

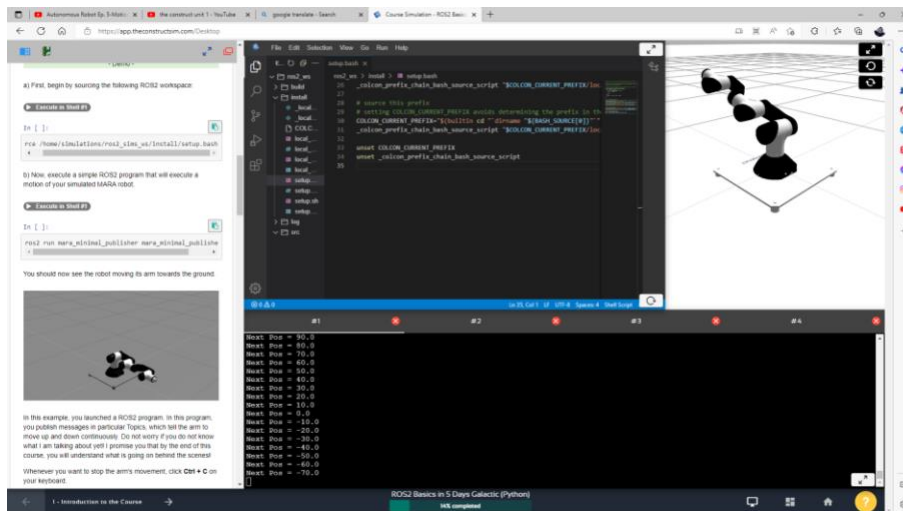




Now, execute a simple ROS2 program that will execute a motion of your simulated MARA robot.

```
#1  #2 
```

```
user:~$ ros2 run mara_minimal_publisher mara_minimal_publisher_v1.py
```



You should now see the robot moving its arm towards the ground.

Whenever you want to stop the arm's movement, click **Ctrl + C** on your keyboard.

```

^CTraceback (most recent call last):
  File "/home/simulations/ros2_sims_ws/install/mara_minimal_publisher/lib/mara_minimal_publisher/mara_minimal_publisher_v1.py", li
n <module>
    sleep(1.)
KeyboardInterrupt
user:~$

```