3211 Group Assignment Report

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Contents

1.		Inst	ruction Table	1
2.		Inst	ructions Description	2
	2.	1	Load	2
	2.2	2	BNE	2
	2.3	3	Store	2
	2.	4 B	it_Flip	2
	2.	5	ROL	3
	2.0	6	XOR	3
	2.	7	Parity	4
	2.8	8	Set_Sig	4
3.		Har	dware Supported Operations	5
	3.	1	PC Loading	5
	3.2	2	Special Register Loading	5
4.		Har	dware Components	6
	4.	1	ALU	6
	4.2	2	Instruction Memory	6
	4.	3	Data Memory	6
	4.4	4	I/O Unit	7
	4.	5	Data Forwarder	7
4.		ASI	P Control	7
	4.	1 Re	eceive Signal	8
	4.2	2 Se	end Signal	8
	4.	3 O _l	peration Flag	8
	4.4	4 Bι	usy Signal	8
	4.	5	ASIP Handshake and Usage	8
		Red	eiving Data from Network to Host CPU	9
		Ser	nding Data from Host CPU to Network	9
5.		Pro	cessor Performance1	0
	5.	1 M	etrics1	0
	5.2	2 Cr	ritical Path1	0
5.	Αį	ppei	ndix1	1
	5.	1 As	ssembly Code1	1

1.Instruction Table

Mnemonic	Description	Type	Registers	OPCODE	Extra notes
NOP	-	-	-	0000	-
LOAD	Load 2 Bytes from memory	I-	Rd,	0001	Uses absolute
	to Rd	type	Rt,addr		address not offset
BNE	Branch to addr if Rs not	I-	Rd, Rt,	0010	Uses absolute
	equal to Rt	type	addr		address not offset
STORE	Save 2 Bytes from Rs to	I-	Rd, Rt,	0011	Uses absolute
	memory	type	addr		address not offset
BIT_FLIP	Flip data in Rs according to	R-	Rd, Rs, Rt	0100	-
	secret key in Rd and save to	type			
	Rt				
ROL	Rotate-left-shift Rs by Rt	R-	Rd, Rs, Rt	0101	-
	and save to Rd	type			
XOR	XOR Rs and save to Rd	R-	Rd, Rs, Rt	0110	does not use Rt
		type			register
PARITY	Check parity bit of Rs with	R-	Rd, Rs, Rt	0111	-
	Rt and save result to Rd	type			
Set_Sig	Set imm as status register	I-	Rd, Rs,	1000	Set_Sig only needs
	value (status register is a	type	imm		immediate input
	special register separate				because it is using
	from the main register				pre-defined signal.
	block)				

Table 1.1: ISA instruction description and their mnemonics

Instructions **Description**

2.1 Load

Instruction Type: I-type Registers: Rd, Rt

Immediate: absolute address in data memory Description: Loads two bytes from the absolute address that is passed to it as an immediate and saves the result to register Rd.

Note that load used absolute address and register Rt is not used.

Example: .data

key: .word 0xAAAA

.text main:

load\$1, \$0, 0

22 BNE

Instruction Type: I-type Registers: Rd, Rt

Immediate: absolute address to jump to Description: Will branch to the given absolute address if registers Rd and Rt are not equal.

Note that BNE uses absolute address.

Example .data

Data1: .word 0xAAAA Data2: .word 0xAAAB

.text Main:

> Load \$1,\$0,0 Load \$2, \$0,1 BNE \$1,\$2, attack

Attack:

This is where BNE jumps to

2.3 Store

Instruction type: I-type Registers: Rd, Rt

Immediate: absolute address to store the

data to in data memory

Description: will store the data in Rd register

in the given address in data memory Note that store uses absolute address.

```
Example
  .data
Data1: .word 0xAAAA
Data2: .word 0xAAAB
  .text
Main:
# This code is swapping the memory
content
# by first loading them to
registers and then storing them
from the
 # registers in their new location
  Load $1,$0,0
  Load $2, $0,1
  Store $1, $0,1
  Store $2, $0, 0
```

2. 4 Bit Flip

Instruction Type: R-type Registers: Rd, Rs, Rt

Description: Uses the Rt register to flip selected bits in the Rs register. The Rt register is assumed to contain the secret key. The top 4 bits of the Rt register determine which blocks of 4-bits get flipped in the Rs register.

The bits of the Rs register will be flipped as such:

Rs	1111 1111 1111 1111
Rt	1010
Rd	0000 1111 0000 1111

Example .data Secret key: .word 0xAAAA # top 4 bits are : 1010 Data_to_flip: .word 0xAAAB .text Main: # This code performs a bit flip on Data_to_flip by the top four bits of Secret key # the expected result stored to offset 3 is 0x5A5B \$1,\$0,0 Load \$2, \$0,1 Load Bit_Flip \$2, \$2, \$1 Store \$2, \$0, 3

2.5 ROL

Instruction Type: R-type Registers: Rd, Rs, Rt

Description: rotate-left-shift data in register Rs by Rt and stores the value in Rd. The Rt register is assumed to contain the secret key. As mentioned, the first Byte of secret key will be used for Bit_flip. The remaining 12 bits are then grouped into 3 bit blocks (r_i) as shown in the table. Each D_i block of data is then rotated-left-shift by r i bits.

Secret key:

•				
Bit_flip	r1	r2	r3	r4
XXXX	001	010	011	100

Data:

D1	D2	D3	D4
1100	0100	1000	1100

Output

Garpar							
	0110	0001	0001	1100			

Example
 .data

Data_to_shift: .word 0xF29C

Secret_key: word 0xC48C
 .text

Load \$1, \$0, 0

Load \$2, \$0, 1

Rol \$3, \$2, \$1

Store \$4, \$0, 3

2.6 XOR

Instruction Type: R-type Registers: Rd, Rs, Rt

Description: The instruction performs the XOR operation on each 4-bit sized group. The resulting value is then stored in Rd. As the result is less than 16 bits, the upper 12 bits with be padded with 0s. The Rt register is unused in this operation.

Data:

D1	D2	D3	D4			
1100	0100	1000	1100			
Output						
0000 0000		0000	1100			

2.7 **Parity**

Instruction Type: R-type Registers: Rd, Rs, Rt

Description: generate the parity bit for Rs and store result into Rd. The Rt register is unused for this operation. The last bit of Rd will be used for storing the parity result with the upper 15 padded with 0. The design uses an even parity, such that 0 corresponds to an even number of 1s and 1 an odd.

Data1:

2.8

D1	D2		D3	D4		
1100	0100		1000	1100		
Output 1						
0000	0000	C	0000	0000		
Data2:	Data2:					
D1	D2		D3	D4		
1100	0100		1001	1100		
Output2						
0000	0000	(0000	0001		

Instruction Type: I-Type

Set Sig

Register: special status register

Immediate: 4-bit immediate determining the

state of the processor

Description: Instruction sets the status

register by a given immediate.

The status bits are as follows:

3	2	1	0
busy	attack	error	valid

Busy: asserted when the ASIP is busy

processing data

Attack: asserted when a data packet from the network contains tampered data, i.e. the given

tag does not match the generated tag

Error: asserted when a data packet from the host processor has encountered a transfer issue, i.e. the given parity bit does not match the generated parity.

Valid: asserted when data from the network is free of error. Valid data is sent through the ASIP output to the host processor.

Example

.data

Secret key: word 0xC48C

example data recieve and polling loop Load \$1, \$0, 0

While:

set sig 0000 # clear all status bits

Bne \$1, \$0, do recv

Do recv:

set sig 1000 # set busy

check parity

generate tag

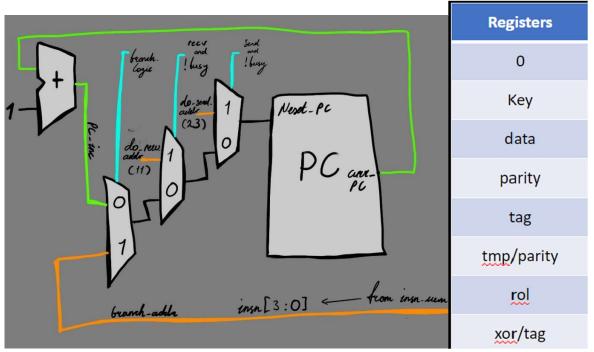
Set sig 1001 # set valid and busy

Bne \$1, \$0, while

3. Hardware Supported Operations

3.1 PC Loading

The ASIP uses hardware to load program counter. There are 3 multiplexers used to derive the next PC. The address of the receive function is 11 and the send function 23. Picture 3.1 shows the block diagram for this component.



Picture 3.1: PC loading in hardware

Picture 3.2: instruction memory special registers

3.2 Special Register Loading

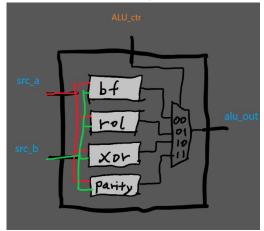
The ASIP has 16 registers each 16 bit wide. The ASIP uses special Registers to store the data sent from network or CPU, tag, parity bit and the secret key. The following are the special registers.

- \$1: stores the secret key
- \$2: stores data from network or CPU
- \$3: stores parity bit
- \$4: stores the tag of the input data

4. Hardware Components

4.1 ALU

The ALU uses the ALU_ctr signal to control the output. The bit_flip instruction is implemented by translating a 4-bit key flip value to 16 -bits and then performing a xor with the data input from Rs. ROL is implemented by concatenation. Parity is implemented by xor-ing together all bits.



Sketch 4.1 ALU_wrapper memory management



Sketch 4.3

4.2 Instruction Memory

The instruction memory consists of a 36-entry long array of 16-bit wide instructions. The reset signal is used to initialise the memory unit to its default values, as specified by the data_memory component. A 6-bit address is used to read an instruction from memory which is then passed out of the component. The component is falling edge triggered. Implementation details can be found in instruction_memory.vhd.

4.3 Data Memory

Data memory holds 16 entries size16-bits, address 0 is used to store the secret key value, address 1 is data being send to network, and address 2 is the tag for sent data (Sketch 4.3). All other memory entries are not used. Excluding the key value, all memory entries are initialised to 0 upon reset. Write is falling edge triggered and requires the write enable signal to also be asserted. Memory reads are continuous and are updated on a falling clock edge. See data_memory.vhd for further information.

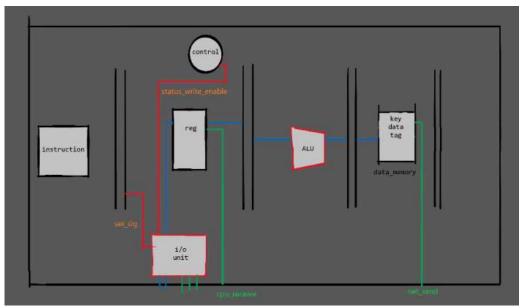
4.4 I/O Unit

I/O unit is used to process data received from host CPU and network. It keeps track of the status register which asserts the busy handshake signal with the network and host CPU, whist also providing alerts upon attack and error occurrences. Furthermore, the status register along with the send and receive input signals controls the hardware supported PC loading.

HDL design for I/O unit is found in io unit.vhd.

Status signal used for pc(colored in red lable with +) and output to host CPU (colored in black,lable with -)

3	2	1	0
Busy+	Attack-	Error-	Valid-



Sketch 4.4 for I/O unit datapath

4.5 Data Forwarder

Data forwarder follows the implementation shown in the data slides, minus the Load Use Hazard (LUH), as this issue was not present in the firmware, it was decided to remove the functionality to preserve a faster datapath. Furthermore, the Data Forwarder only supports the forwarding of ALU components, branch and store instructions need two empty cycles between uses of the same register.

4. ASIP Control

4.1 Receive Signal

Receive signal is an external signal which is set by the testbench.

Receive signal is set if:

- If busy signal is 0
 - \circ If operation flag is set to 1. (For information regarding operation flag read section 4.3)
 - If network is still transmitting data

4.2 Send Signal

Send signal is an external signal which is set by the testbench. Send signal is set if:

- if busy signal is 0
 - If operation flag is set to 0. (For information regarding operation flag read section 4.3)
 - If CPU is still transmitting data.

4.3 Operation Flag

Operation flag is used to make sure the host program switches between receive and send operations and that neither is starving. Operation flag is set to 1 when a receive operation is to be run, and 0 for send. If either send or receive are not ready upon their corresponding turn, the operation bit is toggled.

4.4 Busy Signal

The busy signal is asserted when the ASIP is processing data. When it is de-asserted, the ASIP has finished processing data, and the host can check the output signals.

4.5 ASIP Handshake and Usage

The ASIP and the host communicate via a handshake process using the control signals recv, send, attack, and busy. Following are the steps in the handshake, and the behaviour of each control signal.

Receiving Data from Network to Host CPU

Network	ASIP	Host CPU			
	AOII	11031 01 0			
Put input on network_in.					
Assert send to indicate to the ASIP to start					
processing.	A (1 (' ' ' ' ' ' ' ' ' ' ' ' ' ' ' ' '				
	Assert busy to indicate it is working.				
It is now safe to remove input from network_in.					
	If the tag does not match, assert attack for 3 clock cycles and stop, otherwise, skip to after 'END ATTACK'.				
If attack is asserted, then the input was corrupted.					
	De-assert busy.				
	END ATTACK				
	Assert valid.				
	Put output on network_out for one clock cycle.	Retrieve output within one clock cycle.			
	De-assert busy and valid.				
END VALID					

Sending Data from Host CPU to Network

Host CPU	ASIP	Network				
Put input on cpu_in.						
Assert recv to indicate to the ASIP to start processing.						
	Assert busy to indicate it is working.					
It is now safe to remove input from cpu_in.						
	If the parity check fails, assert error for 3 clock cycles, otherwise, skip to after 'END ERROR'.					
If error is asserted, then the data was corrupted.						
·	De-assert busy.					
	END ERROR					
	De-assert busy.					
	Put output on network_out until the next valid network_out data.	Retrieve output before the next network send is available.				
	END VALID					

5. Processor Performance

5.1 Metrics

Metric	Score
Minimum Clock delay	4.045 ns
Clock frequency	247 MHz
Throughput (Upload Download)	233.1 Mbps (116.6 Mbps)
LUT usage	319
FF usage	421
Power usage	4.01 W
Junction Temperature	43.4°C

5.2 Critical Path



The design is limited by its critical path of 4.045ns delay. If this path were reduced or optimised, the delay for the design could be further reduced to 3.861ns resulting an improved clock frequency of 259MHz.

The longest path through the circuits is from the exit point of the MEM/WB stage register through the forwarding unit and ending at the EX/MEM register.

If the EX stage were to be split to two sections, with a new stage added for the forwarding unit, then the critical path could be reduced allowing for a shorter clock delay and a larger clock frequency. However, this would increase the length of the pipeline, thus slightly reducing the throughput of the processor

5. Appendix

5.1 Assembly Code

```
current firmware>
   this version assumes 5-stage pipelined processor
   .data
key: # the address of key is hardset and known, in memory it'll be at @
    .word 0xAAAA # 1010 101 010 101 010
                   # 15 11 8 5 20
   .text
main:
              $1, $0, 0
   load
                                      # key is at offset 0+0
while:
   # clear signals/ set status reg
   # busy <=0;
   # valid <= 0;
   # attack <= 0;
   # error <= 0;
   # signal register: busy | attack | error | valid
   set_sig 0000
                  # set three bit ctr sig to 0000
   # go to do_recieve
    # handled by hardware:
    # if recv && not busy <- PC = do_recieve
recv_done:
   # reset busy
   set_sig 0000
   # go to do_send
   # handled by hardware:
   # if send && not busy <- PC = do_send
   # unconditional jump to while
           $1, $0, while # $0 = 0, $1 = AAAA
    bne
    nop
```

```
do_receive:
    # the test bench can theoretically pipe data into regs
    # if not we need an instruction for loading from network
    set_sig 1000
                   # set busy, WE ARE BUSY PROCESSING IGNORE NEW DATA
                   # to allow $2, $3, $4 to load by hardware
    nop
   # recieve signal high : data loaded
    # $2 contains input data, 32-bits
    # $3 reserved for parity
    # $4 contains input tag
    #checking tag
    bit_flip $5, $2, $1
                              # bit flip data ($2) by key ($1)
   # rol insn has id stage during previous insn's wb
    # ensure the processor writes on a rising edge, and reads on a falling
    rol
            $6, $5, $1
                               # rol fliped data ($5) by key ($1)
            $7, $6, $0
    XOR
                               # xor the bits of tag, this is an 8 bit res
    nop
    nop
                $7, $4, attack # if tag($7) != tag($4) then attack sit
    bne
                               # control stall if branch is true
    nop
           $1, $0, recv_done
                              # $0 = 0, $1 = AAAA
    # valid <= 1; branch delay slot
    set_sig 1001
                               # set three bit ctr sig to 001
attack:
   # attack <= 1;
    set_sig 1100
           $1, $0, recv_done
    bne
                                # jump to recv_done
    nop
do_send:
                   # set busy, WE ARE BUSY PROCESSING IGNORE NEW DATA
    set_sig 1000
                   # to allow $2, $3, $4 to load
    nop
```

```
# or some kind of load instruction
   # $2 contains input data, 32-bits
   # $3 contains parity
   # $4 reserved for input tag
   #checking parity
   parity $5, $2, $3
                          # check parity of input data ($2) with input parity bit ($3),
                          # put result in rd ($5)
   nop
   nop
          $5, $2, error # if parity error
   bne
   nop
   # generating tag
   bit_flip $5, $2, $1
                             # bit flip data ($2) by key ($1)
   # rol insn has id stage during previous insn's wb
   # ensure the processor writes on a rising edge, and reads on a falling
   rol
           $6, $5, $1
                             # rol fliped data ($5) by key ($1)
   XOR
            $7, $6, $0 # xor the bits of tag, this is an 8 bit result
   nop
   # write data
   store $2, $0, (out_location_data) # store data at 0 + out_location_data
   store $7, $0, (out_location_tag) # store generated tag at 0 + out_location_tag
                                             # jump to while
          $1, $0, while # $0 = 0, $1 = AAAA
   bne
error:
   # soft_error <= '1';</pre>
   set_sig 1010
   bne
         $1, $0, while
                            # jump to while
   nop
```

See linked: Processor Source code.