Homework 1

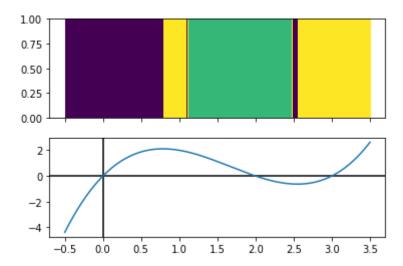
Do the programing part of Homework 1 in this notebook. Predefined are function *stubs*. That is, the name of the function and a basic body is predefined. You need to modify the code to fulfil the requirements of the homework.

```
In [1]: # import numpy and matplotlib
import numpy as np
import matplotlib.pylab as plt
# We give the matplotlib instruction twice, because firefox sometimes gets
# note these `%`-commands are not actually Python commands. They are Jupyte
%matplotlib notebook
%matplotlib notebook
```

```
In [47]: def f(x):
             return x*(x-2)*(x-3)
         def f prime(x):
             return 3*x*x-10*x+6
         def T f(quess):
             #do one iteration of the newton method. f prime(quess) != 0
             return guess - (f(guess)/f prime(guess))
         def newt(guess, max iterates = 20, tolerance=0.0001):
             # Repeat a maximum of 20 times or until our quess is close enough to a
             while(max iterates > 0 or not abs(f(guess)) <= tolerance):</pre>
                  guess = T f(guess)
                 max iterates -= 1
                                        #We do not want the max iterations to exceed
             #reutn root or np.nan if no root is found
             return quess if abs(f(quess)) <= tolerance else np.nan</pre>
         v_newt = np.vectorize(newt)
```

```
In [3]:
        # N is how many points we will sample
        N = 500
        xs = np.linspace(-.5, 3.5, N)
        ys = v_newt(xs)
        # Create a figure with two plots stacked vertically. One will be for
        # the basins of attraction and one will be for graphing f.
        fig, (ax1, ax2) = plt.subplots(nrows=2, sharex=True)
        # The `imshow` command assumes every pixel takes up one unit of space. By
        # defining the `extent` we can tell imshow that we want the units to be
        # something else. An extent is [x min, x max, y min, y max]
        extent = [xs.min(), xs.max(), 0, 1]
        # The `imshow` command expects a 2d array, but `ys` is a 1d array. We can
        # make it a 2d array with the command `np.array([ys])`
        ax1.imshow(np.array([ys]), extent=extent, aspect="auto")
        # Draw some axis lines on the second plot
        ax2.axhline(y=0, color='k')
        ax2.axvline(x=0, color='k')
        # Plot the function
        ax2.plot(xs, f(xs))
```

Out[3]: [<matplotlib.lines.Line2D at 0x111da6f10>]

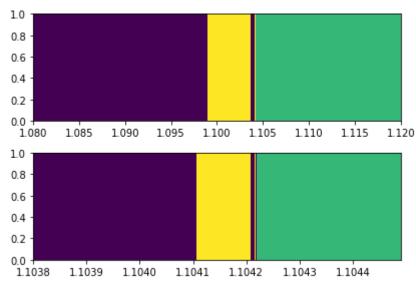


```
In [4]: # Make a graph that is "zoomed-in" to the boundary between two basins of at
# Sample 500 points from the interval [1.08, 1.12]
xs1 = np.linspace(1.08, 1.12, 500)
ys1 = v_newt(xs1)

# Sample 1000 points from the interval [1.1038, 1.10449]
# Resolution was increased to show the repetitive structure would still hol
xs2 = np.linspace(1.1038, 1.10449, 1000)
ys2 = v_newt(xs2)

# Create a figure with two plots stacked vertically. They will not share x
# of each other
fig, (ax1, ax2) = plt.subplots(nrows=2)

ax1.imshow(np.array([ys1]), extent=[xs1.min(), xs1.max(), 0, 1], aspect="au
ax2.imshow(np.array([ys2]), extent=[xs2.min(), xs2.max(), 0, 1], aspect="au
plt.tight_layout()
```



In []:

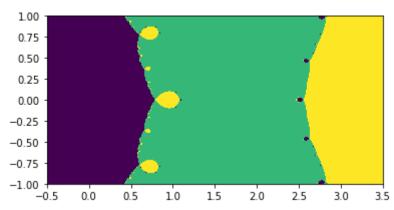
Complex Newton's Method

```
In [46]: #
# This function is provided for you to use later
#

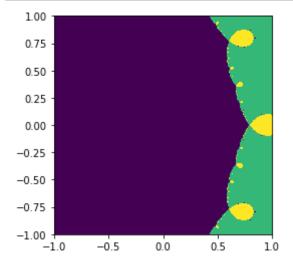
def make_complex_grid(z_low, z_high, N=100):
    """Create an N x N 2d array of complex numbers whose lower-left
    corner is give by `z_low` and upper-right corner is given by `z_high`""
    reals = np.linspace(np.real(z_low), np.real(z_high), N)
    imags = np.linspace(np.imag(z_low), np.imag(z_high), N)
    a, b = np.meshgrid(reals, imags)
    return b*1J + a
```

```
In [7]: def newt second(guess array, tries=20):
            # do the iteration 20 times or until a root is found
            while(tries > 0):
                guess_array = T_f(guess_array)
                tries -= 1
            #reutn root or np.nan if no root is found
            return guess array
        xs = np.array([1,2,3,4, 2000])
        print("v newt and newt2 should give similar results. v newt:\n", v newt(xs)
        v newt and newt2 should give similar results. v newt:
                                                       3.0000012]
         [3.
                     2.
                                3.
                                           3.
         and newt2:
                     2.
                                3.
                                           3.
                                                       3.015201261
         [3.
In [8]: # There are many numpy functions that will be helpful for implementing `cla
        # For example, `np.round`. You can google for these.
        #
        # Another helpful tip is fancy indexing: If `xs` is an array, to set
        # all elements of `xs` which are less than four to zero, you can do
        # `xs[xs < 4] = 0`. To set all elements of `xs` that are less than four k
        # than three to zero, you can do xs[(xs < 4) & (xs > 3)] = 0. Note the
        #
        def clamped newt(ga, iterations=20):
            ga = newt2(ga, iterations)
            ga[ga < 1] = 0
            ga[(1 \le ga) \& (ga < 2.5)] = 2
            qa[2.5 \le qa] = 3
            return np.real(np.round(ga))
        xs = np.array([1,2,3,4, 2000])
        print("clamped newt should the same outputs as newt2, but rounded to the "
              "nearest root. newt2:\n", newt2(xs), "\n and clamped newt:\n", clampe
        clamped newt should the same outputs as newt2, but rounded to the nearest
        root. newt2:
         [3.
                     2.
                                3.
                                           3.
                                                       3.015201261
         and clamped newt:
         [3. 2. 3. 3. 3.]
```

```
In [9]: N = 1000
zs = make_complex_grid(-.5-1j, 3.5+1j, N)
fig, ax = plt.subplots()
extent = [np.real(zs).min(), np.real(zs).max(), np.imag(zs).min(), np.imag(ax.imshow(clamped_newt(zs), cmap="viridis", extent=extent, origin="lower")
plt.show()
```



```
In [10]: N = 1000
zs = make_complex_grid(-1-1j, 1+1j, N)
fig, ax = plt.subplots()
extent = [np.real(zs).min(), np.real(zs).max(), np.imag(zs).min(), np.imag(ax.imshow(clamped_newt(zs), cmap="viridis", extent=extent, origin="lower")
plt.show()
```



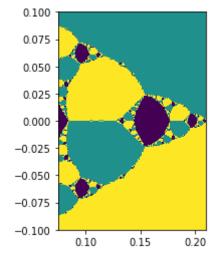
A new function

```
In [41]: def f_new(x):
    return 3*x**3 - 2*x + 1

def f_new_prime(x):
    return 9*(x**2) - 2

def my_fractal(x, iterations = 30):
    #similar to clamped newt but for function 3*x^3 - 2*x + 1
    x = newt2(x, iterations)
    x[np.isreal(x)] = 1
    x[np.imag(x) > 0] = 2
    x[np.imag(x) < 0] = 3
    return np.real(np.round(x))</pre>
```

```
In [30]: N = 500
   zs = make_complex_grid(.075-0.1j, 0.21+0.1j, N)
   fig, ax = plt.subplots()
   extent = [np.real(zs).min(), np.real(zs).max(), np.imag(zs).min(), np.imag(ax.imshow(colorify(zs), cmap="viridis", extent=extent, origin="lower")
   plt.show()
```



Common Fractals

```
In [31]:
         # Below are some functions that you might find useful
         #
         # needed for plotting many line segments
         from matplotlib import collections
         # If you want more context to understand this function, google "higher orde
         def repeat(func, times=5):
              """Returns a function that applys `func` to its input
             `times` number of times."""
             def new func(x):
                 for _ in range(times):
                     x = func(x)
                  return x
             return new func
         def render segments to array(segments, array, extent=[0, 1, 0, 1]):
              """Given a list of segments `segments` and a 2d numpy array `array`,
              "draw" the segments to the array. The resulting array is suitable for {
m d}
             with `imshow`. """
             from skimage.draw import line
             array = array.copy()
             h, w = array.shape
             for (p1, p2) in segments:
                  # conver the xy-coordinates to array indices
                 plx = np.clip(int((pl[0] - extent[0]) / (extent[1] - extent[0]) * w
                 p2x = np.clip(int((p2[0] - extent[0]) / (extent[1] - extent[0]) * w
                 ply = np.clip(int((p1[1] - extent[2]) / (extent[3] - extent[2]) * h
                 p2y = np.clip(int((p2[1] - extent[2]) / (extent[3] - extent[2]) * h
                 coords = line(ply, plx, p2y, p2x)
                 array[coords] = 1
             return array
```

In []:

Cantor Set

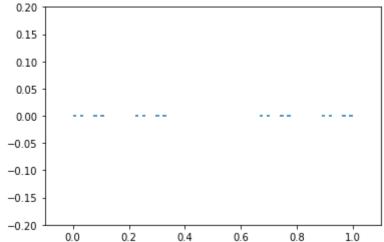
```
In [33]: # create a function that repeats `cantroize` several times.
multi_cantorize = repeat(cantorize, 4)

fig, ax = plt.subplots()

lines = collections.LineCollection(multi_cantorize(starting_segments))
# plot line
ax.add_collection(lines)

ax.set_xlim(-.1, 1.1)
ax.set_ylim(-.2, .2)

plt.show()
```



```
In [ ]:
```

Koch Snowflake

```
In [ ]:
In [ ]:
In [ ]:
```

```
In [45]: #
# Estimate the box-counting dimension of the Koch snowflake
#
extent = [0, 1, -.5, .5]
#different box lengths
lengths = np.linspace(10, 100, 50)

first_part = [((0,0), (1,0))]
koch_parts = kochize(starting_segments)

x = np.log(lengths)
y = np.log([render_segments_to_array(koch_segments, np.zeros((1, int(N))),
# The best fit. The slope approximates dimension.
slope, intercept = np.polyfit(x, y, 1)
print("The dimension is approximately", slope)
```

The dimension is approximately 1.0130760162782304

Strange Koch

```
In [ ]:
In [ ]:
```

Boundary Dimensions

```
In []:
In [26]: #
# Graph the boundary of the Newton fractal determined by f(x)=x(x-2)(x-3)
#
In []: #
# Estimate the fractal dimension of the boundary of the Newton fractal give
# In []:
```