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Question 1:

initializing variables

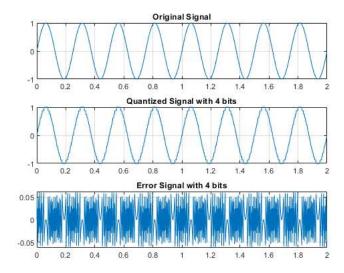
```
Ts = 0.002;
N = 1000;
f = 4;
b = 0; %bits
t = (0:N-1)*Ts;
original_signal = sin(2*pi*f*t);
 for b = 4:4:16
    % defining the quantized signal
     quantized_signal = quantization(original_signal, b);
     error_signal = original_signal - quantized_signal;
     subplot(3,1,1);
     plot(t, original_signal);
     title('Original Signal');
     grid on
     subplot(3,1,2);
     plot(t, quantized_signal);
     title(sprintf('Quantized Signal with %d bits',b));
     grid on
     subplot(3,1,3);
     plot(t, error_signal);
title(sprintf('Error Signal with %d bits',b));
     grid on
     max_err = max(error_signal);
disp(sprintf('The amplitude for %d bits error signal is: ',b)); disp(max_err);
end
```

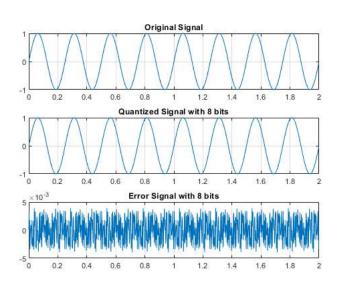
```
The amplitude for 4 bits error signal is: 0.0621

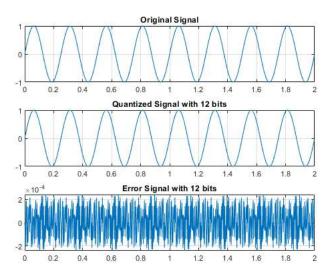
The amplitude for 8 bits error signal is: 0.0039

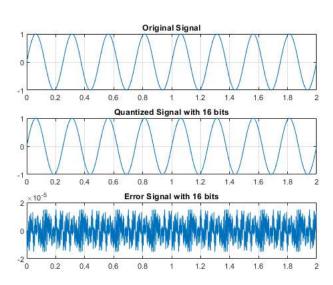
The amplitude for 12 bits error signal is: 2.4326e-04

The amplitude for 16 bits error signal is: 1.5146e-05
```



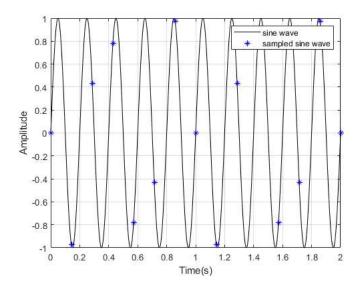


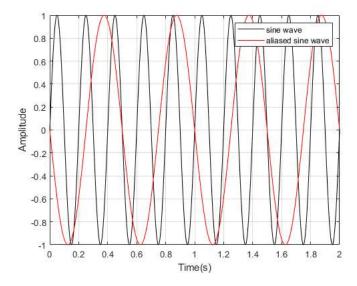




Question 2:

```
N = 1000;
f = 5;
T = 1/f;
fs = 7;
Ts = 1/fs;
t = linspace(0,2,1000);
signal = sin(2*pi*f*t);
t_sampled = 0:Ts:2;
signal_sampled = sin(2*pi*f*t_sampled);
signal_aliased = -1*sin(2*pi*2*t);
figure;
plot(t, signal, 'k'); hold on; plot(t_sampled, signal_sampled, 'b*'); hold off;
xlabel('Time(s)'); ylabel('Amplitude'); grid on; legend('sine wave', 'sampled sine wave');
figure;
plot(t, signal, 'k'); hold on; plot(t, signal_aliased, 'r'); hold off;
xlabel('Time(s)'); ylabel('Amplitude'); grid on; legend('sine wave', 'aliased sine wave');
```

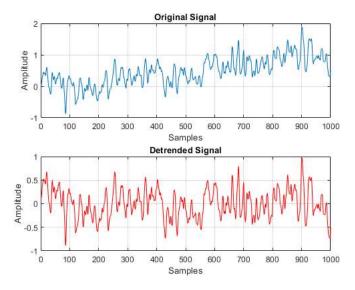




Question 3:

```
% Loading the signal data \\
s = load('data_c1.mat');
dataset = s.x;
\% segmenting the data
segmented_data = cell(1,length(dataset)/100);
for l=1:100:length(dataset)
    segmented_data{k} = dataset(1:1+99);
    k = k+1;
% evaluating the mean in each segment
means = cell(1,length(dataset)/100);
for i=1:length(segmented_data)
    mean_segment = segmented_data(i);
means{i} = mean(mean_segment{1,1});
\ensuremath{\mathrm{\%}} evaluating the variance in each segment
variance = cell(1,length(dataset)/100);
for j=1:length(segmented_data)
    variance_segment = segmented_data(j);
    variance{j} = var(variance_segment{1,1});
disp('Means for 10 segments:'); disp(means);
disp('Variance for 10 segments:'); disp(variance);
disp('The variance and mean are different for each segment, therefore, the signal is nonstationary.');
\ensuremath{\mathtt{\%}} The variance and mean are different for each segment, therefore, the signal is nonstationary.
```

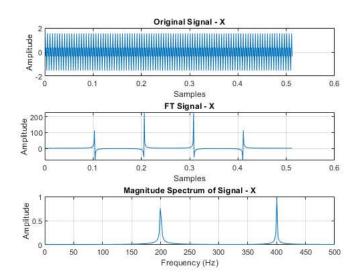
```
% applying MATLAB's detrend operator
d_dataset = detrend(dataset);
% segmenting the detrended signal
d_segmented_data = cell(1,length(d_dataset)/100);
for d_l=1:100:length(d_dataset)
    d_segmented_data{d_k} = d_dataset(d_1:d_1+99);
    d_k = d_k+1;
% calculating the mean for the detrended signal
d_means = cell(1,length(d_dataset)/100);
for d_i=1:length(d_segmented_data)
    d_mean_segment = d_segmented_data(d_i);
    d_{means}\{d_i\} = mean(d_{mean}_{segment}\{1,1\});
% calculating the variance for the detrended signal
d_variance = cell(1,length(d_dataset)/100);
for d_j=1:length(d_segmented_data)
    d_variance_segment = d_segmented_data(d_j);
    d\_variance\{d\_j\} = var(d\_variance\_segment\{1,1\});
end
disp('Means for 10 segments of detrended signal:'); disp(d_means);
\label{linear_disp} disp('Variance for 10 segments of detrended signal:'); \ disp(d\_variance);
disp('the variance for the detrended signal compared to the original signal are very (extremely) close in values but the mean values are more different between the
\% the variance for the detrended signal compared to the original signal are very (extremely) close in values
\% but the mean values are more different between the original signal and the detrended signal.
% plotting the two signals: original and detrended
figure;
subplot(2,1,1);
plot(dataset);
xlabel('Samples');
ylabel('Amplitude');
title('Original Signal');
grid on;
subplot(2,1,2);
plot(d_dataset,'r');
xlabel('Samples');
ylabel('Amplitude');
title('Detrended Signal');
grid on;
Means for 10 segments:
  Columns 1 through 5
    {[0.1461]}
                 {[-0.1058]}
                               {[0.1875]}
                                              {[0.3915]}
                                                            {[0.3092]}
  Columns 6 through 10
                 {[0.6808]}
                               {[0.6537]}
    {[0.4516]}
                                             {[1.0329]}
                                                           {[0.9620]}
Variance for 10 segments:
  Columns 1 through 5
    {[0.0878]}
                 {[0.0518]}
                               {[0.0897]}
                                             {[0.0448]}
                                                           {[0.0939]}
  Columns 6 through 10
                 {[0.0828]}
    {[0.0995]}
                              {[0.0424]}
                                             {[0.0582]}
                                                           {[0.1378]}
The variance and mean are different for each segment, therefore, the signal is nonstationary.
           _____
Means for 10 segments of detrended signal:
  Columns 1 through 5
    {[0.1807]} {[-0.1835]} {[-0.0026]}
                                               {[0.0891]}
                                                            {[-0.1055]}
  Columns 6 through 10
    {[-0.0755]}
                 {[0.0413]}
                                {[-0.0981]}
                                               {[0.1687]}
                                                             {[-0.0146]}
Variance for 10 segments of detrended signal:
  Columns 1 through 5
    {[0.0963]}
                 {[0.0561]}
                               {[0.0827]}
                                             {[0.0406]}
                                                           {[0.0957]}
  Columns 6 through 10
    {[0.0858]}
                 {[0.0807]}
                              {[0.0440]}
                                            {[0.0578]}
                                                           {[0.1518]}
the variance for the detrended signal compared to the original signal are very (extremely) close in values but the mean values are more different between the origin
```

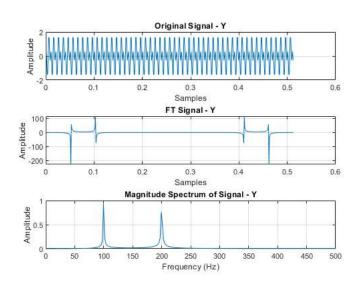


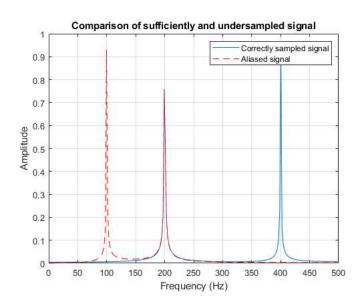
Question 4:

```
% data given:
N = 512;
fs = 1000;
T = 1/fs;
f1 = 200;
f2_1 = 400;
f2_2 = 900;
\ensuremath{\mathrm{\%}} frequency and time vector calculated:
t1 = (0:N-1)*T;
t = (1:N)/fs;
% defining the sinusoidal waves:
x = sin(2*pi*f1*t) + sin(2*pi*f2_1*t);
y = sin(2*pi*f1*t) + sin(2*pi*f2_2*t);
\ensuremath{\text{\%}} applying FT to the sinusoidal waves:
x_{ft} = fft(x);
y_{ft} = fft(y);
\% magnitude of the spectrum:
x_abs = abs(x_ft/N);
x_{spec} = x_{abs}(1:N/2+1);
x_{spec}(2:end-1) = 2*x_{spec}(2:end-1);
y_abs = abs(y_ft/N);
y_{spec} = y_{abs(1:N/2+1)};
y_spec(2:end-1) = 2*y_spec(2:end-1);
f_axis = fs*(0:(N/2))/N;
figure;
subplot(3,1,1);
plot(t, x); title('Original Signal - X'); xlabel('Samples'); ylabel('Amplitude'); grid on;
subplot(3,1,2);
plot(t, \ x\_ft); \ title('FT \ Signal - X'); \ xlabel('Samples'); \ ylabel('Amplitude'); \ grid \ on;
subplot(3,1,3);
plot(f_axis, x_spec); title('Magnitude Spectrum of Signal - X');
xlabel('Frequency (Hz)'); ylabel('Amplitude'); grid on;
subplot(3,1,1);
plot(t, y); title('Original Signal - Y'); xlabel('Samples'); ylabel('Amplitude'); grid on;
subplot(3,1,2);
plot(t, y_ft); title('FT Signal - Y'); xlabel('Samples'); ylabel('Amplitude'); grid on;
subplot(3,1,3);
plot(f_axis, y_spec); title('Magnitude Spectrum of Signal - Y');
xlabel('Frequency (Hz)'); ylabel('Amplitude'); grid on;
% final plot
figure;
plot(f_axis, x_spec, '-');
hold on
plot(f_axis, y_spec, '--r');
legend('Correctly sampled signal', 'Aliased signal');
```

Warning: Imaginary parts of complex X and/or Y arguments ignored. Warning: Imaginary parts of complex X and/or Y arguments ignored.







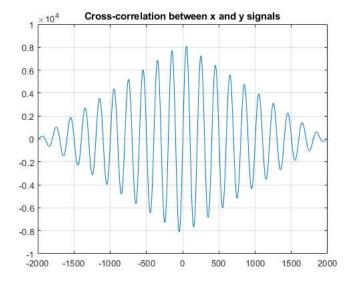
Question 5:

```
%Loading the signal data
s = load('sines1.mat');
d_x = s.x;
d_y = s.y;

fs = 2000;
%f = 10;

% frequency and time vector calculated:
N = length(d_x);
f = (1:N)*fs/N;
t = (1:N)/fs;

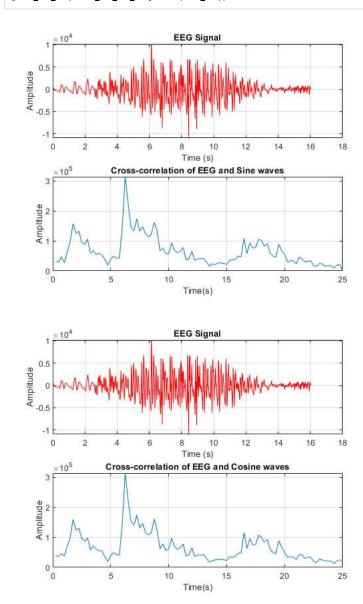
% cross-correlation between two the two signals
[c2,lags2] = xcorr(d_x,d_y);
figure;
plot(lags2, c2); grid on;
title('Cross-correlation between x and y signals');
```



Question 6:

```
s = load('eeg_data.mat');
eeg = s.eeg;
fs = 50;
Ts = 1/fs;
\ensuremath{\mbox{\%}} frequency and time vector calculated:
N = length(eeg);
f = (1:N)*fs/N;
t = (1:N)/fs;
% Correlation with Sinusoidal waves
corr_sin = [];
min_corr_sin = [];
freq_sin = [];
for i = 1:25/0.25
    sine_signal = sin(2*pi*(0.25*i)*t);
    [corr, lag] = xcorr(eeg, sine_signal);
    corr_sin(i) = max(corr);
min_corr_sin(i) = min(corr);
freq_sin(i) = i*0.25;
end
figure;
subplot(2,1,1);
plot(t,\ eeg, 'r');\ title('EEG\ Signal');\ xlabel('Time\ (s)');\ ylabel('Amplitude');\ grid\ on;
subplot(2,1,2);
plot(freq_sin, corr_sin); title('Cross-correlation of EEG and Sine waves');
\verb|xlabel('Time(s)'); ylabel('Amplitude'); grid on; \\
\ensuremath{\mathrm{\%}} getting the max values of correlation
[corr_sin_max, corr_sin_max_ind] = max(corr_sin);
```

```
\% Correlation with Cosine waves
corr_cos = [];
min_corr_cos = [];
freq_cos = [];
for j = 1:25/0.25
    cosine_signal = cos(2*pi*(0.25*j)*t);
    [corr2, lag2] = xcorr(eeg, cosine_signal);
    corr_cos(j) = max(corr2);
    min_corr_cos(j) = min(corr2);
    freq_cos(j) = j*0.25;
end
figure;
subplot(2,1,1);
plot(t, eeg,'r'); title('EEG Signal'); xlabel('Time (s)'); ylabel('Amplitude'); grid on;
subplot(2,1,2);
plot(freq_cos, corr_cos); title('Cross-correlation of EEG and Cosine waves');
xlabel('Time(s)'); ylabel('Amplitude'); grid on;
\mbox{\ensuremath{\mbox{\%}}} getting the max values of correlation
[corr_cos_max, corr_cos_max_ind] = max(corr_cos);
```

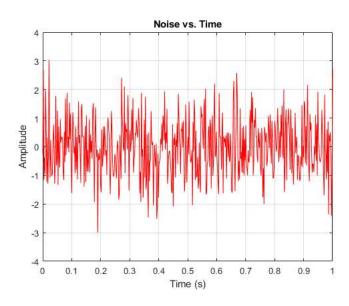


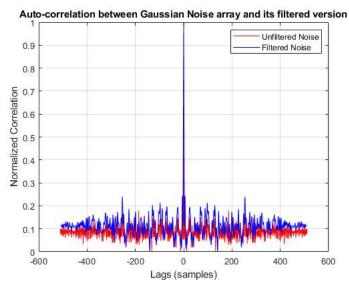
Question 7:

constructing the noise array

```
H = [1/3 1/3 1/3];
noise = randn(1, 512);
```

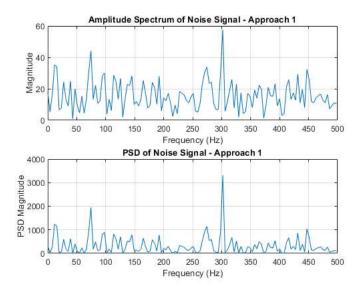
```
% adding the filter
y = [];
for i = 3:length(noise)
    y(i-2) = (1/3)*(noise(i) + noise(i-1) + noise(i-2));
end
t = (0:length(noise)-1)*(1/(length(noise)-1));
plot(t, noise,'r');
title('Noise vs. Time'); xlabel('Time (s)'); ylabel('Amplitude'); grid on;
[noise_corr, noise_lag] = xcorr(noise, noise);
norm_corr = (noise_corr - min(noise_corr))./(max(noise_corr) - min(noise_corr));
[filter_corr, filter_lag] = xcorr(y, y);
norm_corr_2 = (filter_corr - min(filter_corr))./(max(filter_corr) - min(filter_corr));
figure;
plot(noise_lag, norm_corr, 'r'); hold on;
plot(filter_lag, norm_corr_2, 'b'); hold off;
title('Auto-correlation between Gaussian Noise array and its filtered version');
xlabel('Lags (samples)'); ylabel('Normalized Correlation');
legend('Unfiltered Noise', 'Filtered Noise'); grid on;
\ensuremath{\mathtt{\%}} By normalizing the auto-correlation, it can be seen that white noise if
\ensuremath{\mathrm{\%}} uncorrelated sample to sample but the moving average filter has caused
\ensuremath{\mathrm{\%}} some correlations between the sample points. This is because the filter
\ensuremath{\text{\%}} output depends on the preceeding sample values.
```

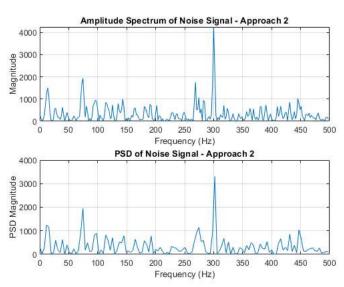




```
[waveform_noise, time, waveform, snr_out] = sig_noise(300, -12, 256);
% Approach one
L = length(waveform_noise);
fs = 1000;
f = fs/(L-1)*(0:L-1);
f1 = f(1:end/2);
\% taking the FT of the noise signal
noise_ft = fft(waveform_noise);
noise_ft_abs = abs(noise_ft);
noise_spec = noise_ft_abs(1:L/2);
figure;
subplot(2,1,1); plot(f1, noise_spec);
title('Amplitude Spectrum of Noise Signal - Approach 1'); xlabel('Frequency (Hz)'); ylabel('Magnitude'); grid on;
subplot(2,1,2); plot(f1, noise_spec.^2);
title('PSD of Noise Signal - Approach 1'); xlabel('Frequency (Hz)'); ylabel('PSD Magnitude'); grid on;
% Approach two
[w_corr, w_lags] = xcorr(waveform_noise, waveform_noise);
L2 = length(w_corr);
f_1 = fs/(L2-1)*(0:L2-1);
f2 = f_1(1:end/2);
w_corr_ft = fft(w_corr);
w_corr_ft_abs = abs(w_corr_ft);
w_corr_spec = w_corr_ft_abs(1:L2/2);
subplot(2,1,1); plot(f2, w_corr_spec);
title('Amplitude Spectrum of Noise Signal - Approach 2'); xlabel('Frequency (Hz)'); ylabel('Magnitude'); grid on;
subplot(2,1,2); plot(f1, noise_spec.^2);
title('PSD of Noise Signal - Approach 2'); xlabel('Frequency (Hz)'); ylabel('PSD Magnitude'); grid on;
```

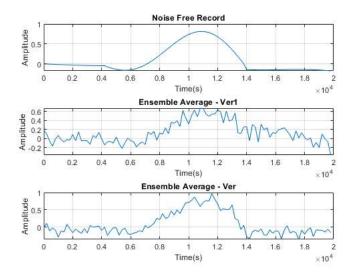
Warning: Integer operands are required for colon operator when used as index. Warning: Integer operands are required for colon operator when used as index.





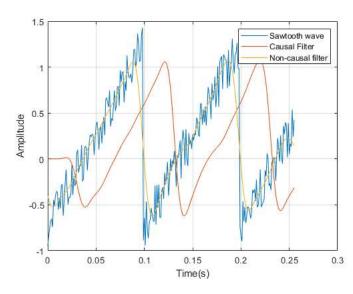
Question 9:

```
s = load('ver_problem2.mat');
actual_ver = s.actual_ver; % the noise-free VER
ver = s.ver; % 100 noise signals recorded with a fixed reference signal
ver1 = s.ver1; % 100 records recorded with a reference signal that varies randomly by +-150 ms
ts = 0.005;
fs = 1/ts;
% ensemble averages
ver_avg = mean(ver);
ver1_avg = mean(ver1);
N = length(actual_ver);
N1 = length(ver);
N2 = length(ver1);
t = (0:N-1)*fs;
t1 = (0:N1-1)*fs;
t2 = (0:N2-1)*fs;
\ensuremath{\text{\%}} plotting the ensemble averages
figure;
subplot(3,1,1);
plot(t, actual_ver); title('Noise Free Record');
xlabel('Time(s)'); ylabel('Amplitude'); grid on;
subplot(3,1,2);
plot(t2, ver1_avg); title('Ensemble Average - Ver1');
xlabel('Time(s)'); ylabel('Amplitude'); grid on;
subplot(3,1,3);
plot(t1, ver_avg); title('Ensemble Average - Ver');
xlabel('Time(s)'); ylabel('Amplitude'); grid on;
```



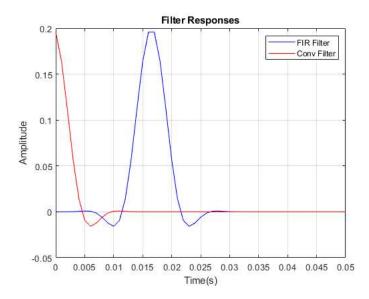
Question 10:

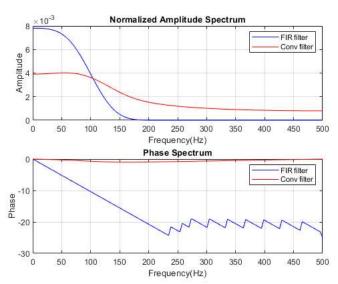
```
s = load('sawth.mat'); % loading the dataset
signal = s.x;
fc = 40; % cutoff frequency
fs = 1000;
ts = 1/fs;
order = 65;
L = length(signal);
t = (0:L-1)/fs;
wc = fc/(fs/2);
b = fir1(order, wc, 'low', blackmanharris(order+1));
% Adding the filter in two ways
filt_FIR = filter(b, 1, signal);
filt_conv = conv(signal, b, 'same');
plot(t, signal); hold on; plot(t, filt_FIR); hold on; plot(t, filt_conv); hold off;
xlabel('Time(s)'); ylabel('Amplitude'); grid on;
legend('Sawtooth wave','Causal Filter', 'Non-causal filter');
\% from the plots above, it can be seen that due to the introduced delay \% from the casaul filter, the peaks show up later in time using the FIR \%
% filter. However, in the plot where the filtering is done through
% convolution, the output of the filtered signal is occuring before the
% actual Sawtooth wave signal which indicates non-causality.
```

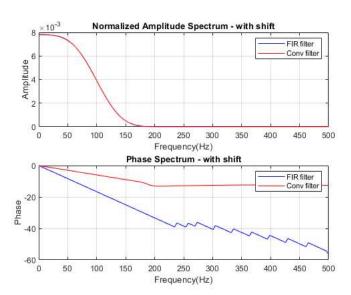


Question 11:

```
fs = 1000:
ts = 1/fs;
fc = 100;
wc = fc/(fs/2);
order = 33;
fir = fir1(order, wc, 'low', blackmanharris(order+1));
impulse = zeros(1, 256);
impulse(1) = 1;
filt_FIR = filter(fir, 1, impulse);
filt_conv = conv(impulse, fir, 'same');
t = (0:length(impulse)-1)*ts;
index = find(t == 0.05);
% plotting the filter responses:
figure:
plot(t(1:index), filt_FIR(1:index),'-b'); hold on;
plot(t(1:index), filt_conv(1:index), '-r'); hold off;
title('Filter Responses'); xlabel('Time(s)'); ylabel('Amplitude');
legend('FIR Filter','Conv Filter'); grid on;
L = length(impulse);
FIR_ft = fft(filt_FIR)/L;
conv_ft = fft(filt_conv)/L;
f = fs*(0:(L/2))/L;
\% plotting the amplitude spectrums:
spec_FIR = abs(FIR_ft(1:L/2+1));
spec_conv = abs(conv_ft(1:L/2+1));
phase_FIR = unwrap(angle(FIR_ft(1:L/2+1)));
phase_conv = unwrap(angle(conv_ft(1:L/2+1)));
subplot(2,1,1);
plot(f, 2*spec_FIR,'-b'); hold on; plot(f, 2*spec_conv,'-r'); hold off;
title('Normalized Amplitude Spectrum'); xlabel('Frequency(Hz)'); ylabel('Amplitude');
grid on; legend('FIR filter','Conv filter');
subplot(2,1,2);
plot(f, phase_FIR,'-b'); hold on; plot(f, phase_conv,'-r'); hold off;
title('Phase Spectrum'); xlabel('Frequency(Hz)'); ylabel('Phase');
grid on; legend('FIR filter','Conv filter');
% Adding the shift:
impulse2 = [zeros(1,10) 1 zeros(1,245)];
filt2_FIR = filter(fir, 1, impulse2);
filt2_conv = conv(impulse2, fir, 'same');
FIR ft2 = fft(filt2 FIR)/L:
conv_ft2 = fft(filt2_conv)/L;
spec2 FIR = abs(FIR ft2(1:L/2+1));
spec2_conv = abs(conv_ft2(1:L/2+1));
phase2_FIR = unwrap(angle(FIR_ft2(1:L/2+1)));
phase2_conv = unwrap(angle(conv_ft2(1:L/2+1)));
figure;
subplot(2,1,1);
plot(f, 2*spec2_FIR,'-b'); hold on; plot(f, 2*spec2_conv,'-r'); hold off;
title('Normalized Amplitude Spectrum - with shift'); xlabel('Frequency(Hz)'); ylabel('Amplitude');
grid on; legend('FIR filter','Conv filter');
plot(f, phase2_FIR,'-b'); hold on; plot(f, phase2_conv,'-r'); hold off;
title('Phase Spectrum - with shift'); xlabel('Frequency(Hz)'); ylabel('Phase');
grid on; legend('FIR filter','Conv filter');
```



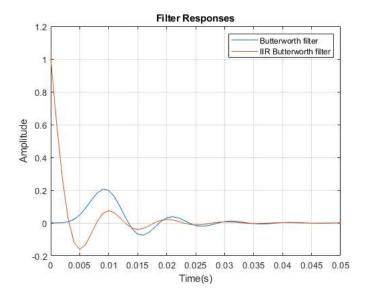


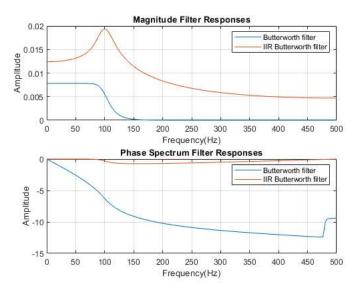


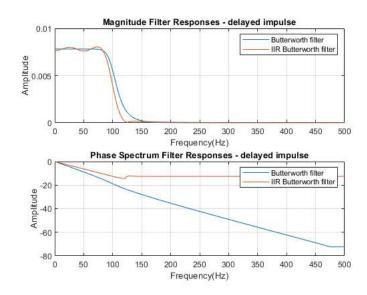
Question 12:

```
fc = 100;
fs = 1000;
ts = 1/fs;
wc = fc/(fs/2);
impulse = [1 zeros(1, 255)];
```

```
L = length(impulse);
[b, a] = butter(8, wc);
y1 = filter(b, a, impulse);
y2 = filtfilt(b, a, impulse);
t = (0:length(impulse)-1).*ts;
index = find(t == 0.05);
% plotting the filter responses:
figure;
plot(t(1:index), y1(1:index)); hold on; plot(t(1:index), y2(1:index)); hold off;
title('Filter Responses'); xlabel('Time(s)'); ylabel('Amplitude');
legend('Butterworth filter','IIR Butterworth filter'); grid on;
% Defining the magnitude and phase response and plotting them:
bw_ft = fft(y1)/L;
iirbw_ft = fft(y2)/L;
f = fs*(0:(L/2))/L;
bw_ft = bw_ft(1:(L/2)+1);
iirbw_ft = iirbw_ft(1:(L/2)+1);
bw_mag = abs(bw_ft).*2;
iirbw_mag = abs(iirbw_ft).*2;
bw_phase = unwrap(angle(bw_ft(1:(L/2)+1)));
iirbw_phase = unwrap(angle(iirbw_ft(1:(L/2)+1)));
figure:
subplot(2,1,1); plot(f, bw_mag); hold on; plot(f, iirbw_mag); hold off;
title('Magnitude Filter Responses'); xlabel('Frequency(Mz)'); ylabel('Amplitude'); legend('Butterworth filter','IIR Butterworth filter'); grid on;
subplot(2,1,2); plot(f, bw_phase); hold on; plot(f, iirbw_phase); hold off;
title('Phase Spectrum Filter Responses'); xlabel('Frequency(Hz)'); ylabel('Amplitude');
legend('Butterworth filter','IIR Butterworth filter'); grid on;
\% showing absence of ripples:
impulse2 = [zeros(1,20) 1 zeros(1, 235)];
y3 = filter(b,a,impulse2);
y4 = filtfilt(b, a, impulse2);
bw_ft2 = fft(y3)/L;
iirbw_ft2 = fft(y4)/L;
f3 = fs*(0:(L/2))/L;
bw_ft2 = bw_ft2(1:(L/2)+1);
iirbw_ft2 = iirbw_ft2(1:(L/2)+1);
bw_mag2 = abs(bw_ft2).*2;
iirbw_mag2 = abs(iirbw_ft2).*2;
bw phase2 = unwrap(angle(bw ft2(1:(L/2)+1)));
iirbw_phase2 = unwrap(angle(iirbw_ft2(1:(L/2)+1)));
figure:
subplot(2,1,1); plot(f3, bw_mag2); hold on; plot(f3, iirbw_mag2); hold off; title('Magnitude Filter Responses - delayed impulse'); xlabel('Frequency(Hz)'); ylabel('Amplitude');
legend('Butterworth filter','IIR Butterworth filter'); grid on;
subplot(2,1,2); plot(f3, bw_phase2); hold on; plot(f3, iirbw_phase2); hold off;
title('Phase Spectrum Filter Responses - delayed impulse'); xlabel('Frequency(Hz)'); ylabel('Amplitude');
legend('Butterworth filter','IIR Butterworth filter'); grid on;
```







Question 13:

data given:

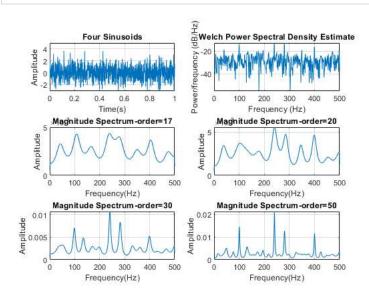
```
N = 1000;

SNR = -12;

fs = 1000;

ts = 1/fs;
```

```
f1 = 100;
f2 = 240;
f3 = 280:
f4 = 400;
t = (1:N)/fs;
sine_wave = sig_noise([f1, f2, f3, f4], SNR, 1000);
figure;
subplot(3,2,1);
plot(t, sine_wave);
title('Four Sinusoids'); xlabel('Time(s)'); ylabel('Amplitude'); grid on;
subplot(3,2,2);
pwelch(sine_wave,N,[],[],fs);
[Pxx_17,F_17] = pyulear(sine_wave,17,1024,N);
subplot(3,2,3);
plot(F_17, Pxx_17);
title('Magnitude Spectrum-order=17'); xlabel('Frequency(Hz)');
ylabel('Amplitude'); grid on;
[Pxx_20,F_20] = pyulear(sine_wave,20,1024,N);
subplot(3,2,4);
plot(F_20, Pxx_20);
title('Magnitude Spectrum-order=20'); xlabel('Frequency(Hz)');
ylabel('Amplitude'); grid on;
[Pxx_30,F_30] = pyulear(sine_wave,30,1024,N);
subplot(3,2,5);
plot(F_30, Pxx_30);
title('Magnitude Spectrum-order=30'); xlabel('Frequency(Hz)');
ylabel('Amplitude'); grid on;
[Pxx_50,F_50] = pyulear(sine_wave,50,1024,N);
subplot(3,2,6);
plot(F_50, Pxx_50);
title('Magnitude Spectrum-order=50'); xlabel('Frequency(Hz)');
ylabel('Amplitude'); grid on;
```



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