

Easy Altivar ATV610 Parameter List



1 [Simply start] 5 4 5 -

1.1 [Macro Config] [F [[Start/Stop] 6 5 £ 5 [Auto/Manual] Ь Я П П [PID controller] b P . c [Preset speeds] b P 5 P 1.2 [Simply start] 5 , □ -[Nominal Motor Power] n P r [Nom Motor Current] 🗖 [[Motor Th Current] I H [Acceleration] A [[[Deceleration] d E [[Low speed 1 L 5 P [High speed] H 5 P [Output Ph Rotation] PHF

1.3 [Modified parameters] L □ d -

[OutPhaseLoss Assign] a P L

[Ref Freq 1 Config] F -

[2/3-Wire Control] £ [

[Dual rating] d r b

2 [Display] / a n -

2.1 [Motor parameters] ☐ ☐ a -

```
[Motor Speed] 5 P d
[Motor voltage] u p P
[Motor Power] p P r
[Motor Torque] a E r
[Motor Current] L [
[Motor Therm State] L H r
```

2.2 [Drive parameters] | | | | | |

```
[Pre-Ramp Ref Freq] F - H
[Ref Frequency] L F
[Motor Frequency] r F
[Mains Voltage] u L n
[DC bus voltage] V b u 5
[Drive Therm State] £ H d
[Used param. set] [ F P S
[Motor Run Time] r L H
[Power-on time] P L H
[IGBT Warning Counter] L R C
[PID reference] - P
[PID feedback] - PF
[PID Error] - P
[PID Output] - P o
```

2.3 [I/O Map] ₁ □ □ -

```
[Digital Input Map] L
[Analog inputs image] A R - [Al(x) assignment] A I X A [Al(x) Min. Value] U I L X [Al(x) Max Value] U I H X [Al(x) Min. Value] L - L X
       [Al(x) Max Value] [ - H X
       [Al(x) filter] A , X F where x is a number from 1 to 5
[Analog outputs image] A \circ A [AQ(x) assignment] A \circ X
       [AQ(x) min Output] _ _ _ L X
       [AQ(x) max Output] _ _ _ H X
       [AQ(x) min output] F = L X
       [AQ(x) max output] R<sub>D</sub> H X
[Scaling AQ(x)min] R 5 L X
[Scaling AQ(x)max] R 5 H X
[AQ(x) Filter] R<sub>D</sub> X F
where x is a number from 1 to 2
```

[Digital Output Map] L a F 2.4 [Energy parameters] E n P -

```
[Motor Consumption (GWh] \Pi E \exists [Motor Consumption (MWh] \Pi E \exists
[Motor Consumption (kWh] [ E |
[Motor Consumption (Wh] ПЕ 🛭
```

2.5 [Communication map] [□ □ □ -

```
[Command Channel] [ [ ] d [
[Pre-Ramp Ref Freq] F r H
[CIA402 State Reg] E L R
[Modbus network diag] П п 🗗
```

```
[COM LED] [I d b |
    [Mdb Frame Nb] // / c E
    [Mdb NET CRC errors] [7 | E c
    [Com. scanner input map] | 5 R - [Com Scan In(x) val.] | 7 R I to | 7 R B [Com scan output map] | 5 R -
        [Com Scan Out(x) val.] n [ | to n [ ]
[Modbus HMI diag] \Pi \stackrel{.}{=} \stackrel{.}{H}
    [COM LED] 17 d b 2
    [Command word image] [ W , -
    [Modbus Cmd] [ \Pi d
    [COM. Module cmd.] [ \Pi d 3
[Freq. ref. word map] r W r -
[Modbus Ref Freq] L F r
    [Com Module Ref Freq] L F - 3
```

2.6 [Application Parameters] Fig. -

```
[Variable Speed Pump] \sqcap PP -
   [Available Pumps] \Pi P R \cap
    [Nb of Staged Pumps] P 5 n
   [Lead Pump] PL id
    [Next Staged Pump] Pn L 5
    [Next Destaged Pump] P n L d
   [Pump (x) State] P X S
   [Pump (x) State] P X E
[Pump (x) Runtime] P X = E
   [Pump (x) Nb Starts] P X n 5
    where x is a number from 1 to 6
[Booster Control Pump] b c P
   [Booster Status] 6 c 5
```

3 [Diagnostics] d ₁ R -

[Last Warning] L FIL -[last Error] L F E [Nb Of Starts] n 5 // [Motor Run Time] r E H [Other State] 5 5 L [Identification] a , d

3.2 [Error history] P F H -

```
[Last Error (X)] dP I to dPB [Drive state] H 5 X
    [Last Error (x) Status] E P x
[ETI state word] P x
    [Motor current] L [ P x
     [Output frequency] - FPx
    [Elapsed time] r E P x
[DC bus voltage] u L P x
[Motor therm state] E H P x
     [Command Channel] d [ [ x
    [Ref Freq Channel] d r [ x
     [Motor Torque] 

E P X
     [Drive Thermal State] Ł d P x
    [IGBT Junction Temp] Ł J P x
[Switching Frequency] 5 F P x
    where x is a number from 1 to 8
```

3.3 [Warnings] FL - -

```
[Actual Warnings] A L r d
[Warning History] R L h
```

4 [Complete settings] [5 b

```
4.1 [Motor parameters] ☐ P A -
     [Motor Standard] b F
     [Nominal Motor Power] n P
     [Nom Motor Voltage] 🗓 n 5
     [Nom Motor Current] n [ r
     [Nominal Motor Freq] F - 5
[Nominal Motor Speed] - 5 P
     [Max frequency] E F -
     [Motor Th Current] , E H
     [Output Ph Rotation] PH
     [Motor control type] [ L L
     [U/F Profile] PF
     [U1] u /
     [F1] F /
     [U2] u 2
     [F2] F 2
     [U3] u 3
     [F3] F 3
     [U4] u 4
     [F4] F 4
     [U5] u 5
     [F5] F 5
     [IR compensation] u F
     [Slip compensation] 5 L P
     [Switching frequency] 5 F
     [Switch Freq Type] 5 F L
     [Noise Reduction] nrd
     [Motor surge limit.] 5 V L
     [Attenuation Time] 5 o P
     [Current Limitation] [ L ,
     [Autotuning] Ł 🔟
     [Autotuning Status] Ł u 5
     [Dual rating] dr E
     [Boost activation] b - F
     [Boost] boo
     [Freq Boost] F A b
```

4.2 [Input/Output] . . . -

```
[2/3-Wire Control] L [
[2-wire type] E E E [Reverse Assign] - - 5
[DI1 Assignment] L , I [
      [DI1 Low Assignment] L /L
      [DI1 High Assignment] L I H
[DI1 Delay] L I d

[DI2 Assignment] L 12 C -

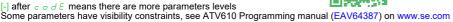
[DI3 Assignment] L 13 C -

[DI4 Assignment] L 14 C -

[DI5 Assignment] L 15 C -
[DI6 Assignment ] L , E [
[DI11 Assignment] L , I I E
| D112 Assignment | L | 12 | E | |
| D113 Assignment | L | 13 | E | |
| D114 Assignment | L | 14 | E | |
| D115 Assignment | L | 15 | E | |
[DI16 Assignment] L , 16 [
[Ref Freq template] b 5 P
[Al1 configuration] F , I - [Al1 assignment] F , I F
      [Al1 Type] R , I L
[Al1 Min. Value] u , L
      [Al1 Max Value] u , H /
      [Al1 Min. Value] [ r L | [Al1 Max Value] [ r H |
     [Al1 filter] A , IF
[Al1 Interm. point X] A , IE
[Al1 Interm. point Y] A , IS
[Al2 configuration] F , 2
[Al3 configuration] F , 3 -
[Al4 configuration] F
[Al5 configuration] R , 5 -
[AlV1 assignment] R V I R
[DQ11 configuration] do | | - | DQ12 configuration] do | 2 - |
[R1 configuration] - [R1 Assignment] -
      [R1 Delay time] r I d
[R1 Active at] r I 5
[R1 Holding time] r I H
[R2 configuration ] r 2
[R3 configuration] - 3 -
[R4 configuration] - 4 -
```

[R5 configuration]





[R6 configuration] - 5 -	[Flow rate unit] 5 u F r	[Pumps Configuration] Pull P-
[AQ1 configuration]	[Temperature unit] 5 \(\tilde{L} \) \(\tilde{P} \)	[Pump 1 Cmd Assign] P
[AQ1 assignment] F a / -	[Currency unit list] 5 \Box \Box	[Pump 1 Ready Assign] P
[AQ1 Type] R o I L [AQ1 min output] R o L I	[Liquid Density] - H - [PID controller] - I	[Pump 2 Cmd Assign] ПРага [Pump 2 Ready Assign] ПРага
[AQ1 max output] F = H /	[PID Feedback] F d b	[Pump 3 Cmd Assign] $\Pi P = 3$
[AQ1 min output] u a L /	[Type of control] $E \circ E = E$	[Pump 3 Ready Assign] $\sqcap P$
[AQ1 max output] u a H /	[PID feedback Assign] P + F	[Pump 4 Cmd Assign] $\sqcap P \circ \mathcal{A}$
[Scaling AQ1 min] F 5 L I	[Min PID feedback] P , F /	[Pump 4 Ready Assign] ПР
[Scaling AQ1 max] F 5 H I	[Max PID feedback] P F 2	[Pump 5 Cmd Assign] $\Pi P = 5$
[AQ1 Filter] R a I F	[PID feedback] r P F	[Pump 5 Ready Assign] 7 P
[AQ2 configuration] 🛭 🗗 🗗 -	[Min fbk Warning] P R L [Max fbk Warning] P R H	[Pump 6 Cmd Assign] ☐ P □ 5 [Pump 6 Ready Assign] ☐ P □
.3 [Command and Reference] [┌ ┌ ┌ -	[PID Reference] r F -	[Pump Cycling Mode] PPC
[Low Speed] L 5 P	[Intern PID Ref] P	[Lead Pump Altern.] $\Pi P L R$
[High Speed] H 5 P	[Ref Freq 1 Config] F - /	[Altern Wait Time] 🗇 🛭 🗜
[Ref Freq 1 Config] F r /	[Min PID Process] P , P	[Pump Auto Cycling] ПР с Р
[Reverse Disable] For the [Stop Key Enable] Post Enable Post Enable	[Max PID Process] P P 2	[Pump Ready Delay] IT P I d
[Control Mode] [H [F	[Internal PID ref] F F	[MultiPump ErrorResp] ПР F Ь
[Command Switching] [[5	[Auto/Manual assign.] P R ப [Manual PID reference] P ப	[Booster Control] b 5 c − [Booster Control] b c Π
[Cmd channel 1] [d /	[PID preset references] Pr	[Stage/Destage Cond.] 5 d c П -
[Cmd channel 2] [d 2	[2 PID Preset Assign] P - 2	[Boost Working range] b c W h
[Freq Switch Assign] r F [[4 PID Preset Assign] Pr 4	[Booster Stg Delay] 6 5 d
[Ref Freq 2 Config] F - 2	[Ref PID Preset 2] r P 2	[Booster Dstg Delay] b d d
[Copy Ch1-Ch2] [a P	[Ref PID Preset 3] F P 3	[Boost Override range] b c o f
[Forced Local Freq] F L a E [Time-out forc. local] F L a E	[Ref PID Preset 4] r P 4 [Predictive Speed Ref] F P 1	[Booster S/D Interval] b 5 d b
[Forced Local Assign] F L a	[Speed input %] P 5 r	4.5 [Generic monitoring] ☐ P
[HMI cmd.] $b \Pi P$	[Settings] 5 £ -	[Stall monitoring] 5 E P r -
•	[PID Prop.Gain] - P G	[Stall monitoring] 5 E P =
.4 [Generic functions] [5 [F -	[PID Intgl.Gain] - 15	[Stall Max Time] 5 L P
[Ramp] - A П Р - [Ramp Type] - P Ł	[PID derivative gain] r d [[Stall Current] 5 E P 2 [Stall Frequency] 5 E P 3
[Ramp Type]	[PID ramp] P - P	[Stail Frequency] 5 E P 3 [Therm sensor monit] 17 E 5 P -
[Acceleration] A [[PID Inversion] P , [[PID Min Output] P o L	[Al2 Th Monitoring] £ h 2 5
[Deceleration] d E [[PID Max Output] P a H	[Al2 Type] A . 2 L
[Begin Acc round] E A I	[PID error Warning] PEr	[Al2 Th Warn Level] £ h 2 R
[End Acc round] E A 2	[PID Integral OFF] P , 5	[Al2 Th Error Level] L h 2 F
[Begin Dec round] <i>E Fl ∃</i> [End Dec round] <i>E Fl Ч</i>	[PID acceleration time] A C C P	[Al2 Th Error Resp] E h 2 b [Al2 Th Value] E h 2 V
[Ramp 2 Thd] F r E	[PID Start Ref Freq] 5 F 5 [Sleep/Wakeup] 5 P W	[Al3 Th Monitoring] E h 3 5
[Ramp Switch Assign] - P 5	[Sleep menu] 5 L P -	[Al3 Type] A J E
[Acceleration 2] A C 2	[Sleep Detect Mode] 5 L P II	[Al3 Th Warn Level] L h 3 R
[Deceleration 2] d E d	[Sleep Switch Assign] 5 L PW	[Al3 Th Error Level] L h 3 F
[Dec.Ramp Adapt] b r F [+/- speed] u P d -	[Inst. Flow Assign.] F 5 1 R	[Al3 Th Error Resp] £ h 3 b [Al3 Th Value] £ h 3 V
[+ Speed Assign] u 5 P -	[Sleep Flow Level] 5 L n L [OutletPres Assign] P 5 2 R	[Al4 Th Monitoring] E h 4 5
[- Speed Assign] d 5 P -	[Sleep Pressure Level] 5 L P L	[Al4 Th Warn Level] L h 4 A
[Ref Frequency Save] 5 £ r	[Sleep Min Speed] 5 L 5 L	[Al4 Th Error Level] E h 4 F
[Stop configuration] 5 Ł Ł -	[Sleep Power Level] 5 L P r	[Al4 Th Error Resp] E h 4 b
[Type of stop] 5 Ł Ł [Freewheel Stop] 5 Ł	[Sleep Delay] 5 L P d	[Al4 Th Value] 上 h 서 V [Al5 Th Monitoring] 上 h 5 5
[Freewheel stop Thd] F F E	[Boost] 5 b b - [SLeep Boost Speed] 5 b b 5	[Al5 Th Warn Level] E h 5 R
[Fast Stop Assign] F 5 L -	[Sleep Boost Time] 5 L b E	[Al5 Th Error Level] E h 5 F
[Ramp Divider] d [F	[Advanced sleep check] A d 5 -	[Al5 Th Error Resp] E h 5 b
[DC Injection Assign] d [[Sleep Mode] R 5 L П	[Al5 Th Value] <i>E h</i> 5 V
[DC Inj Level 1] , d [[DC Inj Time 1] b d ,	[Sleep Condition] A 5 L C	4.6 [Error/Warning handling] [5₩ 🛭 -
[DC Inj Level 2] I d [2	[Sleep Check Delay] # 5 L d [Check Sleep Ref spd] # 5 L c	[Fault Reset] - 5 -
[DC Inj Time 2] Ł d [[Wake up menu] W K P -	[Fault Reset Assign] - 5 F
[Auto DC injection] Fld [-	[Wake Up Mode] W u P II	[Prod Restart Assign] - PR
[Auto DC injection] A d [[Wake Up Process level] \w \u P F	I [Product restart] ┌ P [Auto Fault Reset] ℛ Ł ┌ -
[Auto DC inj Level 1] 5 d E [Auto DC inj Time 1] b d E	[Wake Up Process Error] W u P E	[Auto Fault Reset] RE c
[Auto DC inj Time 1] E & E T	[OutletPres Assign] P 5 2 R	[Fault Reset Time] E R c
[Auto DC inj Time 2] E d [2	[Wake Up Press level] ₩ ⊔ P L [Wake Up Delay] ₩ ⊔ P d	[Catch on the fly] F L
[Jog]	[Threshold reached] E H r E -	[Catch On Fly] F L r
[Jog Assign] J o G -	[High Current Thd] [L d	[Catch on Fly Sensitivity] $V \subset b$
[Jog Frequency] J [F	[Low I Threshold] [E d L	[Motor thermal monit]
[Jog Delay] J 🖟 Ł [Preset Speeds] P 5 5 -	[Motor Freq Thd] F E d	[Motor Therm Thd] E E d
[2 Preset Freq] P 5 2	[Low Freq.Threshold] F L d L [Freq. threshold 2] F Z d	[MotorTemp ErrorResp] a L L
[4 Preset Freq] P 5 4	[2 Freq. Threshold] F 2 d L	[Output phase Loss] PL
[8 Preset Freq] P 5 B	[Motor Therm Thd] E E d	[OutPhaseLoss Assign] [OutPhaseLoss Assign]
[16 Preset Freq] P 5 1 6	[Reference high Thd] r E d	[OutPhaseLoss Delay] a d b [Input phase loss] a P L -
[Preset Speed 2] 5 P 2 [Preset Speed 3] 5 P 3	[Reference low Thd] r E d L	[InPhaseLoss Assign] PL
[Preset Speed 4] 5 P 4	[Mains contactor command] L L [-	[External error] E E F -
[Preset Speed 5] 5 P 5	[Mains V. time out] L c E [Mains Contactor] L L c	[Ext Error assign] E Ł F
[Preset Speed 6] 5 P 5	[Drive Lock] L E 5	[Ext Error Resp] E P L
[Preset Speed 7] 5 P 7	[Parameters switching] / L P -	[Undervoltage handling] $_{\perp}$ 5 $_{b}$ -
[Preset Speed 8] 5 P B	[2 Parameter sets] c h fl I	[Undervoltage Resp] ω 5 b [Mains voltage] ω c E 5
[Preset Speed 9] 5 P 9 [Preset Speed 10] 5 P 1 0	[3 Parameter sets] c h A 2	[Undervoltage level] u 5 L
[Preset Speed 11] 5 P	[Parameter Selection] 5 P 5 [Stop after speed timeout] P r 5 P -	[UnderVolt timeout] u 5 Ł
[Preset Speed 12] 5 P 1 2	joiop aiter speed tilleout FF 3F -	[Stop Type PLoss] 5 £ P
[Preset Speed 13] 5 P I 3		
[Preset Speed 14] 5 P 14	[Low Speed Timeout] Ł L 5 [Sleep Offset Thres.] 5 L E	[UnderV. restart tm] Ł 5 Π
	[Low Speed Timeout] £ L 5 [Sleep Offset Thres.] 5 L E [Advanced sleep check] # d 5	[UnderV. restart tm] £ 5 П [Prevention level] ப Р L
[Preset Speed 15] 5 P / 5	[Low Speed Timeout] £ £ 5 [Sleep Offset Thres.] 5 £ £ [Advanced sleep check] # £ 5 [Sleep Mode] # 5 £ //	[UnderV. restart tm] £ 5 П [Prevention level] ப Р L [Max stop time] 5 £ П
Preset Speed 15] 5 P 15 Preset Speed 16] 5 P 16	[Low Speed Timeout] £ L 5 [Sleep Offset Thres.] 5 L E [Advanced sleep check] R d 5 [Sleep Mode] R 5 L R [Sleep Condition] R 5 L E	[UnderV. restart tm] £ 5 П [Prevention level] ப Р L
[Preset Speed 15] 5 P / 5	[Low Speed Timeout] £ L 5 [Sleep Offset Thres.] 5 L E [Advanced sleep check] A J 5 [Sleep Mode] A 5 L A [Sleep Condition] A 5 L C [Sleep Check Delay] A 5 L J	[UnderV. restart tm] £ 5 П [Prevention level]
[Preset Speed 15] 5 P 15 [Preset Speed 16] 5 P 15 [Skip Frequency] J P F [Skip Frequency 2] J F Z [3rd Skip Frequency] J F 3	[Low Speed Timeout] £ L 5 [Sleep Offset Thres.] 5 L E [Advanced sleep check] A d 5 [Sleep Mode] A 5 L D [Sleep Condition] A 5 L D [Sleep Check Delay] A 5 L D [Check Sleep Ref spd] A 5 L D	[UnderV. restart tm] £ 5 П [Prevention level] u P L [Max stop time] 5 £ П [DC bus maintain time] £ b 5 [Ground Fault] □ r F L [Ground Fault Activation] □ r F L [4-20 mA loss] L F L
[Preset Speed 15] 5 P 5 [Preset Speed 16] 5 P 6 [Skip Frequency] J P F [Skip Frequency 2] J F 2 [3rd Skip Frequency] J F 3 [Skip Freq.Hysteresis] J F H	[Low Speed Timeout] £ L 5 [Sleep Offset Thres.] 5 L E [Advanced sleep check] A J 5 [Sleep Mode] A 5 L A [Sleep Condition] A 5 L C [Sleep Check Delay] A 5 L J	[UnderV. restart tm] £ 5 П [Prevention level] \Box P L [Max stop time] S E R [DC bus maintain time] E E E [Ground Fault] \Box E E E [Ground Fault Activation] \Box E E E [4-20 mA loss] E E E [Al1 4-20mA loss] E E E
[Preset Speed 15] 5 P 15 [Preset Speed 16] 5 P 15 [Skip Frequency] J P F [Skip Frequency 2] J F Z [3rd Skip Frequency] J F 3	[Low Speed Timeout] £ £ 5 [Sleep Offset Thres.] 5 £ E [Advanced sleep check] A d 5 [Sleep Mode] A 5 £ R [Sleep Condition] A 5 £ C [Sleep Check Delay] A 5 £ d [Check Sleep Ref spd] A 5 £ C [Booster Control] £ 5 £ C	[UnderV. restart tm] £ 5 П [Prevention level] u P L [Max stop time] 5 £ П [DC bus maintain time] £ b 5 [Ground Fault] □ r F L [Ground Fault Activation] □ r F L [4-20 mA loss] L F L

```
[Al4 4-20mA loss] L F L 4
[Al5 4-20mA loss] L F L 5
       [Error detection disable] In H
           [ErrorDetect Disable] In H
       [Fieldbus Interrupt Resp] [ L L
           [Modbus Error Resp] 5 L L
      [Communication Module] [ o [ o ] o [ [Fieldbus Interrupt Resp] [ L L
       [Tuning Error Resp] & n L
       [Process underload] __ L __
            [Unld T. Del. Detect] u L E
            [Unld.Thr.Nom.Speed] L u n
            [Unld.Thr.0.Speed] L u L
           [Unld. FreqThr. Det.] - Пид
[Hysteresis Freq] 5 - b
           [Underload Mangmt.] u d L
[Underload T.B.Rest.] F L u
       [Process overload] ... L ...
            [Ovld Time Detect.] L o L
            [Ovld Detection Thr.] L a c
           [Hysteresis Freq] 5 - b
[Ovld.Proces.Mngmt] - d L
            [Overload T.B.Rest.] F L a
       [Warning groups config] F [ F
           [Warn grp 1 definition] R / c [Warn grp 2 definition] R 2 c
           [Warn grp 3 definition] R \ni c
[Warn grp 4 definition] R \ni c
[Warn grp 5 definition] R \ni c
4.7 [Maintenance] [ 5 ∏ R -
       [Diagnostics] d R u
            [FAN Diagnostics] F n E
            [LED Diagnostics] h L E
```

[IGBT Diagnostics with motor] , W E [IGBT Diagnostics w/o motor] , W o E [Fan management] F A D A -

[Fan mode] F F П

[Time Counter Reset] - Pr

[Overmodul. Activation] D V II F

5 [Communication] [□ □ □ -

```
[Modbus Address] F d d
[Modbus baud rate] L b r
[Modbus Format] E F o
[ModbusTimeout] L L D
[Com. scanner input] , L 5
   [Scan. IN1 address] n II F
   [Scan. IN2 address] n II A 2
   [Scan. IN3 address] ¬ П Я Э
    [Scan. IN4 address] 🖪 🛭 🗗 🛱 4
   [Scan. IN5 address] n II F 5
   [Scan. IN6 address] ¬ П Я Б
   [Scan. IN7 address] ¬ П Я 7
   [Scan. IN8 address] n II A B
[Com. scanner output] D E 5 -
   [Scan.Out1 address] n c R
    [Scan.Out2 address] n c 月 2
   [Scan.Out3 address] n = F 3
   [Scan.Out4 address] n c R 4
   [Scan.Out5 address] n c R 5
   [Scan.Out6 address] n c R 5
   [Scan.Out7 address] n c F 7
    [Scan.Out8 address] n c R B
[Profibus] Pbc - [Address] Rdrc
```

```
6 [File management] F □ L -
6.1 [Transfer config file] L [ F -
    [Copy to the drive] \circ PF [Copy from the drive] 5 RF
6.2 [Factory settings] F [ 5 -
     [Config. Source] F [ 5 ,
     [Parameter group list] F - 4 -
     [Go to Factory Settings] [ F 5
     [Save Configuration] 5 [ 5
6.3 [Firmware Update] F W □ P -
    [Identification]
     [Package version] PF u
```

[Package Type] PK EP [Package Version] P K V 5 [Update Firmware] F W F P [Abort Firmware Update] F W [L

7 [My preferences] ☐ ☐ P -

```
7.1 [Language] L n [ -
7.2 [Password] [ a d -
     [Password status] P 5 5 E [Password] P W d
     [Upload rights] u L
     [Download rights] d L r
7.3 [Customization] [ 4 5 -
     [Display screen type] \sqcap 5 \sqsubset -
         [Display value type] \Pi d E
         [Parameter Selection] \sqcap P =
7.4 [Access Level] L A c -
     [Basic] b R 5
```

[Expert] E P -

7.5 [LCD settings] c n L -[Screen Contrast] _ 5 _ 5 [Standby] 5 b 9 [Display Terminal locked] K L E K



Troubleshooting \(\square\)







Scan the QR code in front of the drive to get the error codes explanations in the Diagnostics section.

Notes