

TNR 14

GuiRng

Guido's World Language reference Introduction

GuiR Setup Help

Reload Step Execute Abort

13
12
11
10
9
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5
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2
1

1 2 3 4 5 6 7 8 9

Robots position is 5 5 N and carrying 0 beepers

Code editor World editor

File Edit

```
1 define hadapkanan:  
2   turnleft  
3   turnleft  
4   turnleft  
5  
6   move  
7   move  
8   move  
9   move  
10  move  
11  hadapkanan  
12  move  
13  move  
14  move  
15  hadapkanan  
16  move  
17  move  
18  hadapkanan  
19  move  
20  hadapkanan  
21  move  
22  turnoff
```

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21/09/2019

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1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 16 17

Robots position is 15 6 E and carrying 64 beepers

Code editor World editor

File Edit

```
1 define jalan2:
2   move
3   putbeeper
4   move
5   putbeeper
6 define jalan1:
7   move
8   putbeeper
9 define hadapkanan:
10  turnleft
11  turnleft
12  turnleft
13 define jalan3:
14  move
15  turnleft
16  move
17  putbeeper
18
19 jalan2
20 jalan1
21 move
22 hadapkanan
23 jalan2
24 move
25 hadapkanan
26 jalan2
27 move
28 turnleft
29 jalan2
30 move
31 turnleft
32 jalan2
33 jalan1
34 move
35 move
36 move
37 move
38 move
39 turnleft
40 putbeeper
```

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1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 16 17

Robots position is 15 6 E and carrying 64 beepers

Code editor World editor

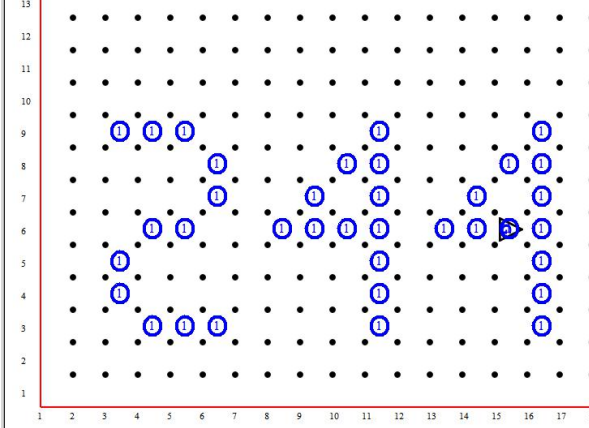
File Edit

```
1 define jalan2:
2   move
3   putbeeper
4   move
5   putbeeper
6 define jalan1:
7   move
8   putbeeper
9 define hadapkanan:
10  turnleft
11  turnleft
12  turnleft
13 define jalan3:
14  move
15  turnleft
16  move
17  putbeeper
18
19 jalan2
20 jalan1
21 move
22 hadapkanan
23 jalan2
24 move
25 hadapkanan
26 jalan2
27 move
28 turnleft
29 jalan2
30 move
31 turnleft
32 jalan2
33 jalan1
34 move
35 move
36 move
37 move
38 move
39 turnleft
40 putbeeper
```

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Robots position is 15 6 E and carrying 64 beepers

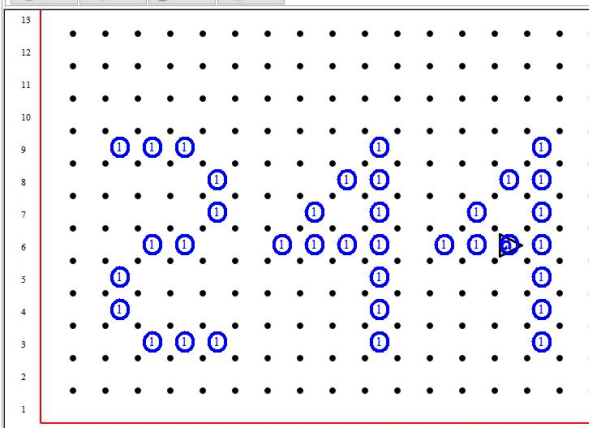
Code editor World editor

```
1 define jalan2:
2   move
3   putbeeper
4   move
5   putbeeper
6 define jalan1:
7   move
8   putbeeper
9 define hadapkanan:
10  turnleft
11  turnleft
12  turnleft
13 define jalan3:
14  move
15  turnleft
16  move
17  putbeeper
18
19 jalan2
20 jalan1
21 move
22 hadapkanan
23 jalan2
24 move
25 hadapkanan
26 jalan2
27 move
28 turnleft
29 jalan2
30 move
31 turnleft
32 jalan2
33 jalan1
34 move
35 move
36 move
37 move
38 move
39 turnleft
40 putbeeper
```

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Robots position is 15 6 E and carrying 64 beepers

Code editor World editor

```
41 jalan1
42 jalan1
43 jalan1
44 jalan1
45 jalan1
46 jalan1
47 turnleft
48 jalan3
49 hadapkanan
50 jalan3
51 hadapkanan
52 jalan3
53 turnleft
54 jalan2
55 move
56 hadapkanan
57 move
58 move
59 move
60 turnleft
61 move
62 move
63 move
64 move
65 move
66 turnleft
67 putbeeper
68 jalan1
69 jalan1
70 jalan1
71 jalan1
72 jalan1
73 jalan1
74 turnleft
75 jalan3
76 hadapkanan
77 jalan3
78 turnoff
79 hadapkanan
80 jalan3
```

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Robots position is 15 6 E and carrying 64 beepers

Code editor World editor

```

File Edit
43 jalan1
44 jalan1
45 jalan1
46 jalan1
47 turnleft
48 jalan3
49 hadapkanan
50 jalan3
51 hadapkanan
52 jalan3
53 turnleft
54 jalan2
55 move
56 hadapkanan
57 move
58 move
59 move
60 turnleft
61 move
62 move
63 move
64 move
65 move
66 turnleft
67 putbeeper
68 jalan1
69 jalan1
70 jalan1
71 jalan1
72 jalan1
73 jalan1
74 turnleft
75 jalan3
76 hadapkanan
77 jalan3
78 turnoff
79 hadapkanan
80 jalan3
81 turnleft
82 jalan2

```

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Robots position is 10 2 W and carrying 57 beepers

Code editor World editor

```

File Edit
1 define hadapkanan:
2   turnleft
3   turnleft
4   turnleft
5 define gerakletak:
6   move
7   putbeeper
8 define jalan:
9   move
10  turnleft
11
12 gerakletak
13 gerakletak
14 jalan
15 gerakletak
16 gerakletak
17 jalan
18 gerakletak
19 gerakletak
20 jalan
21 gerakletak
22 gerakletak
23 turnleft
24 turnleft
25 move
26 move
27 move
28 hadapkanan
29 gerakletak
30 gerakletak
31 jalan
32 gerakletak
33 gerakletak
34 jalan
35 gerakletak
36 gerakletak
37 jalan
38 gerakletak
39 gerakletak
40 jalan

```

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8
7
6
5
4
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1

1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 16 17

Robots position is 10.2 W and carrying 57 beepers

Code editor World editor

File Edit

```
41 move
42 move
43 move
44 move
45 move
46 hadapkanan
47 move
48 move
49 move
50 move
51 turnleft
52 move
53 gerakletak
54 turnleft
55 turnleft
56 gerakletak
57 gerakletak
58 turnleft
59 turnleft
60 move
61 turnleft
62 gerakletak
63 gerakletak
64 gerakletak
65 gerakletak
66 gerakletak
67 gerakletak
68 gerakletak
69 turnleft
70 jalan
71 gerakletak
72 turnleft
73 move
74 move
75 move
76 move
77 hadapkanan
78 move
79 move
80 move
```

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11
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8
7
6
5
4
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2
1

1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 16 17

Robots position is 10.2 W and carrying 57 beepers

Code editor World editor

File Edit

```
71 gerakletak
72 turnleft
73 move
74 move
75 move
76 move
77 hadapkanan
78 move
79 move
80 move
81 move
82 move
83 move
84 turnleft
85 gerakletak
86 gerakletak
87 jalan
88 gerakletak
89 gerakletak
90 gerakletak
91 gerakletak
92 gerakletak
93 gerakletak
94 jalan
95 gerakletak
96 gerakletak
97 jalan
98 gerakletak
99 gerakletak
100 gerakletak
101 jalan
102 gerakletak
103 gerakletak
104 hadapkanan
105 move
106 move
107 hadapkanan
108 turnoff
109 move
110 gerakletak
```

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Code editor World editor

File Edit

```
1 define maju5:
2   move
3   move
4   move
5   move
6   putbeeper
7   turnleft
8   turnleft
9   turnleft
10  move
11  maju5
12  maju5
13  maju5
14  maju5
15  turnleft
16  turnleft
17  move
18  turnoff
```

Robots position is 2 1 5 and carrying 0 beepers

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Code editor World editor

File Edit

```
1 define a2:
2   move
3   turnleft
4   move
5   putbeeper
6   turnleft
7   turnleft
8   move
9   turnleft
10  move
11  define kanan:
12    turnleft
13    turnleft
14    turnleft
15  move
16  a2
17  move
18  a2
19  move
20  a2
21  kanan
22  move
23  kanan
24  a2
25  move
26  a2
27  move
28  a2
29  move
30  turnoff
```

Robots position is 2 3 W and carrying 0 beepers