

Final 2020

$$(4) \quad \underbrace{\left(1 + \frac{dy}{dx}\right)}_{\text{inner derivative}} \cos(x+y) = 2y \frac{dy}{dx} \cos x + y^2(-\sin x)$$

$$x=0, y=0$$

$$\left(1 + \frac{dy}{dx}\right) \underbrace{\cos 0}_{=1} = 0 + 0 \Rightarrow \frac{dy}{dx} = -1$$

\Rightarrow The tangent line equation is $y-0 = \frac{dy}{dx}(x-0)$

$$\text{for point } (0,0) \Rightarrow y = -1 \cdot x = -x$$

$$(5) \quad a) \int_0^1 \ln x \, dx = \underbrace{x \ln x \Big|_0^1}_{=0-0=0} - \underbrace{\int_0^1 x \cdot \frac{1}{x} \, dx}_{=x \Big|_0^1 = 1} = -1$$

use integration by parts with

$$u' = 1 \Rightarrow u = x$$

$$v' = \ln x \Rightarrow v' = \frac{1}{x}$$

$$b) \int \frac{x^2+1}{x^2-1} \, dx$$

$$\frac{(x^2+1) : (x^2-1) = 1 + \frac{2}{x^2-1}}{-\frac{(x^2-1)}{2}}$$

$$\text{Partial fractions: } \frac{2}{x^2-1} = \frac{A}{x+1} + \frac{B}{x-1} = \frac{A(x-1) + B(x+1)}{x^2-1}$$

$$0 \cdot x = Ax + Bx \Rightarrow A + B = 0$$

$$2 = -A + B \Rightarrow A = -1, B = 1$$

$$\Rightarrow \int \frac{x^2 + 1}{x^2 - 1} dx = \int \left(1 - \frac{1}{x+1} + \frac{1}{x-1} \right) dx$$

$$= x - \ln|x+1| + \ln|x-1| + C$$

$$= x + \ln \left| \frac{x-1}{x+1} \right| + C$$

$$(6) \int_0^{\infty} \frac{\ln x + e^{-x}}{1+x^2} dx$$

The integrand has a vertical asymptote at $x=0$,
(because of $\ln x$)

So let's check $x \searrow$ and $x \rightarrow \infty$

independently:

$$I_1 = \int_0^1 \frac{\ln x + e^{-x}}{1+x^2} dx = \int_0^1 \frac{\ln x}{1+x^2} dx + \int_0^1 \frac{e^{-x}}{1+x^2} dx$$

cont. on $[0,1]$,
so no issue here!

$$\text{Now } \int_0^1 \frac{\ln x}{1+x^2} dx > \int_0^1 \ln x dx = -1 \quad \text{by (5a)}$$

As $\frac{\ln x}{1+x^2}$ does not change sign on $[0,1]$,

I_1 converges. (It's bound by 0 and -1)

$$\begin{aligned}
 I_2 &= \int_e^{\infty} \frac{\ln x + e^{-x}}{1+x^2} dx \leq \int_e^{\infty} \frac{\ln x + e^{-x}}{x^2} dx \\
 &\leq \int_e^{\infty} \frac{\ln x + \ln x}{x^2} dx \quad \begin{array}{l} \text{since} \\ \ln x \geq e^{-x} \\ \text{for } x \geq e \\ \text{(actually } \ln x > e^{-x} \text{)} \\ \text{for } x \geq e \end{array} \\
 &= 2 \int_e^{\infty} \frac{\ln x}{x^2} dx \quad \begin{array}{l} u = \ln x \\ u' = \frac{1}{x} \\ v' = \frac{1}{x^2} \\ v = -\frac{1}{x} \end{array} \\
 &= 2 \int_e^{\infty} \ln x \cdot \frac{1}{x^2} dx = 2 \cdot \left(\underbrace{\left[-\frac{\ln x}{x} \right]_e^{\infty}}_{\substack{\text{converges} \\ \text{for } x \rightarrow \infty}} - \underbrace{\int_e^{\infty} -\frac{1}{x} \cdot \frac{1}{x} dx}_{\substack{\text{converges} \\ \text{since} \\ \int_e^{\infty} \frac{1}{x^2} dx \text{ converges} \\ \text{for } \alpha > 1}} \right) \\
 &\quad \underbrace{\hspace{15em}}_{\text{converges}}
 \end{aligned}$$

As the integrand does not switch sign on $[e, \infty)$,

I_2 also converges.

$$I_3 = \int_1^e \frac{\ln x + e^{-x}}{1+x^2} dx$$

converges, as no discontinuities
and fixed bounds that are not discontinuities.

$\Rightarrow I_1 + I_2 + I_3$ converges

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a)

$$\int_{y_0=2}^{y(t)} \frac{dy}{y^3} = \int_{t_0=0}^t t^3 dt$$

as $y_0 = y(t_0) = y(0) = 2$

$$\Rightarrow -\frac{1}{2} y^{-2} \Big|_2^{y(t)} = \frac{1}{4} t^4 \Big|_0^t$$

$$\Rightarrow \frac{1}{8} - \frac{1}{2} \frac{1}{y^2(t)} = \frac{1}{4} t^4 \Rightarrow \frac{1}{4} - \frac{1}{2} t^4 = \frac{1}{y^2(t)}$$

$$\Rightarrow y(t) = \frac{1}{\sqrt{\frac{1}{4} - \frac{1}{2} t^4}}$$

(choose pos. root to match initial condition)

$$y(0) = \frac{1}{\sqrt{\frac{1}{4}}} = 2$$

b) For $t > 0$, $\frac{dy}{dt} = 0$ iff $y = 0$

And

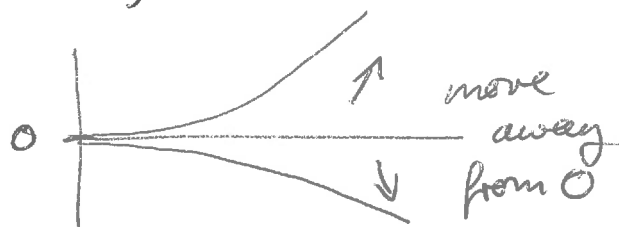
$$\frac{dy}{dt} > 0$$

for $y > 0$

$$\frac{dy}{dt} < 0$$

for $y < 0$

$y=0$ equilibrium point
and unstable



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$$\|u\|^2 \cdot \|v\|^2 = (u \cdot v)^2 + \|u \times v\|^2$$

$$u \cdot v = \|u\| \|v\| \cos \theta$$

θ angle between u and v

$$\|u \times v\| = \|u\| \|v\| \sin \theta$$

$$\Rightarrow (u \cdot v)^2 + \|u \times v\|^2 = \|u\|^2 \|v\|^2 (\underbrace{\cos^2 \theta + \sin^2 \theta}_{=1}) = \|u\|^2 \|v\|^2 \checkmark$$

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$$\begin{pmatrix} 2 & 0 & 2 & 4 & -2 \\ 0 & 1 & 0 & 1 & -2 \\ 2 & -1 & 2 & 3 & 0 \\ 1 & 1 & 1 & 3 & -3 \end{pmatrix} \xrightarrow{\begin{array}{l} R_1 \rightarrow R_1 \\ R_3 - R_1 \rightarrow R_3 \\ R_4 - \frac{R_1}{2} \rightarrow R_4 \end{array}} \begin{pmatrix} 1 & 0 & 1 & 2 & -1 \\ 0 & 1 & 0 & 1 & -2 \\ 0 & -1 & 0 & -1 & 2 \\ 0 & 1 & 0 & 1 & -2 \end{pmatrix}$$

$$\begin{array}{l} R_3 + R_2 \rightarrow R_3 \\ -R_4 + R_2 \rightarrow R_4 \end{array} \xrightarrow{\quad} \begin{pmatrix} 1 & 0 & 1 & 2 & -1 \\ 0 & 1 & 0 & 1 & -2 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{pmatrix}$$

$$\Rightarrow x = \begin{pmatrix} -1 \\ -2 \\ 0 \\ 0 \end{pmatrix} + \lambda \begin{pmatrix} 1 \\ 0 \\ -1 \\ 0 \end{pmatrix} + \mu \begin{pmatrix} 2 \\ 1 \\ 0 \\ -1 \end{pmatrix}$$

Check (not required!)

$$A \begin{pmatrix} -1 \\ -2 \\ 0 \\ 0 \end{pmatrix} = \begin{pmatrix} -2+0 \\ 0-2 \\ -2+2 \\ -1+2 \end{pmatrix} = \begin{pmatrix} -2 \\ -2 \\ 0 \\ -3 \end{pmatrix} = b \quad \checkmark$$

$$A \begin{pmatrix} 1 \\ 0 \\ -1 \\ 0 \end{pmatrix} = \begin{pmatrix} 2-2 \\ 0-0 \\ 2-2 \\ 1-1 \end{pmatrix} = 0 \quad \checkmark$$

$$A \begin{pmatrix} 2 \\ 1 \\ 0 \\ -1 \end{pmatrix} = \begin{pmatrix} 4+0-4 \\ 0+1-1 \\ 4-1-3 \\ 2+1-3 \end{pmatrix} = 0 \quad \checkmark$$

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$$a) \quad L(\lambda y + \mu x) = L \begin{pmatrix} \lambda y_1 + \mu x_1 \\ | \\ \lambda y_5 + \mu x_5 \end{pmatrix} = \begin{pmatrix} 0 \\ \lambda y_1 + \mu x_1 \\ | \\ \lambda y_4 + \mu x_4 \end{pmatrix}$$

$$= \lambda \begin{pmatrix} 0 \\ y_1 \\ | \\ y_4 \end{pmatrix} + \mu \begin{pmatrix} 0 \\ x_1 \\ | \\ x_4 \end{pmatrix} = \lambda Ly + \mu Lx \quad \checkmark$$

$$b) \quad S = \begin{pmatrix} 0 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 \end{pmatrix}$$

$\uparrow \quad \uparrow \quad \uparrow \quad \uparrow$
 $e_2 \quad e_3 \quad e_4 \quad e_5$

$$e_2 = \begin{pmatrix} 0 \\ 1 \\ 0 \\ 0 \\ 0 \end{pmatrix} \leftarrow 1 \text{ at second position, } \underline{e_2}$$

c) We immediately see that columns 1-4 have pivots,

so

$$\text{Range } S = \text{span} \{e_2, e_3, e_4, e_5\}$$

$$\text{Ker } S = \text{span} \{e_5\}$$

← since pivot is missing in fifth column!



where all entries are zero, and we have to replace the missing pivot with -1

constant included in span

$$\Rightarrow \begin{pmatrix} 0 \\ 0 \\ 0 \\ 0 \\ -1 \end{pmatrix} = -1 \begin{pmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 1 \end{pmatrix} \leftarrow e_5$$

d) Rank-nullity theorem for an $n \times m$ matrix S says that:

$$\text{rank } S + \text{nullity } S = m$$

$$\text{or } \dim \text{Range } S + \dim \text{Ker } S = m$$

$$\text{Here: } 4 + 1 = 5 \quad \checkmark$$