

# Convex Optimization

## Lecture 4: Two-phase Simplex, Degenerated form and Duality of LP

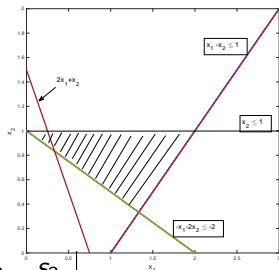
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*Autumn Semester 2025*

# Outline

- 1 Two-phase Simplex Method
- 2 Two-phase Simplex Method by Matrix Operation
- 3 Infeasible and Unbounded Problems
- 4 Degenerated Linear Programming
- 5 Duality in Linear Programming
- 6 Network Max-flow Problem

# Linear Programming: the two-phase problem (1)

$$\begin{aligned} & \text{Max. } 2x_1 + x_2 \\ & \text{s. t. } \begin{cases} x_1 - x_2 \leq 1 \\ x_1 + 2x_2 \geq 2 \\ x_2 \leq 1 \\ x_1, x_2 \geq 0 \end{cases} \end{aligned} \quad (1)$$



	z	$x_1$	$x_2$	$s_1$	$s_2$	$s_3$	
	1	-2	-1	0	0	0	0
$s_1$	0	1	-1	1	0	0	1
$s_2$	0	1	2	0	-1	0	2
$s_3$	0	0	1	0	0	1	1

- $x_1 = x_2 = 0$  is not a basic solution for the problem
- There is no start point

# Linear Programming: the two-phase problem (2)

- Introduce slack variable  $s_1$ ,  $s_2$  and  $s_3$

$$\begin{array}{ll} \text{Max.} & 2x_1 + x_2 \\ \text{s.t.} & \begin{cases} x_1 - x_2 + s_1 = 1 \\ x_1 + 2x_2 - s_2 = 2 \\ x_2 + s_3 = 1 \\ x_1, x_2, s_1, s_2, s_3 \geq 0 \end{cases} \end{array}$$

- Let  $x_1 = x_2 = 0$ , we check whether we can have a basic solution
- The answer is **No** since  $s_2 = -2$

- Introduce artificial/auxiliary variable  $a_1$

$$\begin{array}{ll} \text{Max.} & 2x_1 + x_2 \\ \text{s.t.} & \begin{cases} x_1 - x_2 + s_1 = 1 \\ x_1 + 2x_2 - s_2 + a_1 = 2 \\ x_2 + s_3 = 1 \\ x_1, x_2, s_1, s_2, s_3, a_1 \geq 0 \end{cases} \end{array}$$

- Let  $x_1 = x_2 = 0$ , we check whether we can have a basic solution
- The answer is **Yes** since  $a_1 = 2$

# Linear Programming: the two-phase problem (3)

- We solve the auxiliary problem first
- Find out the minimum  $a_1$  that satisfies the equations

$$\begin{array}{ll} \text{Max.} & -a_1 \\ \text{s.t.} & \begin{cases} x_1 - x_2 + s_1 = 1 \\ x_1 + 2x_2 - s_2 + a_1 = 2 \\ x_2 + s_3 = 1 \\ x_1, x_2, s_1, s_2, s_3, a_1 \geq 0 \end{cases} \end{array}$$

	B	z	$a_1$	$x_1$	$x_2$	$s_1$	$s_2$	$s_3$	C
$R_0$		1	1	0	0	0	0	0	0
$R_1$	$s_1$	0	0	1	-1	1	0	0	1
$R_2$	$a_1$	0	1	1	2	0	-1	0	2
$R_3$	$s_3$	0	0	0	1	0	0	1	1

# Linear Programming: the two-phase problem (4)

## Phase-I: pre-processing

	B	z	$a_1$	$x_1$	$x_2$	$s_1$	$s_2$	$s_3$	C
$R_0$		1	1	0	0	0	0	0	0
$R_1$	$s_1$	0	0	1	-1	1	0	0	1
$R_2$	$a_1$	0	1	1	2	0	-1	0	2
$R_3$	$s_3$	0	0	0	1	0	0	1	1

$$R_0 = R_0 - R_2 \Downarrow$$

	B	z	$a_1$	$x_1$	$x_2$	$s_1$	$s_2$	$s_3$	C
$R_0$		1	0	-1	-2	0	2	0	-2
$R_1$	$s_1$	0	0	1	-1	1	0	0	1
$R_2$	$a_1$	0	1	1	2	0	-1	0	2
$R_3$	$s_3$	0	0	0	1	0	0	1	1

Pre-processing: to make sure the coefficients of all basic variables on  $R_0$  are zeros

# Linear Programming: the two-phase problem (5)

	B	z	$a_1$	$x_1$	$x_2$	$s_1$	$s_2$	$s_3$	C
$R_0$		1	0	-1	-2	0	2	0	-2
$R_1$	$s_1$	0	0	1	-1	1	0	0	1
$R_2$	$a_1$	0	1	1	2	0	-1	0	2
$R_3$	$s_3$	0	0	0	1	0	0	1	1

swap  $x_2$  in  $\Downarrow$  swap  $a_1$  out

	B	z	$a_1$	$x_1$	$x_2$	$s_1$	$s_2$	$s_3$	C
$R_0$		1	1	0	0	0	0	0	0
$R_1$	$s_1$	0	0.5	1.5	0	1	-0.5	0	2
$R_2$	$x_2$	0	1	1	2	0	-1	0	2
$R_3$	$s_3$	0	-0.5	-0.5	0	0	0.5	1	0

- To this end, this auxiliary problem reaches the optima
- We will solve the original problem with this tableau
- Only need to replace the objective function

# Linear Programming: the two-phase problem (6)

## Phase-II

	B	z	$x_1$	$x_2$	$s_1$	$s_2$	$s_3$	C
$R_0$		1	-2	-1	0	0	0	0
$R_1$	$s_1$	0	1.5	0	1	-0.5	0	2
$R_2$	$x_2$	0	1	2	0	-1	0	2
$R_3$	$s_3$	0	-0.5	0	0	0.5	1	0

$$R_0 = R_0 + R_2/2 \downarrow$$

	B	z	$x_1$	$x_2$	$s_1$	$s_2$	$s_3$	C
$R_0$		1	-1.5	0	0	-0.5	0	1
$R_1$	$s_1$	0	1.5	0	1	-0.5	0	2
$R_2$	$x_2$	0	1	2	0	-1	0	2
$R_3$	$s_3$	0	-0.5	0	0	0.5	1	0

- At Phase-II, the auxiliary variables like  $a_1$  can be simply ignored!!

Pre-processing: to make sure the coefficients of all basic variables on  $R_0$  are zeros



# Linear Programming: the two-phase problem (7)

## Phase-II

$B$		$z$	$x_1$	$x_2$	$s_1$	$s_2$	$s_3$	$C$
$R_0$		1	-1.5	0	0	-0.5	0	1
$R_1$	$s_1$	0	1.5	0	1	-0.5	0	2
$R_2$	$x_2$	0	1	2	0	-1	0	2
$R_3$	$s_3$	0	-0.5	0	0	0.5	1	0

swap-in  $x_1$   $\Downarrow$  swap-out  $s_1$

$B$		$z$	$x_1$	$x_2$	$s_1$	$s_2$	$s_3$	$C$
$R_0$		1	0	0	1	-1	0	3
$R_1$	$x_1$	0	1.5	0	1	-0.5	0	2
$R_2$	$x_2$	0	0	2	-2/3	-2/3	0	2/3
$R_3$	$s_3$	0	0	0	1/3	1/3	1	2/3

# Linear Programming: the two-phase problem (8)

## Phase-II

$B$		$z$	$x_1$	$x_2$	$s_1$	$s_2$	$s_3$	$C$
$R_0$		1	0	0	1	-1	0	3
$R_1$	$x_1$	0	1.5	0	1	-0.5	0	2
$R_2$	$x_2$	0	0	2	-2/3	-2/3	0	2/3
$R_3$	$s_3$	0	0	0	1/3	1/3	1	2/3

swap-in  $s_2$   $\Downarrow$  swap-out  $s_3$

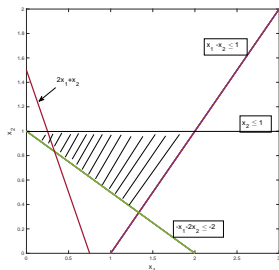
$B$		$z$	$x_1$	$x_2$	$s_1$	$s_2$	$s_3$	$C$
$R_0$		1	0	0	2	0	3	5
$R_1$	$x_1$	0	1.5	0	1.5	0	1.5	3
$R_2$	$x_2$	0	0	2	0	0	2	2
$R_3$	$s_2$	0	0	0	1/3	1/3	1	2/3

# Linear Programming: the two-phase problem (9)

	B	z	$x_1$	$x_2$	$s_1$	$s_2$	$s_3$	C
$R_0$		1	0	0	2	0	3	5
$R_1$	$x_1$	0	1.5	0	1.5	0	1.5	3
$R_2$	$x_2$	0	0	2	0	0	2	2
$R_3$	$s_2$	0	0	0	1/3	1/3	1	2/3

- We know that  $x_1 = 2, x_2 = 1, s_2 = 2, s_1 = s_3 = 0$

$$\begin{aligned} & \text{Max. } 2x_1 + x_2 \\ \text{s. t. } & \begin{cases} x_1 - x_2 \leq 1 \\ x_1 + 2x_2 \geq 2 \\ x_2 \leq 1 \\ x_1, x_2 \geq 0 \end{cases} \end{aligned} \quad (1)$$



## Supporting Theorem for Two-Phase Method

- Given the original problem is **P**, the auxiliary is **A**

$$\begin{array}{ll}
 \mathbf{P}: \text{Max. } C^T X & \mathbf{A}: \text{Max. } - \sum_{i=1}^m a_i \\
 \text{s. t. } \left\{ \begin{array}{l} e_{11}x_1 + \cdots + e_{1n}x_n = b_1 \\ e_{21}x_1 + \cdots + e_{2n}x_n = b_2 \\ \cdots \\ e_{m1}x_1 + \cdots + e_{mn}x_n = b_m \\ x_{1\dots n} \geq 0 \end{array} \right. & \text{s. t. } \left\{ \begin{array}{l} e_{11}x_1 + \cdots + e_{1n}x_n + a_1 = b_1 \\ e_{21}x_1 + \cdots + e_{2n}x_n + a_2 = b_2 \\ \cdots \\ e_{m1}x_1 + \cdots + e_{mn}x_n + a_m = b_m \\ x_{1\dots n} \geq 0, a_{1\dots m} \geq 0 \end{array} \right.
 \end{array}$$

**Theorem:** **P** has a feasible solution  $\Leftrightarrow$  **A** has optimal value 0.

# Proof for the Supporting Theorem

- $\mathbf{P}$  has a feasible solution  $\implies \mathbf{A}$  has optimal value 0.
- Given the feasible solution for  $\mathbf{P}$  is  $[x_1^*, x_2^*, \dots, x_n^*]^T$
- $\implies [x_1^*, x_2^*, \dots, x_n^*, 0, \dots, 0]^T$  is feasible for  $\mathbf{A}$
- Moreover,  $[x_1^*, x_2^*, \dots, x_n^*, 0, \dots, 0]^T$  is optimal for  $\mathbf{A}$  with value 0
- $\mathbf{P}$  has a feasible solution  $\iff \mathbf{A}$  has optimal value 0.
- Given the optimal solution for  $\mathbf{A}$  is  $[x_1^*, x_2^*, \dots, x_n^*, a_1^*, \dots, a_k^*]^T$  with value 0
- $\implies [a_1^*, \dots, a_k^*] = [0, \dots, 0]^T$
- $\implies [x_1^*, x_2^*, \dots, x_n^*]^T$  is feasible for  $\mathbf{P}$

— proved —

# Linear Programming: the two-phase problem (9)

- Summary
  - When there is no basic solution
  - LP problem should be addressed in two phases
  - **Phase-I:** 1. Introduce artificial variables; 2. Solve an auxiliary problem
  - **Phase-II:** 1. Replace to original objective; 2. Solve the original problem
  - Keep the basic variables to 0 in the objective

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# Two-phase Simplex by Matrix Operation (1)

- Similar as before, in order to address LP in large-scale
- We should do Simplex with matrix operations
- In the following, we will formulate the Simplex method in matrix operations



## Two-phase Simplex by Matrix Operation (2)

- We now consider how to solve LP in two phases
- Let's consider the first phase problem
- $C_b = [0 \ 1 \ 0]$ ,  $C_n = [1 \ 0 \ 0]$

$$\begin{aligned} & z + a_1 = 0 \\ \text{s.t. } & \begin{cases} x_1 - x_2 + s_1 = 1 \\ -x_1 - 2x_2 + s_2 - a_1 = -2 \\ x_2 + s_3 = 1 \\ a_1, x_1, x_2, s_1, s_2, s_3 \geq 0 \end{cases} \end{aligned} \quad (2)$$

$$B = \begin{bmatrix} s_1 & a_1 & s_3 \\ 1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \quad N = \begin{bmatrix} x_1 & x_2 & s_2 \\ 1 & -1 & 0 \\ -1 & -2 & 1 \\ 0 & 1 & 0 \end{bmatrix} \quad b = \begin{bmatrix} 1 \\ -2 \\ 1 \end{bmatrix}$$

## Two-phase Simplex by Matrix Operation: Phase-1 (1)

- $C_b = C_b + \sum_i a_i =, C_n = [-1 \ 0 \ 0]$

$$B = \begin{bmatrix} s_1 & a_1 & s_3 \\ 1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \quad N = \begin{bmatrix} x_1 & x_2 & s_2 \\ 1 & -1 & 0 \\ -1 & -2 & 1 \\ 0 & 1 & 0 \end{bmatrix} \quad b = \begin{bmatrix} 1 \\ -2 \\ 1 \end{bmatrix}$$

- Let  $k = 1$ ,  $p_k = N(:, k)$ , calculate  $y_k = B^{-1} \cdot p_k$ ,  $b_1 = B^{-1} \cdot b$
- $\frac{b_1}{y_k} = \{\frac{1}{-1}, \frac{-2}{-1}, \frac{1}{-1}\}$ ,  $r = 2$ , we get  $s_2$
- Swap-in  $x_0$  to **B**, swap-out  $s_2$  to **N**
- $C_b = [0 \ -1 \ 0]$ ,  $C_n = [0 \ 0 \ 0]$

$$B = \begin{bmatrix} s_1 & x_0 & s_3 \\ 1 & -1 & 0 \\ 0 & -1 & 0 \\ 0 & -1 & 1 \end{bmatrix} \quad B^{-1} = \begin{bmatrix} s_1 & x_0 & s_3 \\ 1 & -1 & 0 \\ 0 & -1 & 0 \\ 0 & -1 & 1 \end{bmatrix} \quad N = \begin{bmatrix} s_2 & x_1 & x_2 \\ 0 & 1 & -1 \\ 1 & -1 & -2 \\ 0 & 0 & 1 \end{bmatrix}$$

# Summary over Two-phase Simplex

## A Stage-1: Solve the auxiliary problem

- 1 Set  $k=1$ , Repeat
- 2 Find out  $r$  by  $\arg \min_r \{B^{-1} \cdot b. / B^{-1} \cdot N(:, k)\}$
- 3 Swap-in  $N(:, k)$  to  $B$ , Swap-out  $B(:, r)$  to  $N_2$
- 4  $Cn(k) \Leftarrow Cb(r)$
- 5 Find out  $k$  by  $\arg \min_k \{C_b \cdot B^{-1} N - C_n\}$

## B Stage-2: Solve the original problem

- 1 Set  $C_b = [0 \ \cdots \ 0]$ ,  $C_n = -C \cdot N \cdot B^{-1}$
- 2  $B_2 = N$ ,  $N_2 = B^{-1}$ ,  $b = B^{-1} \cdot b$
- 3 Repeat
- 4 Find out  $k$  by  $\arg \min_k \{C_b \cdot B_2^{-1} N_2 - C_n\}$
- 5 Find out  $r$  by  $\arg \min_r \{B_2^{-1} \cdot b. / B_2^{-1} \cdot N_2(:, k)\}$
- 6 Swap-in  $N_2(:, k)$  to  $B_2$ , Swap-out  $B_2(:, r)$  to  $N_2$
- 7  $Cn(k) \Leftarrow Cb(r)$

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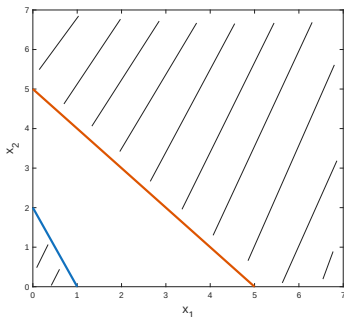
# Infeasible Linear Programming Problem (1)

- In practice, not all the LP problems are feasible
- When the feasible set is empty, it becomes infeasible

# Infeasible Linear Programming Problem (2)

- An LP is **infeasible** if there is no feasible solution

$$\begin{array}{ll} \text{Max.} & 3x_1 + x_2 \\ \text{s.t.} & \begin{cases} 2x_1 + x_2 \leq 2 \\ x_1 + x_2 \geq 5 \\ x_1, x_2 \geq 0 \end{cases} \end{array} \quad (3)$$



# Infeasible Linear Programming Problem (3)

- An LP is **infeasible** if there is no feasible solution
- Introduce slack variable  $s_1$  and  $s_2$
- Introduce artificial/auxiliary variable  $a_1$

$$\begin{array}{ll} \text{Max.} & 3x_1 + x_2 \\ \text{s.t.} & \begin{cases} 2x_1 + x_2 + s_1 = 2 \\ x_1 + x_2 - s_2 = 5 \\ x_1, x_2, s_1, s_2 \geq 0 \end{cases} \end{array}$$

$$\begin{array}{ll} \text{Max.} & 3x_1 + x_2 \\ \text{s.t.} & \begin{cases} 2x_1 + x_2 + s_1 = 2 \\ x_1 + x_2 - s_2 + a_1 = 5 \\ x_1, x_2, s_1, s_2, a_1 \geq 0 \end{cases} \end{array}$$

# Infeasible Linear Programming Problem (3)

- Solve the auxiliary problem first

$$\text{Max. } 3x_1 + x_2$$

$$\text{s.t. } \begin{cases} 2x_1 + x_2 + s_1 = 2 \\ x_1 + x_2 - s_2 + a_1 = 5 \\ x_1, x_2, s_1, s_2, a_1 \geq 0 \end{cases}$$

$$\text{Max. } -a_1$$

$$\text{s.t. } \begin{cases} 2x_1 + x_2 + s_1 = 2 \\ x_1 + x_2 - s_2 + a_1 = 5 \\ x_1, x_2, s_1, s_2, a_1 \geq 0 \end{cases}$$

## Phase-I: pre-processing

	B	z	$a_1$	$x_1$	$x_2$	$s_1$	$s_2$	C
$R_0$		1	1	0	0	0	0	0
$R_1$	$s_1$	0	0	2	1	1	0	2
$R_2$	$a_1$	0	1	1	1	0	-1	5

$$R_0 = R_0 - R_2 \downarrow$$

	B	z	$a_1$	$x_1$	$x_2$	$s_1$	$s_2$	C
$R_0$		1	0	-1	-1	0	1	-5
$R_1$	$s_1$	0	0	2	1	1	0	2
$R_2$	$a_1$	0	1	1	1	0	-1	5



## Infeasible Linear Programming Problem (4)

## Phase-I: Round-1

	B	z	$a_1$	$x_1$	$x_2$	$s_1$	$s_2$	C
$R_0$		1	0	-1	-1	0	1	-5
$R_1$	$s_1$	0	0	2	1	1	0	2
$R_2$	$a_1$	0	1	1	1	0	-1	5



	B	z	$a_1$	$x_1$	$x_2$	$s_1$	$s_2$	C
$R_0$		1	0	0	0	-0.5	0.5	-4
$R_1$	$x_1$	0	0	1	1	1	0	2
$R_2$	$a_1$	0	1	0	0.5	-0.5	-1	4



	B	z	$a_1$	$x_1$	$x_2$	$s_1$	$s_2$	C
$R_0$		1	0	1	0	1	1	-3
$R_1$	$x_1$	0	0	2	1	1	0	2
$R_2$	$a_1$	0	1	-1	0	-1	-1	3

## Infeasible Linear Programming Problem (5)

	B	z	$a_1$	$x_1$	$x_2$	$s_1$	$s_2$	C
$R_0$		1	0	1	0	1	1	-3
$R_1$	$x_1$	0	0	2	1	1	0	2
$R_2$	$a_1$	0	1	-1	0	-1	-1	3

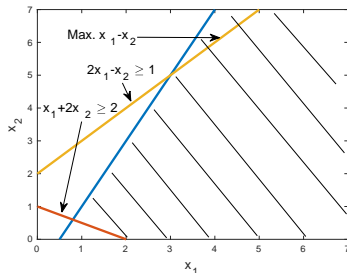
$$\begin{aligned}
 & \text{Max.} \quad -a_1 \\
 \text{s.t.} \quad & \begin{cases} 2x_1 + x_2 + s_1 = 2 \\ x_1 + x_2 - s_2 + a_1 = 5 \\ x_1, x_2, s_1, s_2, a_1 \geq 0 \end{cases}
 \end{aligned}$$

- **Phase-I:** we cannot reach the optima for the auxiliary problem
- There is no way to optimize it further
- It becomes the criteria for us to judge whether a problem is feasible

## Unbounded Linear Programming Problem (1)

- In some cases, the maximum/minimum value could be  $\infty / -\infty$
- In such cases, the LP problems are unbounded

$$\begin{aligned} & \text{Max. } x_1 - x_2 \\ \text{s.t. } & \begin{cases} 2x_1 - x_2 \geq 1 \\ x_1 + 2x_2 \geq 2 \\ x_1, x_2 \geq 0 \end{cases} \end{aligned} \quad (4)$$



# Unbounded Linear Programming Problem (2)

- An LP is **unbounded** if its feasible solution is infinity
- Introduce slack variable  $s_1$  and  $s_2$
- Introduce artificial/auxiliary variable  $a_1$  and  $a_2$

$$\begin{array}{ll} \text{Max.} & x_1 - x_2 \\ \text{s.t.} & \begin{cases} 2x_1 - x_2 - s_1 = 1 \\ x_1 + 2x_2 - s_2 = 2 \\ x_1, x_2, s_1, s_2 \geq 0 \end{cases} \end{array}$$

$$\begin{array}{ll} \text{Max.} & x_1 - x_2 \\ \text{s.t.} & \begin{cases} 2x_1 - x_2 - s_1 + a_1 = 1 \\ x_1 + 2x_2 - s_2 + a_2 = 2 \\ x_1, x_2, s_1, s_2, a_1, a_2 \geq 0 \end{cases} \end{array}$$

# Unbounded Linear Programming Problem (2)

- Solve the auxiliary problem first

$$\begin{array}{ll} \text{Max. } x_1 - x_2 & \text{Max. } -a_1 - a_2 \\ \text{s.t. } \begin{cases} 2x_1 - x_2 - s_1 + a_1 = 1 \\ x_1 + 2x_2 - s_2 + a_2 = 2 \\ x_1, x_2, s_1, s_2, a_1, a_2 \geq 0 \end{cases} & \text{s.t. } \begin{cases} 2x_1 - x_2 - s_1 + a_1 = 1 \\ x_1 + 2x_2 - s_2 + a_2 = 2 \\ x_1, x_2, s_1, s_2, a_1, a_2 \geq 0 \end{cases} \end{array}$$

## Phase-I: pre-processing

B	z	$a_1$	$a_2$	$x_1$	$x_2$	$s_1$	$s_2$	C
	1	1	1	0	0	0	0	0
$a_1$	0	1	0	2	-1	-1	0	1
$a_2$	0	0	1	1	2	0	-1	2

$$R_0 = R_0 - R_1 - R_2 \downarrow$$

B	z	$a_1$	$a_2$	$x_1$	$x_2$	$s_1$	$s_2$	C
	1	0	0	-3	-1	1	1	-3
$a_1$	0	1	0	2	-1	-1	0	1
$a_2$	0	0	1	1	2	0	-1	2

# Unbounded Linear Programming Problem (3)

- Phase-I

## Phase-I: Round-1

B	z	$a_1$	$a_2$	$x_1$	$x_2$	$s_1$	$s_2$	C
	1	0	0	-3	-1	1	1	-3
$a_1$	0	1	0	2	-1	-1	0	1
$a_2$	0	0	1	1	2	0	-1	2



B	z	$a_1$	$a_2$	$x_1$	$x_2$	$s_1$	$s_2$	C
	1	1.5	0	0	-2.5	-0.5	1	-1.5
$x_1$	0	1	0	2	-1	-1	0	1
$a_2$	0	-0.5	1	0	2.5	0.5	-1	1.5

# Unbounded Linear Programming Problem (4)

## Phase-I: Round-2

B	z	$a_1$	$a_2$	$x_1$	$x_2$	$s_1$	$s_2$	C
	1	1.5	0	0	-2.5	-0.5	1	-1.5
$x_1$	0	1	0	2	-1	-1	0	1
$a_2$	0	-0.5	1	0	2.5	0.5	-1	1.5



B	z	$a_1$	$a_2$	$x_1$	$x_2$	$s_1$	$s_2$	C
	1	1	1	0	0	0	0	0
$x_1$	0	0.8	0.4	2	0	-0.8	-0.4	1.6
$x_2$	0	-0.5	1	0	2.5	0.5	-1	1.5

# Unbounded Linear Programming Problem (5)

$$\begin{array}{ll} \text{Max.} & x_1 - x_2 \\ \text{s.t.} & \begin{cases} 2x_1 - x_2 - s_1 + a_1 = 1 \\ x_1 + 2x_2 - s_2 + a_2 = 2 \\ x_1, x_2, s_1, s_2, a_1, a_2 \geq 0 \end{cases} \end{array}$$

**Phase-II: replace  $R_0$**

B	z	$a_1$	$a_2$	$x_1$	$x_2$	$s_1$	$s_2$	C
	1	1	1	0	0	0	0	0
$x_1$	0	0.8	0.4	2	0	-0.8	-0.4	1.6
$x_2$	0	-0.5	1	0	2.5	0.5	-1	1.5



B	z	$a_1$	$a_2$	$x_1$	$x_2$	$s_1$	$s_2$	C
	1	1	1	-1	1	0	0	0
$x_1$	0	0.8	0.4	2	0	-0.8	-0.4	1.6
$x_2$	0	-0.5	1	0	2.5	0.5	-1	1.5



# Unbounded Linear Programming Problem (6)

## Phase-II: Pre-processing

B	z	$a_1$	$a_2$	$x_1$	$x_2$	$s_1$	$s_2$	C
	1	1	1	-1	1	0	0	0
$x_1$	0	0.8	0.4	2	0	-0.8	-0.4	1.6
$x_2$	0	-0.5	1	0	2.5	0.5	-1	1.5

$$R_0 = R_0 + R_1/2 - R_2/2.5 \downarrow$$

B	z	$a_1$	$a_2$	$x_1$	$x_2$	$s_1$	$s_2$	C
	1	0.6	-0.2	0	0	-0.6	0.2	0.2
$x_1$	0	0.8	0.4	2	0	-0.8	-0.4	1.6
$x_2$	0	-0.5	1	0	2.5	0.5	-1	1.5

# Unbounded Linear Programming Problem (7)

## Phase-II: Round-1

B	z	$a_1$	$a_2$	$x_1$	$x_2$	$s_1$	$s_2$	C
	1	0.6	-0.2	0	0	-0.6	0.2	0.2
$x_1$	0	0.8	0.4	2	0	-0.8	-0.4	1.6
$x_2$	0	-0.5	1	0	2.5	0.5	-1	1.5



B	z	$a_1$	$a_2$	$x_1$	$x_2$	$s_1$	$s_2$	C
	1	0	1	0	3	0	-1	2
$x_1$	0	0	2	2	4	0	-2	4
$s_1$	0	-0.5	1	0	2.5	0.5	-1	1.5

- To this end, we see this problem is not bounded

# Theorem about the Feasibility of LP

- For an arbitrary LP problem in standard form, the following statements hold
  - ① If there is no optimal solution, then the problem is either infeasible or unbounded
  - ② If a feasible solution exists, then a basic feasible solution exists

# Outline

- 1 Two-phase Simplex Method
- 2 Two-phase Simplex Method by Matrix Operation
- 3 Infeasible and Unbounded Problems
- 4 Degenerated Linear Programming**
- 5 Duality in Linear Programming
- 6 Network Max-flow Problem

# Degenerated Linear Programming Problem (1)

- In our previous lectures, we presented the Simplex method
- Essentially, we jump from one vertex to another to find out the extreme
- The jumping (or swap-in and swap-out operation) always makes the objective function better
- However, this is not necessarily true

# Degenerated Linear Programming Problem (2)

- An LP is **degenerate** if in a basic feasible solution, one of the basic variables takes on a zero value

$$\begin{aligned} & \text{Max. } x_1 + x_2 + x_3 \\ & \text{s.t. } \begin{cases} x_1 + x_2 \leq 1 \\ -x_2 + x_3 \leq 0 \\ x_1, x_2 \geq 0 \end{cases} \end{aligned} \quad (5)$$

	z	$x_1$	$x_2$	$x_3$	$s_1$	$s_2$	
	1	-1	-1	-1	0	0	0
$s_1$	0	1	1	0	1	0	1
$s_2$	0	0	-1	1	0	1	0

- $s_1 = 1, s_2 = 0$

# Degenerated Linear Programming Problem (3)

- An LP is **degenerate** if in a basic feasible solution, one of the basic variables takes on a zero value

	z	$x_1$	$x_2$	$x_3$	$s_1$	$s_2$	
	1	-1	-1	-1	0	0	0
$s_1$	0	1	1	0	1	0	1
$s_2$	0	0	-1	1	0	1	0



	z	$x_1$	$x_2$	$x_3$	$s_1$	$s_2$	
	1	0	0	-1	1	0	1
$x_1$	0	1	1	0	1	0	1
$s_2$	0	0	-1	1	0	1	0

- $x_1 = 1, s_2 = 0$

# Degenerated Linear Programming Problem (4)

- Degeneracy happens

	z	$x_1$	$x_2$	$x_3$	$s_1$	$s_2$	
	1	0	0	-1	1	0	1
$x_1$	0	1	1	0	1	0	1
$s_2$	0	0	-1	1	0	1	0



	z	$x_1$	$x_2$	$x_3$	$s_1$	$s_2$	
	1	0	-1	0	1	1	1
$x_1$	0	1	1	0	1	0	1
$x_3$	0	0	-1	1	0	1	0

- $x_1 = 1, x_3 = 0$



# Degenerated Linear Programming Problem (5)

- Converges

	z	$x_1$	$x_2$	$x_3$	$s_1$	$s_2$	
	1	0	-1	0	1	1	1
$x_1$	0	1	1	0	1	0	1
$x_3$	0	0	-1	1	0	1	0

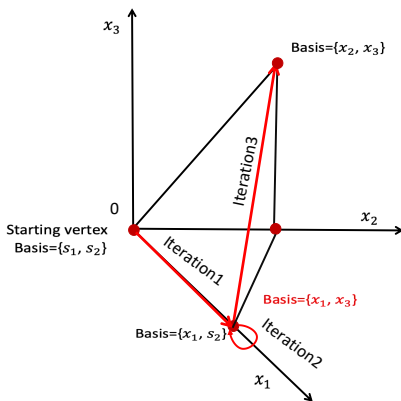


	z	$x_1$	$x_2$	$x_3$	$s_1$	$s_2$	
	1	1	0	0	2	1	2
$x_2$	0	1	1	0	1	0	1
$x_3$	0	1	0	1	1	1	1

- $x_2 = 1, x_3 = 1$

# Degenerated Linear Programming Problem (6)

- In practice, there are several ways to address the degeneracy



$$(s_1 = 1, s_2 = 0) \rightarrow (x_1 = 1, s_2 = 0) \rightarrow (x_1 = 1, x_3 = 0) \rightarrow (x_2 = 1, x_3 = 1)$$

# Degenerated Linear Programming Problem (7)

- When the degeneracy lasts for a few steps, and the iteration goes back to previous basis
- They cycling happens
- Rules to avoid cycling
  - 1 **Rule-1:** Choose the variable with the most negative coefficient to enter-in
  - 2 **Rule-2:** When there are more than one entering or leaving variables, select the one with the smallest index
- **Rule-2** is also known as **Bland's rule**
- The order is defined as  $a_1, \dots, a_k, x_1, \dots, x_n, s_1, \dots, s_m$ , from now on

# Outline

- 1 Two-phase Simplex Method
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# Duality of Linear Programming (1)

- Given the following problem

$$\begin{aligned} & \text{Max. } 7x_1 + 4x_2 \\ \text{s.t. } & \begin{cases} 2x_1 + x_2 \leq 20 \\ x_1 + x_2 \leq 18 \\ x_1 \leq 8 \\ x_1, x_2 \geq 0 \end{cases} \end{aligned} \quad (1)$$

- Given  $y_1 \geq 0$ ,  $y_2 \geq 0$ ,  $y_3 \geq 0$ , the following holds

$$\begin{aligned} & \text{Max. } 7x_1 + 4x_2 \\ \text{s.t. } & \begin{cases} y_1(2x_1 + x_2) \leq 20y_1 \\ y_2(x_1 + x_2) \leq 18y_2 \\ y_3x_1 \leq 8y_3 \\ x_1, x_2 \geq 0 \end{cases} \end{aligned} \quad (2)$$

# Duality of Linear Programming (2)

$$\begin{array}{ll} \text{Max.} & 7x_1 + 4x_2 \\ \text{s.t.} & \begin{cases} y_1(2x_1 + x_2) \leq 20y_1 \\ y_2(x_1 + x_2) \leq 18y_2 \\ y_3x_1 \leq 8y_3 \\ x_1, x_2 \geq 0 \end{cases} \end{array} \quad (2)$$

- So we have

$$(2y_1 + y_2 + y_3)x_1 + (y_1 + y_2)x_2 \leq 20y_1 + 18y_2 + 8y_3 \quad (3)$$

# Duality of Linear Programming (3)

$$\begin{aligned} & \text{Max. } 7x_1 + 4x_2 \\ \text{s.t. } & \begin{cases} 2x_1 + x_2 \leq 20 \\ x_1 + x_2 \leq 18 \\ x_1 \leq 8 \\ x_1, x_2 \geq 0 \end{cases} \end{aligned} \quad (1)$$

- Since we have

$$(2y_1 + y_2 + y_3)x_1 + (y_1 + y_2)x_2 \leq 20y_1 + 18y_2 + 8y_3 \quad (3)$$

- Let's define another problem

$$\begin{aligned} & \text{Min. } 20y_1 + 18y_2 + 8y_3 \\ \text{s.t. } & \begin{cases} 2y_1 + y_2 + y_3 \geq 7 \\ y_1 + y_2 \geq 4 \\ y_1, y_2, y_3 \geq 0 \end{cases} \end{aligned} \quad (4)$$

- Problems in Eqn. 4 and Eqn. 1 are the dual problem of each other

# Duality of Linear Programming (4)

$$\begin{array}{ll} \text{Max.} & 7x_1 + 4x_2 \\ \text{s.t.} & \begin{cases} 2x_1 + x_2 \leq 20 \\ x_1 + x_2 \leq 18 \\ x_1 \leq 8 \\ x_1, x_2 \geq 0 \end{cases} \end{array} \quad (1)$$

$$\begin{array}{ll} \text{Min.} & 20y_1 + 18y_2 + 8y_3 \\ \text{s.t.} & \begin{cases} 2y_1 + y_2 + y_3 \geq 7 \\ y_1 + y_2 \geq 4 \\ y_1, y_2, y_3 \geq 0 \end{cases} \end{array} \quad (4)$$

- Solving above problem, we have
- **The maximum is 78** when  $x_1 = 2, x_2 = 16$

- Solving above problem, we have
- **The minimum is 78** when  $y_1 = 3, y_2 = 1, y_3 = 0$

- They share the same extreme value, which can be revealed by

$$(2y_1 + y_2 + y_3)x_1 + (y_1 + y_2)x_2 \leq 20y_1 + 18y_2 + 8y_3 \quad (3)$$



# Weak Duality Theorem (1)

- The primal problem

$$\text{Max. } \sum_{j=1}^n c_j x_j$$

$$\text{s.t. } \sum_{j=1}^n a_{ij} x_j \leq b_i, i = 1, \dots, m$$

$$x_j \geq 0, j = 1, \dots, n$$

- The dual problem

$$\text{Min. } \sum_{i=1}^m b_i y_i$$

$$\text{s.t. } \sum_{i=1}^m y_i a_{ij} \geq c_j, j = 1, \dots, n$$

$$y_i \geq 0, i = 1, \dots, m$$

- If  $(x_1, \dots, x_n)$  is feasible for the primal and  $(y_1, \dots, y_m)$  is feasible for the dual, then**

$$\sum_j c_j x_j \leq \sum_i b_i y_i. \quad (5)$$

## Weak Duality Theorem (2)

$$\sum_j c_j x_j \leq \sum_i b_i y_i. \quad (5)$$

- **Proof:** since  $\sum_{i=1}^m y_i a_{ij} \geq c_j, j = 1, \dots, n$  and  $x_j \geq 0$

$$\sum_j c_j x_j \leq \sum_{j=1}^n \left( \sum_{i=1}^m y_i a_{ij} \right) x_j$$

$$= \sum_{ij} y_i a_{ij} x_j$$

$$= x_1 \sum_{i=1}^m y_i a_{i1} + \dots + x_n \sum_{i=1}^m y_i a_{in}$$

$$= \sum_{i=1}^m \left( \sum_{j=1}^n a_{ij} x_j \right) y_i$$

$$\xrightarrow{\sum_{j=1}^n a_{ij} x_j \leq b_i} \leq \sum_i b_i y_i$$

# Strong Duality Theorem

- The primal problem

$$\begin{aligned} & \text{Max.} \quad \sum_{j=1}^n c_j x_j \\ \text{s.t.} \quad & \sum_{j=1}^n a_{ij} x_j \leq b_i, i = 1, \dots, m \\ & x_j \geq 0, j = 1, \dots, n \end{aligned}$$

- The dual problem

$$\begin{aligned} & \text{Min.} \quad \sum_{i=1}^m b_i y_i \\ \text{s.t.} \quad & \sum_{i=1}^m y_i a_{ij} \geq c_j, j = 1, \dots, n \\ & y_i \geq 0, i = 1, \dots, m \end{aligned}$$

- If  $x^* = (x_1^*, \dots, x_n^*)$  is the optimal solution for the primal and  $y^* = (y_1^*, \dots, y_m^*)$  is the optimal solution for the dual, then**

$$\sum_j c_j x_j^* = \sum_i b_i y_i^*. \quad (6)$$

## Solve LP by its Dual (1)

- Given following problem

$$\begin{array}{ll} \text{Max.} & -x_1 - 3x_2 \\ \text{s.t.} & \begin{cases} x_1 + x_2 \geq 4 \\ -4x_1 + x_2 \leq -1 \\ x_2 \geq 3 \\ x_1, x_2 \geq 0 \end{cases} \end{array} \quad (7)$$

- Reorganize it into following form

$$\begin{array}{ll} \text{Min.} & x_1 + 3x_2 \\ \text{s.t.} & \begin{cases} x_1 + x_2 \geq 4 \\ 4x_1 - x_2 \geq 1 \\ x_2 \geq 3 \\ x_1, x_2 \geq 0 \end{cases} \end{array} \quad (8)$$

## Solve LP by its Dual (2)

- Given following problem

$$\begin{aligned} &\text{Min. } x_1 + 3x_2 \\ &\text{s.t. } \begin{cases} x_1 + 3x_2 \geq 4 \\ 4x_1 - x_2 \geq 1 \\ x_2 \geq 3 \\ x_1, x_2 \geq 0 \end{cases} \end{aligned} \quad (7)$$

- $c = [1 \ 3]$ ,  $b = [4 \ 1 \ 3]^T$

$$A = \begin{bmatrix} 1 & 3 \\ 4 & -1 \\ 0 & 1 \end{bmatrix}.$$

- Its dual problem is

$$\begin{aligned} &\text{Max. } 4y_1 + y_2 + 3y_3 \\ &\text{s.t. } \begin{cases} y_1 + 4y_2 \leq 1 \\ 3y_1 - y_2 + y_3 \leq 3 \\ y_1, y_2 \geq 0 \end{cases} \end{aligned} \quad (8)$$

- $c = [4 \ 1 \ 3]$ ,  $b = [1 \ 3]^T$

$$A^T = \begin{bmatrix} 1 & 4 & 0 \\ 3 & -1 & 1 \end{bmatrix}.$$

## Solve LP by its Dual (3)

$$\begin{aligned}
 &\text{Max. } 4y_1 + y_2 + 3y_3 \\
 &\text{s.t. } \begin{cases} y_1 + 4y_2 \leq 1 \\ 3y_1 - y_2 + y_3 \leq 3 \\ y_1, y_2 \geq 0 \end{cases}
 \end{aligned} \tag{8}$$

	z	$y_1$	$y_2$	$y_3$	$s_1$	$s_2$	f
	1	-4	-1	-3	0	0	0
$s_1$	0	1	4	0	1	0	1
$s_2$	0	3	-1	1	0	1	3

## Solve LP by its Dual (4)

## Round-1

	z	$y_1$	$y_2$	$y_3$	$s_1$	$s_2$	f
	1	-4	-1	-3	0	0	0
$s_1$	0	1	4	0	1	0	1
$s_2$	0	3	-1	1	0	1	3



	z	$y_1$	$y_2$	$y_3$	$s_1$	$s_2$	f
	1	0	15	-3	4	0	4
$y_1$	0	1	4	0	1	0	1
$s_2$	0	0	-13	1	-3	1	0

## Solve LP by its Dual (5)

## Round-2

	z	$y_1$	$y_2$	$y_3$	$s_1$	$s_2$	f
	1	0	15	-3	4	0	4
$y_1$	0	1	4	0	1	0	1
$s_2$	0	0	-13	1	-3	1	0



	z	$y_1$	$y_2$	$y_3$	$s_1$	$s_2$	f
	1	0	-24	0	-5	3	4
$y_1$	0	1	4	0	1	0	1
$y_3$	0	1	4	0	1	0	1



## Solve LP by its Dual (6)

## Round-3

	z	$y_1$	$y_2$	$y_3$	$s_1$	$s_2$	f
	1	0	-24	0	-5	3	4
$y_1$	0	1	4	0	1	0	1
$y_3$	0	1	4	0	1	0	1



	z	$y_1$	$y_2$	$y_3$	$s_1$	$s_2$	f
	1	6	0	0	1	3	10
$y_2$	0	1	4	0	1	0	1
$y_3$	0	3.25	0	1	0.25	1	3.25

## Solve LP by its Dual (7)

	z	$y_1$	$y_2$	$y_3$	$s_1$	$s_2$	f
	1	6	0	0	1	3	10
$y_2$	0	1	4	0	1	0	1
$y_3$	0	3.25	0	1	0.25	1	3.25

$$\begin{aligned}
 &\text{Min. } x_1 + 3x_2 \\
 &\text{s.t. } \begin{cases} x_1 + 3x_2 \geq 4 \\ 4x_1 - x_2 \geq 1 \\ x_2 \geq 3 \\ x_1, x_2 \geq 0 \end{cases}
 \end{aligned} \tag{9}$$

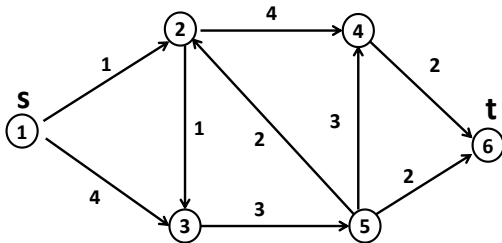
- The maximum is 10, when  $y_1 = 0$ ,  $y_2 = 0.25$  and  $y_3 = 3.25$
- According to “**Strong Duality Theorem**”,  $x_1 + 3x_2 = 10$

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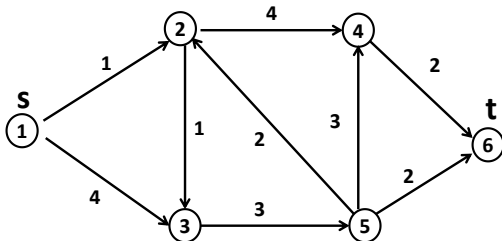
# Network Max-flow Problem: the motivation

- Given an oil pipeline network as follows
- What is the maximum sent, per hour, from source to a sink



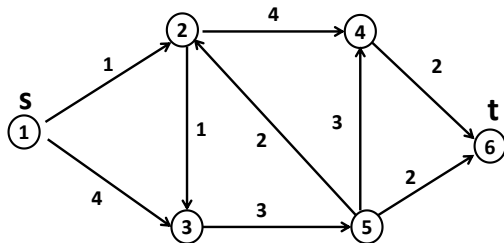
- Given a directed, capacitated network  $G = (N, A)$  with arc capacities  $u_{ij} \geq 0, \forall (i, j) \in A$ , determine the maximum possible amount of flow from a designated source node **s** to a sink node **t** while obeying all arc capacities

# Network Max-flow Problem: analysis (1)



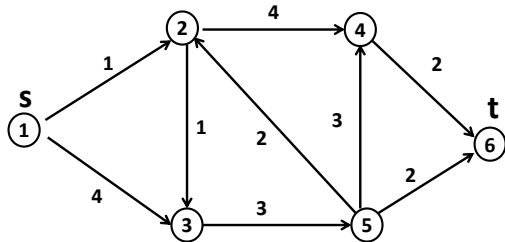
- Given a directed, capacitated network  $G = (N, A)$  with arc capacities  $u_{ij} \geq 0, \forall (i, j) \in A$ , determine the maximum possible amount of flow from a designated source node **s** to a sink node **t** while obeying all arc capacities
- What is the objective?
- What are the constraints?

# Network Max-flow Problem: analysis (2)



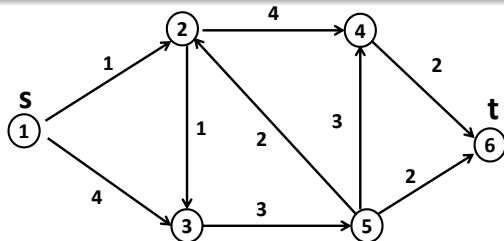
- Let's look at the constraints first!
- Given the maximum flow along arc  $\langle i, j \rangle$  is  $u_{ij}$
- Given the planned flow along arc  $\langle i, j \rangle$  is  $x_{ij}$
- We have  $0 \leq x_{ij} \leq u_{ij}$

# Network Max-flow Problem: analysis (3)



- Let's look at the constraints first!
- For **node 2**, we have  $x_{12} + x_{52} = x_{24} + x_{23}$
- For **node 3**, we have  $x_{13} + x_{23} = x_{35}$
- For **node 4**, we have  $x_{24} + x_{54} = x_{46}$
- For **node 5**, we have  $x_{35} = x_{52} + x_{54} + x_{56}$

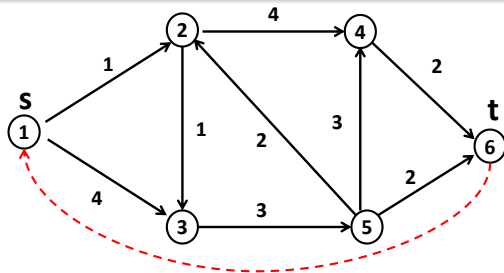
# Network Max-flow Problem: analysis (4)



- Let's look at the objective
- We should maximize  $x_{12} + x_{13}$  or maximize  $x_{46} + x_{56}$
- Under the following constraints
  - 1  $x_{12} + x_{52} = x_{24} + x_{23}$
  - 2  $x_{13} + x_{23} = x_{35}$
  - 3  $x_{24} + x_{54} = x_{46}$
  - 4  $x_{35} = x_{52} + x_{54} + x_{56}$
  - 5  $0 \leq x_{ij} \leq u_{ij}$

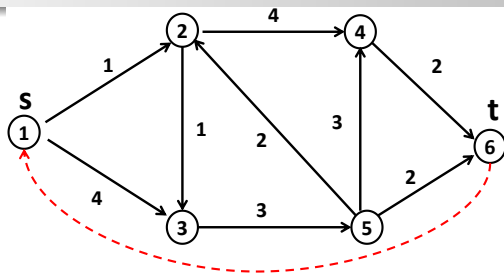


# Network Max-flow Problem: analysis (5)



- Alternatively, we can maximize  $x_{61}$
- Under the following constraints
  - 1  $x_{12} + x_{52} = x_{24} + x_{23}$
  - 2  $x_{13} + x_{23} = x_{35}$
  - 3  $x_{24} + x_{54} = x_{46}$
  - 4  $x_{35} = x_{52} + x_{54} + x_{56}$
  - 5  $x_{46} + x_{56} = x_{61}$
  - 6  $0 \leq x_{ij} \leq u_{ij}$

# Network Max-flow Problem: the model



Max.  $x_{61}$

$$\text{s.t.} \left\{ \begin{array}{rcl} x_{12} + x_{52} - x_{24} - x_{23} & = & 0 \\ x_{13} + x_{23} - x_{35} & = & 0 \\ x_{24} + x_{54} - x_{46} & = & 0 \\ x_{35} - x_{52} - x_{54} - x_{56} & = & 0 \\ x_{46} + x_{56} - x_{61} & = & 0 \\ x_{ij} & \leq & u_{ij} \\ x_{ij} & \geq & 0 \end{array} \right. \quad (10)$$

```

1 %%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
2 % @author: Wan-Lei Zhao
3 % @date: 2025-9-29
4 % @solution to maxflow problem
5 % x12: 1 x13: 2 x23: 3 x24: 4 x35: 5
6 % x46: 6 x52: 7 x54: 8 x56: 9 x61: 10
7 %%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
8
9 f = [0 0 0 0 0 0 0 0 0 -1];
10 Ae = [1 0 -1 -1 0 0 1 0 0 0;
11       0 1 1 0 -1 0 0 0 0 0;
12       0 0 0 1 0 -1 0 1 0 0;
13       0 0 0 0 1 0 -1 -1 -1 0;
14       0 0 0 0 0 1 0 0 1 -1];
15 be = [0 0 0 0 0]';
16 lb = [0 0 0 0 0 0 0 0 0 0]';
17 ub = [1 4 1 4 3 2 2 3 2 5]';
18 [x, fval] = linprog(f, [], [], Ae, be, lb, ub)

```