

> Part#1:

❖ UVM Environment:

```
ALSU_if.sv
interface ALSU_if(input bit clk);

parameter INPUT_PRIORITY = "A";
parameter FULL_ADDER = "ON";
logic cin, rst, red_op_A, red_op_B, bypass_A, bypass_B, direction, serial_in;
logic [2:0] opcode;
logic signed [2:0] A, B;
logic [15:0] leds;
logic signed [5:0] out;

endinterface
```

```
≡ alsu_test.sv

■ alsu_test.sv
      `ifndef ALSU_TEST_PKG_SV
      `define ALSU_TEST_PKG_SV
      package alsu_test_pkg;
          import uvm_pkg::*;
          import alsu_env_pkg::*;
           `include "uvm_macros.svh"
          class alsu_test extends uvm_test;
               `uvm_component_utils(alsu_test)
11
12
13
              alsu_env env0;
              function new(string name = "alsu_test",uvm_component parent = null);
15
16
17
18
                   super.new(name,parent);
              function void build_phase(uvm_phase phase);
19
20
                   super.build_phase(phase);
                   env0 = alsu_env::type_id::create("env0",this);
22
23
24
25
              task run_phase(uvm_phase phase);
                   super.run_phase(phase);
26
27
                   phase.raise_objection(this);
                   #100; `uvm_info("run_phase", "Welcome to UVM - env0 created",UVM_MEDIUM)
                   phase.drop_objection(this);
35
36
      endpackage
       endif
```

❖ Do file:

```
run.do
1 vlib work
2 vlog -f src_files.list
3 vsim -voptargs=+acc work.top_tb -classdebug -uvmcontrol=all
4 add wave /top_tb/alsu_if/*
5 run -all
```

❖ Results:

Part#2: Driving the interface:

❖ UVM Environment:

```
ALSU_if.sv

interface ALSU_if(input bit clk);

parameter INPUT_PRIORITY = "A";
parameter FULL_ADDER = "ON";
logic cin, rst, red_op_A, red_op_B, bypass_A, bypass_B, direction, serial_in;
logic [2:0] opcode;
logic signed [2:0] A, B;
logic [15:0] leds;
logic signed [5:0] out;

endinterface
```

```
package alsu_test_pkg;
           import uvm_pkg::*;
           import alsu_env_pkg::*;
           `include "uvm_macros.svh"
           class alsu_test extends uvm_test;
               `uvm_component_utils(alsu_test)
               alsu_env env0;
               virtual ALSU_if alsu_test_vif;
               function new(string name = "alsu_test",uvm_component parent = null);
                   super.new(name, parent);
               function void build_phase(uvm_phase phase);
                   super.build_phase(phase);
                   if(!uvm_config_db #(virtual ALSU_if)::get(this,"","ALSU_IF",alsu_test_vif))
                       `uvm_fatal("build_phase","Test - unable to get the virtual interface")
                   uvm_config_db #(virtual ALSU_if)::set(this,"*","CFG", alsu_test_vif);
                   env0 = alsu_env::type_id::create("env0",this);
               task run_phase(uvm_phase phase);
30
                   super.run_phase(phase);
                   phase.raise_objection(this);
                   #100; `uvm_info("run_phase", "Inside the ALSU test",UVM_MEDIUM)
                   phase.drop_objection(this);
               endtask
           endclass
       endpackage
```

```
package alsu_env_pkg;
          import uvm_pkg::*;
6
          import alsu_driver_pkg::*;
          `include "uvm_macros.svh"
          class alsu_env extends uvm_env;
              `uvm_component_utils(alsu_env)
              alsu_driver driver;
              function new(string name = "alsu_env", uvm_component parent = null);
                  super.new(name, parent);
              endfunction
              function void build_phase(uvm_phase phase);
                  super.build_phase(phase);
                  driver = alsu_driver::type_id::create("driver",this);
              endfunction
          endclass
      endpackage
```

```
package alsu_driver_pkg;

import uvm_pkg::*;

import uvm_macros.svh"

class alsu_driver extends uvm_driver;

vvm_component_utils(alsu_driver)

virtual ALSU_if alsu_driver_vif;

function new(string name = "alsu_driver",uvm_component parent = null);

super.new(name,parent);
endfunction

function void build_phase(uvm_phase phase);

super.build_phase(phase);

if(!uvm_config_db #(virtual ALSU_if)::get(this,"","CFG",alsu_driver_vif))

'uvm_fatal("build_phase","Driver - unable to get the virtual interface")

endfunction
```

```
25
               task run_phase(uvm_phase phase);
26
                    super.run_phase(phase);
27
28
                    phase.raise_objection(this);
29
30
                    alsu_driver_vif.rst = 1;
31
                    @(negedge alsu_driver_vif.clk);
32
                    alsu_driver_vif.rst = 0;
33
34
                    repeat(10) begin
35
                        alsu_driver_vif.cin = $random();
36
                        alsu_driver_vif.red_op_A = $random();
37
                        alsu_driver_vif.red_op_B = $random();
38
                        alsu_driver_vif.bypass_A = $random();
39
                        alsu_driver_vif.bypass_B = $random();
                        alsu_driver_vif.direction = $random();
                        alsu_driver_vif.serial_in = $random();
41
42
                        alsu_driver_vif.opcode = $random();
                        alsu_driver_vif.A = $random();
44
                        alsu_driver_vif.B = $random();
45
                        @(negedge alsu_driver_vif.clk);
                    end
47
48
                    phase.drop_objection(this);
49
               endtask
           endclass
51
52
       endpackage
```

* Results:

```
# UVM_INFO verilog_src/questa_uvm_pkg-1.2/src/questa_uvm_pkg.sv(277) & 0: reporter [Questa UVM] QUESTA_UVM-1.2.3

# UVM_INFO verilog_src/questa_uvm_pkg-1.2/src/questa_uvm_pkg.sv(278) & 0: reporter [Questa UVM] questa_uvm::init(all)

# UVM_INFO & 0: reporter [RNTST] Running test alsu_test...

# UVM_INFO alsu_test.sv(34) & 100: uvm_test_top [run_phase] Inside the ALSU test

# UVM_INFO verilog_src/uvm-1.ld/src/base/uvm_objection.svh(1267) & 100: reporter [TEST_DONE] 'run' phase is ready to proceed to the 'extract' phase

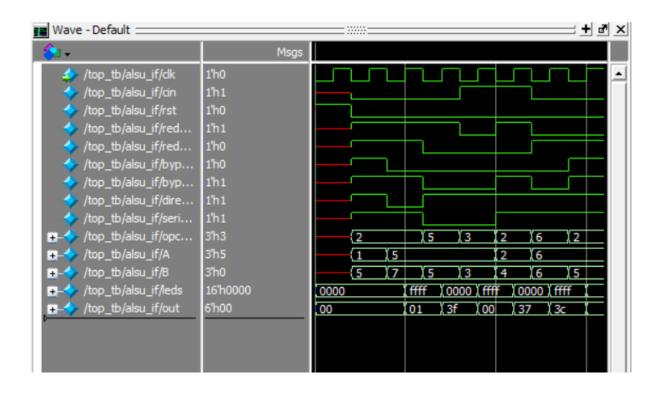
# --- UVM Report Summary ---

# ** Report counts by severity

# UVM_INFO : 5

# UVM_ERROR : 0

# IVM_ERROR : 0
```



> Part#3: config object:

```
ALSU_if.sv
interface ALSU_if(input bit clk);

parameter INPUT_PRIORITY = "A";
parameter FULL_ADDER = "ON";
logic cin, rst, red_op_A, red_op_B, bypass_A, bypass_B, direction, serial_in;
logic [2:0] opcode;
logic signed [2:0] A, B;
logic [15:0] leds;
logic signed [5:0] out;

endinterface
```

Test:

```
≡ alsu_test.sv
       package alsu_test_pkg;
            import uvm_pkg::*;
import alsu_env_pkg::*;
            import config_obj_pkg::*;
`include "uvm_macros.svh"
                   `uvm_component_utils(alsu_test)
                  alsu_env env0;
alsu_config alsu_config_obj_test;
                  function new(string name = "alsu_test",uvm_component parent = null);
                       super.new(name,parent);
                  function void build_phase(uvm_phase phase);
                       super.build_phase(phase);
                       alsu_config_obj_test = alsu_config::type_id::create("alsu_config_obj_test");
                       if(!uvm_config_db #(virtual ALSU_if)::get(this,"","ALSU_IF",alsu_config_obj_test.alsu_config_if))
    `uvm_fatal("build_phase","Test - unable to get the virtual interface")
uvm_config_db #(alsu_config)::set(this,"*","CFG", alsu_config_obj_test);
                       env0 = alsu_env::type_id::create("env0",this);
                  task run_phase(uvm_phase phase);
                       super.run_phase(phase);
phase.raise_objection(this);
                       #100; `uvm_info("run_phase", "Inside the ALSU test",UVM_MEDIUM)
                       phase.drop_objection(this);
```

• Config object:

```
package config_obj_pkg;
  import uvm_pkg::*;
  `include "uvm_macros.svh"

class alsu_config extends uvm_object;
  `uvm_object_utils(alsu_config)

  virtual ALSU_if alsu_config_if;

  function new(string name = "alsu_config_obj");
    super.new(name);
  endfunction
  endclass

endpackage
```

Env:

```
package alsu_env_pkg;
    import uvm_pkg::*;
    import alsu_driver_pkg::*;
    include "uvm_macros.svh"
   class alsu_env extends uvm_env;
        'uvm_component_utils(alsu_env)
        alsu_driver driver;
        function new(string name = "alsu_env",uvm_component parent = null);
            super.new(name, parent);
        endfunction
        function void build_phase(uvm_phase phase);
            super.build_phase(phase);
            driver = alsu_driver::type_id::create("driver",this);
        endfunction
   endclass
endpackage
```

• Driver:

```
package alsu_driver_pkg;
            import uvm_pkg::*;
            import config_obj_pkg::*;
            `include "uvm_macros.svh"
10
            class alsu_driver extends uvm_driver;
                 `uvm_component_utils(alsu_driver)
                 virtual ALSU_if alsu_driver_vif;
14
15
                 alsu_config alsu_config_obj_driver;
                 function new(string name = "alsu_driver",uvm_component parent = null);
16
17
18
19
                     super.new(name, parent);
20
21
                 function void build_phase(uvm_phase phase);
                     super.build_phase(phase);
22
23
24
25
                     if(!uvm_config_db #(alsu_config)::get(this,"","CFG",alsu_config_obj_driver))
   `uvm_fatal("build_phase","Driver - unable to get the virtual interface")
26
27
28
                 function void connect_phase(uvm_phase phase);
                      super.connect_phase(phase);
31
                     alsu_driver_vif = alsu_config_obj_driver.alsu_config_if;
```

```
task run_phase(uvm_phase phase);
                     super.run_phase(phase);
37
38
                     phase.raise_objection(this);
                     alsu_driver_vif.rst = 1;
                     @(negedge alsu_driver_vif.clk);
                     alsu_driver_vif.rst = 0;
                     repeat(10) begin
45
                         alsu_driver_vif.cin = $random();
46
                         alsu_driver_vif.red_op_A = $random();
                         alsu_driver_vif.red_op_B = $random();
alsu_driver_vif.bypass_A = $random();
                         alsu_driver_vif.bypass_B = $random();
50
                         alsu_driver_vif.direction = $random();
51
                         alsu_driver_vif.serial_in = $random();
52
                         alsu_driver_vif.opcode = $random();
                         alsu_driver_vif.A = $random();
alsu_driver_vif.B = $random();
54
55
                         @(negedge alsu_driver_vif.clk);
56
                     end
57
58
                     phase.drop_objection(this);
59
                endtask
60
            endclass
61
       endpackage
```

❖ Result:

```
# UVM_INFO verilog_src/questa_uvm_pkg-1.2/src/questa_uvm_pkg.sv(277) % 0: reporter [Questa_UVM] QUESTA_UVM-1.2.3
# UVM_INFO verilog_src/questa_uvm_pkg-1.2/src/questa_uvm_pkg.sv(278) % 0: reporter [Questa_UVM] questa_uvm::init(all)
# UVM_INFO & 0: reporter [RNTST] Running test alsu_test...
# UVM_INFO alsu_test.sv(36) % 100: uvm_test_top [run_phase] Inside the ALSU test
# UVM_INFO verilog_src/uvm-1.1d/src/base/uvm_objection.svh(1267) % 100: reporter [TEST_DONE] 'run' phase is ready to proceed to the 'extract' phase
# --- UVM Report Summary ---
# ** Report counts by severity
# UVM_INFO: 5
# UVM_WARNING: 0
# UVM_ERROR: 0
# IVM_ERROR: 0
# IVM_ERROR
```

Waveform:

