

# Object Tracking

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[24]: import cv2 as cv
      from tracker import *
      import sys

[15]: # Create tracker object
      tracker = EuclideanDistTracker()

[16]: # object detector
      object_detector = cv.createBackgroundSubtractorMOG2(history=100, varThreshold=50)

[25]: url = r'C:\Users\choice com\Desktop\python\highway.mp4'
      video = cv.VideoCapture(url)

[27]: img = cv.VideoCapture(url)
      if img is None:
          print("Can't load image, please check the path", file=sys.stderr)
          sys.exit(1)

[ ]: while True:
      success , frame =video.read()
      #     height, width, _ = frame.shape
      #     print(height,width)

      # Extract Region of interest(roi)
      roi = frame
      # apply Mask
      mask = object_detector.apply(roi)

      _, mask = cv.threshold(mask, 254, 255, cv.THRESH_BINARY)
      contours, _ = cv.findContours(mask, cv.RETR_TREE, cv.CHAIN_APPROX_SIMPLE)
      detections = []
      for cnt in contours:
          # Calculate area and remove small elements
          area = cv.contourArea(cnt)
          if area > 100:
              #cv2.drawContours(roi, [cnt], -1, (0, 255, 0), 2)
              x, y, w, h = cv.boundingRect(cnt)
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detections.append([x, y, w, h])
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[ ]: # 2. Object Tracking
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boxes_ids = tracker.update(detections)
for box_id in boxes_ids:
    x, y, w, h, id = box_id
    cv2.putText(roi, str(id), (x, y - 15), cv2.FONT_HERSHEY_PLAIN, 2, (255, 0, 0), 2)
    cv2.rectangle(roi, (x, y), (x + w, y + h), (0, 255, 0), 3)
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[ ]: # show the results
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cv.imshow('rio', rio)
cv.imshow('mask', mask)
cv.imshow('video', frame)
key = cv.waitKey(30)

if key & 0xff == ord('q'):
    break

video.release()
cv.destroyAllWindows()
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