

Sister Nivedita University

Name: Fahad Dubey Sec: B

Department: B.Tech CSE Sem: 6

Subject: Digital Signal Processing

Enrollment No.: 2111200001217

Reg No.: 210012175539

Q.1.

$$x(t) = 2\sin(40\pi t) - 3\sin(100\pi t) + \cos(50\pi t)$$

> To determine the minimum, sampling frequency,

We need to find the highest frequency component in the analog signal, which is given by $x(t)$ signal.

Here, the highest frequency component in the signal is $f_{\max} = 100\text{Hz}$ (corresponding to the term $3\sin(100\pi t)$).

> According to the Nyquist - Shannon sampling theorem,

the sampling frequency (f_s) should be at least twice the maximum frequency component (f_{\max}).

Sister Nivedita University

Name: Fahad Dubey Sec: B

Department: B.Tech CSE Sem: 6

Subject: Digital Signal Processing

Enrollment No.: 2111200001217

Reg No.: 210012175539

Q.1.

$$x(t) = 2\sin(40\pi t) - 3\sin(100\pi t) + \cos(50\pi t)$$

> To determine the minimum sampling frequency,

We need to find the highest frequency component in the analog signal, which is given by $x(t)$ signal.

Here, the highest frequency component in the signal is $f_{\max} = 100\text{Hz}$ (corresponding to the term $3\sin(100\pi t)$).

> According to the Nyquist - Shannon sampling theorem,

the sampling frequency (f_s) should be at least twice the maximum frequency component (f_{\max}).

Therefore the minimum sampling frequency (f_s) required is:

$$f_s = 2f_{\max} = 2 \times 100 = 200 \text{ Hz}$$

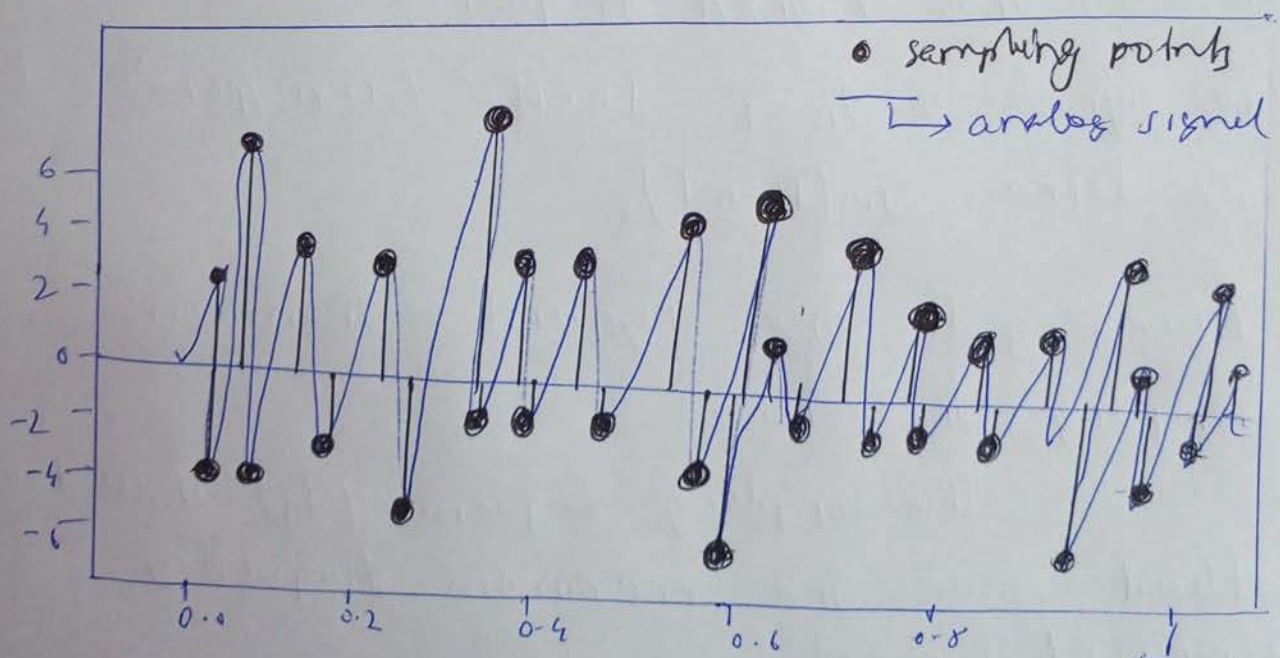
> Sampled version:

$$x[n] = 2\sin 40\pi n - 3\sin 100\pi n + \cos 50\pi n$$

$$= 2\sin 40\pi \frac{n}{\frac{200}{5}} - 3\sin 100\pi \frac{n}{\frac{200}{2}} + \cos 50\pi \frac{n}{\frac{200}{4}}$$

$$= 2\sin \frac{40\pi n}{5} - 3\sin \frac{100\pi n}{2} + \cos \frac{50\pi n}{4}$$

> Sketch of the waveform & the sampling points:



Q1. To determine whether the signal $x[n] = u[n]$ is an energy or power signal, we need to evaluate its energy or power over all time.

The energy of discrete-time signal is given

by:

$$E_x = \sum_{n=-\infty}^{\infty} |x[n]|^2$$

The power of discrete-time signal is given

by:

$$P_x = \lim_{N \rightarrow \infty} \frac{1}{2N+1} \sum_{n=-N}^N |x[n]|^2$$

> Now, the energy & power of the given signal $x[n] = u[n]$ will be evaluated, here $u[n]$ is unit step signal, we have

$$x[n] = \begin{cases} 1 & \text{for } n \geq 0 \\ 0 & \text{otherwise} \end{cases}$$

> Now evaluating the energy,

$$E_x = \sum_{n=-\infty}^{\infty} |x[n]|^2 = \sum_{n=0}^{\infty} |1|^2 = \sum_{n=0}^{\infty} 1 = \infty$$

Since, the energy of the signal $x[n] = u[n]$ is ∞ , it is an energy signal.

> Now evaluating the power,

$$P_n = \lim_{N \rightarrow \infty} \frac{1}{2N+1} \sum_{n=-N}^N |x[n]|^2$$

$$= \lim_{N \rightarrow \infty} \frac{1}{2N+1} \sum_{n=0}^N |1|^2 =$$

$$= \lim_{N \rightarrow \infty} \frac{N+1}{2N+1} = \frac{1}{2}$$

Since, the power of the signal $x[n]$
 $= u(2n)$ is finite (equal to $\frac{1}{2}$), it is
a power signal.

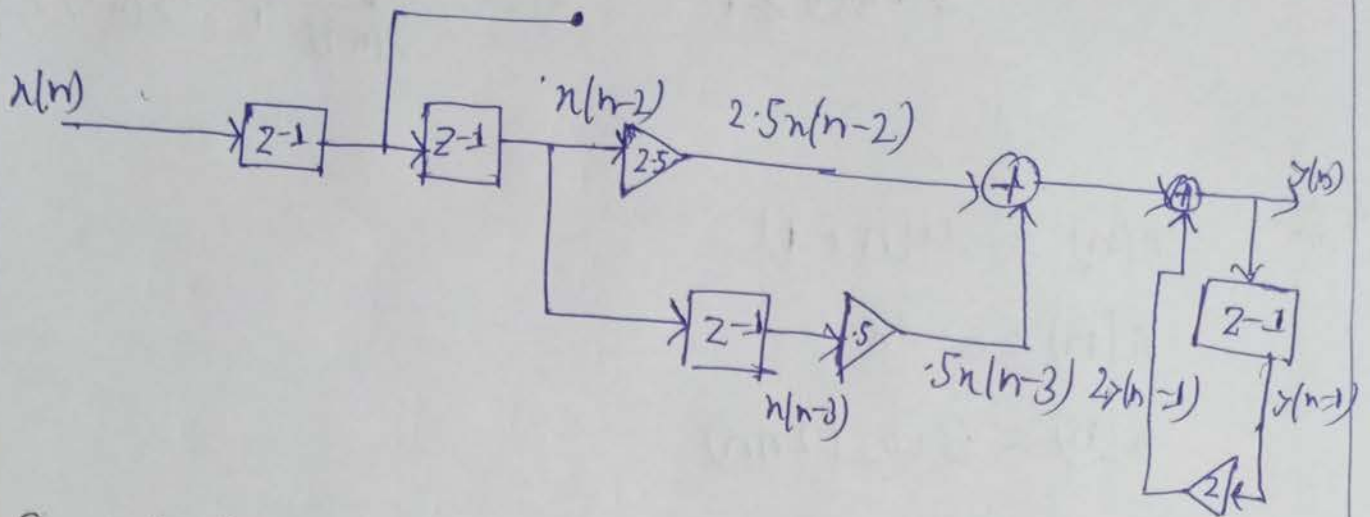
In summary:

- > The signal $x[n] = u(2n)$ is an energy signal cause its energy is ∞ .
- > The signal $x[n] = u(2n)$ is a power signal cause its power is finite.

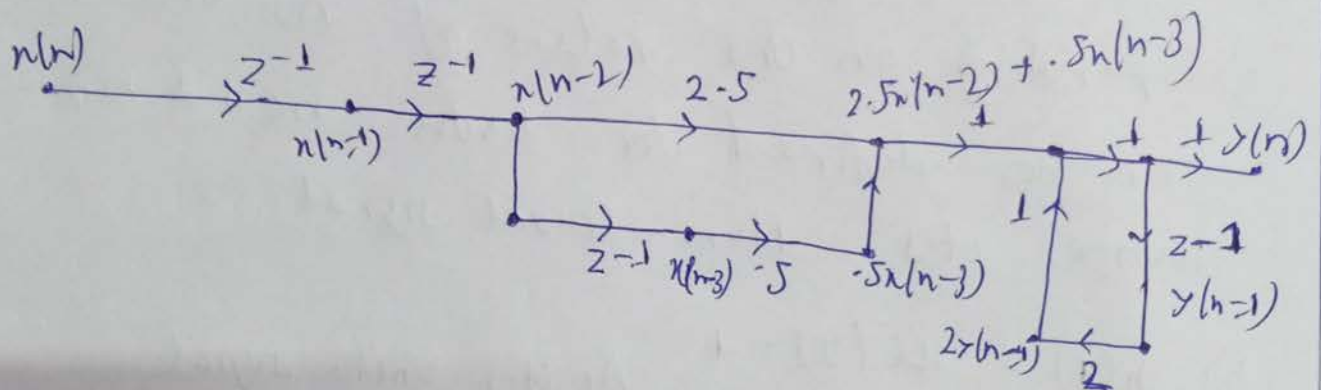
93.

a) $y(n] = 2x(n-1] + 2.5x[n-2] + .5x[n-3]$

Block Diagram of $y(n]$:

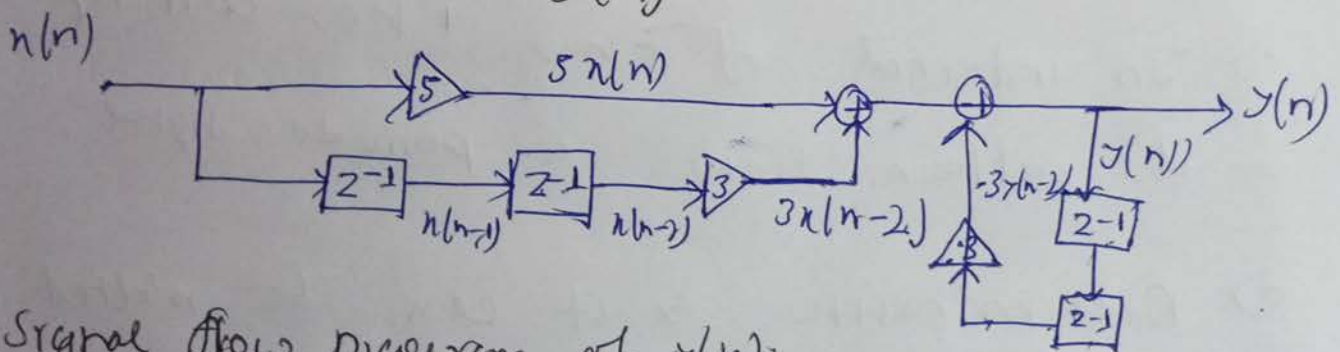


Signal flow diagram of $y(n]$:

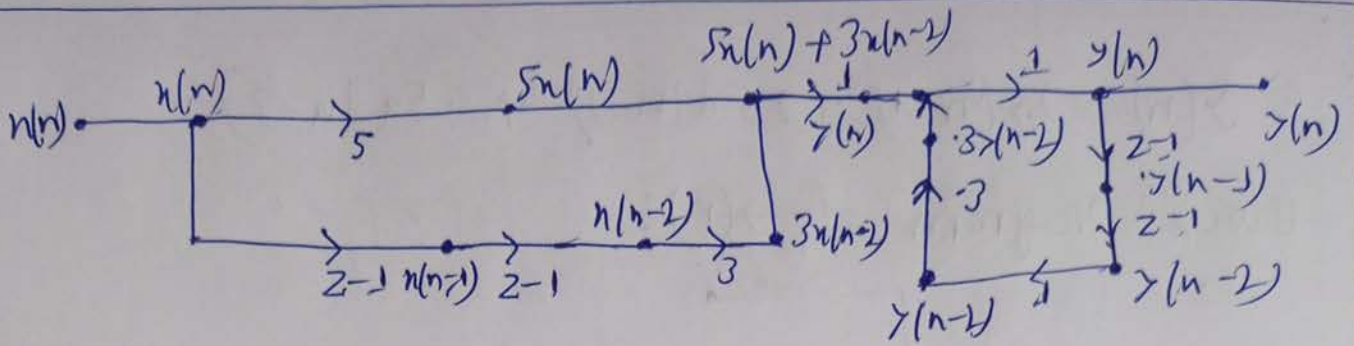


b) $y(n] = 3x(n-2] + 5x(n)] + .3y(n-2]$

Block Diagram of $y(n]$:



Signal flow Diagram of $y(n]$:



$$x(n) = u(n+1)$$

$$x(n) = e^{-3n}$$

$$x(n) = 3 \cos(2\pi n)$$

i)

$$x(n) = u(n+1)$$

c) depending on the value of n , the system can be defined for both $n < 0$ & $n \geq 0$.
Hence, this is a Non-Causal signal.

$$b) x(1) = u(2) = 1$$

$$x(-1) = u(0) = 1$$

As this is a unit signal, hence, this is an even signal.

c) In interval of every 4 sec, it will repeat its pattern, hence a periodic signal.

d) Deterministic as it can be plotted like unit step signal.

4.ii.

$$x(n) = e^{-3n}$$

a) ~~Causal signal~~ ~~is defined for only $n \geq 0$.~~
But here $-(3n)$ represents all inputs are negative.

Hence, it is anti-causal signal.

$$b) x(1) = e^{-3}$$

$$x(-1) = e^3$$

As $x(1) \neq x(-1)$ Hence it is a odd signal.

c) Non-periodic.

d) Deterministic

4.iii

$$x(n) = 3 \cos(2\pi n)$$

a) As n can be both +ve & -ve hence it is a Non-causal signal.

b) Even signal as it keeps repeating itself after every 2π

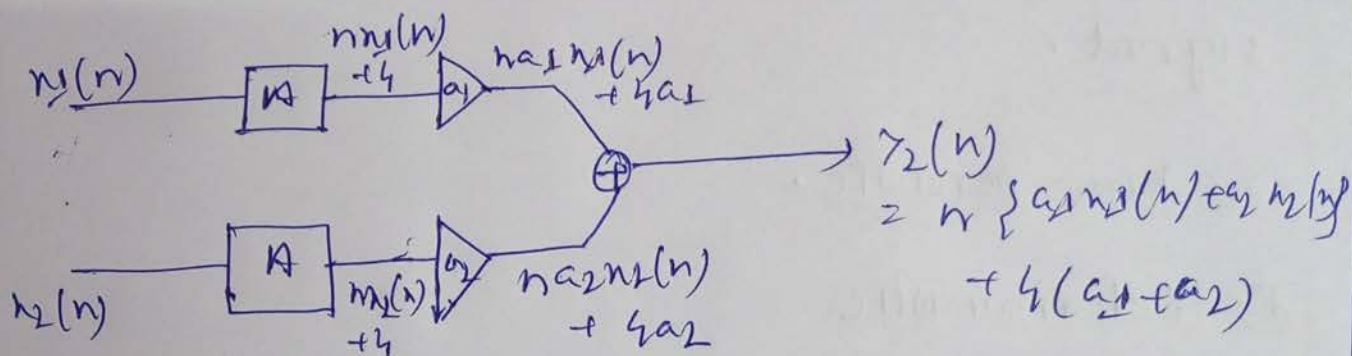
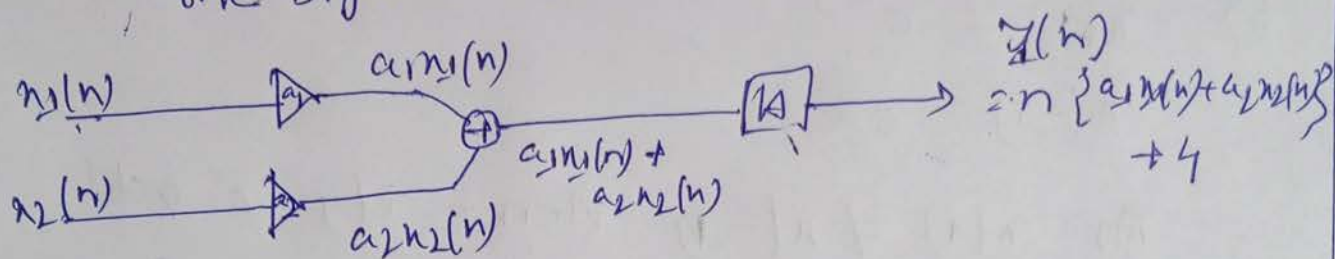
c) Periodic

d) Deterministic

95. a) $y(n) = nx(n) + 4$

a) Checking Linearity: A system is called Linear if it follows the principle of superposition.

let, $x_1(n)$ & $x_2(n)$ are 2 components of the signal $x(n)$.



As $y_1 \neq y_2$, Hence the system is not Linear.

b) Checking Causality: system is causal if its o/p doesn't depend on

future inputs or outputs.

$\forall n > 0$ or $\forall n \leq 0$; its input only depends on present inputs.

for, $n = -3$, $y(-3) = -3x(-3) + 4$

$n = -2$, $y(-2) = -2x(-2) + 4$

⋮

$n = 2$, $y(2) = 2x(2) + 4$

∴ output only depends on present input, hence the system is causal.

c) checking if system is dynamic: Dynamic if output depends on past or future input.

Here, output only depends on present inputs hence it is a static system.

d) checking if time invariant: A system is said time invariant if its input & output doesn't change with time.

$x(n)$ — $\boxed{14}$ — $y(n) = n x(n) + 4$

$x(n)$ — $\boxed{z^{-1}}$ — $x(n-1)$ — $\boxed{14}$ — $y(n-1)$

$y(n-1) = (n-1)x(n-1) + 4$

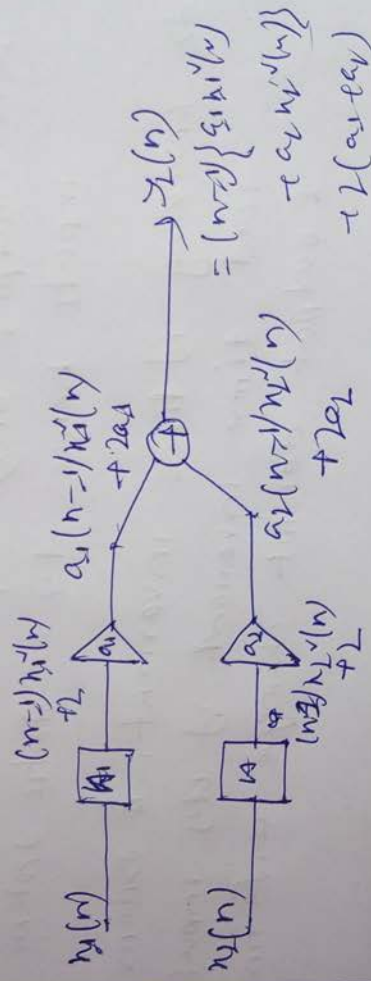
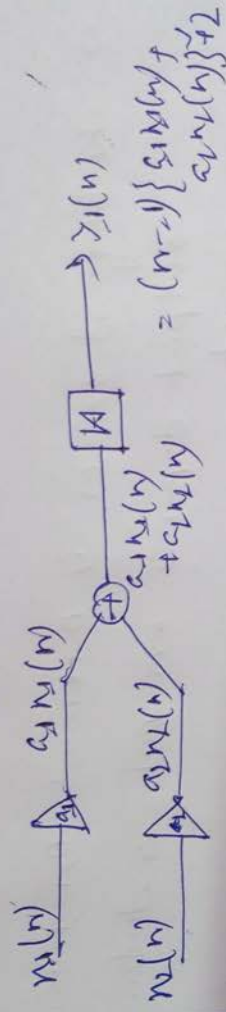
$x(n)$ — $\boxed{14}$ — $y(n)$ — $\boxed{z^{-1}}$ — $y(n-1)$

∴ Hence, it is a time invariant system.

$$y(n) = (n-1)x^v(n) + 2$$

a) Checking Linearity: A system is called linear if it follows the principle of superposition.

Let, $x_1(n)$ & $x_2(n)$ are 2 components of the signal $x(n)$.



As $y_1 \neq y_2$, Hence the system is not linear

b) Checking causality: system is causal if its o/p doesn't depend on future input or outputs.

An, system only depends on present inputs.

$$\text{for } x = -1, \quad y(-1) = -2x(-1) + 2$$

$$y(-2) = -3x(-2) + 2$$

$$\vdots$$

$$y(2) = x(2) + 2$$

Hence, the system is causal.

c) checking if system is dynamic: system

is dynamic if output depends

on present past or future input.

None output, only depends on present input hence it is a static system.

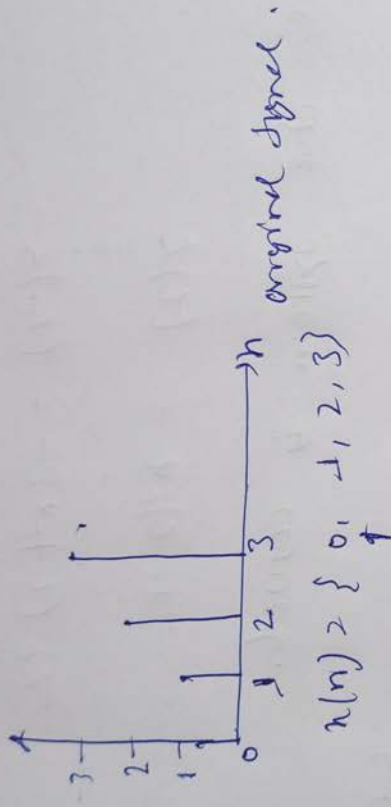
d) Checking if time invariant: A system is said time invariant if its

input & output doesn't change with time.

$$x_1 = (n-2) \quad x(n-1) \quad x(n) \quad x(n+1) \quad x(n+2)$$

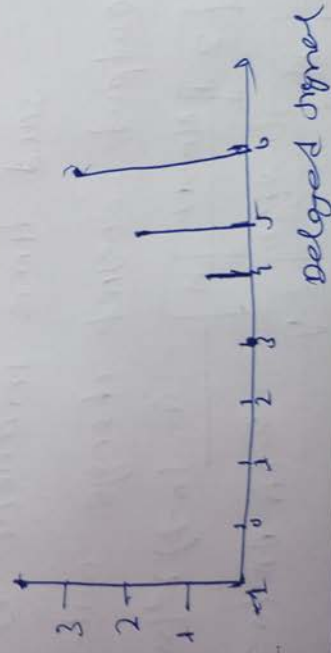
$$x_2 = (n-1) \quad x(n) \quad x(n+1) \quad x(n+2) \quad x(n+3)$$

As $y_1 \neq y_2$, hence it's a time variant system.



c) let, $y_1(n) = x(n-3)$
 $\therefore y_1(0) =$ hence, here the signal is
 $y_1(1)$ delayed by 3 units.

when $n=3$; $y_1(3) = x(0) = 0$
 $n=4$; $y_1(4) = x(1) = 1$
 $n=5$; $y_1(5) = x(2) = 2$
 $n=6$; $y_1(6) = x(3) = 3$



5.c.

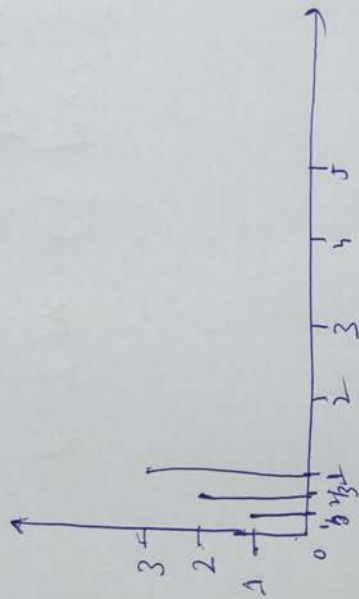
$$\text{let } n_2(n) = n(3n)$$

$$\text{when, } n=0, \quad n_2(0) = n(0) = 0$$

$$n=1, \quad n_2(1) = n(3) = 3$$

$$n=\frac{2}{3}, \quad n_2\left(\frac{2}{3}\right) = n(2) = 2$$

$$n=\frac{1}{3}, \quad n_2\left(\frac{1}{3}\right) = n(1) = 1$$



Here, signal has been downsampled.

b.

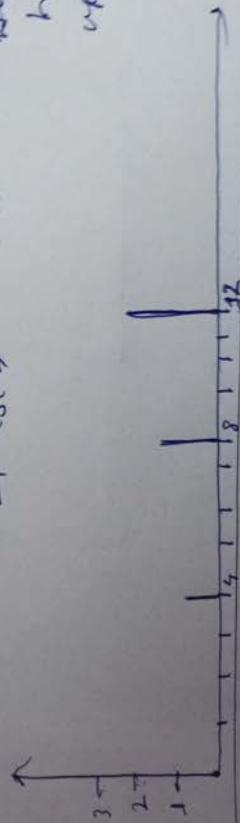
$$\text{let } n_3(n) = n(n/4)$$

$$\text{when, } n=0, \quad n_3(0) = n(0) = 0$$

$$n=4, \quad n_3(4) = n(1) = 1$$

$$n=8, \quad n_3(8) = n(2) = 2$$

$$n=12, \quad n_3(12) = n(3) = 3$$



Here signal has been upsampled.

5.c.

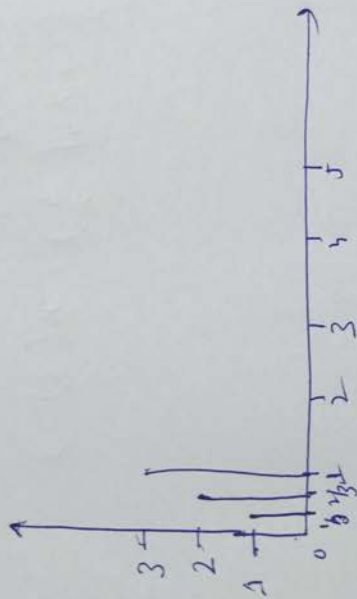
$$\text{let } x_2(n) = x(3n)$$

$$\text{when, } n=0, \quad x_2(0) = x(0) = 0$$

$$n=1, \quad x_2(1) = x(3) = 3$$

$$n=\frac{2}{3}, \quad x_2\left(\frac{2}{3}\right) = x(2) = 2$$

$$n=\frac{1}{3}, \quad x_2\left(\frac{1}{3}\right) = x(1) = 1$$



Here, signal has been downsampled.

b.

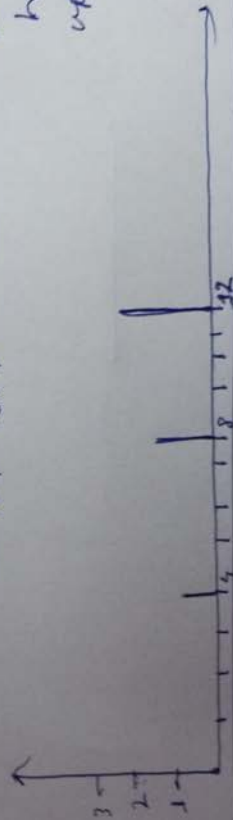
$$\text{let } x_3(n) = x(n/4)$$

$$\text{when, } n=0, \quad x_3(0) = x(0) = 0$$

$$n=4, \quad x_3(4) = x(1) = 1$$

$$n=8, \quad x_3(8) = x(2) = 2$$

$$n=12, \quad x_3(12) = x(3) = 3$$



Here signal has been upsampled.

d.

$$x(-2n)$$

↳ here the signal is folded & scaled 'too'

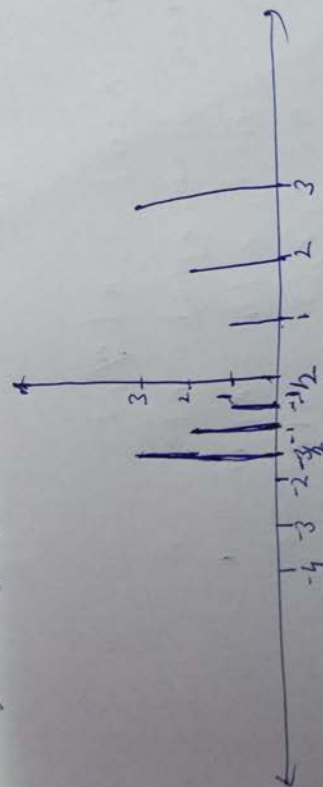
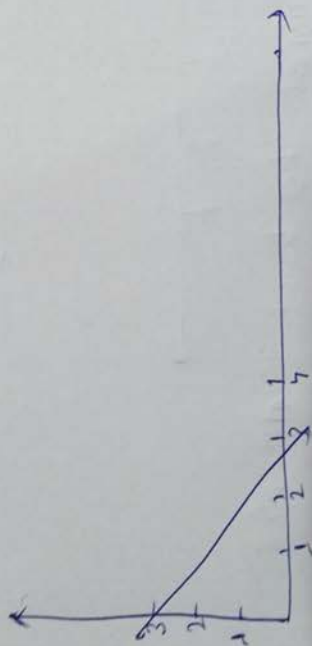
$$\text{Let } x_4(n) = x(-2n)$$

$$\text{When } n=0, \quad x_4(0) = x(0) = 0$$

$$n = -1/2, \quad x_4(-1/2) = x(1) = 1$$

$$n = -1, \quad x_4(-1) = x(2) = 2$$

$$n = -3/2, \quad x_4(-3/2) = x(3) = 3$$



d.

$$n(-2n)$$

↳ have the signal to folded & scaled 'too'.

$$\text{let } n_4(n) > n(-2n)$$

$$\text{when } n=0, \quad n_4(0) = n(0) = 0$$

$$n = -1/2, \quad n_4(-1/2) = n(1) = 1$$

$$n = -1, \quad n_4(-1) = -n(1) = 2$$

$$n = -3/2, \quad n_4(-3/2) = n(3) = 3$$

