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$$w^* = \underset{w}{\operatorname{argmin}} \left\{ \sum_{i=1}^N L(w, x_i, y_i) + \lambda \sum_{j=1}^d |w_j|^p \right\} \quad [1]$$

Problem 1: show that the objective in (1) is equivalent to

$$w^* = \underset{w}{\operatorname{argmin}} \sum_{i=1}^N L(w, x_i, y_i) \quad [2]$$

subject to $\sum_{j=1}^d |w_j|^p \leq r$

Proof: Both [1] and [2] are convex and smooth

The solution for the first problem is for $j \in [d]$:

$$\sum_{i=1}^N \frac{\partial L(\hat{w}, x_i, y_i)}{\partial w_j} + \lambda p |\hat{w}_j|^{p-1} \cdot \operatorname{sgn}(\hat{w}_j) = 0$$

The KKT condition of the second problem is

$$\sum_{i=1}^N L(w, x_i, y_i) + u \left(r - \sum_{j=1}^d |w_j|^p \right) \quad (3)$$

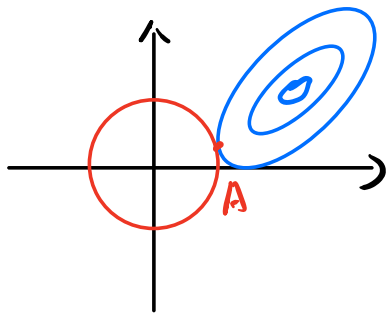
for $j \in [d]$ $\sum_{i=1}^N \frac{\partial L(\hat{w}, x_i, y_i)}{\partial w_j} - u p |\hat{w}_j|^{p-1} \cdot \operatorname{sgn}(\hat{w}_j) = 0$

and

$$u \left(r - \sum_{j=1}^d |\hat{w}_j|^p \right) = 0$$

First of all. By KKT, only when u and $r - \sum_{j=1}^d |w_j|^p$ equals to zero. Now observe that when $u = -\lambda$, then essentially (1) and (3) are doing the same minimization problem as λr is a constant term. Hence, we can substitute $u = -\lambda$

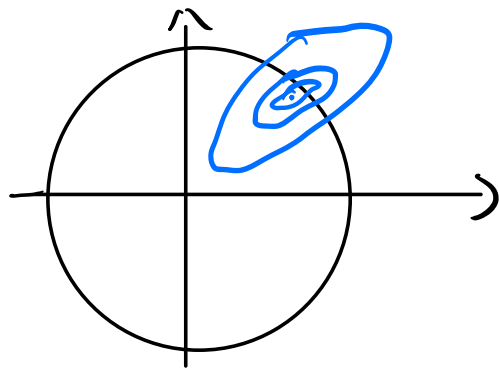
Case 1: if $r = \sum_{j=1}^d |w_j|$, graphically this corresponds to the following case



$r = \sum_{j=1}^d |\hat{w}_j|^p$, so the optimal solution is taken when the constraint and the objective touches each other

In this case, $\mu \neq 0$. Now observe that when $\mu = -\lambda$, then essentially (1) and (3) are doing the same minimization problem as λr is a constant term. Hence, if $\lambda \neq 0$ in [1], then let $r = \sum_{j=1}^d |w_j|^p$ in [2].

Case 2: if $\mu = 0$, then $\lambda = 0$, $r > \sum_{j=1}^d |w_j|^p$



Graphically, this corresponds to the case when the constraint includes the w^* , so we don't need to find the "tangency point" and the constraint is loose at the optimal

Hence, to summarize the solution

$$\begin{cases} \text{if } \lambda = 0 & \text{then } r > \sum_{j=1}^d |\hat{w}_j|^p \\ \text{if } \lambda > 0 & \text{then } r = \sum_{j=1}^d |\hat{w}_j|^p \end{cases} \left(\hat{w}_j \text{ depends on the dataset} \right)$$

Problem 2

$$y = w \cdot x + r, \quad r \sim N(0, \sigma_x^2) \quad (3)$$

Without knowing anything else besides the assumption in (3), can we compute the maximum likelihood estimate for the linear regression parameters w from a given dataset under this noise model?

Answer: No, we cannot.

for a given (x, y)

$$p(y|x, w, \sigma_x) = \prod_{i=1}^N p(y_i | x_i; w, \sigma_{x_i})$$

$$\hat{w}_L = \arg \max_w \prod_{i=1}^N \frac{1}{\sigma_{x_i} \sqrt{2\pi}} \exp \left(- \frac{(y_i - f(x_i; w))^2}{2\sigma_{x_i}^2} \right)$$

The problem is in this setting, we do not know the value of each σ_{x_i} which corresponds to x_i . In other words, we don't have exact knowledge about the distribution of any certain y_i , so we cannot calculate the term containing σ_{x_i} in the above expression.

Problem 3 Now suppose we know the value of the noise variance $\sigma_{x_i}^2$ at every training input x_i for $i=1, \dots, N$. Can we compute maximum likelihood estimate for w ?

Answer. Yes, we can.

$$p(y, x, w, \sigma_x) = \prod_{i=1}^N p(y_i | x_i; w, \sigma_{x_i})$$

$$\hat{w}_L = \underset{w}{\operatorname{argmax}} \prod_{i=1}^N \frac{1}{\sigma_{x_i} \sqrt{2\pi}} \exp \left(-\frac{(y_i - f(x_i, w))^2}{2\sigma_{x_i}^2} \right)$$

We know the value of each x_i, y_i, σ_{x_i} for $i \in [N]$

Hence, \hat{w}_L can be calculated using the above formula.

The intuition is we know the distribution of the noise now, so we can measure how close y_i is from $f(x_i, w)$ [the likelihood that y_i can be explained by the parameter]

$$\log p(y | x; w, \sigma) = \frac{1}{N} \sum_{i=1}^N \left[-\frac{(y_i - f(x_i, w))^2}{2\sigma_{x_i}^2} - \log \sigma_{x_i} \sqrt{2\pi} \right]$$

$$= -\frac{1}{2N} \sum_{i=1}^N \left[\frac{(y_i - f(x_i, w))^2}{\sigma_{x_i}^2} \right] - \frac{1}{N} \sum_{i=1}^N \log \sigma_{x_i} - \log \sqrt{2\pi}$$

$$\text{Hence } \underset{w}{\operatorname{argmax}} \log p(y | x; w, \sigma) = \underset{w}{\operatorname{argmin}} \sum_{i=1}^N \frac{(y_i - f(x_i, w))^2}{2\sigma_{x_i}^2}$$

$g(w) = \sum_{i=1}^N \frac{(y_i - f(x_i; w))^2}{2\sigma_{x_i}^2}$ is convex, optimal point taken when

FOC is satisfied.

$$\frac{\partial g(w)}{\partial w_i} = 0 \quad \text{for } i \in [n]$$

w is the vector that satisfies all of the FOC constraints.

Problem 4: Show that the softmax model is over parameterized.
 that is, show that for any w_c for $c=1, \dots, C$, there is a different
 value that yields exactly the same $p(y|x)$ for every x .
 Then show for $C=2$ softmax is equivalent to logistic regression.

Pf: Let θ be a fixed vector, consider $w_c - \theta$

$$\begin{aligned} p(y=c|x) &= \frac{\exp[(w_c - \theta) \cdot x]}{\sum_{k=1}^C \exp[(w_k - \theta) \cdot x]} \\ &= \frac{\exp[w_c \cdot x] / \exp(\theta \cdot x)}{\sum_{k=1}^C \exp(w_k \cdot x) / \exp(\theta \cdot x)} \\ &= \frac{\exp(w_c \cdot x)}{\sum_{k=1}^C \exp(w_k \cdot x)} = \text{softmax}(w_c \cdot x) \end{aligned}$$

Hence, if (w_1, w_2, \dots, w_C) minimizes the log loss, then
 $(w_1 - \theta, w_2 - \theta, \dots, w_C - \theta)$ also minimizes the log loss.

Since choice of θ is arbitrary, we can set $\theta = w_k$ for $k \in [C]$,
 then the k -th row of W will become $w_k - w_k = \vec{0}$. We just need
 to optimize the other $C-1$ parameters of the softmax.

For softmax when $C=2$, we have

$$p(y=1|x) = \frac{\exp(w_1 \cdot x)}{\exp(w_1 \cdot x) + \exp(w_2 \cdot x)}$$

$$\begin{aligned}
 &= \frac{\exp(w_1 x) / \exp(w_0 x)}{[\exp(w_1 x) / \exp(w_0 x)] + 1} \\
 &= \frac{\exp[(w_1 - w_0)x]}{1 + \exp[(w_1 - w_0)x]} \\
 &= \frac{1}{1 + e^{-(w_1 - w_0)x}}
 \end{aligned}$$

This is exactly the form of logistic regression.

Problem 5:

(a) the log loss of the linear C-way softmax classification model using feature mapping $\phi(x)$

Answer:

$$\text{Let } p(\gamma^{(i)} = c | x) = \frac{\exp(W_c \cdot x^{(i)})}{\sum_{j=1}^C \exp(W_j \cdot x^{(i)})}$$

$$L(w) = -\frac{1}{N} \sum_{i=1}^N \sum_{k=1}^C \mathbb{1}\{\gamma^{(i)} = k\} \cdot \log(p(\gamma^{(i)} = k | x^{(i)}))$$

(b) its gradient with respect to w

WLOG, consider $\frac{\partial L(w)}{\partial w_1}$

$$\frac{\partial L(w)}{\partial w_1} = -\frac{1}{N} \sum_{i=1}^N \left[\frac{\partial}{\partial w_1} \left[\mathbb{1}\{\gamma^{(i)} = 1\} \cdot \log \left(\frac{e^{w_1 \cdot x^{(i)}}}{\sum_{j=1}^C e^{w_j \cdot x^{(i)}}} \right) \right. \right. \\ \left. \left. + \dots + \mathbb{1}\{\gamma^{(i)} = c\} \cdot \log \left(\frac{e^{w_c \cdot x^{(i)}}}{\sum_{j=1}^C e^{w_j \cdot x^{(i)}}} \right) \right] \right]$$

First deal with:

$$\frac{\partial}{\partial w_1} \left[\mathbb{1}\{\gamma^{(i)} = 1\} \cdot \log \left(\frac{e^{w_1 \cdot x^{(i)}}}{\sum_{j=1}^C e^{w_j \cdot x^{(i)}}} \right) \right]$$

$$= \frac{\partial}{\partial w_1} \left[\mathbb{1}\{\gamma^{(i)} = 1\} \cdot \left(w_1 \cdot x^{(i)} - \log \sum_{j=1}^C e^{w_j \cdot x^{(i)}} \right) \right]$$

$$= \mathbb{1}\{\gamma^{(i)}=1\} \cdot x^{(i)} - \mathbb{1}\{\gamma^{(i)}=1\} \cdot \frac{\exp(w_1 \cdot x^{(i)}) \cdot x^{(i)}}{\sum_{j=1}^C \exp(w_j \cdot x^{(i)})}$$

Then deal with $k \neq 1$, wLOG, $k=2$.

$$2 \left[\mathbb{1}\{\gamma^{(i)}=2\} \cdot \log \left(\frac{e^{w_2 \cdot x^{(i)}}}{\sum_{j=1}^C e^{w_j \cdot x^{(i)}}} \right) \right]$$

$$= \frac{2w_1}{2w_1} \left[\mathbb{1}\{\gamma^{(i)}=2\} \cdot (w_2 \cdot x^{(i)} - \log \sum_{j=1}^C e^{w_j \cdot x^{(i)}}) \right]$$

$$= - \mathbb{1}\{\gamma^{(i)}=2\} \cdot \frac{\exp(w_1 \cdot x^{(i)}) \cdot x^{(i)}}{\sum_{j=1}^C \exp(w_j \cdot x^{(i)})}$$

$$\text{Hence } \frac{\partial L(w)}{\partial w_1} = -\frac{1}{N} \sum_{i=1}^N \left[\mathbb{1}\{\gamma^{(i)}=1\} \cdot x^{(i)} - \frac{\exp(w_1 \cdot x^{(i)}) \cdot x^{(i)}}{\sum_{j=1}^C \exp(w_j \cdot x^{(i)})} \right]$$

$$\text{Hence, the new parameter } w_{t+1} \text{ is}$$

$$w_{t+1} = w_t + \frac{1}{N} \cdot 2 \cdot \sum_{i=1}^N x^{(i)} \cdot \left(\mathbb{1}\{\gamma^{(i)}=k\} - \frac{\exp(w_k \cdot x^{(i)})}{\sum_{j=1}^C \exp(w_j \cdot x^{(i)})} \right)$$

α is the learning rate

Problem 6 is written in haichuan-wang-sol2-P6.ipynb.

Problem 8 is written in haichuan-wang-sol2-P8.ipynb.