

Optimization Techniques of Multi-Cooperative Systems (MCTR 1021)

Tutorial (04) Genetic Algorithm (GA)

Presented by:

Mohamed A. Ibrahim, Jessica Magdy, Dalia Mamdouh, Mohamed Ashraf, Abdulrahman Yasser, Dr. Omar M. Shehata

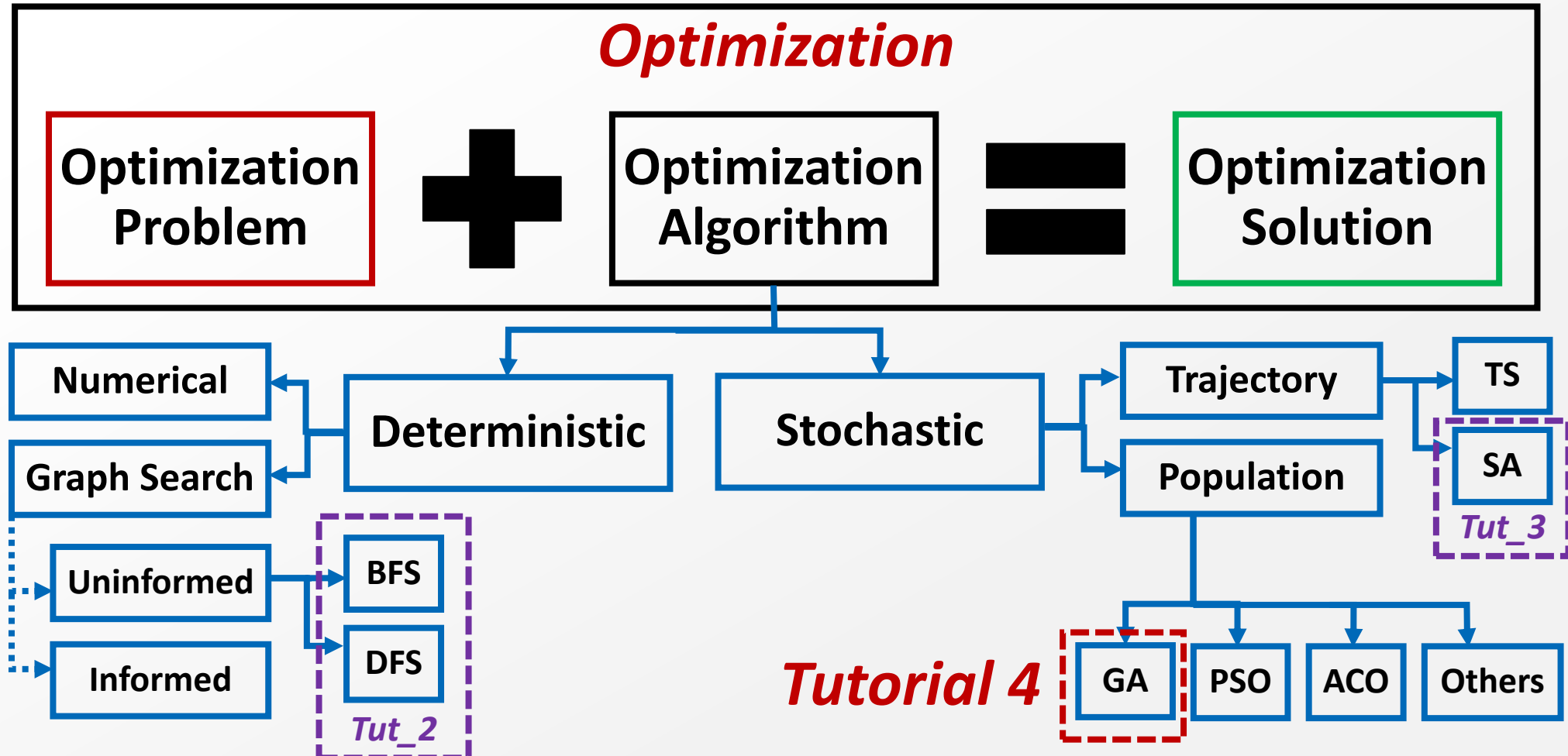
Outline

- Tutorial 3 Recap
- Genetic Algorithm
- Application to Function Optimization
- Assembly Line Balancing Problem
- Techniques Comparison

Tutorial 3 Recap: Course Overview

- Tutorial 3 Recap

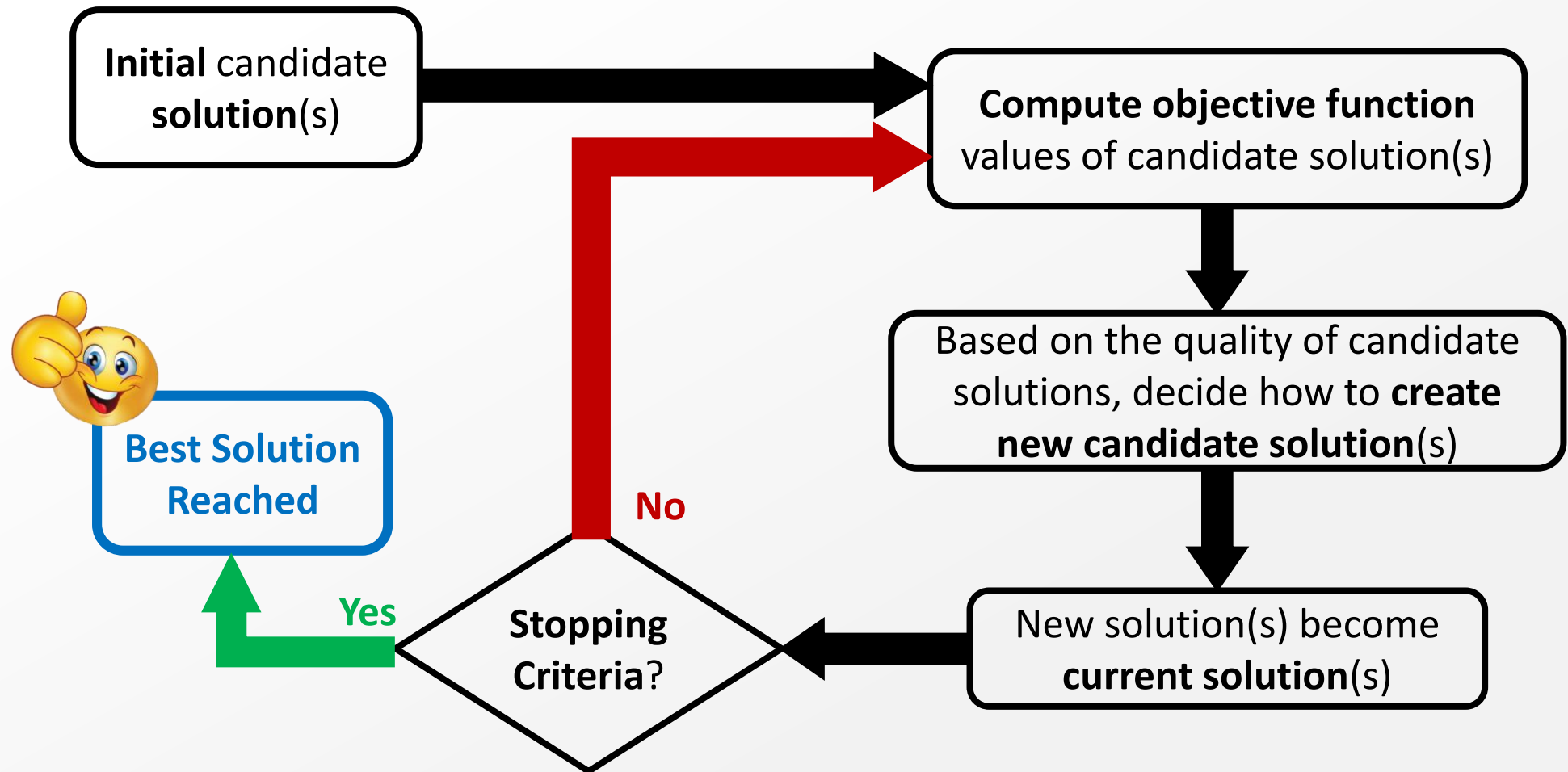
- Genetic Algorithm
- Application to Function Optimization
- Assembly Line Balancing Problem
- Techniques Comparison



Tutorial 3 Recap: Metaheuristics Flow Chart

- Tutorial 3 Recap

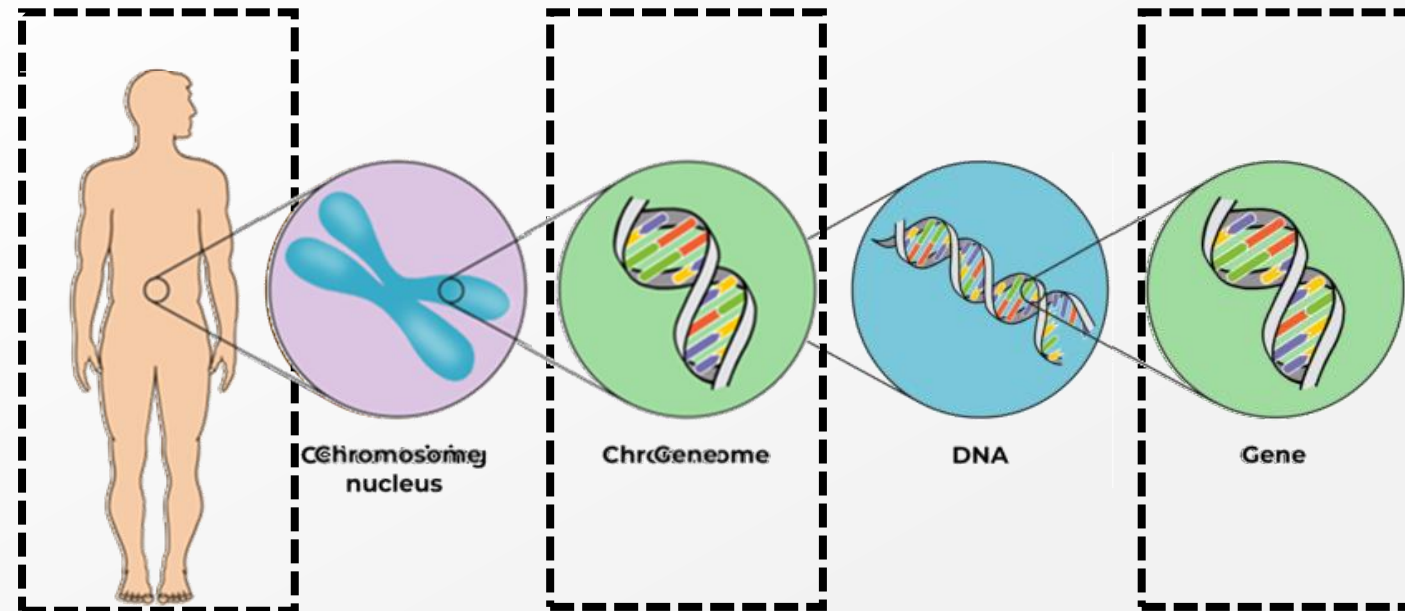
- Genetic Algorithm
- Application to Function Optimization
- Assembly Line Balancing Problem
- Techniques Comparison



Genetic Algorithm

- Tutorial 3 Recap
- **Genetic Algorithm**
- Application to Function Optimization
- Assembly Line Balancing Problem
- Techniques Comparison

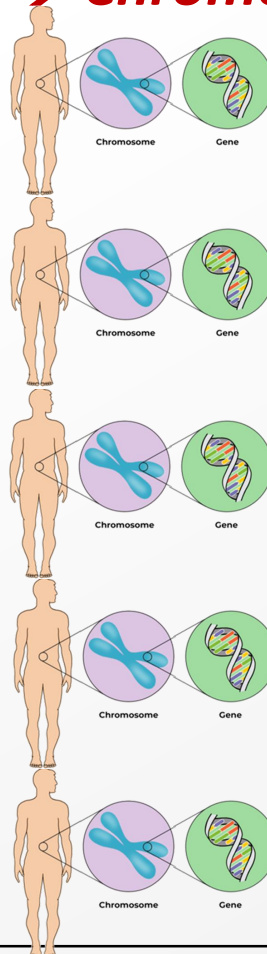
- Genetic Algorithm (GA) was developed by Holland (1975) and was popularized by Goldberg (1989) inspired by the **genetic evolution**.



- Tutorial 3 Recap
- **Genetic Algorithm**
- Application to Function Optimization
- Assembly Line Balancing Problem
- Techniques Comparison

Genetic Algorithm

Individual → Chromosome → Genes



Population
(0)

+

Time
(0)

=

Generation
(0)

⋮

Population
(i)

+

Time
(i)

=

Generation
(i)



Genetic Algorithm

- Tutorial 3 Recap
- **Genetic Algorithm**
- Application to Function Optimization
- Assembly Line Balancing Problem
- Techniques Comparison

- The basic idea behind the GA is the Darwinian principle of **survival of the fittest** among organisms threatened by predators and environmental hazards.
- The fittest members have a better chance of survival than others.
- They are more likely to adapt to evolving conditions, and **their offspring may inherit** their traits and learn their skills, thus producing even fitter future generations.
- Furthermore, genetic **mutations** occur randomly in members of species, and some of those mutations **may improve** the chances of long-term persistence of fit individuals and their evolutionary descendants.

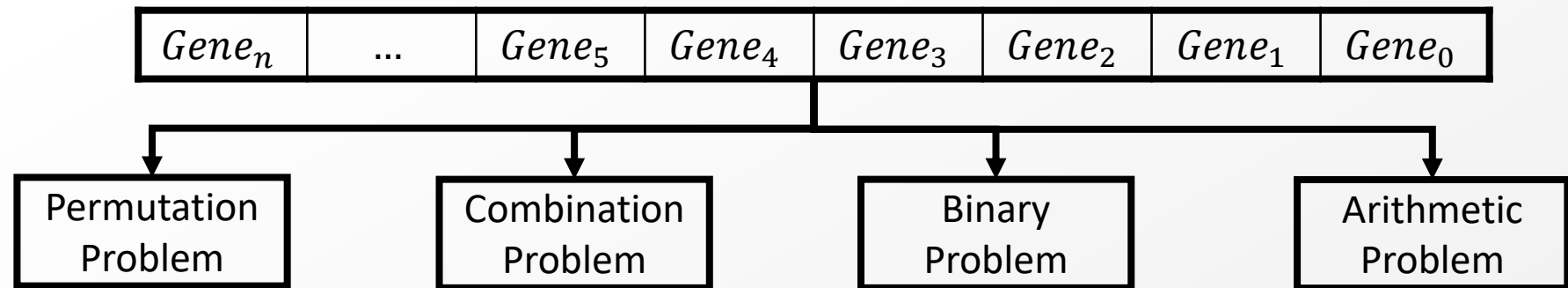
Genetic Algorithm: Analogy

- Tutorial 3 Recap
- **Genetic Algorithm**
- Application to Function Optimization
- Assembly Line Balancing Problem
- Techniques Comparison

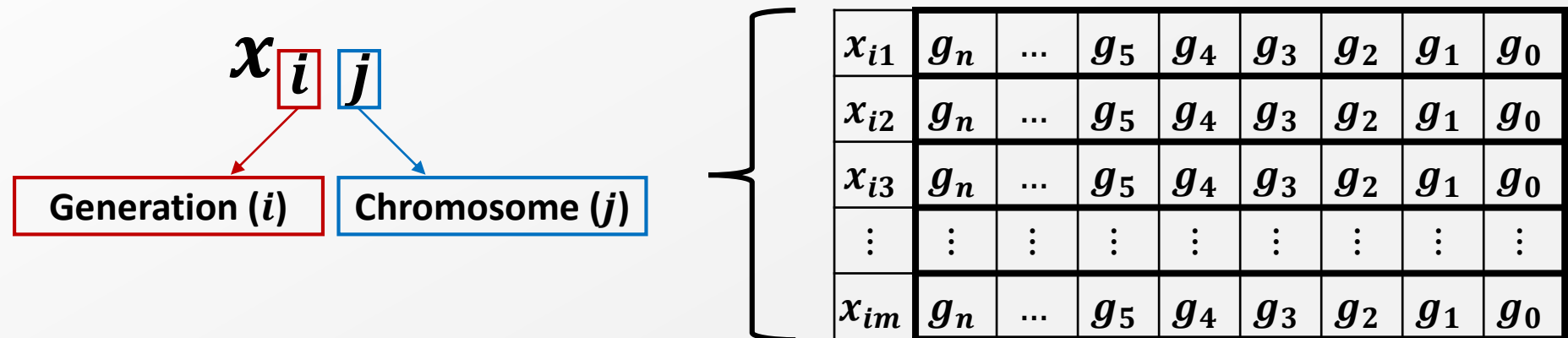
Optimization Algorithm	Genetic Algorithm
Decision Variable	Gene
Solution	Chromosome \equiv Individual
(N) Solutions/Iteration	Population Size
Max. Number of Iterations	Number of Generations
Objective Function	Fitness Function
Old Solution	Parent
New Solution	Off-spring
Best Solution	Elite
Selection of Solutions	Surviving Parents
Generation of Solutions	Genetic Operators

Genetic Algorithm: Solution Representation

- Chromosome Representation: (n Genes)



- Generation Representation: (m Chromosomes)



- Tutorial 3 Recap
- **Genetic Algorithm**
- Application to Function Optimization
- Assembly Line Balancing Problem
- Techniques Comparison

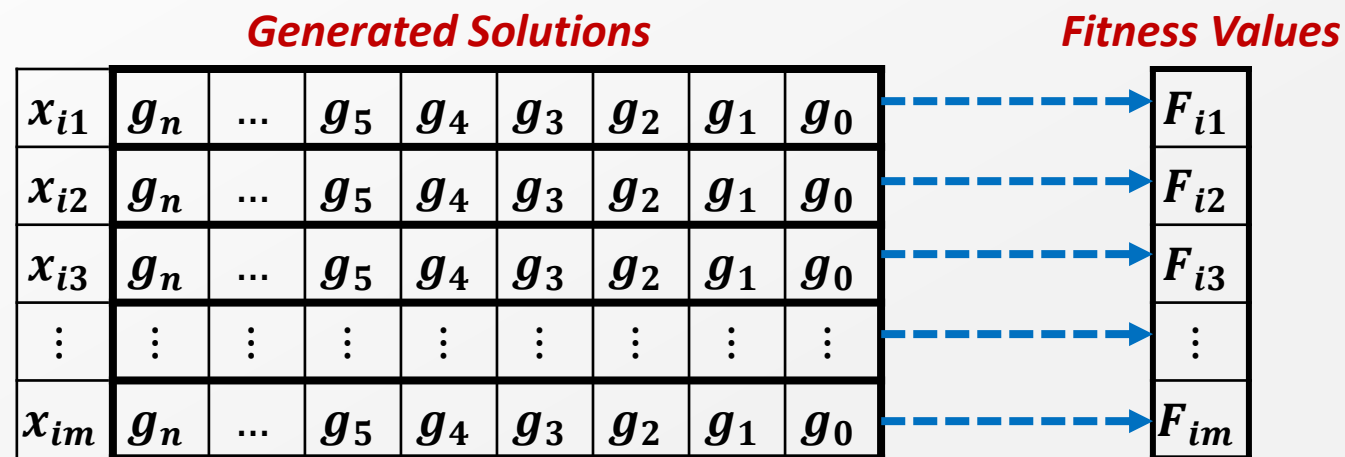
Genetic Algorithm: Fitness Function

- **For a multi-objective function**

$$F(x) = \min \left(f_1 + f_2 + \frac{1}{f_3} \right)$$

Minimize f_1 and f_2 & maximize f_3

- Evaluate the fitness value for each chromosome



- Tutorial 3 Recap
- **Genetic Algorithm**
- Application to Function Optimization
- Assembly Line Balancing Problem
- Techniques Comparison

Genetic Algorithm: Process

- Tutorial 3 Recap
- **Genetic Algorithm**
- Application to Function Optimization
- Assembly Line Balancing Problem
- Techniques Comparison

1. Select parents from old generation to mate.

(Parents Selection)

2. Perform GA operators from the selected parents to produce new off-springs.

(Cross-Over & Mutation)

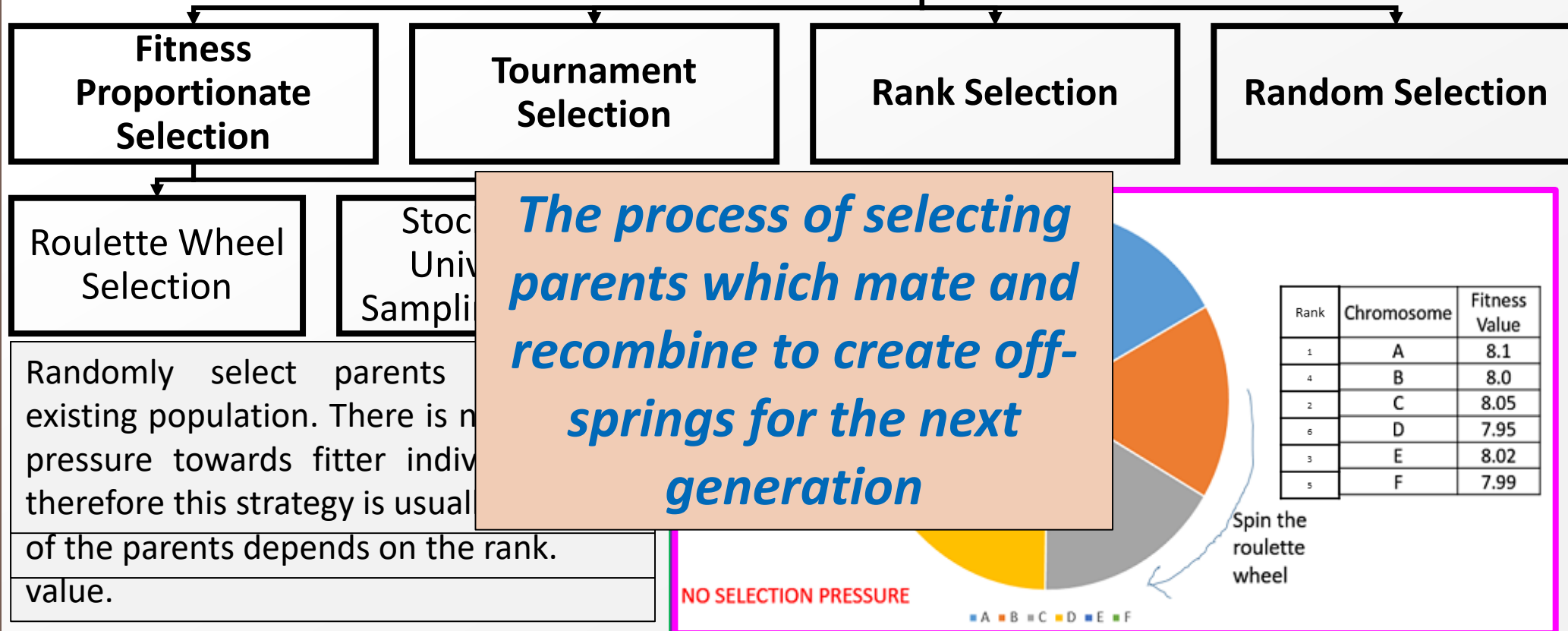
3. Which individuals are to be kicked out to be replaced by new children and which are to be kept in the next generation.

x_{i1}	New Children
\vdots	
x_{ij}	
x_{ij+1}	Survivors
\vdots	
x_{im}	

(Survivor Selection)

- Tutorial 3 Recap
- **Genetic Algorithm**
- Application to Function Optimization
- Assembly Line Balancing Problem
- Techniques Comparison

Genetic Algorithm: **Parent Selection**



Multiple Fixed Points → multiple parents

- Tutorial 3 Recap
- **Genetic Algorithm**
- Application to Function Optimization
- Assembly Line Balancing Problem
- Techniques Comparison

Genetic Algorithm: GA Operators

Elitism

- The chromosomes with the best fitness values.
- Elitism is usually applied in a GA with a **low** probability – p_e .

(Survivors)?

Cross-Over

- The crossover operator is analogous to **reproduction and biological crossover**.
- In each cross-over process, **2 parents** are selected to produce **2 off-springs** using the genetic material of the parents.
- Crossover is usually applied in a GA with a **high** probability – p_c .

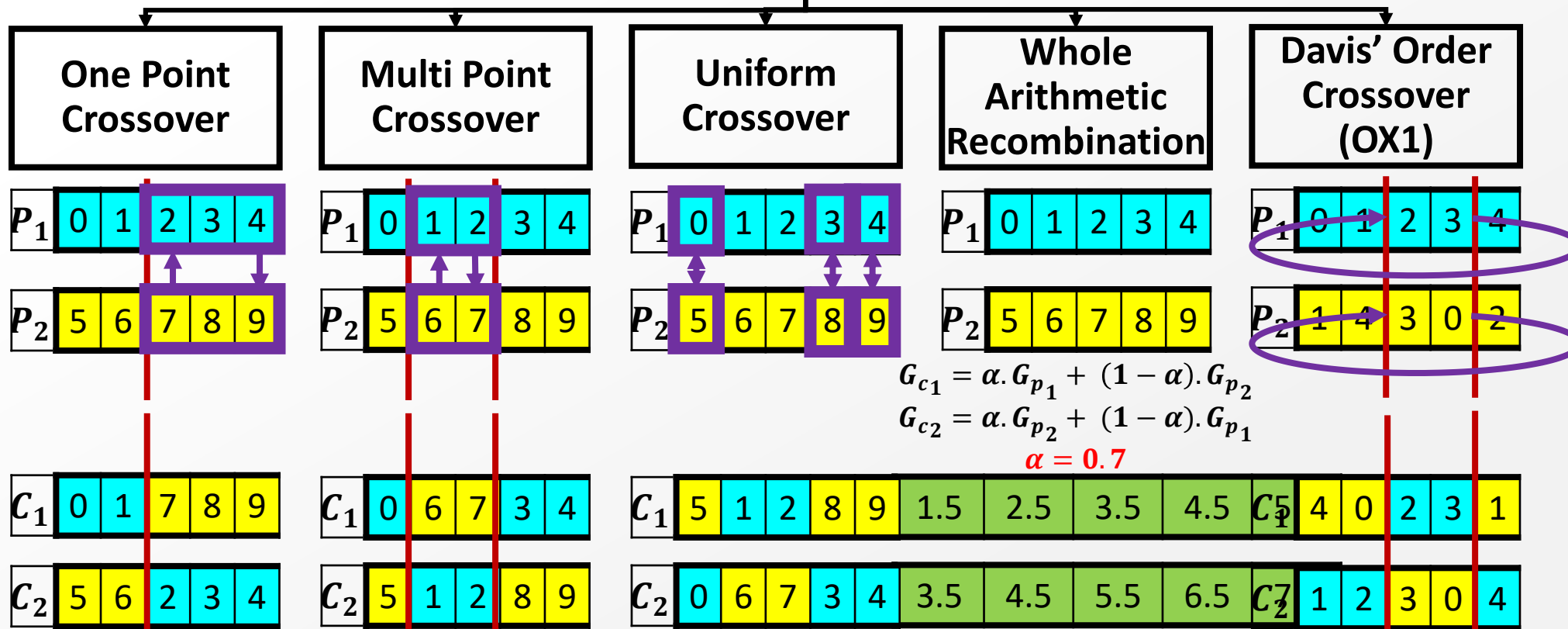
Mutation

- mutation may be defined as a **small random tweak** in the chromosome, to get a new solution.
- It is used to **maintain and introduce diversity** in the genetic population
- In each Mutation process, **1 parent** is selected to produce **1 child**.
- Mutation is usually applied with a **low** probability – p_m

$$p_e + p_c + p_m \leq 100\%$$

- Tutorial 3 Recap
- **Genetic Algorithm**
- Application to Function Optimization
- Assembly Line Balancing Problem
- Techniques Comparison

Genetic Algorithm: **Cross-Over**



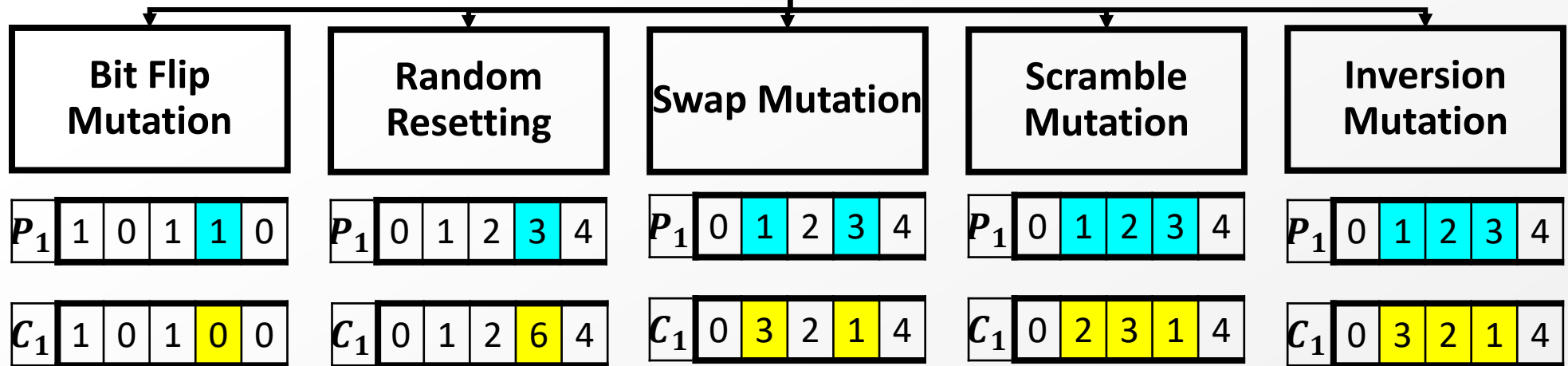
Used for permutation based crossovers with the intention of transmitting information about relative ordering to the off-springs.

- Tutorial 3 Recap
- **Genetic Algorithm**
- Application to Function Optimization
- Assembly Line Balancing Problem
- Techniques Comparison

Genetic Algorithm:

Mutation

Exploration

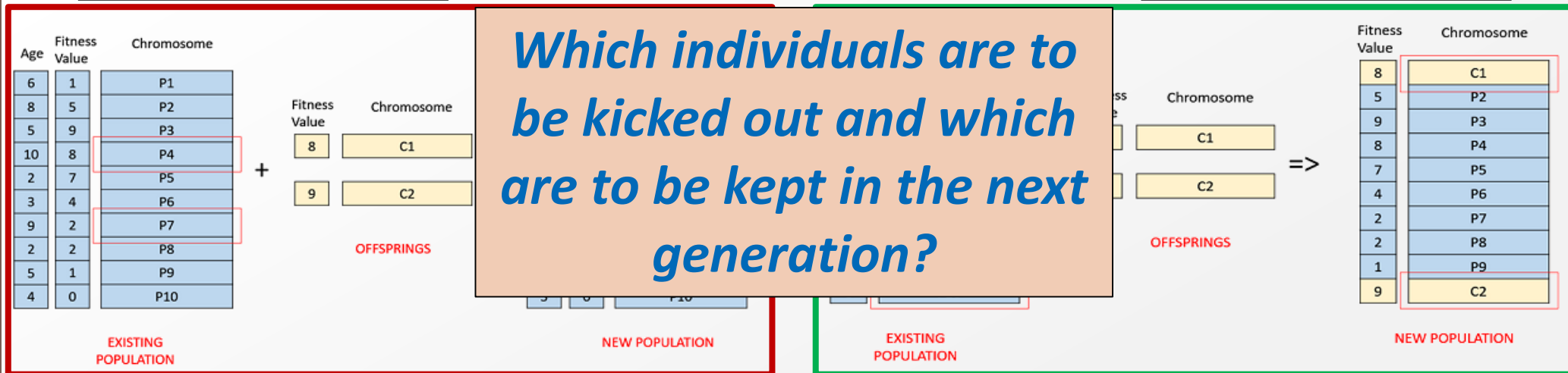


Select a subset of genes like in scramble mutation, but instead of shuffling the subset, we merely invert the entire string in the subset.

Genetic Algorithm: Survivor Selection

Age Based Selection

Fitness Based Selection



The newly generated children tend to kick-out the members with the worst fitness value. Thus, **the survivors from old generation are the Elite Members.**

recent Members.

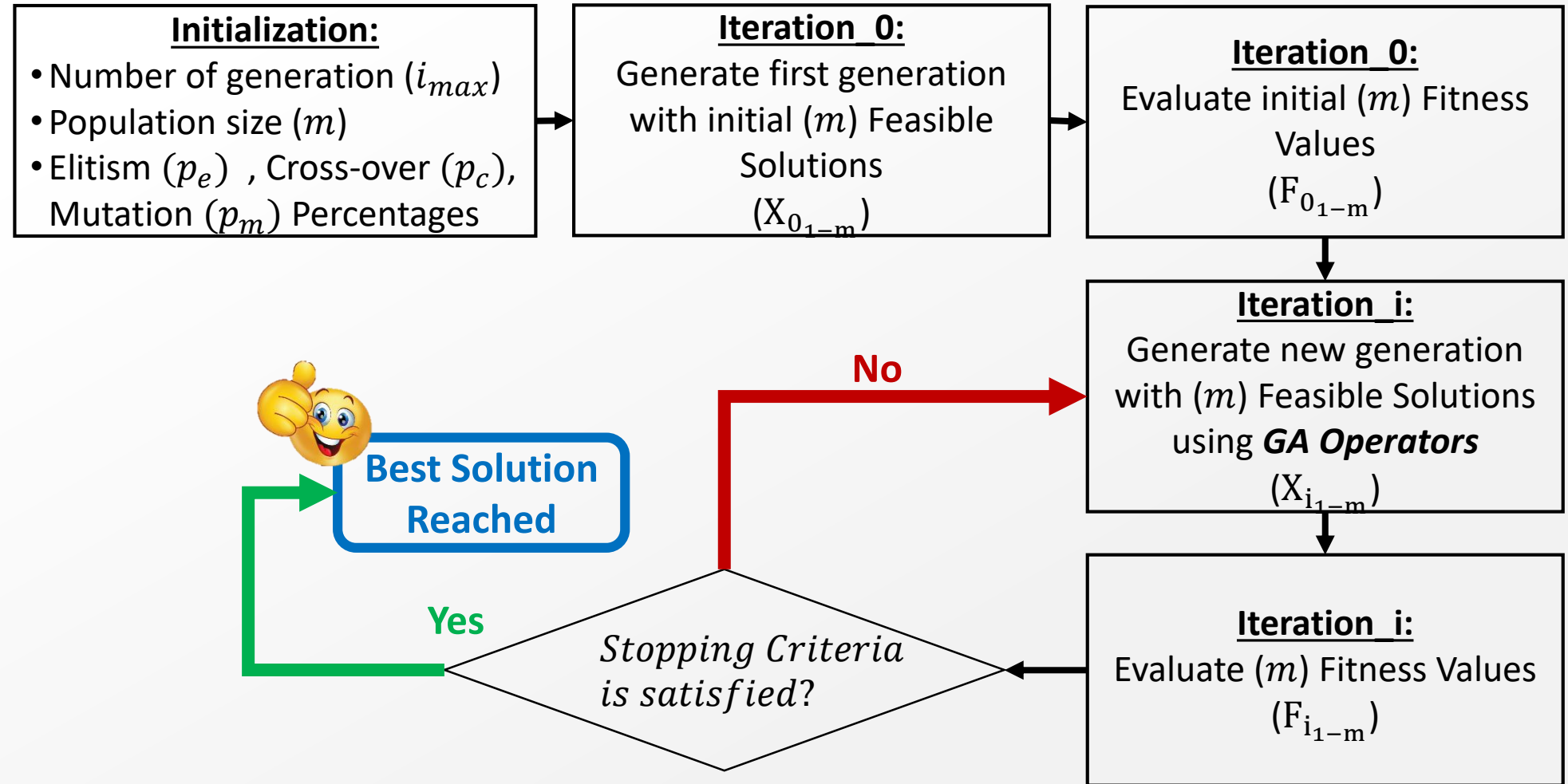
Genetic Algorithm: Stopping Criteria

- Tutorial 3 Recap
- **Genetic Algorithm**
- Application to Function Optimization
- Assembly Line Balancing Problem
- Techniques Comparison

- When there has been no improvement in the population for X iterations.
- When we reach an absolute number of generations.
- When the objective function value has reached a certain pre-defined value.

Genetic Algorithm: Flow Chart

- Tutorial 3 Recap
- **Genetic Algorithm**
- Application to Function Optimization
- Assembly Line Balancing Problem
- Techniques Comparison



- Tutorial 3 Recap
- **Genetic Algorithm**
- Application to Function Optimization
- Assembly Line Balancing Problem
- Techniques Comparison

Genetic Algorithm: **Algorithm**

- Decision Variables: $\underline{x} = x_1, x_2, \dots, x_p$
- Objective Function: $f(\underline{x})$
- Initialize $\underline{x}, i_{max}, m, p_e, p_c, p_m, x^*, f^*$

While **Stopping Criteria** Ex. ($i \leq i_{max}$):

Generate random new population with (m) chromosomes x_{new} :

- p_e Elite members are survived from x_{prev}
- p_c Cross-over best members from x_{prev}
- p_m mutate worst members from x_{prev}

Compute fitness value: $f(x_{new})$

Update iteration counter: $i = i + 1$

Output best reached solution x^*, f^*

Case#1: Function Minimization using GA

- Tutorial 3 Recap
- Genetic Algorithm
- **Application to Function Optimization**
- Assembly Line Balancing Problem
- Techniques Comparison

- **Problem Statement:**

Find the minimum point of the function:

$$f(x) = -x^3 + 60x^2 - 900x - 100$$

subject to: $0 \leq x \leq 32$

- **Use GA with the following parameters:**

- Number of generations = 200
- Population size = 5 → 5 chromosomes
- 20% elitism (as survivor selection) → 1 member
- 60% cross-over (*Elites parents selection & 1 point cross-over*) → 3 members
- 20% mutation (*Worst Member parent selection & Flip*) → 1 member

- Perform 1 iteration only.

Case#1: Function Minimization using GA

- Tutorial 3 Recap
- Genetic Algorithm
- **Application to Function Optimization**
- Assembly Line Balancing Problem
- Techniques Comparison

- **Solution Representation:**

- Chromosome Representation: (Binary)

$X = 0$

$Gene_5$	$Gene_4$	$Gene_3$	$Gene_2$	$Gene_1$	$Gene_0$
0	0	0	0	0	0

$X = 32$

1	0	0	0	0	0
---	---	---	---	---	---

- Generation Representation: (5 Chromosomes)

x_{i1}	g_5	g_4	g_3	g_2	g_1	g_0
x_{i2}	g_5	g_4	g_3	g_2	g_1	g_0
x_{i3}	g_5	g_4	g_3	g_2	g_1	g_0
x_{i4}	g_5	g_4	g_3	g_2	g_1	g_0
x_{i5}	g_5	g_4	g_3	g_2	g_1	g_0

Case#1: Function Minimization using GA

- **Iteration_0:** Initial Solution

x_{01}	1	0	0	0	0	0	$X = 32$	---	F_{01}	228
x_{02}	0	1	0	0	0	1	$X = 17$	---	F_{02}	-2973
x_{03}	0	0	0	1	0	0	$X = 4$	---	F_{03}	-2804
x_{04}	0	0	1	0	1	0	$X = 10$	---	F_{04}	-4100
x_{05}	0	1	0	1	0	1	$X = 21$	---	F_{05}	-1801

→ Elite

- Tutorial 3 Recap
- Genetic Algorithm
- **Application to Function Optimization**
- Assembly Line Balancing Problem
- Techniques Comparison

Case#1: Function Minimization using GA

• *Iteration_1:*

x_{11}	0	0	1	0	1	0	→ Elite of Iteration_0
x_{12}							→ Cross-over Members
x_{13}							
x_{14}							
x_{15}	0	0	0	1	0	1	→ Mutation Member

Mutation Parent	1	0	0	0	0	0
Mutation Child	0	0	0	1	0	1

→ Worst of Iteration_0

- Tutorial 3 Recap
- Genetic Algorithm
- **Application to Function Optimization**
- Assembly Line Balancing Problem
- Techniques Comparison

Case#1: Function Minimization using GA

• **Iteration_1:** Cont'd

x_{11}	0	0	1	0	1	0	→ Elite of Iteration_0
x_{12}	0	0	1	0	0	1	→ Cross-over
x_{13}	0	1	0	0	1	0	Members
x_{14}							
x_{15}	0	0	0	1	0	1	→ Mutation Member

Cross-over Parent1	0	0	1	0	1	0
Cross-over Parent2	0	1	0	0	0	1
Cross-over Child1	0	0	1	0	0	1
Cross-over Child2	0	1	0	0	1	0

→ Elite of Iteration_0

→ 2nd Elite of Iteration_0

- Tutorial 3 Recap
- Genetic Algorithm
- **Application to Function Optimization**
- Assembly Line Balancing Problem
- Techniques Comparison

Case#1: Function Minimization using GA

• **Iteration_1:** Cont'd

x_{11}	0	0	1	0	1	0	→ Elite of Iteration_0
x_{12}	0	0	1	0	0	1	→ Cross-over
x_{13}	0	1	0	0	1	0	Members
x_{14}	0	0	1	1	0	0	
x_{15}	0	0	0	1	0	1	→ Mutation Member

Cross-over Parent1	0	0	1	0	1	0	→ Elite of Iteration_0
Cross-over Parent2	0	0	0	1	0	0	→ 3 rd Elite of Iteration_0
Cross-over Child1	0	0	1	1	0	0	Randomly Select one of the off-springs to survive
Cross-over Child2	0	0	0	0	1	0	

- Tutorial 3 Recap
- Genetic Algorithm
- **Application to Function Optimization**
- Assembly Line Balancing Problem
- Techniques Comparison

Case#1: Function Minimization using GA

• **Iteration_1:** Cont'd

x_{11}	0	0	1	0	1	0	$X = 10$	\dashrightarrow	F_{11}	-4100	\rightarrow Elite
x_{12}	0	0	1	0	0	1	$X = 9$	\dashrightarrow	F_{12}	-4069	
x_{13}	0	1	0	0	1	0	$X = 18$	\dashrightarrow	F_{13}	-2692	
x_{14}	0	0	1	1	0	0	$X = 12$	\dashrightarrow	F_{14}	-3988	
x_{15}	0	0	0	1	0	1	$X = 5$	\dashrightarrow	F_{15}	-3225	

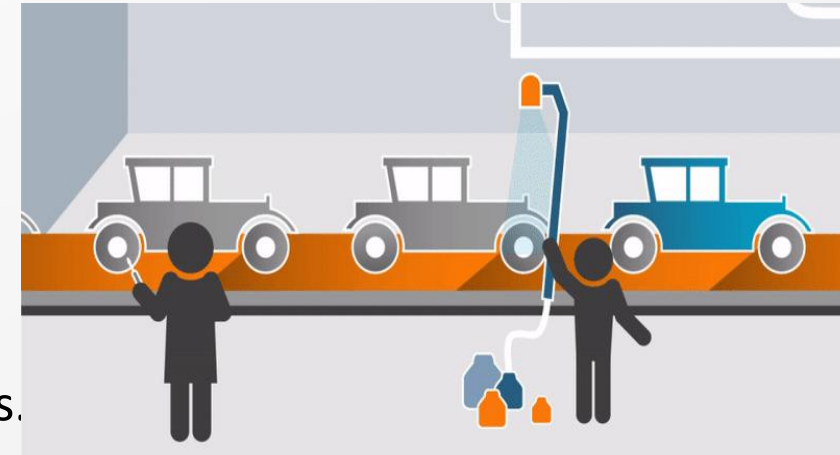
Continue iterating with the same manner

- Tutorial 3 Recap
- Genetic Algorithm
- **Application to Function Optimization**
- Assembly Line Balancing Problem
- Techniques Comparison

Case#2: Assembly Line Balancing

- Tutorial 3 Recap
- Genetic Algorithm
- Application to Function Optimization
- **Assembly Line Balancing Problem**
- Techniques Comparison

- Let there be n tasks (each with time requirement t_i) to be completed by m workstations with a predefined sequence.
- **Decision Variables:**
 - Which task i is done by which workstation j .
- **Objective Function:**
 - Minimize the number of used workstations.
- **Constraint Equation and Inequalities:**
 - Sequential order of tasks (i.e. precedence constraints).
 - Cycle time of the assembly line.
 - Maximum number of workstations.

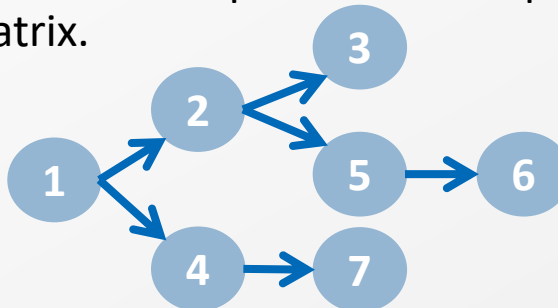


Case#2: Assembly Line Balancing

- Tutorial 3 Recap
- Genetic Algorithm
- Application to Function Optimization
- **Assembly Line Balancing Problem**
- Techniques Comparison

- **Given Data:**

- Time Requirements of each task:
 $t = [t_i] = [1, 5, 4, 3, 5, 6, 5]$
- Required cycle time: $C = 8$
- Precedence Constraints:
 - This can be represented as a vector of tuples.
 $P = [(1, 2), (1, 4), (2, 3), (2, 5), (4, 7), (5, 6)]$
 - Or it can be represented as a precedence matrix.



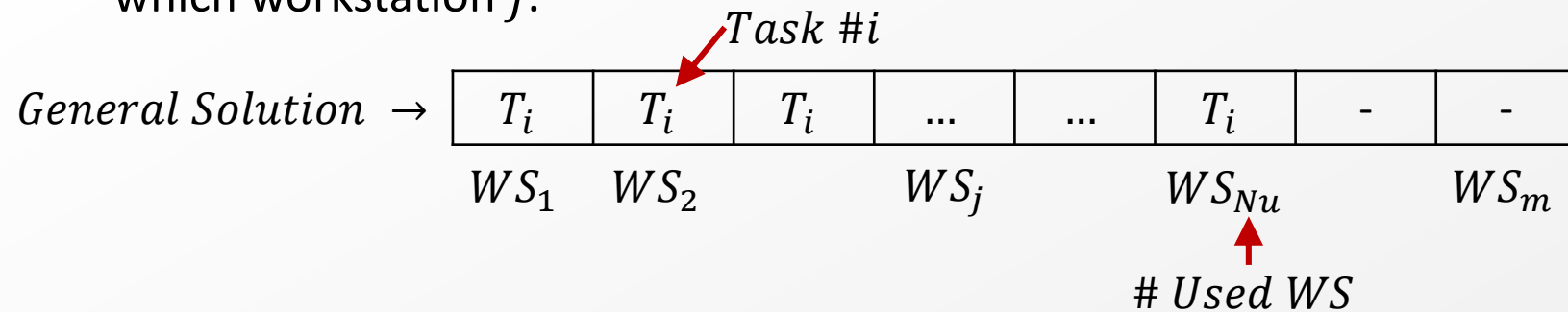
P_{ij} is whether task i has a precedence relation with task j .

	T1	T2	T3	T4	T5	T6	T7
T1	0	1	0	1	0	0	0
T2		0	1	0	1	0	0
T3			0	0	0	0	0
T4				0	0	0	1
T5					0	1	0
T6						0	0
T7							0

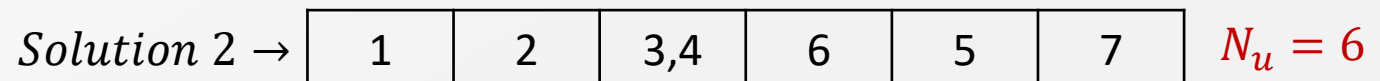
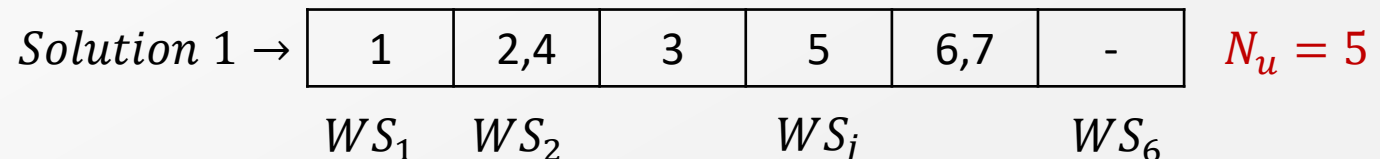
Assembly Line Balancing: Formulation

- ***Solution Representation:***

- Which task i is done by which workstation j .



- **Example:**



- Tutorial 3 Recap
- Genetic Algorithm
- Application to Function Optimization
- **Assembly Line Balancing Problem**
- Techniques Comparison

Assembly Line Balancing: Formulation

- Tutorial 3 Recap
- Genetic Algorithm
- Application to Function Optimization
- **Assembly Line Balancing Problem**
- Techniques Comparison

- **Objective Function:**

- Minimize the number of used workstations.

$$\min f = \min N_u$$

OR

- Minimize the smoothing index (to make sure the workstations are equally loaded as well).

$$\min f = \min SI$$

$$SI = \sqrt{\frac{\sum_{i=1}^{N_u} (WL_i - WL_{max})^2}{N_u}}$$

N_u = number of used WS

WL_i = work load of WS_i

WL_{max} = maximum workload across all WS

Assembly Line Balancing: Formulation

- Tutorial 3 Recap
- Genetic Algorithm
- Application to Function Optimization
- **Assembly Line Balancing Problem**
- Techniques Comparison

- **Constraint Equation and Inequalities:**

- Sequential order of tasks (i.e. precedence constraints).

- Cycle time of the assembly line.

$$WL_i \leq C = 8$$

$$WL_i = \sum t_j ; \text{if } T_j \text{ in } WS_i$$

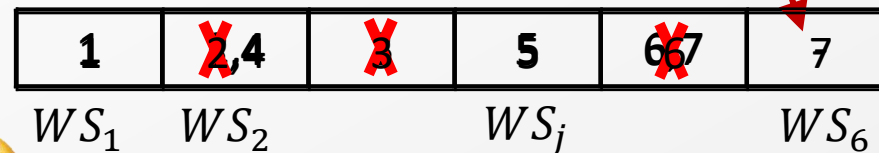
- Maximum number of workstations.

$$N_u \leq m = 6$$

Time Requirements of each task:
 $t = [t_i] = [1, 5, 4, 3, 5, 6, 5]$

	T1	T2	T3	T4	T5	T6	T7
T1	0	1	0	1	0	0	0
T2		0	1	0	1	0	0
T3			0	0	0	0	0
T4				0	0	0	1
T5					0	1	0
T6						0	0
T7							0

Solution 1 →



Assembly Line Balancing: GA

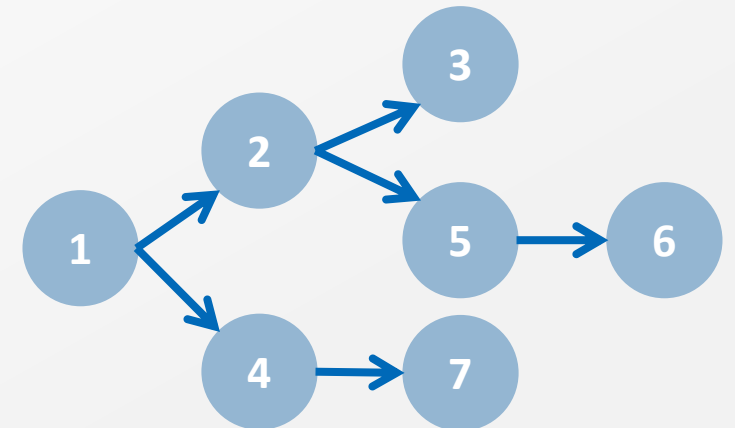
- Tutorial 3 Recap
- Genetic Algorithm
- Application to Function Optimization
- **Assembly Line Balancing Problem**
- Techniques Comparison

- **Given Data:**

- Time Requirements of each task:
 $t = [t_i] = [1, 5, 4, 3, 5, 6, 5]$
- Required cycle time: $C = 8$
- Maximum number of workstations: $m = 6$
- Optimize the smoothing index of the AL.

- **Use GA with the following parameters:**

- Number of generations = 200
- Population size = 4 → 4 chromosomes
- 20% elitism (as survivor selection) → 1 member
- 60% cross-over (*Elites parents selection & Davis' Order Crossover*) → 2 members
- 20% mutation (*Worst Member parent selection & swapping*) → 1 member



Assembly Line Balancing: GA

- **Solution Representation:**

- Chromosome Representation: (Permutation)

$Gene_5$	$Gene_4$	$Gene_3$	$Gene_2$	$Gene_1$	$Gene_0$
Ti	Ti	Ti	Ti	Ti	Ti

- Generation Representation: (4 Chromosomes)

x_{i1}	g_5	g_4	g_3	g_2	g_1	g_0
x_{i2}	g_5	g_4	g_3	g_2	g_1	g_0
x_{i3}	g_5	g_4	g_3	g_2	g_1	g_0
x_{i4}	g_5	g_4	g_3	g_2	g_1	g_0

- Tutorial 3 Recap

- Genetic
Algorithm

- Application to
Function
Optimization

- **Assembly Line
Balancing
Problem**

- Techniques
Comparison

Assembly Line Balancing: GA

• **Iteration_0:** Initial Solution

x_{01}	1	2	3	4,5	6	7	✓
x_{02}	1,2	3,4	5	6	7		✓
x_{03}	1,4	2	3	5	6	7	✓
x_{04}	1	2,4	3	5	6	7	✓

Feasibility Check

Tws_{01}	1	5	4	8	6	5
Tws_{02}	6	7	5	6	5	
Tws_{03}	4	5	4	5	6	5
Tws_{04}	1	8	4	5	6	5

Cycle Time: $C = 8$
Max. workstations: $m = 6$
Time Requirements of each task:
 $t = [t_i] = [1, 5, 4, 3, 5, 6, 5]$

	T1	T2	T3	T4	T5	T6	T7
T1	0	1	0	1	0	0	0
T2		0	1	0	1	0	0
T3			0	0	0	0	0
T4				0	0	0	1
T5					0	1	0
T6						0	0
T7							0

$$SI = \sqrt{\frac{\sum_{i=1}^{N_u} (WL_i - WL_{max})^2}{N_u}}$$

- Tutorial 3 Recap
- Genetic Algorithm
- Application to Function Optimization
- **Assembly Line Balancing Problem**
- Techniques Comparison

- Tutorial 3 Recap
- Genetic Algorithm
- Application to Function Optimization
- **Assembly Line Balancing Problem**
- Techniques Comparison

Assembly Line Balancing: GA

- **Iteration_0:** Initial Solution

x_{01}	1	2	3	4,5	6	7	F_{01}	3.807
x_{02}	1,2	3,4	5	6	7		F_{02}	1.414
x_{03}	1,4	2	3	5	6	7	F_{03}	1.354
x_{04}	1	2,4	3	5	6	7	F_{04}	3.807

→ Elite

Feasibility Check

Tws_{01}	1	5	4	8	6	5
Tws_{02}	6	7	5	6	5	
Tws_{03}	4	5	4	5	6	5
Tws_{04}	1	8	4	5	6	5

Cycle Time: $C = 8$
Max. workstations: $m = 6$
Time Requirements of each task:
 $t = [t_i] = [1, 5, 4, 3, 5, 6, 5]$

	T1	T2	T3	T4	T5	T6	T7
T1	0	1	0	1	0	0	0
T2		0	1	0	1	0	0
T3			0	0	0	0	0
T4				0	0	0	1
T5					0	1	0
T6						0	0
T7							0

$$SI = \sqrt{\frac{\sum_{i=1}^{N_u} (WL_i - WL_{max})^2}{N_u}}$$

Assembly Line Balancing: GA

• Iteration_1:

x_{11}	1,4	2	3	5	6	7
x_{12}						
x_{13}						
x_{14}	1	2	5	3,4	6	7

→ Elite of Iteration_0

→ Cross-over Members

→ Mutation Member

Mutation Parent	1	2	3	4,5	6	7
Mutation Child	1	2	5	3,4	6	7

→ Worst of Iteration_0

Cycle Time: $C = 8$
Max. workstations: $m = 6$
Time Requirements of each task:
 $t = [t_i] = [1, 5, 4, 3, 5, 6, 5]$

	T1	T2	T3	T4	T5	T6	T7
T1	0	1	0	1	0	0	0
T2		0	1	0	1	0	0
T3			0	0	0	0	0
T4				0	0	0	1
T5					0	1	0
T6						0	0
T7							0

$$SI = \sqrt{\frac{\sum_{i=1}^{N_u} (WL_i - WL_{max})^2}{N_u}}$$

- Tutorial 3 Recap
- Genetic Algorithm
- Application to Function Optimization
- **Assembly Line Balancing Problem**
- Techniques Comparison

Assembly Line Balancing: GA

• **Iteration_1:** Cont'd

x_{11}	1,4	2	3	5	6	7
x_{12}	1,2	3	5	6	7	4
x_{13}	1,4	3	5	6	7	2
x_{14}	1	2	5	3,4	6	7

→ Elite of Iteration_0

→ Cross-over Members

→ Mutation Member

Cycle Time: $C = 8$							
Max. workstations: $m = 6$							
Time Requirements of each task: $t = [t_i] = [1, 5, 4, 3, 5, 6, 5]$							
	T1	T2	T3	T4	T5	T6	T7
T1	0	1	0	1	0	0	0
T2		0	1	0	1	0	0
T3			0	0	0	0	0
T4				0	0	0	1
T5					0	1	0
T6						0	0
T7							0

$$SI = \sqrt{\frac{\sum_{i=1}^{N_u} (WL_i - WL_{max})^2}{N_u}}$$

Cross-over Parent1	1,2	3,4	5	6	7	
Cross-over Parent2	1,4	2	3	5	6	7
Cross-over Child1	1,2	3	5	6	7	4
Cross-over Child2	1,4	3	5	6	7	2

→ 2nd Elite of Iteration_0

→ Elite of Iteration_0

- Tutorial 3 Recap
- Genetic Algorithm
- Application to Function Optimization
- **Assembly Line Balancing Problem**
- Techniques Comparison

Assembly Line Balancing: GA

• **Iteration_1:** Cont'd

x_{11}	1,4	2	3	5	6	7	✓
x_{12}	1,2	3	5	6	7	4	✗
x_{13}	1,4	3	5	6	7	2	✗
x_{14}	1	2	5	3,4	6	7	✓

Feasibility Check

Tws_{11}	4	5	4	5	6	5
Tws_{12}	5	4	5	6	5	3
Tws_{13}	4	4	5	6	5	5
Tws_{14}	1	5	5	7	6	5

Cycle Time: $C = 8$
Max. workstations: $m = 6$
Time Requirements of each task:
 $t = [t_i] = [1, 5, 4, 3, 5, 6, 5]$

	T1	T2	T3	T4	T5	T6	T7
T1	0	1	0	1	0	0	0
T2		0	1	0	1	0	0
T3			0	0	0	0	0
T4				0	0	0	1
T5					0	1	0
T6						0	0
T7							0

$$SI = \sqrt{\frac{\sum_{i=1}^{N_u} (WL_i - WL_{max})^2}{N_u}}$$

- Tutorial 3 Recap
- Genetic Algorithm
- Application to Function Optimization
- **Assembly Line Balancing Problem**
- Techniques Comparison

Assembly Line Balancing: GA

• **Iteration_1:** Cont'd

x_{11}	1,4	2	3	5	6	7
x_{12}	1,2	3,4	5	6	7	
x_{13}	1,4	2	5	6	7	3
x_{14}	1	2	5	3,4	6	7

→ Elite of Iteration_0

→ Cross-over Members

→ Mutation Member

Cross-over Parent1	1,2	3,4	5	6	7	
Cross-over Parent2	1,4	2	3	5	6	7
Cross-over Child1	1,2	3,4	5	6	7	
Cross-over Child2	1,4	2	5	6	7	3

→ 2nd Elite of Iteration_0

→ Elite of Iteration_0

Cycle Time: $C = 8$
Max. workstations: $m = 6$
Time Requirements of each task:
 $t = [t_i] = [1, 5, 4, 3, 5, 6, 5]$

	T1	T2	T3	T4	T5	T6	T7
T1	0	1	0	1	0	0	0
T2		0	1	0	1	0	0
T3			0	0	0	0	0
T4				0	0	0	1
T5					0	1	0
T6						0	0
T7							0

$$SI = \sqrt{\frac{\sum_{i=1}^{N_u} (WL_i - WL_{max})^2}{N_u}}$$

- Tutorial 3 Recap
- Genetic Algorithm
- Application to Function Optimization
- **Assembly Line Balancing Problem**
- Techniques Comparison

Assembly Line Balancing: GA

• **Iteration_1:** Cont'd

x_{11}	1,4	2	3	5	6	7	✓
x_{12}	1,2	3,4	5	6	7		✓
x_{13}	1,4	2	5	6	7	3	✓
x_{14}	1	2	5	3,4	6	7	✓

Feasibility Check

Tws_{11}	4	5	4	5	6	5
Tws_{12}	6	7	5	6	5	
Tws_{13}	4	5	5	6	5	4
Tws_{14}	1	5	5	7	6	5

Cycle Time: $C = 8$
Max. workstations: $m = 6$
Time Requirements of each task:
 $t = [t_i] = [1, 5, 4, 3, 5, 6, 5]$

	T1	T2	T3	T4	T5	T6	T7
T1	0	1	0	1	0	0	0
T2		0	1	0	1	0	0
T3			0	0	0	0	0
T4				0	0	0	1
T5					0	1	0
T6						0	0
T7							0

$$SI = \sqrt{\frac{\sum_{i=1}^{N_u} (WL_i - WL_{max})^2}{N_u}}$$

- Tutorial 3 Recap
- Genetic Algorithm
- Application to Function Optimization
- **Assembly Line Balancing Problem**
- Techniques Comparison

Assembly Line Balancing: GA

• **Iteration_1:** Cont'd

x_{11}	1,4	2	3	5	6	7	F_{11}	1.354	→ Elite
x_{12}	1,2	3,4	5	6	7		F_{12}	1.414	
x_{13}	1,4	2	5	6	7	3	F_{13}	1.354	→ Elite
x_{14}	1	2	5	3,4	6	7	F_{14}	2.8577	

Feasibility Check

Tws_{11}	4	5	4	5	6	5
Tws_{12}	6	7	5	6	5	
Tws_{13}	4	5	5	6	5	4
Tws_{14}	1	5	5	7	6	5

Cycle Time: $C = 8$
Max. workstations: $m = 6$
Time Requirements of each task:
 $t = [t_i] = [1, 5, 4, 3, 5, 6, 5]$

	T1	T2	T3	T4	T5	T6	T7
T1	0	1	0	1	0	0	0
T2		0	1	0	1	0	0
T3			0	0	0	0	0
T4				0	0	0	1
T5					0	1	0
T6						0	0
T7							0

$$SI = \sqrt{\frac{\sum_{i=1}^{N_u} (WL_i - WL_{max})^2}{N_u}}$$

- Tutorial 3 Recap
- Genetic Algorithm
- Application to Function Optimization
- **Assembly Line Balancing Problem**
- Techniques Comparison

Optimization Techniques Comparison

- Tutorial 3 Recap
- Genetic Algorithm
- Application to Function Optimization
- Assembly Line Balancing Problem
- **Techniques Comparison**

	Simulated Annealing (SA)	Genetic Algorithm (GA)
Technique Category	Trajectory-based	Population-based
Inspiration	Physical Annealing of Metals	Genetic Evolution of Living Creatures
Solution(s) Representation	1 Solution/iteration	<ul style="list-style-type: none"> • Each iteration is composed of (1) Population • Each population has (N) Chromosomes • Each Chromosome has (M) Genes
Generation of New Solution Criteria	Generation Criteria is based on the solution representation • Ex.: Swapping or Remove and insert in case of permutation sol rep	GA Operators <ul style="list-style-type: none"> • Elitism • Cross-Over • Mutation

Optimization Techniques Comparison

- Tutorial 3 Recap
- Genetic Algorithm
- Application to Function Optimization
- Assembly Line Balancing Problem
- **Techniques Comparison**

	Simulated Annealing (SA)	Genetic Algorithm (GA)
Convergence Criteria	Temperature Cooling Criteria <ul style="list-style-type: none"> • Linear $T_i = T_0 - \beta i$ • Geometry $T_i = T_0 \alpha^i$ 	Number of Generations
Acceptance Criteria	<ul style="list-style-type: none"> • If new sol is better, accept new solution • If new sol is worse, based on probability $P = e^{-\frac{ \Delta F }{T_i}}$, and random num r $\begin{cases} P < r & \text{reject Sol} \\ P > r & \text{accept Sol} \end{cases}$ 	All Solutions in the populations are accepted as long as: <ul style="list-style-type: none"> • Solutions generated are feasible. • No duplicate solutions in the population specially in the early iterations to avoid exploitation.
Stopping Criteria	<ul style="list-style-type: none"> • Reaching Final Temperature • Final Number of Iterations 	<ul style="list-style-type: none"> • Final number of generations • Convergence to one solution • Elite is the same across many generations

*Thank
you*



See you Next time ... 😊