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Mesoscale Discrete Element Model for Concrete and Its Combination with FEM

Jan Stránský

Department of Mechanics

Faculty of Civil Engineering

Czech Technical University in Prague

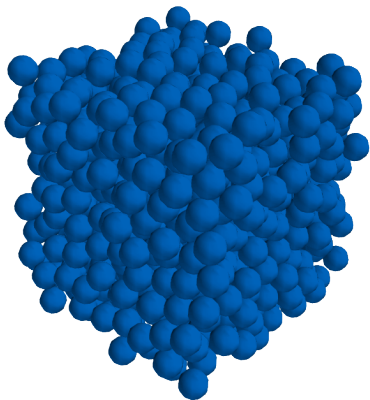
26th April 2018

- 1 Discrete element method
- 2 Macroscopic elastic properties of DEM models
- 3 DEM – FEM coupling
- 4 Mesoscale DEM model for concrete
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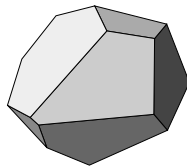
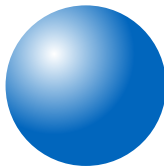
DISCRETE ELEMENT METHOD (DEM)

- **set of rigid particles**
- **various particle shapes**
- motion, contact detection
- Newton's laws of motion
- contact laws



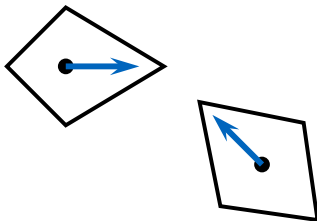
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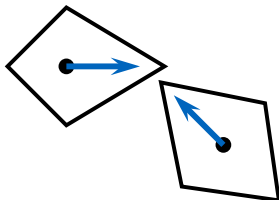


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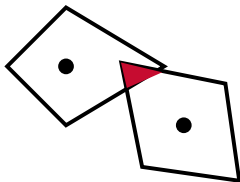
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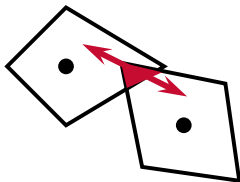
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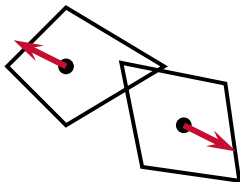
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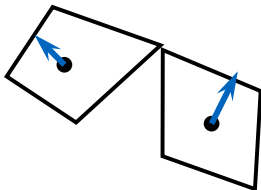
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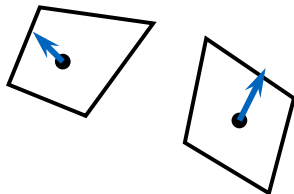


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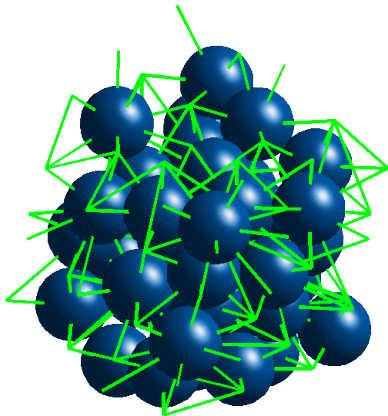


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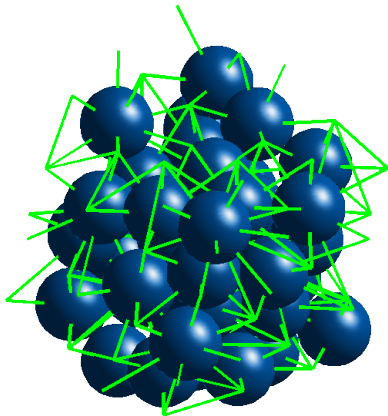


DISCRETE ELEMENT METHOD PARTICLE MODEL FOR CONCRETE

- **by Šmilauer & Jirásek**
- uniform spheres
- artificial discretization
- random close packing
- cohesive links
- interaction ratio
- normal and shear stress
- damage and plasticity
- uniaxial tests illustration

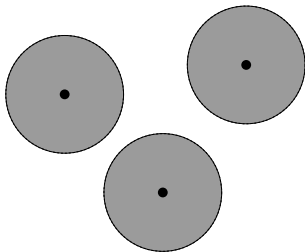
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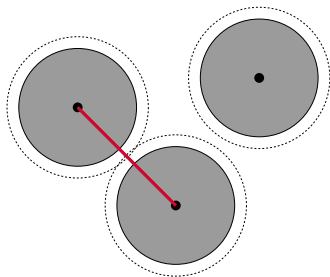
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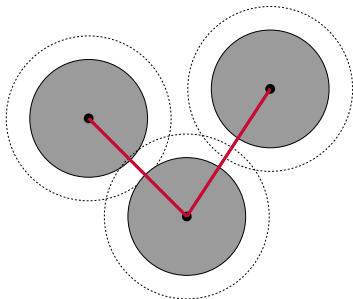
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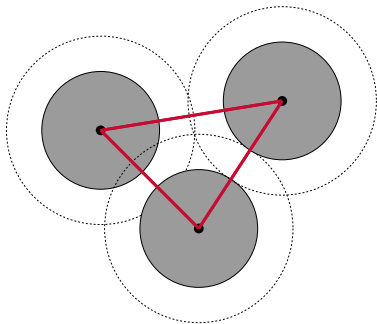
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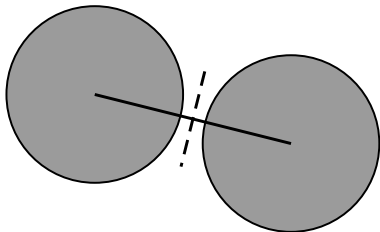
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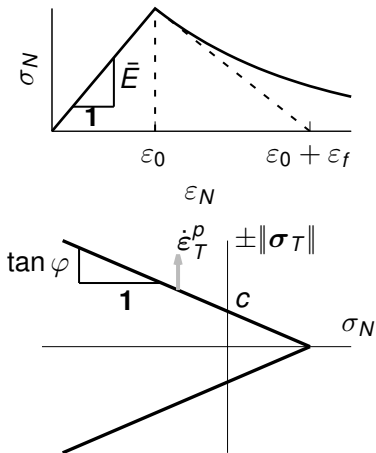
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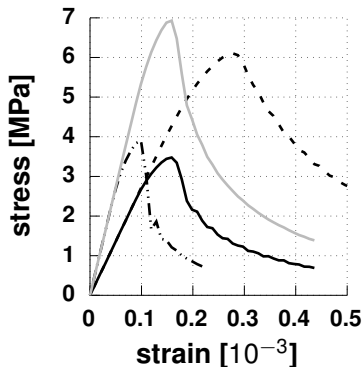
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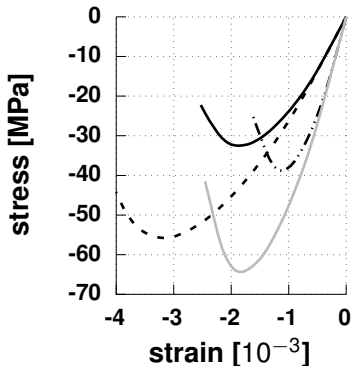
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micro parameters: \bar{E} , \bar{G}

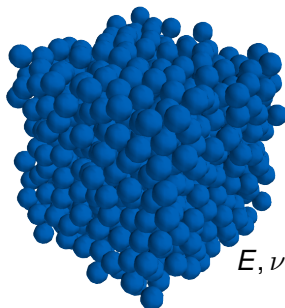
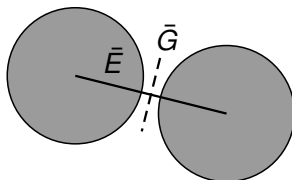
macro parameters: E , ν

Numerical solution

- dynamic DEM, static FEM
- periodic BCs

Analytical solution

- affine displacement
- stiffness tensor
- uniform distribution of link directions





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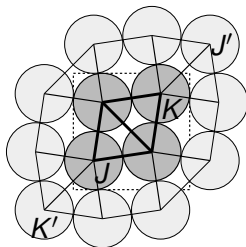
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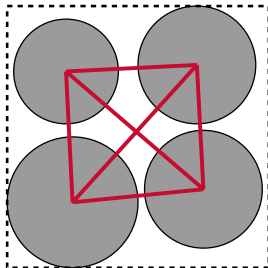
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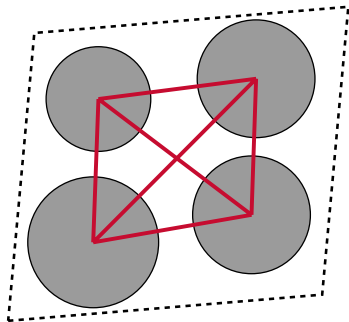
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$$\mathbb{D}_e = \frac{1}{V} \sum_c L^c A^c (\bar{E} \mathbf{N}^c + \bar{G} \mathbf{T}^c)$$

$$E = \frac{\sum L^c A^c}{3V} \cdot \frac{\bar{E} (2\bar{E} + 3\bar{G})}{4\bar{E} + \bar{G}}$$
$$\nu = \frac{\bar{E} - \bar{G}}{4\bar{E} + \bar{G}}$$



micro parameters: \bar{E}, \bar{G}

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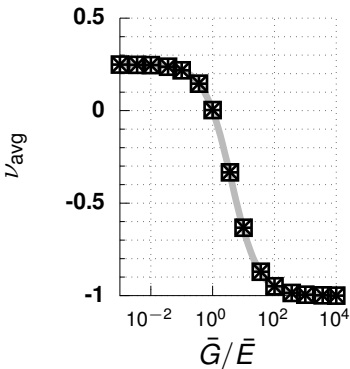
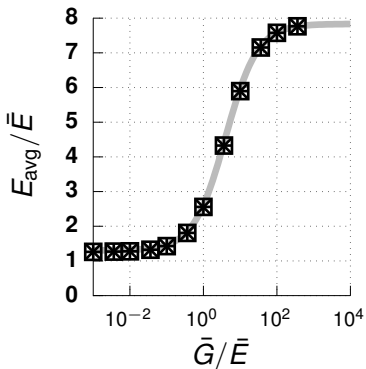
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MACROSCOPIC ELASTIC PROPERTIES OF DEM MODELS

RESULTS

interaction ratio = 1.50

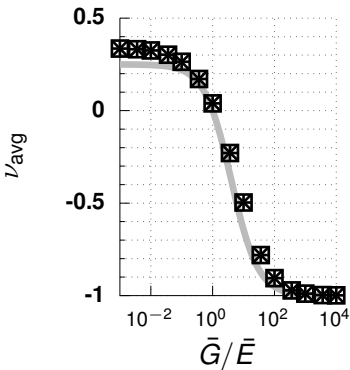
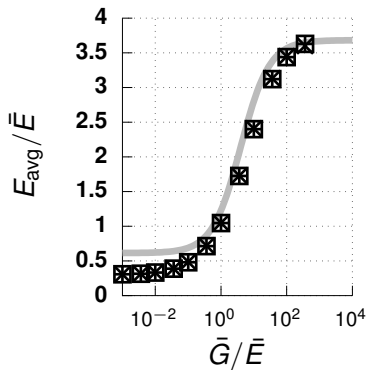




MACROSCOPIC ELASTIC PROPERTIES OF DEM MODELS

RESULTS

interaction ratio = 1.05



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DEM – FEM COUPLING

MOTIVATION

DEM

discrete domains



FEM

continuous domains



DEM

discrete domains



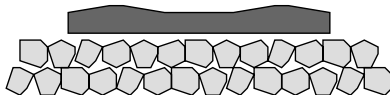
FEM

continuous domains

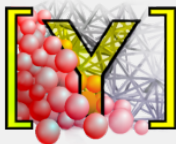


Combination

- **monolithic application – redoing what already exists**
- **combination of existing codes**



YADE



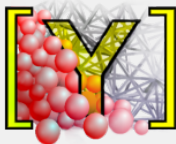
- DEM analysis
- free
- open source
- C++ core
- Python user interface

OOFEM



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YADE



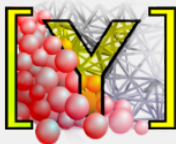
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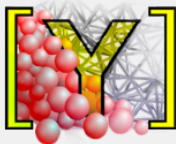
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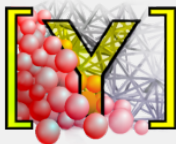
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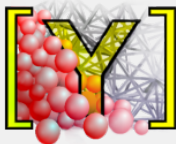
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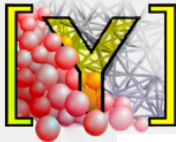


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DEM – FEM COUPLING MOTIVATION

YADE



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OOFEM

OOFEM.ORG

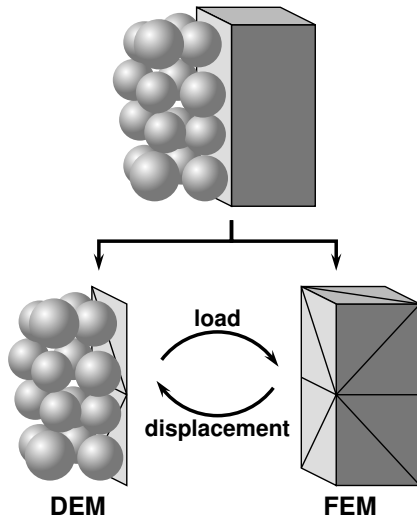
analysis

source

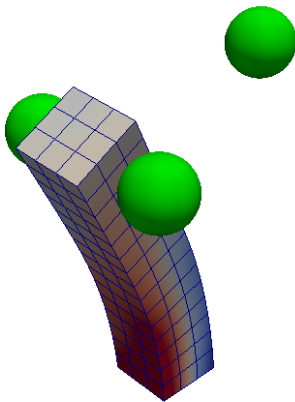
user interface



DEM – FEM COUPLING SURFACE COUPLING



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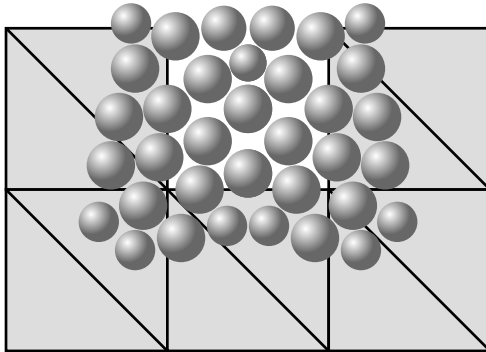




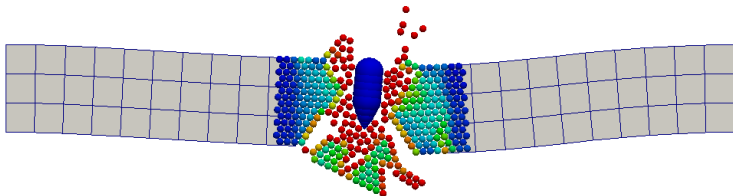
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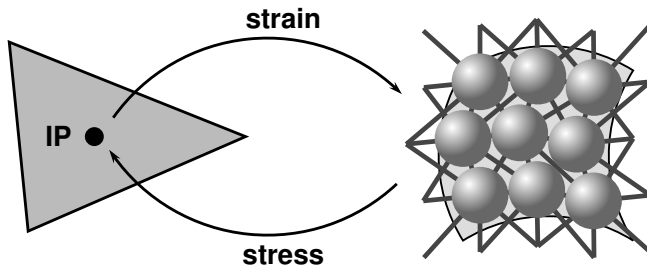
DEM – FEM COUPLING VOLUME COUPLING



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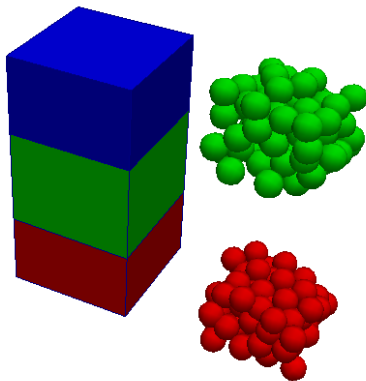


DEM – FEM COUPLING FE×DE (MULTISCALE) COUPLING



DEM – FEM COUPLING

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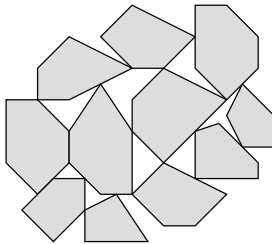




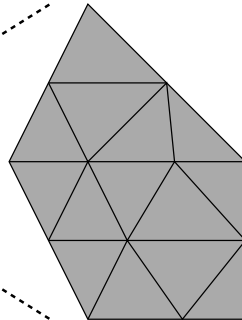
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DEM – FEM COUPLING CONTACT COUPLING

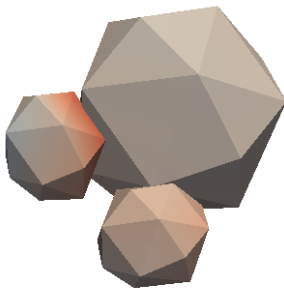


DEM



FEM

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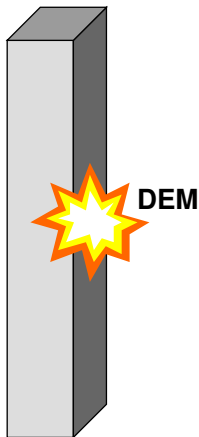
DEM – FEM COUPLING SEQUENTIAL COUPLING

- **Processes separable in time**
- FEM model for concrete by Grassl & Jirásek
- DEM ($\sigma_{DEM}, \Omega_{DEM}$) \rightarrow
 \rightarrow FEM ($\sigma, \omega, \kappa_D, \kappa_P$)



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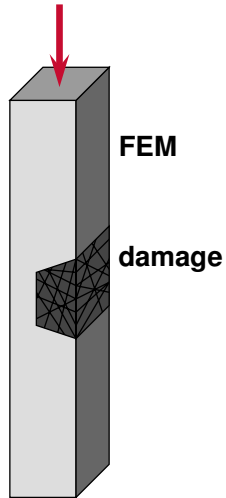


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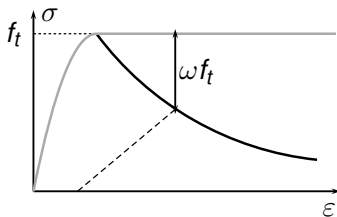
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$$\begin{aligned}\omega &= 0 \\ \kappa_D &= 0 \\ \kappa_P &< 1\end{aligned}$$

$$\begin{aligned}\omega &> 0 \\ \kappa_D &> 0 \\ \kappa_P &= \kappa_D + 1\end{aligned}$$

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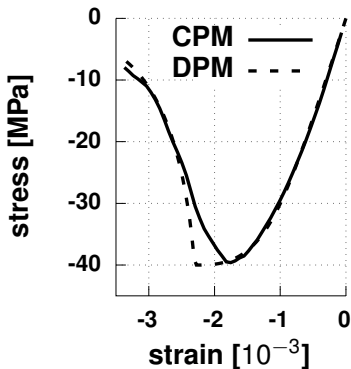
$$\Omega = -\frac{1}{2}\text{tr}(\Omega) \mathbf{1} + \frac{15}{2N} \sum_c \hat{\omega}^c \mathbf{n}^c \otimes \mathbf{n}^c =$$

$$= -\mathbf{1} \frac{3}{2N} \sum_c \hat{\omega}^c + \frac{15}{2N} \sum_c \hat{\omega}^c \mathbf{n}^c \otimes \mathbf{n}^c$$

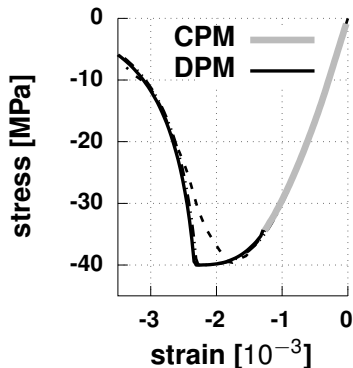
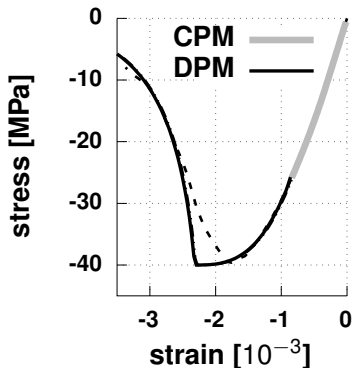
$$\omega_{FEM} = \omega(\Omega) = \omega(\Omega_1, \Omega_2, \Omega_3)$$

$$\kappa_D = \kappa_D(\omega), \kappa_P = \kappa_P(\omega)$$

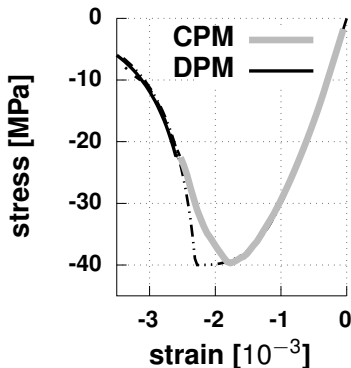
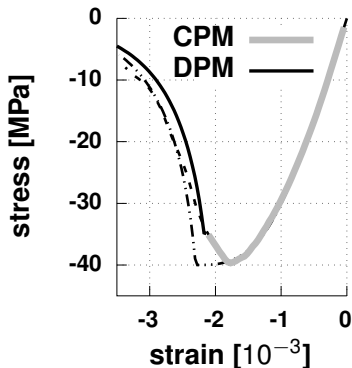
Results - uniaxial compression



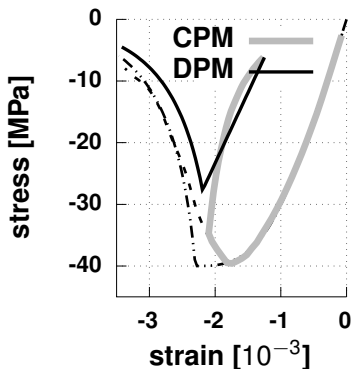
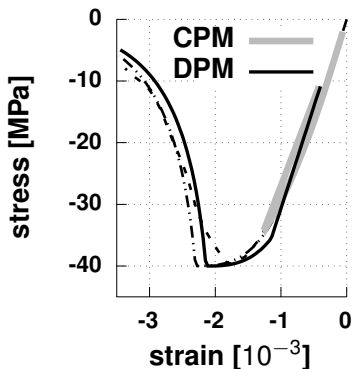
Results - uniaxial compression



Results - uniaxial compression

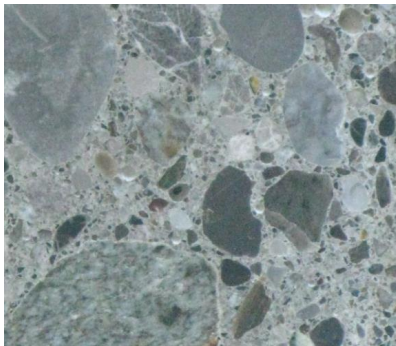


Results - uniaxial compression

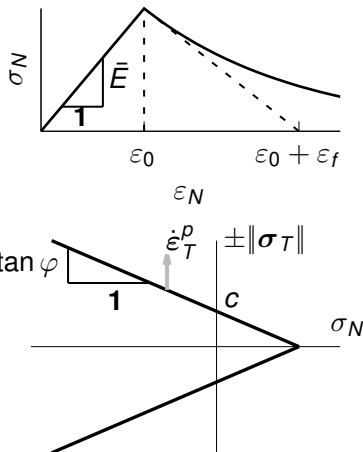


- 1 Discrete element method
- 2 Macroscopic elastic properties of DEM models
- 3 DEM – FEM coupling
- 4 Mesoscale DEM model for concrete**
- 5 Conclusions

- **three phase material**
 - **mortar matrix**
 - **aggregate inclusions**
 - **ITZ**
- one material model
- 2 types of DEM particles
- 3 types of links
- ITZ link
 - weaker
 - less stiff
 - more brittle



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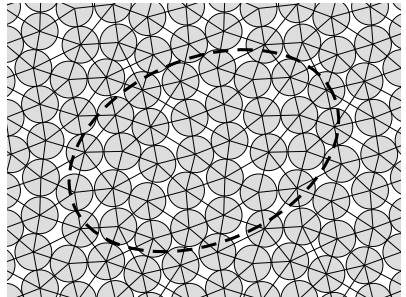


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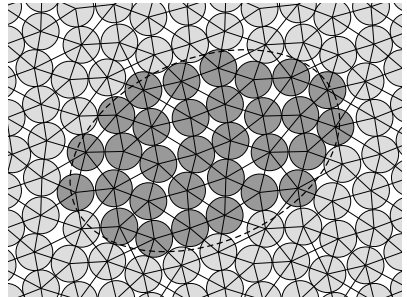
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MESOSCALE DEM MODEL FOR CONCRETE

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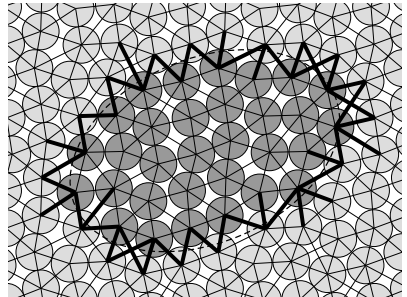


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MESOSCALE DEM MODEL FOR CONCRETE

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- **Experiment Beygi et al.**
- E, f_t, f_c, G_f
- different grading curves
- same total amount of aggregates
- two types of concrete

MESOSCALE DEM MODEL FOR CONCRETE VALIDATION

- Experiment Beygi et al.
- E, f_t, f_c, G_f
- different grading curves
- same total amount of aggregates
- two types of concrete

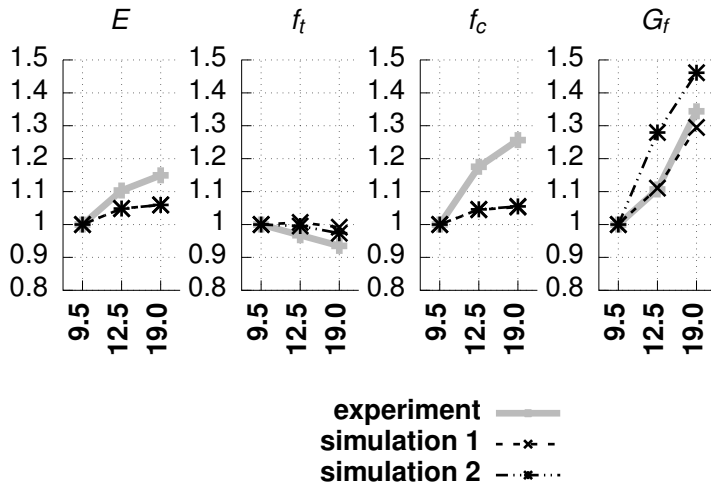
max. aggreg	9.5	12.5	19.0
powder	205	205	205
sand	917	917	917
4.75 - 9.5	750	300	300
9.5 - 12.5	-	450	300
12.5 - 19.0	-	-	150

MESOSCALE DEM MODEL FOR CONCRETE VALIDATION

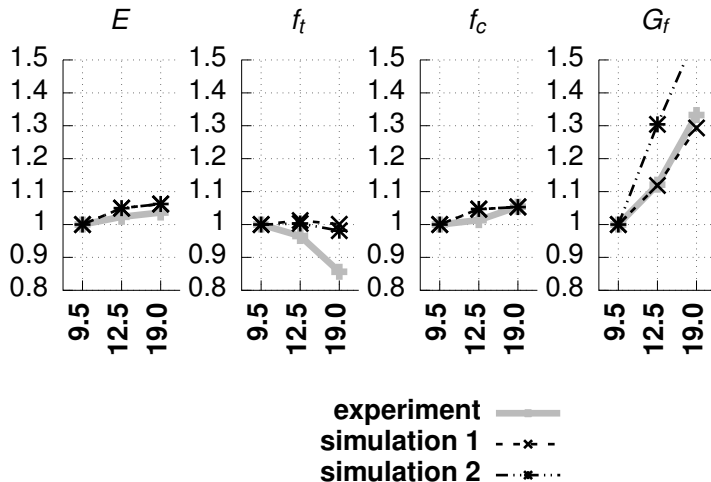
- Experiment Beygi et al.
- E, f_t, f_c, G_f
- different grading curves
- same total amount of aggregates
- two types of concrete

	C	W
low s.	325.8	187.0
high s.	422.4	160.7

MESOSCALE DEM MODEL FOR CONCRETE VALIDATION



MESOSCALE DEM MODEL FOR CONCRETE VALIDATION



- 1 Discrete element method
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Conclusions

- **macroscopic elastic properties of particle models**
- **discrete (couple) stress tensor**
- **DEM – FEM coupling, new open source package**
- **sequential DEM – FEM coupling**
- **mesoscale discrete element model for concrete**

Future work

- new formula for discrete couple stress tensor verification
- more detailed parameter study of MCPM
- more examples of sequential DEM – FEM coupling
- more examples of concurrent DEM – FEM coupling



Question

What other formulas for the evaluation of the couple stress tensor in a discrete system are used? What are their differences, advantages and disadvantages compared to the newly derived formula?

Answer

Bardet & Vardoulakis and Chang & Kuhn:

$$\mu_{ji} + \varepsilon_{jkl} \Sigma_{jlk} = \dots$$

$$\Sigma_{kji} + \Sigma_{jki} = \dots$$

New formula

$$V\bar{\mu} = V\mathbf{x}^0 \otimes (\mathbf{1} \times \bar{\sigma}) + \sum_e \mathbf{x} \otimes \mathbf{c}^e$$

Question

Volume or surface coupling of discrete and continuum methods usually leads to undesirable reflection and dispersion of waves on their interface. Does any of the methods eliminate this problem?

Answer

No.

Question

The mesoscale model presented in part 3 is composed of spherical particles. Their size has no physical interpretation and it seems that it may be chosen almost arbitrarily. Is the response of the model independent on the size of these particles?

Answer

- The model is **NOT** independent on particle size.
- For each particle size, the model should be calibrated independently.

Question

It is stated that it is possible to split the summation assuming uniform distribution of the product of contact areas and lengths in the equation 3.35. However, I have the impression that the distribution may be considered arbitrary. For the presented summation split, it is necessary to assume independence of the normal direction n and the product of contact areas and lengths AL .

Answer

$$\mathbf{D}_e = \frac{1}{V} \sum_c L^c A^c (\bar{\mathbf{E}} \mathbf{N}^c + \bar{\mathbf{G}} \mathbf{T}^c)$$

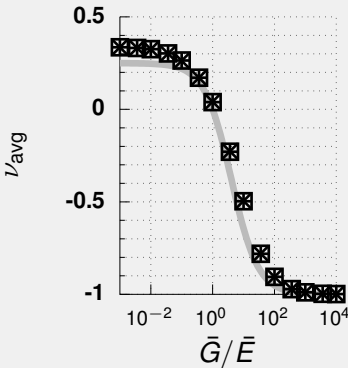
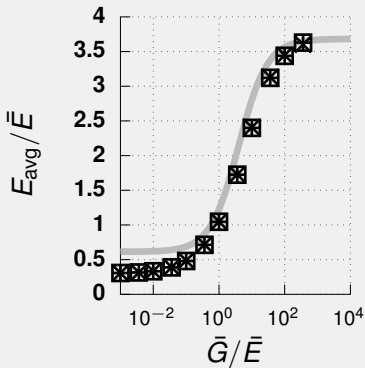
$$E = \frac{\sum L^c A^c}{3V} \cdot \frac{\bar{E} (2\bar{E} + 3\bar{G})}{4\bar{E} + \bar{G}}$$

$$\nu = \frac{\bar{E} - \bar{G}}{4\bar{E} + \bar{G}}$$

- I considered it as a part of the assumption of uniform distribution of link directions
- match of the results
- Least effect for low values of interaction ratio

Question

Figures 3.8-3.11 show the difference of derived analytical formula and the real macroscopic response for low and high values of interaction ratio. Is there a simple explanation of the observed dependency on interaction ratio? Why is the estimation of elastic parameters so much different for low values of interaction ratio?

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- systematic error in my evaluation
- not fulfilled assumptions of the gray estimation

Question

Is it possible to get such accurate estimation also for non-spherical particles (like ellipsoids) for the whole range of shear and normal stiffness?

Answer

I believe yes, but have not tested it nor did any research.

Question

Please, explain in more detail your statement from page 9:

A “small” change of positions of particles can cause a sudden (“big”) change of the stiffness of the system. For this reason, implicit integration schemes are in general not suitable for numerical solution and an explicit time integration scheme is usually applied to solve equations of motion

Answer

- not very good expressions, *not suitable* is too strong
- *sudden change of stiffness* = zero or nonzero stiffness
- What I meant: explicit time integration is “less complex”

Question

You assume an affine displacement of individual particles. This kinematic assumption is not fulfilled for heterogeneous materials because of perturbations of displacement field due to spatially variable stiffness. What is the influence of this assumption on the accuracy of obtained properties, with respect to the results presented in section 3.4.2?

Answer

- **method is designed for homogeneous materials**
- **for heterogeneous material, each phase could be evaluated independently and another homogenization method could be used to determine overall elastic parameters.**

Question

Please, explain in more detail your statement on page 43:

The resulting (couple) stress tensor does not depend on the choice of the point of moment equilibrium.

The resulting (couple) stress tensor does not depend on the choice of particles' reference points.

Answer









These are necessary conditions for macro (couple) stress tensor according to Chang & Kuhn.

Question

Please, explain what you have tried to show with table 4.1 on page 46.

Answer

Simple illustration of (couple) stress tensor

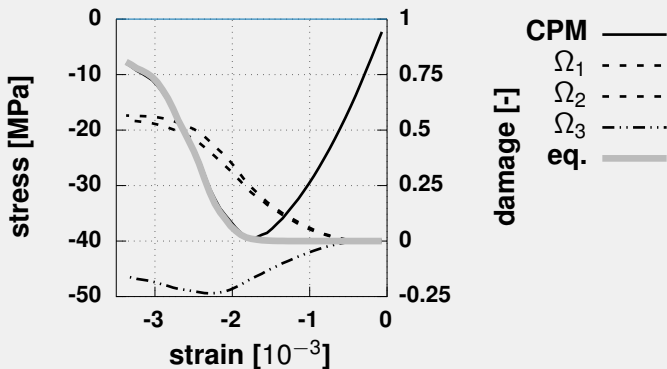
	σ	μ		σ	μ
	$\begin{bmatrix} \cdot & \cdot \\ \cdot & \cdot \end{bmatrix}$	$\begin{bmatrix} \cdot & \cdot \\ \cdot & \cdot \end{bmatrix}$		$\begin{bmatrix} \cdot & \cdot \\ \cdot & \cdot \end{bmatrix}$	$\begin{bmatrix} \cdot & 2 \\ \cdot & \cdot \end{bmatrix}$
	$\begin{bmatrix} 2 & \cdot \\ \cdot & \cdot \end{bmatrix}$	$\begin{bmatrix} \cdot & \cdot \\ \cdot & \cdot \end{bmatrix}$		$\begin{bmatrix} \cdot & \cdot \\ \cdot & \cdot \end{bmatrix}$	$\begin{bmatrix} \cdot & 1 \\ \cdot & \cdot \end{bmatrix}$
	$\begin{bmatrix} 1 & \cdot \\ \cdot & \cdot \end{bmatrix}$	$\begin{bmatrix} \cdot & \cdot \\ \cdot & \cdot \end{bmatrix}$		$\begin{bmatrix} \cdot & 2 \\ \cdot & \cdot \end{bmatrix}$	$\begin{bmatrix} \cdot & \cdot \\ \cdot & \cdot \end{bmatrix}$
	$\begin{bmatrix} \cdot & 2 \\ 2 & \cdot \end{bmatrix}$	$\begin{bmatrix} \cdot & \cdot \\ \cdot & \cdot \end{bmatrix}$		$\begin{bmatrix} \cdot & \cdot \\ 1 & \cdot \end{bmatrix}$	$\begin{bmatrix} \cdot & \cdot \\ \cdot & \cdot \end{bmatrix}$

Question

Please, explain based on which considerations you got the calibration formulas in equations (6.17)-(6.19)

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IN PRAGUE**DISCUSSION****JAN ZEMAN, QUESTION 5****Answer**

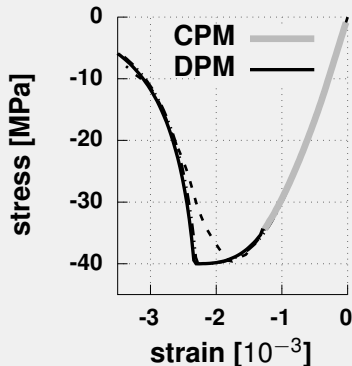
$$\omega = 2.09 (0.85\Omega_1 + 0.15\Omega_3)^{4.7}$$



Answer

if $\omega \leq m$ then $\kappa_D = 0, \kappa_P = \kappa_P(\omega), \omega = 0$

$$m = 5 \cdot 10^{-4}, \quad \kappa_P = 0.3 + 900\omega$$



Question

Results in figure 8.6 should be explained better. For example, it is not clear what is the meaning of the vertical axis and how the results reflect the influence of the transition zone (as was declared in the objectives of the doctoral thesis).

Answer

- *Since the absolute values of macroscopic quantities can be relatively easily estimated, only values relative to the results for the smallest aggregate size are plotted.*
- More detailed parameter study could be done to assess influence of ITZ.