Robotics Problem Sheet 3

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Notes

The homework serves as preparation for the exams. It is strongly recommended that you solve them before the given deadline - but you do not need to hand them in. Feel free to work on the problems as a group - this is even recommended.

1 Problem

Given a DC-motor with

 $\bullet\,$ no-load speed $N_0\colon\,6{,}000~\mathrm{rpm}$

• stall torque T_s : 0.5 gr·cm

What is the maximum mechanical power of the motor (in Watt)?

2 Problem

Given a spur gear train with 3 axes a_1 to a_3 . On each axis a_i is a gear or two gears $g_{i,x}, x \in \{a,b\}$ with following numbers of teeth

- $g_{1.a}$: 10
- $g_{2.a}$: 20
- $g_{2.b}$: 50
- $g_{3.a}$: 100

Gear $g_{1.a}$ drives $g_{2.a}$, $g_{2.b}$ drives $g_{3.a}$. Given input speed or torque on a_1 calculate the according output on a_3

- input torque a_1 : 10 Nm; output torque a_3 ?
- input speed a_1 : 100 rpm; output speed a_3 ?

3 Problem

Given

- 1. a worm gear G_w with
 - $z_w = 100$ teeth on the worm wheel
- 2. a planetary gear G_p with
 - 4 planet gears
 - $z_p = 50$ teeth on each planet
 - $z_i = 200$ teeth on the internal gear
 - $z_s = 10$ teeth on the sun

What is the gear ratio of G_w , respectively of G_p ?