

# Internship Report

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## NXP IMX8MM-EVK

### Evaluation kit

- NXP LPDDR4 iMX8MM-EVK 2018 version
- [EVK](#)

### Getting started with the EVK

#### Installing Linux

- Download the [Linux binary demo](#).
- Download [UUU](#).

```
~$ chmod a+x UUU
```

```
~$ sudo ./uuu <linux_images_MX8MMEVK.zip>
```

- **NOTE:** Latest Linux distro will not run on this board.
- The error message returned will booting Linux:

```
"Can't find PMIC:PCA9450"
```

- PMIC for our board is:

```
ROHM BD71847MWV
```

- To use the newest BSP, we need to do the PMIC porting for our board.
- Refer to boot switch setup in the startup guide.
- [Linux User Guide](#).
- [Reference Manual](#).

#### PMIC Porting

- Clone repository and checkout the branch for the Linux version.

```
~$ git clone https://source.codeaurora.org/external/imx/linux-imx.git
```

```
~$ git fetch --all
```

```
~$ git checkout -b FAH-imx origin/lf-5.15.y
```

- Disable **PMIC** in **imx8mm-evk.dts**:

```
&pmic_nxp {
    status= "disabled";
};
```

- Disable **PCIe** in **imx8mm-evk.dtsi**:

```
&pcie0{
    status = "disabled";
};
```

- Disable **wdog** driver in **imx8mm-evk.dtsi**:

```
&wdog1 {
    status = "disabled";
};
```

- Generate dtb:

```
~$ export ARCH=arm64
~$ make dtbs
```

- **NOTE:** Do not forget to plug the board with a 12V power supply. The board will shut down if powered with a USB from a PC.

## Load Device Tree File

- copy **.dtb** to TFTP server:

```
sudo cp <DIR>arch/arm64/boot/dts/freescale/imx8mm-evk.dtb ~/tftp/<filename.dtb>
```

- Edit U-boot environment:

```
setenv loadfdt "setenv autoload no; dhcp; setenv serverip <IP_Address>; tftp 0x43000000 <filename.dtb>"
setenv fdtfile <filename.dtb>
saveenv
```

## MCUXpresso SDK

- Download [SDK](#).
- We used MCUXpresso version **2.11.1**.
- **NOTE:** Initialization of pins in **pinmux.c** of a few examples is missing (fixed in new version 2.12.0).

```
void BOARD_InitBootPins(void){
    BOARD_InitPins();//missing function added
}
```

- [PinMux Tool](#).
- Set environment:

```
export ARMGCC_DIR=<DIRECTORY>/gcc-arm-11.2-2022.02-x86_64-arm-none-eabi
```

- To build an example run:

```
<DIR>/armgcc/build_.sh
```

- Running the application on Cortex-4:
  - Setup TFTP on PC:

```
~$ sudo apt update

~$ sudo apt install tftpd-hpa

~$ sudo systemctl status tftpd-hpa

Change username and directory:

~$ sudo nano /etc/default/tftpd-hpa

~$ sudo mkdir /tftp

~$ sudo chown tftp:tftp /tftp

~$ sudo systemctl restart tftpd-hpa

~$ sudo systemctl status tftpd-hpa
```

- Copy .bin to TFTP/:

```
~$ sudo cp release/app.bin ~<DIR>/tftp/

~$ sudo chown tftp:tftp ~<DIR>/tftp/app.bin
```

- Open terminal on PC with the following config:

```
~$ sudo picocom -b 115200 /dev/ttyUSB*
```

- Load u-boot on IMX8MM-EVK.
- To run TCM builds from u-boot:

```
=> setenv <env_name> "dhcp; setenv serverip <ip_addr>; tftp 0x48000000 <application>.bin; cp.b 0x48000000 0x7e0000
0x20000; bootaux 0x7e0000"

=> saveenv

=> run <env_name>
```

- Open terminal for Cortex-M4 to see serial output from the app running on it.

## Testing Examples

- **ECSPI Driver**

- Interrupt B2B Transfer master as loopback using a single board.
- Connect MOSI and MISO pins physically on board (J1003-PIN\_19-ECSPI2\_MOSI & J1003-PIN\_21-ECSPI2\_MISO ).
- Edition in driver code:

Assign **masterTxData** and **masterRxData** buffer to `escpi_transfer_t` object.

- **GPIO Driver**

- Used `led_output` example.
- Digital output -> Digital input (rising edge triggered).
- Changing pin from **ECSPI2\_MOSI** to **SAI5\_RXD0** in `pinmux.c`.

Refer to [PinMux Tool](#) for more information.

- Interrupt Enabled on GPIO pin J1003-38 (originally configured to J1003-19).
- Implement **GPIO3\_Combined\_16\_31\_IRQHandler()** function.

## Extras

- [Logic Analyzer](#)
- [ARM GCC Toolchain](#)

## Spark SDK & UWB

Historical Background of UWB: <https://semiwiki.com/5g/283112-the-story-of-ultra-wideband-part-1-the-genesis/>

## Tools and Software

- SDK & Documentation: <https://www.sparkmicro.com/products/#SDK>.
- The version we used: was **v1.0.0**.
- [CubeIDE](#) for debugging.
- STM32 ST-Link V2.
- [STM32CubeProgrammer](#) to flash .bin files.

## Testing Examples

- Add SDK to the workspace in CubeIDE.
- Connect the EVK board via STM32 ST-Link V2.
- Build the project and start debugging.

- **Audio Streaming**

- Added necessary functions and header files for serial output as implemented in the Hello World example.

```
void iface_board_init(void)
{
    evk_init();
    usb_detect_callback_init();
    usb_connection_init();
}

void evk_usb_device_cdc_send_buf(uint8_t *buf, uint16_t buf_len);
```

- Serial output:

```
~$ sudo picocom -b 112500 /dev/ttyACM*
```

- Generating a custom sine wave and sending it through the wireless core.
  - Codec writes data into DMA then DMA transfer the data to the wireless core.
  - Implementing our sine wave where the codec generates buffer and starts the DMA; "iface\_audio\_evk.c".
  - Amplitude = 32767.0.
  - Sample Rate = 48kHz.

```
uint8_t dummy[256];
static uint16_t ep_max98091_action_produce(void *instance, uint8_t *data, uint16_t size)
{
    (void)instance;

    int16_t *samples = (int16_t *)data;
    uint16_t samples_count = size / 2;
    for (int n = 0; n < samples_count / 2; n = n + 2)
    {
        samples[n] = wave[samples_count];
        samples[n + 1] = samples[n];
        samples_count += 1;
        if (samples_count >= 48000)
        {
            samples_count = 0;
        }
    }

    evk_audio_sai_read_non_blocking(dummy, size);

    return 0;
}

static void ep_max98091_start_produce(void *instance)
{
    (void)instance;
    for (int n = 0; n < 48000; n++)
    {
        wave[n] = (double)(AMP * sinf((M_PI * 2 / SAMPLE_RATE) * FREQUENCY * n));
    }

    evk_audio_sai_start_read_non_blocking();
}
```

## Implementation of Spark Stack on MCUXpresso SDK

- Spark stack [porting guide](#).
- Add Spark Wireless Core API to hello\_world example in XpressoSDK
- Add executables and header files in armgcc/CMakeList.txt.
- Wireless Core API is contained in hello\_world/wireless directory
- Adapt BSP interface. Implemented in hello\_world/**SR1020.h**

### Pin configuration on IMX8-EVK:

J1003 Expansion Connector		
Pin Number	Net Name	Description
1	VEXT_3V3	Power Output, 3.3V
19	ECSPI2_MOSI	SPI2 data signal, master output slave input
21	ECSPI2_MISO	SPI2 data signal, master input slave output
23	ECSPI2_SCLK	SPI2 clock signal
24	GPIO5_IO13	GPIO5 chip select signal
36	GPIO3_IO21	Radio shutdown
37	GPIO3_IO22	Radio reset
38	GPIO3_IO23	External radio interrupt
39	GND	Ground

### Pin configuration on SR1020 chip:

Pin Number	Net Name
1	Radio shutdown
2	IRQ
3	CS
4	SCK
5	MOSI
6	MISO
7	RSTN
8	3V3
9	GND