

HW1 Intelligent Systems
Linear classification & optimization

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Fall 2023

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Q1: Convex optimization (Theory)

A: Finding optimal point

If f is a convex function, it has only one optimal point which is globally optimal.

In order to experiment whether f is convex or non-convex, we construct its **Hessian matrix**.

$$\begin{aligned}f(x_1, x_2) &= 100(x_2 - x_1)^2 + (1 - x_1)^2 \\ \nabla f(x_1, x_2) &= \begin{bmatrix} -200(x_2 - x_1) - 2(1 - x_1) \\ 200(x_2 - x_1) \end{bmatrix} \\ \nabla^2 f(x_1, x_2) &= \begin{bmatrix} 202 & -200 \\ -200 & 200 \end{bmatrix}\end{aligned}$$

Since Hessian matrix is positive definite, we conclude f is a convex function and its global optimal point is where $\nabla f(x_1, x_2) = 0$.

$$\nabla f(x_1, x_2) = \begin{bmatrix} -200(x_2 - x_1) - 2(1 - x_1) \\ 200(x_2 - x_1) \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \rightarrow \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

B: Finding optimal point with steepest descent method

1.

$$\nabla f(x_1, x_2) = \begin{bmatrix} -200(x_2 - x_1) - 2(1 - x_1) \\ 200(x_2 - x_1) \end{bmatrix}$$

2.

```
1: Initial guess  $\mathbf{x}_0$  at  $k = 0$ 
2: while  $\|\nabla f(\mathbf{x}_k)\| > \text{accuracy}$  do
3:   Find the search direction  $\mathbf{s}_k = -\nabla f(\mathbf{x}_k)$ 
4:   Solve for  $\alpha_k$  by decreasing  $f(\mathbf{x}_k + \alpha \mathbf{s}_k)$  significantly
5:     satisfying the Wolfe conditions
6:   Update the result  $\mathbf{x}_{k+1} = \mathbf{x}_k + \alpha_k \mathbf{s}_k$ 
7:    $k \leftarrow k + 1$ 
8: end while
```

$$\mathbf{X}_0 = \begin{bmatrix} 0 \\ 0 \end{bmatrix}, \alpha = 0.5$$

$k = 0$:

$$\nabla f(\mathbf{X}_0) = \begin{bmatrix} -2 \\ 0 \end{bmatrix}$$

$$\mathbf{X}_1 = \mathbf{X}_0 - \alpha \nabla f(\mathbf{X}_0) = \begin{bmatrix} 0 \\ 0 \end{bmatrix} - 0.5 \times \begin{bmatrix} -2 \\ 0 \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

$k = 1$:

$$\nabla f(X_1) = \begin{bmatrix} 200 \\ -200 \end{bmatrix}$$

$$X_2 = X_1 - \alpha \nabla f(X_1) = \begin{bmatrix} 1 \\ 0 \end{bmatrix} - 0.5 \times \begin{bmatrix} 200 \\ -200 \end{bmatrix} = \begin{bmatrix} -99 \\ 100 \end{bmatrix}$$

C: Finding optimal point with Newton method

1.

$$\text{Hessian Matrix: } \nabla^2 f(x_1, x_2) = \begin{bmatrix} 202 & -200 \\ -200 & 200 \end{bmatrix}$$

2.

Algorithm 3: Newton's Method

```
input :  $f : \mathbb{R}^n \rightarrow \mathbb{R}$  a twice-differentiable function  
        $\mathbf{x}^{(0)}$  an initial solution  
output:  $\mathbf{x}^*$ , a local minimum of the cost function  $f$ .  
1 begin  
2    $k \leftarrow 0$  ;  
3   while STOP-CRIT and  $(k < k_{max})$  do  
4      $\mathbf{x}^{(k+1)} \leftarrow \mathbf{x}^{(k)} + \delta^{(k)}$  ;  
5     with  $\delta^{(k)} = -(\mathbf{H}_f(\mathbf{x}^{(k)}))^{-1} \nabla f(\mathbf{x}^{(k)})$  ;  
6      $k \leftarrow k + 1$  ;  
7   return  $\mathbf{x}^{(k)}$   
8 end
```

$$X_0 = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$k = 0$:

$$\nabla f(X_0) = \begin{bmatrix} -2 \\ 0 \end{bmatrix}, \nabla^2 f(X_0) = \begin{bmatrix} 202 & -200 \\ -200 & 200 \end{bmatrix} \rightarrow \nabla^2 f(X_0)^{-1} = \begin{bmatrix} 0.5 & 0.5 \\ 0.5 & 101/200 \end{bmatrix}$$

$$X_1 = X_0 - \nabla^2 f(X_0)^{-1} \nabla f(X_0) = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

Since f is a convex function, it converges to optimal point with 1 iteration.

Q2: Non-convex optimization

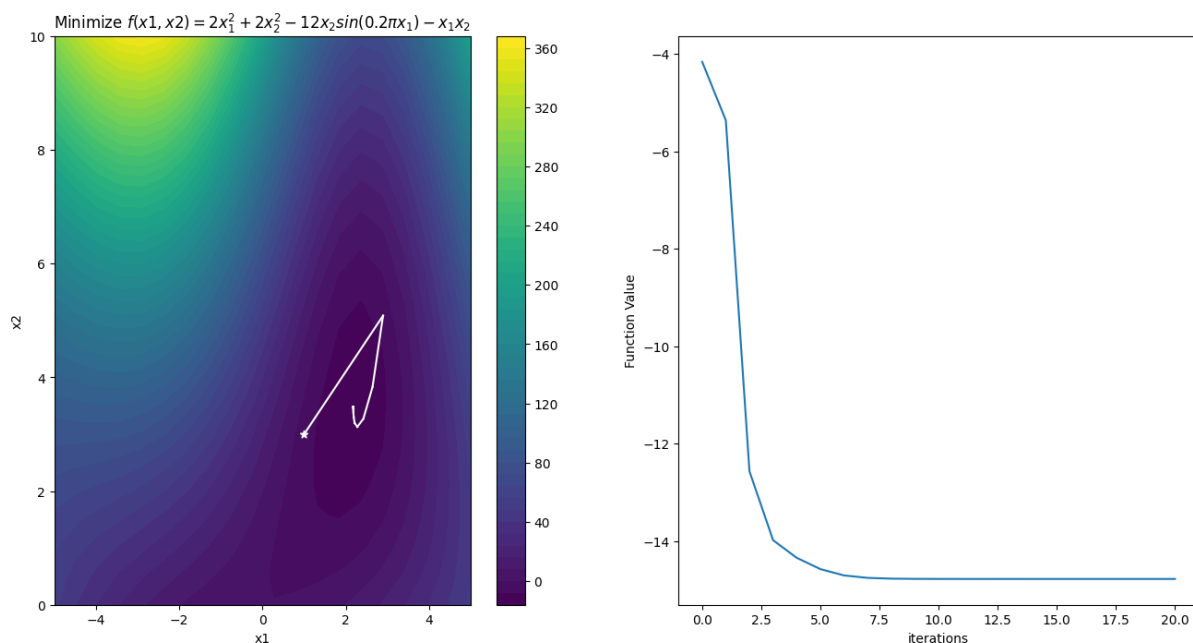
A: Newton implementation

$$f(X) = 2x_1^2 + 2x_2^2 - 12x_2 \sin(0.2\pi x_1) - x_1 x_2$$

$$\nabla f(X) = \begin{bmatrix} 4x_1 - 2.4\pi x_2 \cos(0.2\pi x_1) - x_2 \\ 4x_2 - 12 \sin(0.2\pi x_1) - x_1 \end{bmatrix}$$

$$\nabla^2 f(X) = \begin{bmatrix} 4 + 0.48\pi^2 x_2 \sin(0.2\pi x_1) & -2.4\pi \cos(0.2\pi x_1) - 1 \\ -2.4\pi \sin(0.2\pi x_1) - 1 & 4 \end{bmatrix}$$

When starting from the initial point $X_0 = \begin{bmatrix} 1 \\ 3 \end{bmatrix}$, the Newton method converges to the optimal point $X_* = \begin{bmatrix} 2.18 \\ 3.48 \end{bmatrix}$ with a corresponding value of $f(X_*) = -14.78$. Below, you can observe the convergence plot and the cost function plot over the course of iterations.



B: Meta-heuristic (Simulated annealing)

Pseudocode of simulated annealing is written as follows.

Simulated annealing algorithm

```
1  Select the best solution vector  $x_0$  to be optimized
2  Initialize the parameters: temperature  $T$ , Boltzmann's constant  $k$ , reduction factor  $c$ 
3  while termination criterion is not satisfied do
4      for number of new solution
5          Select a new solution:  $x_0 + \Delta x$ 
6          if  $f(x_0 + \Delta x) > f(x_0)$  then
7               $f_{\text{new}} = f(x_0 + \Delta x)$ ;  $x_0 = x_0 + \Delta x$ 
8          else
9               $\Delta f = f(x_0 + \Delta x) - f(x_0)$ 
10             random  $r(0, 1)$ 
11             if  $r > \exp(-\Delta f/kT)$  then
12                  $f_{\text{new}} = f(x_0 + \Delta x)$ ,  $x_0 = x_0 + \Delta x$ 
13             else
14                  $f_{\text{new}} = f(x_0)$ ,
15             end if
16         end if
17          $f = f_{\text{new}}$ 
18     Decrease the temperature periodically:  $T = c \times T$ 
19 end for
20 end while
```

In this problem neighbors are defined as below:

$$x_{\text{neighbor}} = x_{\text{current}} + N(0,0.5)$$

With choosing the following initial parameters, the best solution is $X_* = \begin{bmatrix} -2.21 \\ -3.56 \end{bmatrix}$ with $f(X_*) = -14.76$.

$$\text{Initial solution: } X_0 = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\text{Initial temprature: } T_0 = 100$$

$$\text{Cooling rate: } T_{k+1} = \frac{T_k}{1+k}$$

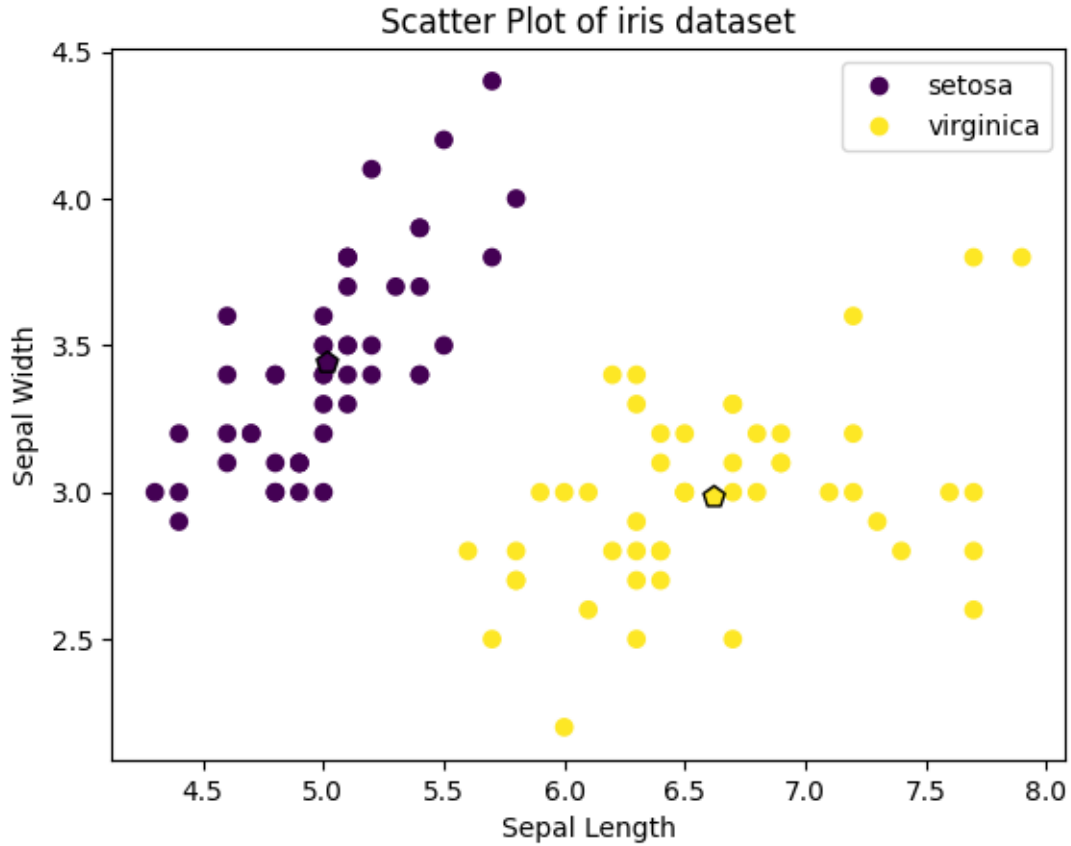
$$\text{Search space: } \begin{bmatrix} -15 < x_1 < 15 \\ -15 < x_2 < 15 \end{bmatrix}$$

$$\text{Num iterations} = 100$$

Q3: SVM

A: Data preparation

The scatter matrix of the Iris dataset is depicted below, with each class's mean represented using a '△' sign.



B: Classifier implementation

In soft SVM, the cost function is as follows. The weights (w) and bias (b) are updated using mini-batch gradient descent, following these update rules:

$$\text{Cost function: } L(w, b, c) = 0.5 \|w\|^2 + C \sum \text{Max}(0, 1 - y_i(w^T x_i + b))$$

$$w \leftarrow w - \eta \nabla L_w = w - \eta w + \eta C y_i x_i$$

$$b \leftarrow b - \eta \nabla L_b = b + \eta C y_i$$

C: Model training

The final weights are recorded as follows:

$$w = \begin{bmatrix} -1.539 \\ 2.48 \end{bmatrix}, b = 0.83$$

D: Performance measurement

The loss and precision for the test set are recorded as follows:

$$\text{loss} = 4.34$$

	precision	recall	f1-score	support
-1	1.00	1.00	1.00	8
1	1.00	1.00	1.00	11
accuracy			1.00	19
macro avg	1.00	1.00	1.00	19
weighted avg	1.00	1.00	1.00	19

Also the classification result is depicted below:

