```
In [17]: %matplotlib inline
```

Vanilla Self Organizing Map (SOM)

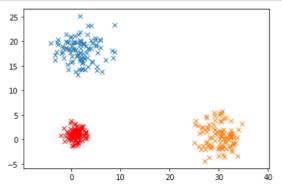
This Jupyter page is a place for you to play around with a BASIC SOM/SOFM.

Code assumptions:

- 8x8 map (that you can make bigger or smaller, no code support here for different topologies)
- Init is a uniformly spaced grid (between data min and max w.r.t. each dimension)
- · I just randomly pick points
- I picked a fixed learning rate that slows the algorithm down (to "converge" over time)
- I only considered the 4 "directly" connected neighbors (no 2D Von Neumann diagonals)

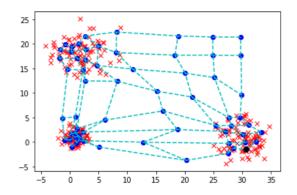
First, lets make our data set

```
In [18]: %matplotlib inline
          import numpy as np
          import matplotlib.pyplot as plt
          import time
          import pylab as pl
          from IPython import display
          from tqdm import tqdm
          NumPointsPerClass = 100
          # class 1
          c1_{mean} = [1,1]
          c1\_cov = [[1, 0], [0, 1]]
          c1_x = np.random.multivariate_normal(c1_mean, c1_cov, NumPointsPerClass)
          # class 2
          c2_{mean} = [2, 18]
          c2\_cov = [[8, 0], [0, 6]]
          c2_x = np.random.multivariate_normal(c2_mean, c2_cov, NumPointsPerClass)
          # class 2
          c3_{mean} = [30, 1]
          c3\_cov = [[6, 0], [0, 6]]
          c3_x = np.random.multivariate_normal(c3_mean, c3_cov, NumPointsPerClass)
          # plot it
          plt.plot(c1_x[:,0], c1_x[:,1], 'rx')
          plt.plot(c2_x[:,0], c2_x[:,1], 'x')
plt.plot(c3_x[:,0], c3_x[:,1], 'x')
          plt.axis('equal')
          plt.show()
          # make data set
          X = np.concatenate((c1_x, c2_x, c3_x), axis=0)
          l1 = np.ones(c1 x.shape[0])
          12 = np.zeros(c2_x.shape[0])
          13 = np.zeros(c3_x.shape[0])
          L = np.concatenate((11, 12, 13), axis=0)
```

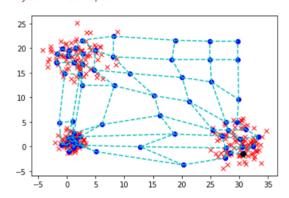


```
In [19]: # size of the SOM
         SomSize = 8
         # make our weight map - pick some subset of our data
         #W = np.zeros((SomSize, SomSize, 2))
         #for i in range(SomSize):
             for j in range(SomSize):
                 whichind = np.random.randint(1,NumPointsPerClass*2)
         #
                 W[i,j,0] = X[whichind,0]
                 W[i,j,1] = X[whichind,1]
         # make our weight map - start with a grid over the space
         W = np.zeros((SomSize,SomSize,2))
         for i in range(SomSize):
            for j in range(SomSize):
                W[i,j,0] = (i/SomSize) * (np.max(X[:,0]) - np.min(X[:,0])) + np.min(X[:,0])
                W[i,j,1] = (j/SomSize) * (np.max(X[:,1]) - np.min(X[:,1])) + np.min(X[:,1])
         # we will store our distances to things in this simple data structure
         DVals = np.zeros((SomSize,SomSize))
         # show plot/animation during algorithm? (if yes, keep NoIts Low!!! (or goes on forever))
         # how many epochs?
        NoIts = 2000
         # learning rate (driven below by iteration counter)
         Lrate = 1.0
         # We can randomly pick samples below (with replacement) or we can ...
         # randomly sort our data and sequentially walk through it
         SampleWithReplacement = 0
         SampleArray = np.random.permutation(NumPointsPerClass*3)
         # the SOM
         for k in tqdm(range(NoIts),'Main Loop'):
            # pick sample
            if( SampleWithReplacement == 1 ):
                RandomSampleIndex = np.random.randint(1,NumPointsPerClass*3)
            else:
                RandomSampleIndex = SampleArray[ k % (NumPointsPerClass*3) ]
            #####################################
            # find Euclidean distance of the selected point to everyone
            # yes, its slow, not teaching you how to efficiently code here! ;-)
            for i in range(SomSize):
                for j in range(SomSize):
                    v = W[i,j,:] - X[RandomSampleIndex,:]
                    v = np.multiply(v,v)
                    v = np.sum(v)
                    DVals[i,j] = np.sqrt(v) # yes, if your just comparing points, need the sqrt?
            # who is the closest to our sampled point? (the winner)
            MIndex = np.unravel index(DVals.argmin(), DVals.shape)
            # Lets slow this algorithm down over time
            Lrate = np.exp((-1.0) * k / (NoIts * 0.5))
            # draw? (and should we do only every say 50 iterations?)
            if( Show == 1 and (k % 50 == 0) ):
                # clear our plot
                pl.clf()
```

```
# nlot the data set
                plt.plot(X[:,0], X[:,1], 'rx')
                # plot our data point
                plt.plot(X[RandomSampleIndex,0], X[RandomSampleIndex,1], 'kd')
                # plot the SOM weight locations
                for i in range(SomSize):
                        for j in range(SomSize):
                               plt.plot(W[i,j,0],W[i,j,1], 'bo')
                # plot their edges
                for i in range(SomSize-1):
                        for j in range(SomSize):
                                plt.plot([W[i,j,0], W[i+1,j,0]], [W[i,j,1], W[i+1,j,1]], 'c--')
                for i in range(SomSize):
                        for j in range(SomSize-1):
                               plt.plot([W[i,j,0], W[i,j+1,0]], [W[i,j,1], W[i,j+1,1]], 'c--')
                # plot the winner
                plt.plot(W[MIndex[0],MIndex[1],0],W[MIndex[0],MIndex[1],1], 'kd')
                # animation, so pause it!
                display.clear_output(wait=True)
                display.display(pl.gcf())
                time.sleep(0.03)
        # now, update
        # look over direct neighbors
        BlendingFactor = 0.1 * Lrate
        # Look above
        indxi = MIndex[0]
        indxj = MIndex[1] - 1
        if( indxj >= 0 ):
                W[indxi,indxj,:] = W[indxi,indxj,:] + BlendingFactor * ( X[RandomSampleIndex,:] - W[indxi,indxj,:] )
        # Look Left
        indxi = MIndex[0] - 1
        indxj = MIndex[1]
        if( indxi >= 0 ):
                W[indxi,indxj,:] = W[indxi,indxj,:] + BlendingFactor * ( X[RandomSampleIndex,:] - W[indxi,indxj,:] )
        # Look right
        indxi = MIndex[0] + 1
        indxj = MIndex[1]
        if( indxi < SomSize ):</pre>
                W[indxi,indxj,:] = W[indxi,indxj,:] + BlendingFactor * ( X[RandomSampleIndex,:] - W[indxi,indxj,:] )
        # Look below
        indxi = MIndex[0]
        indxj = MIndex[1] + 1
        if( indxj < SomSize ):</pre>
                W[indxi,indxj,:] = W[indxi,indxj,:] + BlendingFactor * ( X[RandomSampleIndex,:] - W[indxi,indxj,:] )
        # update our current point
        \texttt{W[MIndex[0],MIndex[1],:] = W[MIndex[0],MIndex[1],:] + Lrate * ( X[RandomSampleIndex,:] - W[MIndex[0],MIndex[1],MIndex[1],MIndex[1],MIndex[1],MIndex[1],MIndex[1],MIndex[1],MIndex[1],MIndex[1],MIndex[1],MIndex[1],MIndex[1],MIndex[1],MIndex[1],MIndex[1],MIndex[1],MIndex[1],MIndex[1],MIndex[1],MIndex[1],MIndex[1],MIndex[1],MIndex[1],MIndex[1],MIndex[1],MIndex[1],MIndex[1],MIndex[1],MIndex[1],MIndex[1],MIndex[1],MIndex[1],MIndex[1],MIndex[1],MIndex[1],MIndex[1],MIndex[1],MIndex[1],MIndex[1],MIndex[1],MIndex[1],MIndex[1],MIndex[1],MIndex[1],MIndex[1],MIndex[1],MIndex[1],MIndex[1],MIndex[1],MIndex[1],MIndex[1],MIndex[1],MIndex[1],MIndex[1],MIndex[1],MIndex[1],MIndex[1],MIndex[1],MIndex[1],MIndex[1],MIndex[1],MIndex[1],MIndex[1],MIndex[1],MIndex[1],MIndex[1],MIndex[1],MIndex[1],MIndex[1],MIndex[1],MIndex[1],MIndex[1],MIndex[1],MIndex[1],MIndex[1],MIndex[1],MIndex[1],MIndex[1],MIndex[1],MIndex[1],MIndex[1],MIndex[1],MIndex[1],MIndex[1],MIndex[1],MIndex[1],MIndex[1],MIndex[1],MIndex[1],MIndex[1],MIndex[1],MIndex[1],MIndex[1],MIndex[1],MIndex[1],MIndex[1],MIndex[1],MIndex[1],MIndex[1],MIndex[1],MIndex[1],MIndex[1],MIndex[1],MIndex[1],MIndex[1],MIndex[1],MIndex[1],MIndex[1],MIndex[1],MIndex[1],MIndex[1],MIndex[1],MIndex[1],MIndex[1],MIndex[1],MIndex[1],MIndex[1],MIndex[1],MIndex[1],MIndex[1],MIndex[1],MIndex[1],MIndex[1],MIndex[1],MIndex[1],MIndex[1],MIndex[1],MIndex[1],MIndex[1],MIndex[1],MIndex[1],MIndex[1],
],:])
# draw the final weight map
pl.clf()
plt.plot(X[:,0], X[:,1], 'rx')
for i in range(SomSize):
        for j in range(SomSize):
                plt.plot(W[i,j,0],W[i,j,1], 'bo')
```



KeyboardInterrupt:



Things for you to ponder

- What is the right map size?
- What is the right map topological and neighborhood structure?
- Does the SOM "converge"?
- Are there always going to be weights "between" our clusters/classes?
- Any way to speed up what I did above?