix(c(5,-3,2,-2,9,-1,3,1,-7), ncol = 3)
b <- c(-1,2,3)
start <- c(1,1,1)
z <- seidel(a, b, start)
z # converged in 10 iterations</pre>
```

sherman.morrison

Sherman-Morrison formula

### **Description**

The Sherman-Morrison formula gives a convenient expression for the inverse of the rank 1 update  $(A + bd^T)$  where A is a  $n \times n$  matrix and b, d are n-dimensional vectors. Thus

$$(A + bd^{T})^{-1} = A^{-1} - \frac{A^{-1}bd^{T}A^{-1}}{1 + d^{T}A^{-1}b}.$$

# Usage

```
sherman.morrison(a, b, d = b, inverted = FALSE)
```

# **Arguments**

a a numeric matrix.b a numeric vector.d a numeric vector.

inverted logical. If TRUE, a is supposed to contain its *inverse*.

64 sweep.operator

### **Details**

Method of sherman.morrison calls BLAS level 2 subroutines DGEMV and DGER for computational efficiency.

# Value

a square matrix of the same order as a.

### **Examples**

```
n <- 10
ones <- rep(1, n)
a <- 0.5 * diag(n)
z <- sherman.morrison(a, ones, 0.5 * ones)
7</pre>
```

sweep.operator

Gauss-Jordan sweep operator for symmetric matrices

# **Description**

Perform the sweep operation (or reverse sweep) on the diagonal elements of a symmetric matrix.

### Usage

```
sweep.operator(x, k = 1, reverse = FALSE)
```

# **Arguments**

x a symmetric matrix.

k elements (if k is vector) of the diagonal which will be sweeped.

reverse logical. If reverse = TRUE the reverse sweep is performed.

# **Details**

The symmetric sweep operator is a powerful tool in computational statistics with uses in stepwise regression, conditional multivariate normal distributions, MANOVA, and more.

### Value

a square matrix of the same order as x.

### References

Goodnight, J.H. (1979). A tutorial on the SWEEP operator. The American Statistician 33, 149-158.

symm.info 65

### **Examples**

symm.info

Compact information to construct the symmetrizer matrix

# **Description**

This function provides the information required to create the symmetrizer matrix.

# Usage

```
symm.info(n = 1)
```

### **Arguments**

n

order of the symmetrizer matrix.

#### **Details**

This function returns a list containing vectors that represent an element of the symmetrizer matrix and is accessed by the indexes in vectors row, col and values contained in val. This information is used by function symm.prod to do some operations involving the symmetrizer matrix without forming it. This information also can be obtained using function symmetrizer.

#### Value

A list containing the following elements:

row	vector of indexes, each entry represents the row index of the symmetrizer matrix.
col	vector of indexes, each entry represents the column index of the symmetrizer matrix.
val	vector of values, each entry represents the value of the symmetrizer matrix at element given by row and col indexes.
order	order of the symmetrizer matrix.

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### See Also

```
symmetrizer, symm.prod
```

# **Examples**

```
z <- symm.info(n = 3)
z # elements in symmetrizer matrix of order 3
N3 <- symmetrizer(n = 3, matrix = TRUE)
N3 # only recommended if n is very small</pre>
```

symm.prod

Matrix multiplication envolving the symmetrizer matrix

# Description

Given the order of a symmetrizer matrix N of order n and a conformable matrix X, performs one of the matrix-matrix operations:

```
    Y = NX, if side = "left", or
    Y = XN, if side = "right",
```

The main aim of symm.prod is to do this matrix multiplication **without forming** the symmetrizer matrix.

# Usage

```
symm.prod(n = 1, x = NULL, side = "left")
```

### **Arguments**

n order of the symmetrizer matrix.

x numeric matrix (or vector).

side a string selecting if symmetrizer matrix is pre-multiplying X, that is side = "left" or post-multiplying X, by using side = "right".

### **Details**

Underlying C code only uses information provided by symm.info to performs the matrix multiplication. The symmetrizer matrix is **never** created.

#### See Also

```
symmetrizer
```

symmetrizer 67

# **Examples**

```
N4 <- symmetrizer(n = 4, matrix = TRUE)
x <- matrix(1:32, ncol = 2)
y <- N4 %*% x

z <- symm.prod(n = 4, x) # N4 is not stored
all(z == y) # matrices y and z are equal!
```

symmetrizer

Symmetrizer matrix

### **Description**

This function returns the symmetrizer matrix of order n which transforms, for every  $n \times n$  matrix A, vec(A) into  $vec((A + A^T)/2)$ .

# Usage

```
symmetrizer(n = 1, matrix = FALSE)
```

# **Arguments**

n order of the symmetrizer matrix.

matrix a logical indicating whether the symmetrizer matrix will be returned.

### Details

This function is a wrapper function for the function symm.info. This function provides the information required to create the symmetrizer matrix. If option matrix = FALSE the symmetrizer matrix is stored in three vectors containing the coordinate list of indexes for rows, columns and the values.

**Warning:** matrix = TRUE is **not** recommended, unless the order n be small. This matrix can require a huge amount of storage.

### Value

Returns an  $n^2$  by  $n^2$  matrix (if requested).

### References

Abadir, K.M., Magnus, J.R. (2005). Matrix Algebra. Cambridge University Press.

Magnus, J.R., Neudecker, H. (2007). *Matrix Differential Calculus with Applications in Statistics and Econometrics*, 3rd Edition. Wiley, New York.

### See Also

```
symm.info
```

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### **Examples**

```
z <- symmetrizer(n = 100)
object.size(z) # 319 Kb of storage

N100 <- symmetrizer(n = 100, matrix = TRUE) # time: < 2 secs
object.size(N100) # 800 Mb of storage, do not request this matrix!

# a small example
N3 <- symmetrizer(n = 3, matrix = TRUE)
a <- matrix(rep(c(2,4,6), each = 3), ncol = 3)
a
b <- 0.5 * (a + t(a))
b
v <- N3 %*% vec(a)
all(vec(b) == as.vector(v)) # vectors are equal!</pre>
```

vec

Vectorization of a matrix

# Description

This function returns a vector obtained by stacking the columns of X.

# Usage

```
vec(x)
```

# Arguments

X

a numeric matrix.

### Value

Let X be a n by m matrix, then vec(X) is a nm-dimensional vector.

```
x <- matrix(rep(1:10, each = 10), ncol = 10)
x
y <- vec(x)
y</pre>
```

vech 69

vech

Vectorization the lower triangular part of a square matrix

# Description

This function returns a vector obtained by stacking the lower triangular part of a square matrix.

# Usage

```
vech(x)
```

# Arguments

Х

a square matrix.

#### Value

Let X be a n by n matrix, then  $\operatorname{vech}(X)$  is a n(n+1)/2-dimensional vector.

# **Examples**

```
x <- matrix(rep(1:10, each = 10), ncol = 10)
x
y <- vech(x)
y</pre>
```

WH.normal

Wilson-Hilferty transformation for chi-squared variates

# **Description**

Returns the Wilson-Hilferty transformation of random variables with chi-squared distribution.

# Usage

```
WH.normal(x)
```

# **Arguments**

Х

vector or matrix of data with, say, p columns.

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### **Details**

Let  $T=D^2/p$  be a random variable, where  $D^2$  denotes the squared Mahalanobis distance defined as

$$D^2 = (\boldsymbol{x} - \boldsymbol{\mu})^T \boldsymbol{\Sigma}^{-1} (\boldsymbol{x} - \boldsymbol{\mu})$$

Thus the Wilson-Hilferty transformation is given by

$$z = \frac{T^{1/3} - (1 - \frac{2}{9p})}{(\frac{2}{9p})^{1/2}}$$

and z is approximately distributed as a standard normal distribution. This is useful, for instance, in the construction of QQ-plots.

### References

Wilson, E.B., and Hilferty, M.M. (1931). The distribution of chi-square. *Proceedings of the National Academy of Sciences of the United States of America* 17, 684-688.

#### See Also

Mahalanobis

### **Examples**

```
x <- iris[,1:4]
z <- WH.normal(x)
par(pty = "s")
qqnorm(z, main = "Transformed distances QQ-plot")
abline(c(0,1), col = "red", lwd = 2, lty = 2)</pre>
```

whitening

Whitening transformation

# **Description**

Applies the whitening transformation to a data matrix based on the Cholesky decomposition of the empirical covariance matrix.

### Usage

```
whitening(x, Scatter = NULL)
```

### Arguments

x vector or matrix of data with, say, p columns.

Scatter covariance (or scatter) matrix  $(p \times p)$  of the distribution, must be positive definite.

If NULL, the covariance matrix is estimated from the data.

wilson.hilferty 71

### Value

Returns the whitened data matrix  $Z = XW^T$ , where

$$\mathbf{W}^T \mathbf{W} = \mathbf{S}^{-1}.$$

with S the empirical covariance matrix.

#### References

Kessy, A., Lewin, A., Strimmer, K. (2018). Optimal whitening and decorrelation. *The American Statistician* **72**, 309-314.

# **Examples**

```
x <- iris[,1:4]
species <- iris[,5]
pairs(x, col = species) # plot of Iris
# whitened data
z <- whitening(x)
pairs(z, col = species) # plot of</pre>
```

wilson.hilferty

Wilson-Hilferty transformation

### **Description**

Returns the Wilson-Hilferty transformation of random variables with Gamma distribution.

# Usage

```
wilson.hilferty(x, shape, rate = 1)
```

### **Arguments**

x a numeric vector containing Gamma distributed deviates.

shape, rate shape and rate parameters. Must be positive.

### **Details**

Let X be a random variable following a Gamma distribution with parameters a = shape and b = rate with density

$$f(x) = \frac{b^a}{\Gamma(a)} x^{a-1} \exp(-bx),$$

where  $x \ge 0$ , a > 0, b > 0 and consider the random variable T = X/(a/b). Thus, the Wilson-Hilferty transformation

$$z = \frac{T^{1/3} - (1 - \frac{1}{9a})}{(\frac{1}{9a})^{1/2}}$$

is approximately distributed as a standard normal distribution. This is useful, for instance, in the construction of QQ-plots.

72 wilson.hilferty

# References

Terrell, G.R. (2003). The Wilson-Hilferty transformation is locally saddlepoint. *Biometrika* **90**, 445-453.

Wilson, E.B., and Hilferty, M.M. (1931). The distribution of chi-square. *Proceedings of the National Academy of Sciences of the United States of America* **17**, 684-688.

### See Also

WH.normal

```
x <- rgamma(n = 300, shape = 2, rate = 1)
z <- wilson.hilferty(x, shape = 2, rate = 1)
par(pty = "s")
qqnorm(z, main = "Transformed Gamma QQ-plot")
abline(c(0,1), col = "red", lwd = 2, lty = 2)</pre>
```

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